

1.A IEEE OVERVIEW NOTES

2 - REAL NUMBERS

Real Numbers = rational + irrational

Rational Numbers = integers + non-integral fractions

- **Integers:** infinite & countable
- **Non-integral fractions:** ratio of 2 integers

Irrational Numbers = $\sqrt{2}$, π , e >>> Defined as a limit of sequences of rational numbers; uncountable

Ways to Represent Real Numbers

- Decimal and binary representation [*Know how to convert to either and decimal*]
- **Non-integral fractions representation**
 - Some have finite binary representation
 - Some have repeating infinite binary representation
 - Ex. $1/10 = (0.0001100110011\dots)_2$
- **Irrational numbers representation**
 - infinite & non-repeating for both binary and decimal representations

3 - COMPUTER REPRESENTATION OF NUMBERS

Easiest Way: in binary in 32 bits for only non-negative integers

- 2^{32} is too big to represent in 32 bits: 1 & 32 zeros = 33 bits
- **Biggest 32 bit #** = $2^{32} - 1$ (32 ones)

Negative Integers Computer Representation

- **Sign-and-modulus:** an extra bit to represent the sign
 - **Biggest #:** $2^{32} - 1$ >>> since one bit is used not to represent the sign
- **2's complement**
 - **Non-negative integers:** $[0, 2^{31} - 1]$
 - **Negative integers:** $[2^{31}, 2^{32} - 1]$
 - e.g. $-x$, where $x = [0, 2^{31} - 1]$
 - So $(-x)$ is stored as a positive integer: $2^{32} - x$
 - Basically to verify, bitstrings of $x + (-x) = 2^{32}$
 - Since $2^{32} - x = (2^{32} - 1 - x) + 1$, and
 - $2^{32} - 1$ is all 1s
 - So change all 1's to 0's and vice versa, and add 1
 - Pros: no special hardware needed for integer subtraction
- **1's complement** = $-x$ is stored as $2^{32} - x - 1$

Non-integral Computer Representation (using binary)

- **Fixed Point Representation**
 - Divided into 3 fields: sign(1) + number before binary decimal point (15) + binary decimal or fraction(16)
 - CONS: limits size of numbers being stored >> only $[2^{-16}, 2^{15}]$
- **Floating Point Representation/exponential/scientific notation**
 - To "normalize" = to use floating point representation
 - **Nonzero Real Numbers (again in binary notation always)**
 - $x = \mp m \times 2^E$, where $1 \leq m < 2$
 - m = significand, E = exponent
 - $m = (b_0 b_1 b_2 \dots)_2$ with $b_0 = 1$
 - Sign (1) + exponent (8) + significand (23)
 - We can represent exponents from $[-128, 127]$
 - Because 8 bits in binary converts to 128 in decimal & 2's complement
 - E.g. we can store big numbers like 2^{71}
 - $(1.00)_2 \times 2^{71}$, where we just store 71 in exponent

precision = hidden bits + E bits.

- **Infinite binary representation:** e.g. $1/10 = (1.100110011\dots)_2 \times 2^{-4}$
- **Number Zero** = can't be normalized; everything is just zero
- **The Gap** = number 1 and the next largest floating point number (**precision**/machine epsilon)
 - $B_0 b_1 b_2 \dots b_{22} = 1.000\dots 0001$, $b_{22} = 1$
 - Precision $\epsilon = 2^{-22}$
 - i.e. number of significant bits
 - *Gap gets bigger as numbers get bigger*
 - **To find gap:** find largest number bigger than 1 in binary and convert into decimal. The gap is the difference
 - **The next bigger floating point number is:** $\epsilon \times 2^E$
 - **Gap between 0 & smallest positive number:** MUCH BIGGER than the other gaps
 - [LATER ON] this gap is filled by subnormal numbers

$$\begin{aligned} &= 2^{k-1} - 1 \\ &= 2^1 - 1 \\ &= 1 \end{aligned}$$

- **Practices:** 11/2 and 1/10
- **Exponent Field for Normalized Numbers**
 - Range is $[1, 254]_{10}$ or $[00000001, 11111110]_2$ or $[-126, 127]$
 - Representing actual exponents values of $E_{\min} = -126$ & $E_{\max} = 127$
 - **Smallest Normalized Number:** 1.000×2^{-126}
 - **Largest Normalized Number:** $1.1111 \times 2^{127} = (2 - 2^{-23}) \times 2^{127}$
- **Last Line:** when everything is just 1 >>> Represent $\mp INF$ & NaN... **depends on fraction field**

