

Exercise Sheet 13

Exercise 1:

(10 pts)

In Exercise 1, Sheet 11, we considered the following Lagrangian ($\alpha = 1$)

$$\mathcal{L}(q, \dot{q}) = -\sqrt{1 - \langle \dot{q}, \dot{q} \rangle} - \langle a, q \rangle,$$

where $(q, \dot{q}) \in \mathbb{R}^6$. The Euler-Lagrange equations are

$$\frac{d}{dt} \left(\frac{\dot{q}}{\sqrt{1 - \langle \dot{q}, \dot{q} \rangle}} \right) + a = 0, \quad (1)$$

and the corresponding canonical Hamilton equations are

$$\begin{cases} \dot{q} = \frac{p}{\sqrt{1 + \langle p, p \rangle}}, \\ \dot{p} = -a. \end{cases} \quad (2)$$

Now consider the following discretization of the Lagrangian \mathcal{L} :

$$\mathbf{L}(q, \tilde{q}) = \epsilon \left(-\sqrt{1 - \frac{\langle \tilde{q} - q, \tilde{q} - q \rangle}{\epsilon^2}} - \frac{1}{2} \langle a, q + \tilde{q} \rangle \right), \quad 0 < \epsilon \ll 1,$$

where $q = q(n)$, $\tilde{q} = q(n+1)$, $n \in \mathbb{N}$. Note that first derivative \dot{q} is discretized by the finite difference $(\tilde{q} - q)/\epsilon$, that is, we assume $\tilde{q} = q + \epsilon \dot{q} + O(\epsilon^2)$.

(i) Show that $\mathbf{L}(q, \tilde{q}) = \epsilon \mathcal{L}(q, \dot{q}) + O(\epsilon^2)$.

(ii) Compute the explicit form of the symplectic map defined by the equations

$$p = -\text{grad}_q \mathbf{L}(q, \tilde{q}), \quad \tilde{p} = \text{grad}_{\tilde{q}} \mathbf{L}(q, \tilde{q}).$$

(iii) Use (ii) to find the discrete analog of equations (2). In other words, compute the quantities $(\tilde{q} - q)/\epsilon$ and $(\tilde{p} - p)/\epsilon$. Check that they converge to (2) in the continuous limit.

(iv) Construct the discrete Euler-Lagrange equations

$$\text{grad}_q \mathbf{L}(q, \tilde{q}) + \text{grad}_q \mathbf{L}(\tilde{q}, q) = 0,$$

where $\tilde{q} = q(n-1)$. Check that they converge to (1) in the continuous limit.



Exercise 2:

(10 pts)

In the canonical Hamiltonian phase space \mathbb{R}^4 consider the discrete dynamical system defined by iterations of the map $\Phi : \mathbb{R}^4 \setminus \{q_1^2 = q_2^2\} \rightarrow \mathbb{R}^4$, $(q_1, q_2, p_1, p_2) \mapsto (\tilde{q}_1, \tilde{q}_2, \tilde{p}_1, \tilde{p}_2)$ given by:

$$\begin{cases} \tilde{q}_1 = p_1(q_1^2 + q_2^2) + 2 q_1 q_2 p_2, \\ \tilde{q}_2 = p_2(q_1^2 + q_2^2) + 2 q_1 q_2 p_1, \\ \tilde{p}_1 = \frac{q_1}{q_1^2 - q_2^2}, \\ \tilde{p}_2 = -\frac{q_2}{q_1^2 - q_2^2}. \end{cases}$$

- (i) Prove that the map Φ preserves the canonical Poisson brackets.
- (ii) Prove that the functions

$$\begin{aligned} F_1(q_1, q_2, p_1, p_2) &:= q_1 p_1 + q_2 p_2, \\ F_2(q_1, q_2, p_1, p_2) &:= q_1 p_2 + q_2 p_1, \end{aligned}$$

are two functionally independent integrals of motion of Φ .

- (iii) Prove that F_1 and F_2 are in Poisson involution, i.e., $\{F_1, F_2\} = 0$

Bonus:

(8 pts)

Consider the change of coordinates $\Psi : \mathbb{R}^4 \setminus \{q_1^2 = q_2^2\} \rightarrow \mathbb{R}^4$, $(q_1, q_2, p_1, p_2) \mapsto (Q_1, Q_2, P_1, P_2)$ defined by:

$$\begin{cases} Q_1 = \frac{1}{2}(\log(q_1 + q_2) + \log(q_1 - q_2)), \\ Q_2 = \frac{1}{2}(\log(q_1 + q_2) - \log(q_1 - q_2)), \\ P_1 = q_1 p_1 + q_2 p_2, \\ P_2 = q_1 p_2 + q_2 p_1. \end{cases}$$

- (i) Prove that the map Ψ preserves the canonical Poisson brackets.
- (ii) Prove that Ψ allows to *linearize* the map Φ :

$$\begin{cases} \tilde{Q}_1 = Q_1 + \nu_1(P_1, P_2), \\ \tilde{Q}_2 = Q_2 + \nu_2(P_1, P_2), \\ \tilde{P}_1 = P_1, \\ \tilde{P}_2 = P_2. \end{cases}$$

Here ν_1 and ν_2 are two functions of the integrals of motion to be determined.