## TECHNISCHE UNIVERSITÄT BERLIN Institut für Mathematik



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**Mathematical Physics I - WS 2018/2019** 

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http://www3.math.tu-berlin.de/geometrie/Lehre/WS18/MP1/

## Exercise Sheet 10

Exercise 1: (8 pts)

Consider a one-dimensional mechanical system describing the motion of a point (mass m=1) under the influence of a potential energy

$$U(q) := \frac{\alpha}{q} + \log\left(\frac{q^2}{1+q^2}\right),\,$$

where  $\alpha > 0$  is a parameter.

- (i) Write down Newton equations and the corresponding dynamical system defined through a system of ODEs in  $\mathbb{R}^2$ .
- (ii) Find the fixed points and investigate their stability. Draw the graph of the potential energy.
- (iii) Make a qualitative analysis of the motion in the phase space  $(q, \dot{q})$ . Find the value(s) of  $\alpha$  such that there exist periodic orbits.

Consider a particle of mass m > 0 in  $\mathbb{R}^n$  with Lagrangian

$$\mathscr{L}(q,\dot{q},t) := e^{\alpha t/m} \left( \frac{1}{2} m \langle \dot{q}, \dot{q} \rangle - U(q) \right), \qquad \alpha > 0.$$

- (i) Write down the Euler-Lagrange equations.
- (ii) Fix n=1 and m=1 and consider  $U(q):=-\beta\,q,\,\beta>0$ . Solve the Euler-Lagrange equation with  $(q(0),\dot{q}(0))=(q_0,0),\,q_0>0$ . Compute  $\lim_{t\to+\infty}\dot{q}$ .

Exercise 3: (6 pts)

Consider a point with mass m=1 moving in  $\mathbb{R}^3$  with Lagrangian

$$\mathscr{L}(q,\dot{q}) := \frac{1}{2} \left( \dot{q}_1^2 + \dot{q}_2^2 + \dot{q}_3^2 \right) + \alpha (q_1 \, \dot{q}_2 - q_2 \, \dot{q}_1), \qquad \alpha > 0.$$

- (i) Write down the Euler-Lagrange equations.
- (ii) Show that the system is invariant under rotations about the  $q_3$ -axis.

Hint: Construct the one-parameter Lie group of rotations about the  $q_3$ -axis,  $\Psi_s:(s,q)\mapsto \widetilde{q}=\Psi_s(q)$ , and its infinitesimal generator. The invariance condition of the Lagrangian is  $\mathscr{L}(q,\dot{q})=\mathscr{L}(\widetilde{q},\dot{\widetilde{q}})$ )

(iii) Use Noether's Theorem to find the integral of motion corresponding to the above symmetry. Check directly (using the equations of motion) that this function is an integral of motion.