Double Precision: More accurate bc can store more bits (total **64 bits**)

Table 2: IEEE Double Precision

Extended Precision: 80 bit word, sign(1) + exponent (15) + fraction (64)

- Leading bit is NOT hidden! **No hidden bit**
- **First number larger than 1 >>> $1 + 2^{-63}$**

5 - ROUNDING AND CORRECTLY ROUNDED ARITHMETIC

Floating Point Numbers

- Floating point numbers is a small subset of real numbers
- Subnormal
- Normal
- ∓ 0
- $\mp INF$
- **** DOES NOT INCLUDE NaN!!!**

If exponent bitstring is $a_1 \dots a_{11}$	Then numerical value represented is
$(0000000000)_2 = (0)_{10}$	$\pm(0.b_1b_2b_3\dots b_{52})_2 \times 2^{-1022}$
$(0000000001)_2 = (1)_{10}$	$\pm(1.b_1b_2b_3\dots b_{52})_2 \times 2^{-1022}$
$(0000000010)_2 = (2)_{10}$	$\pm(1.b_1b_2b_3\dots b_{52})_2 \times 2^{-1021}$
$(0000000011)_2 = (3)_{10}$	$\pm(1.b_1b_2b_3\dots b_{52})_2 \times 2^{-1020}$
\downarrow	\downarrow
$(0111111111)_2 = (1023)_{10}$	$\pm(1.b_1b_2b_3\dots b_{52})_2 \times 2^0$
$(1000000000)_2 = (1024)_{10}$	$\pm(1.b_1b_2b_3\dots b_{52})_2 \times 2^1$
\downarrow	\downarrow
$(1111111100)_2 = (2044)_{10}$	$\pm(1.b_1b_2b_3\dots b_{52})_2 \times 2^{1021}$
$(1111111101)_2 = (2045)_{10}$	$\pm(1.b_1b_2b_3\dots b_{52})_2 \times 2^{1022}$
$(1111111110)_2 = (2046)_{10}$	$\pm(1.b_1b_2b_3\dots b_{52})_2 \times 2^{1023}$
$(1111111111)_2 = (2047)_{10}$	$\pm\infty$ if $b_1 = \dots = b_{52} = 0$, NaN otherwise

When X is Not a Floating Number, you either:

1. x_- : closest floating point number LESS than x
2. x_+ : closest floating point number GREATER than x

Rounding with Single Precision Example

- $x = (b_0b_1b_2\dots b_{23}b_{24}b_{25}\dots)_2 \times 2^E$
- When x is positive
 - x_- is between 0 & $x = (b_0b_1b_2\dots b_{23}b)_{23} \times 2^E$ >>> Truncating m at the 23rd bit
- When x is negative
 - x_+ is between 0 & $x = (b_0b_1b_2\dots b_{23}b)_{23} \times 2^E$ >>> Truncating m at the 23rd bit

Rounding Modes

- **Round down:** $\text{Round}(x) = x_-$
- **Round up:** $\text{Round}(x) = x_+$
- **Round towards zero:** either x_- or x_+ ... **whichever is between 0 & x**
 - **Truncating extra bits**
- **Round to nearest:** either one, whichever is closest to x. **[most used]**
 - If tied, chose one with its *least significant bit equal to zero*

**** always better to round rather than truncate**

- Ex. 3.14159... 3.142 is more accurate than 3.141

Absolute Rounding Error (ARE): difference between $\text{round}(x)$ and x, but depends on rounding mode

- ARE is less than gap between $[x_-, x_+]$
- ARE for **round to nearest** is no more than $\frac{1}{2}$ of that gap^
- **For round to nearest:** $|\text{round}(x) - x| < \frac{1}{2} \epsilon \times 2^E$
- **For other rounding modes:** $|\text{round}(x) - x| < \epsilon \times 2^E$

