Raúl J. Maldonado

*March 23, 1993; Querétaro, México.

Interest Areas: Artificial Inteligence, Control Theory, Robotics and Applied Mathematics.

Education

Tecnológico de Monterrey Monterrey, México B.S. Mechatronic Engineering, 2011 - 2016

Additional Education.....

HsKa, exchange semester Karlsruhe, Germany Courses on environmental, magnetic, physical and electric sensors. 2014 (Jan-Jul)

HsKa, renewable energy program

Diploma on renewable energies storing, production and in-depth theory. 2014 (Jan-Jul)

HWAtech Berlin, automotive summer school

Automotive engineering intensive course —diploma attained.

Udacity, Machine Learning Nanodegree

Specialization course. Project for graduation: NLP "what to read?" recommendations. 2017

Karlsruhe, Germany

Berlin, Germany

Summer 2014

2014 (Jul-Dec)

Mexico City, Mexico

Querétaro, México

ITESM - Monterrey

ITESM - Monterrey

2017 (Jul-Now)

MIT - Boston

2015-2016

2015-2016

Online

Experience

Work Experience Fraunhofer Institute (Full time) — Mechatronic and Smart Data Engineer Karlsruhe, Germany

Vision system and mechatronic implementation of a Sorting Machine for LEGO.

INDI (Part Time) — Design & Control Engineer Monterrey, Mexico Construction of the control, mechanic and electronic system of an exoskeleton. 2015 (Jul-Dec)

Intelimetrica (Full Time) — Big Data Engineer & Data Scientist

• Translate the clients' business needs into data driven solutions.

• Write statistical, data analysis presentations for the customers.

• Work with the DEV Team to implement machine-learning models into web platforms. 2016-2017(Jul)

MX-AI Solutions (Full time) — CEO & Data Scientist Team Leader

Al solutions for business such as: ML model to identify college dropouts, ML based model

for vocational orientation and a AI model for sentiment analysis from images.

Micro/Nano fabrication, MIT's MTL lab

Manufactured a solar cell, a Cantilever (MEM) and a microfluidic device. summer 2015

Mind controlled A.R. Drone, Eduardo Mendivil, Ph.D.

Programed and implemented an EEG waves controlled air drone.

Petrochemical Plant's Control system, Antonio Favela, Ph.D.

Developed the control system of a PEMEX's petrochemical plant.

Robochallenge - Rumania First Place in Air Race, Robochallenge World Cup

Won the first place in the world cup for the fastest most intelligent autonomous air drone 2015-2016

Scientific Papers submitted and being reviewed

Raúl J. Maldonado, Antonio Favela. "Hybrid Modelation and Implementation of an Inverted Pendulum using Discrete State Space Analysis". ISA Transactions, 2017.

Carlos Sotelo, Antonio Favela, David Sotelo, Ezequiel Cruz, Raúl J. Maldonado. "Design of a control structure to dehydrate and desalt crude oil based on the pairing rules criteria." ISA Transactions, 2017.

Languages

Spanish: Native language English: Proficient (TOEFL 640)

German: Intermediate (A2)