TECHNISCHE UNIVERSITÄT BERLIN Institut für Mathematik



Prof. Dr. Yuri B. Suris

Mathematical Physics I - WS 2018/2019

Jan Techter

http://www3.math.tu-berlin.de/geometrie/Lehre/WS18/MP1/

Exercise Sheet 3

Exercise 1: (6 pts)

Consider the following two one-parameter family of maps acting on \mathbb{R}^2 ($t \in \mathbb{R}$):

$$\Phi^t: (x_1, x_2) \mapsto \frac{(2x_1, 2x_2 \cos t + (1 - x_1^2 - x_2^2) \sin t)}{1 + x_1^2 + x_2^2 + (1 - x_1^2 - x_2^2) \cos t - 2x_2 \sin t},$$

and

$$\Psi^t : (x_1, x_2) \mapsto \left(x_1 + t, \frac{x_1 x_2}{x_1 + t}\right).$$

- (i) Prove that both Φ^t and Ψ^t define dynamical systems.
- (ii) Compute the vector fields f and q of Φ^t and Ψ^t respectively.
- (iii) Check whether Φ^t and Ψ^t commute.

Exercise 2: (3 pts)

Consider vector field g from Exercise 1 and reconstruct the corresponding flow Ψ^t in terms of its Lie series, i.e.

$$\Psi^{t}(x_{1}, x_{2})_{i} = \sum_{k=0}^{\infty} \frac{t^{k}}{k!} (L_{g})^{k} (x_{i}), \qquad i = 1, 2.$$

Exercise 3: (5 pts)

Consider the following second-order ODEs in \mathbb{R} :

$$\ddot{x} + \alpha^2 x = 0, \qquad \ddot{x} - \alpha^2 x = 0, \qquad \alpha > 0.$$

For both ODEs:

- (i) Write down the corresponding IVP with initial condition $(x(0), \dot{x}(0)) \in \mathbb{R}^2$.
- (ii) Find an integral of motion, i.e., a function which is invariant under the flow of the IVP.
- (iii) Find the fixed points.
- (iv) Draw the phase portrait. Is there any periodic orbit?
- (v) What can you say about the stability of fixed points (just by looking at the phase portrait)?

Exercise 4: (6 pts)

Let $n \geq 3$, and consider the dynamical system defined by the flow of an n-dimensional IVP with ODEs

$$\dot{x}_i = \prod_{j \neq i}^n x_j, \qquad i = 1, \dots, n. \tag{1}$$

- (i) Prove that the flow is volume preserving.
- (ii) Prove that the functions

$$F_{ij}(x_i, x_j) := x_i^2 - x_j^2, \qquad i, j = 1, \dots, n.$$

are integrals of motion. How many of these are functionally independent?

Hint: Functions are independent, if their gradients are linearly independent.

(iii) Define n new coordinates by the transformation $\varphi: x \mapsto y$ defined by

$$y_i := \frac{1}{x_i} \prod_{j \neq i}^n x_j, \qquad i = 1, \dots, n.$$

Prove that the system of ODEs (1) is transformed into the quadratic system

$$\dot{y}_i = y_i \left(-2y_i + \sum_{j=1}^n y_j \right), \qquad i = 1, \dots, n.$$
 (2)

(iv) Find the functions $K_{ij}(y) := F_{ij}(\varphi^{-1}(y))$. Are the functions K_{ij} , $i, j = 1, \ldots, n$., integrals of motion of the system of ODEs (2)?