Relative Rounding Error

$$\delta = \frac{\text{round}(x)}{x} - 1 = \frac{\text{round}(x) - x}{x} \gg \gg \text{round}(x) = x(1 + \delta)$$

Since for normalized numbers >>> $x = m \times 2^E$, where $m \geq 1$

- For round to nearest: $|\delta| \leq \frac{\frac{1}{2}\epsilon \times 2^E}{2^E} = \frac{1}{2}\epsilon$
- For other rounding modes: $|\delta| < \frac{\epsilon \times 2^E}{2^E} = \epsilon$

Floating Point Operations

$x \oplus y = (x + y)(1 + \delta)$... δ depends on rounding mode ^^ refer above

Rounding Rules Do Not apply for SEQUENCE OF OPERATIONS

E.g. $a + b - c$, where $a = 1$, $b = 2^{-25}$, $c = 1$ & using **single precision** and **rounding to nearest**

- First, turn values into binary
 - $a = c = 1.0 \times 2^0$ and $b = 1.0 \times 2^{-25}$
- First operation: $a + b = 1.000000000000000000000001$
 - Not single precision point so **rounded to just 1**
- Last operation: $1 - c = 1 - 1 = 0$
- **NOT CORRECT**: should be 2^{-25}

How do we correctly round arithmetic operations? Complicated

E.g. $x + y$, single precision & $x = m \times 2^E$ and $y = p \times 2^F$

Case 1: $E = F$

- Just add significands $m \& p \ggg (m + p) \times 2^E$
- **normalization** >> if $m+p > 2$ or $m+p < 1$
 - Ex. $3 = (1.100)_2 \times 2^1$ $2 = (1.000)_2 \times 2^1$ Normalize: $(1.100000000000000000000000)_2 \times 2^1$

Case 2: $E > F$

- Align the significands; i.e. changing the exponents of one number so $E = F$
 - So one number will NOT be normalized
- Ex. $3 = (1.100)_2 \times 2^1$ $3/2 = (1.100)_2 \times 2^1$ $(1.100000000000000000000000)_2 \times 2^1$
- Normalize if necessary

Case 3: when one exponent is wayyy to big

Now consider adding 3 to 3×2^{-23} . We get

Result is not in single precision floating point syntax

- Has more than 24 bits, shown by “|”
- Normalize first then round
- **Must round; there is a tie so use 24th bit**
 - Round up

Cancellation: all bits in 2 numbers cancel each other

E.g. $x - y$; $x = (1.0)_2 \times 2^0$; $y = (1.11\dots1) \times 2^{-1}$

- y has 23 bits after the binary point; y is the next floating number smaller than x)
- We must use a **guard bit**: the extra bit after | aka b_{24} ...important for **subtraction**
 - Sometimes we use up to 3 guardbits

Multiplication: no need to align significands >>> $x \times y = (m \times p) \times 2^{E+F}$

- Multiply significand
- Add exponents
- Normalize

6 - EXCEPTIONAL SITUATIONS

Division by Zero

Before IEEE, dividing by zero was to: (1) Find largest floating number (2) Generate interrupt error

Programmers need to make sure that dividing by zero never happens...you dont need to for floating point arithmetic

Ex. resistance formula: $T = \frac{1}{\frac{1}{R_1} + \frac{1}{R_2}} = \frac{1}{\infty + \frac{1}{R_2}} = \frac{1}{\infty} = 0.$

- If one resistor were to have no resistance, then all current will go through that one...so $T = 0$
- **Valid operations & For any positive value of a**
 - $a / 0 = \infty$
 - $a \times \infty = \infty$
 - $a \pm \infty$
- **Invalid Operations:** shit that makes no sense, **all equal to NaN**
 - $\infty * 0$
 - $0 / 0$
 - $\infty - \infty$
 - **Any NaN related operations**
- To recover from NaN, we can look at the fraction field
- $0 = -0 \gg \infty \neq -\infty$

Arithmetic Comparisons: e.g. comparing a & b

- **Normal comparison operations work for: finite real numbers, floating point numbers & $\pm \infty$**
- **Unordered:** If a or/and b has NaN value: $=$, $<$ & $>$ dont work
 - $(a \leq b) \neq (not(a > b)) \gg$ (true), the second one is (false)

Overflow: the result of arithmetic operation is **finite** but **larger** than the largest floating point number that can be stored
Suppose that the overflowed value is **positive**. Then

rounding model	result
round up	∞
round down	N_{max}
round towards zero	N_{max}
round to nearest	∞

- **Underflow** is said to occur when

$$0 < | \text{true result} | < N_{min},$$

where N_{min} is the **smallest** normal floating point number.

- Historically the response was usually:

replace the result by zero.

- In **IEEE standard**, the result may be a **subnormal** number instead of zero – allowing results **much smaller** than N_{min} .
- But there may still be a significant loss of accuracy, since subnormal numbers have fewer bits of format.

① Decimal to Fraction

$$0.2\overline{72}$$

Solution:

$$x = 0.2\overline{72}$$

$$100x = 2\overline{7.2}$$

$$100x - x = 2\overline{7}$$

$$x = \frac{2\overline{7}}{99}$$

② Binary \leftrightarrow Decimal

$$* 101.11001_2 = (?)_{10}$$

$$= 101 + \frac{11001}{2^5}$$

$$= 2^2 + 2^0 + \frac{(2^0 + 2^3 + 2^4)}{2^5}$$

$$= 5 + (24/32)$$

$$* 0.0101\dots_2 = (?)_{10}$$

$$x = 0.010\overline{1}$$

$$2^2 x = 1.\overline{01}$$

$$3x = 1$$

$$x = 1/3$$

$$* (12)_{10} = (?)_2$$

$$\begin{array}{r|l} 2 & 12 \\ \hline 2 & 6 \\ 2 & 3 \\ 2 & 1 \end{array} \begin{array}{l} 0 \\ 0 \\ 1 \\ 1 \end{array} \uparrow (1100)_{10}$$

$$* (7.35)_{10} = (?)_2 = 111.010110$$

$$\begin{array}{r|l} 2 & 7 \div 2 \\ \hline 2 & 3 \\ 2 & 1 \end{array} \begin{array}{l} 1 \\ 1 \\ 1 \end{array} (111)_2$$

$$0.35 \times 2 = 0.7 \quad (010110)_2$$

$$0.7 \times 2 = 1.4$$

$$0.4 \times 2 = 0.8$$

$$0.8 \times 2 = 1.6$$

$$0.6 \times 2 = 1.2$$

$$0.2 \times 2 = 0.4$$

$$0.4 \times 2 = 0.8$$

③ 2's complement

* normal way: invert & +1

* fast:

- ① from right, copy everything as it is until first 1 (including the first 1)
- ② invert rest before/on left of 1.

$$11001001000$$



$$00110111000$$

CANCELLATION: complete or partial loss of accuracy

Approximating a Derivative by a Difference Quotient: Good Example of Cancellation

Given f a continuous differentiable function, where f' also exists. We have a program that evaluates $f'(x)$.

How do we estimate the derivative of f at x (i.e. $f'(x)$)?

- $f'(x)$ is the slope of tangent line at $(x, f(x))$
 - **Limit of difference quotient** = $\frac{f(x+h) - f(x)}{h}$, as h converges to 0
 - **Evaluate how small h can get...**
 - For $f(x) = (\sin(x))$, assume $x = 1$ & $h = [10^{-1}, 10^{-20}]$
 - **Error** = |derivative - difference quotient|
 - **FINDINGS: GRAPH**
 - As h gets smaller, error gets smaller. But when h gets too small, its worse... WHY? Let $X = 1$
 - When h is slightly bigger than machine epsilon, values $(\sin(x+h) \& \sin(x))$ partially cancel
 - When h is smaller than $\frac{1}{2}$ of machine epsilon, $x+h = 1+h$ is rounded just one
 - No significant digits
 - For $f(x) = \sin(x)$, best to use $h = \sqrt{\epsilon}$
 - **Discretization Error** = using h too big
 - **Cancellation Error** = using h too small
 - **FINDINGS:** initial phase where error gets smaller as h gets smaller (when $h > \epsilon$)
 - Assume $f''(x)$ exists, so z exists. z is between x & $x+h$
 - $f(x+h) = f(x) + hf'(x) + \frac{h^2}{2}f''(z)$
 - Truncate above to **Taylor Series**
 - $\frac{f(x+h) - f(x)}{h} - f'(x) = \frac{h}{2}f''(z)$
 - Difference between difference quotient & exact derivative
 - **Discretization error:** $O(h)$
 - **Difference quotient** = slope of line passing through $(x+h, f(x+h))$ & $(x, f(x))$

SUMMARY: cancellation. Use formula for derivative for function is more accurate than difference quotient

Central Difference Quotient: A more accurate approx

- $\frac{f(x+h) - f(x-h)}{2h}$
- Here we assume $f'''(x)$ exists and is continuous
- **When h is small but large enough that cancellation doesn't happen, central difference works better**
- $f(x+h) = f(x) + hf'(x) + \frac{h^2}{2}f''(x) + \frac{h^3}{6}f'''(z_1)$ (A)
 - z_1 between x & $x+h$
- $f(x-h) = f(x) - hf'(x) + \frac{h^2}{2}f''(x) - \frac{h^3}{6}f'''(z_1)$ (B)
 - z_2 between x & $x-h$
- If we subtract (A) - (B), & divide by $2h$
 $\frac{f(x+h) - f(x-h)}{2h} - f'(x) = \frac{h^2}{12}(f'''(z_1) + f'''(z_2))$. << discretization error for central difference quotient
Discretization error: $O(h^2)$

EXAMPLE: numerical cancellation

- See if good approximate of a ratio that has square roots in numerator. Multiple everything by numerator/numerator
- Use Central Difference Quotient

ROOTS

BISECTION METHOD

1. Find a midpoint of interval $[a, b]$, where $f(a)$ & $f(b)$ have different signs... p = midpoint
 - a. Why different signs? Then we know one is below & other is above and line goes through $x=0$ (i.e. root)
2. Find (p) and $f(p)$ and multiply
 - a. If negative, we take first half of interval $[a, p]$
 - b. If positive, we take $[p, b]$
3. Repeat

SECANT

1. Requires 2 initial approximations $x[0]$ & $x[1]$
2. To find the next value :

$$x_{n+1} = x_n - \frac{f(x_n)(x_n - x_{n-1})}{f(x_n) - f(x_{n-1})}$$

Newton's Method

1. Using an initial approximation $x[0]$ calculate $x[1], x[2] \dots$ Using formula:
2. $g(x) = x - \frac{f(x)}{f'(x)}$
3. Keep putting $x=x[0]$ into $g(x)$ till answer converges

UPPER TRIANGULAR SYSTEM

BACK SUBSTITUTION

Example 1

$$\begin{aligned} 2x_1 + 3x_2 - 5x_3 &= 0 \dots \text{eqn(1)} \\ 7x_2 + 5x_3 &= 3 \dots \text{eqn(2)} \\ 2x_3 &= 4 \dots \text{eqn(3)} \end{aligned}$$

LOWER TRIANGULAR SYSTEM

FORWARD SUBSTITUTION

Example 2

$$\begin{aligned} 2x_3 &= 4 \dots \text{eqn(1)} \\ 7x_2 + 5x_3 &= 3 \dots \text{eqn(2)} \\ 2x_1 + 3x_2 - 5x_3 &= 0 \dots \text{eqn(3)} \end{aligned}$$

Ex: Find the LU Factorization
of $A = \begin{bmatrix} 2 & 2 & 3 \\ 5 & 9 & 10 \\ 4 & 1 & 2 \end{bmatrix}$

Goal $A = \begin{bmatrix} 1 & 0 & 0 \\ * & 1 & 0 \\ * & * & 1 \end{bmatrix} \begin{bmatrix} * & * & * \\ 0 & * & * \\ 0 & 0 & * \end{bmatrix}$ $\begin{matrix} L \\ U \end{matrix}$ $\begin{matrix} * = \text{any} \\ \text{real} \end{matrix}$ #

$A \rightarrow U$

Replace R_i by $R_i - kR_j$

L : records the k -values

$$L = \begin{bmatrix} 1 & 0 & 0 \\ s/2 & 1 & 0 \\ 2-3/4 & 1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 2 & 3 \\ 5 & 9 & 10 \\ 4 & 1 & 2 \end{bmatrix}$$

$$\begin{aligned} R_2 - \frac{5}{2}R_1 & \quad k = \frac{5}{2} \\ R_3 - 2R_1 & \quad k = 2 \end{aligned} \quad \begin{bmatrix} 2 & 2 & 3 \\ 0 & 4 & 5/2 \\ 0 & -3 & -4 \end{bmatrix}$$

$$R_3 + \frac{3}{4}R_2 \quad k = -3/4 \quad \begin{bmatrix} 2 & 2 & 3 \\ 0 & 4 & 5/2 \\ 0 & 0 & -17/8 \end{bmatrix}$$

$A = LU$

$$= \begin{bmatrix} 1 & 0 & 0 \\ s/2 & 1 & 0 \\ 2-3/4 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 2 & 3 \\ 0 & 4 & 5/2 \\ 0 & 0 & -17/8 \end{bmatrix}$$

LU Factorization with no pivoting: <https://www.youtube.com/watch?v=a9S6MMcqxr4>

GEPP: <https://www.youtube.com/watch?v=c0i8hFsOV3A>

LU Factorization with partial pivoting: <https://www.youtube.com/watch?v=f6RT4BI4S7M&t=59s>

$Ly = Pb$, $Ux = Y$: <https://www.youtube.com/watch?v=m3EojSAgIao>

- https://www.youtube.com/watch?v=g7z_oQXJWHs

Integer Representation

- sign & modulus
- 2's complement $(0, 2^{31}-1)$
 $(2^{31}, 2^{32}-1)$

NonIntegral Representation

- fixed $(1, 15, 16) = 32$
- floating $(1, 8, 23)$
 - single $(-126, 127) \Rightarrow E+127$

★ NaN

- $q \Rightarrow b_i = 1$
- $s \Rightarrow b_i = 0$

★ how do we store subnormal?
- modify fraction field

★ Find GAP b/w x & next smallest FPN.

$$2^{-23} \times 2^E$$

★ Precision = # bits in significand (+ hidden)

★ ϵ = gap b/w 1 & next SFPN

$$\epsilon = 2^{-23}$$

★ single: 23 = $(7)_{10}$ } sigdigs.
double: 52 = $(16)_{10}$
quad: 112 = $(34)_{10}$

★ Absolute error: $|\text{round}(x) - x| < \epsilon \times 2^E$

★ relative: $\text{round}(x) = x(1+\delta), |\delta| < \epsilon = \frac{\text{round}(x) - x}{x}$

★ $x \oplus y = (x \pm y)(1+\delta)$

★ $a/0 = \infty, a/\infty = 0$

★ Bisection Method. (Signs) \Rightarrow guarantee but slow

- if $f(x)$ is continuous on $[a, b]$ & $f(a) \cdot f(b) < 0$, then $\exists r$, where $f(r) = 0$
- linear convergence: $0 < c < 1$

★ Newton's:

$$X_1 = X_0 - \frac{f(X_0)}{f'(X_0)} \quad f'(X_0) \neq 0$$

an approx root

- quadratic convergence: $c \neq 0$

- error: $e_n = r - x_n$

$$e_{n+1} = C_n (e_n)^2$$

Know when to stop: $x - x_{n-1} = x_{n+1} - x_n$

★ Order of Convergence.

$$\lim_{n \rightarrow \infty} \frac{|P_{n+1} - P|}{|P_n - P|}^\alpha = k$$

$\alpha = 1$ linear

2 quad

3 ...

k = constant of convergence.

P is the convergence.

ex. $P_n = 9^{-2^n}$ converges quad to ∞

$$\lim_{n \rightarrow \infty} \frac{|x_{n+1} - x|}{|x_n - x|} = c \quad P = \infty$$

iterations Bisection

$$n \geq \frac{\log \left(\frac{b-a}{\epsilon} \right)}{\log 2}$$

Secant:

- derivative too annoying, so dude diff. to replace
- superlinearly

$$X_{n+1} = X_n - \frac{f(X_n)(X_n - X_{n-1})}{f(X_n) - f(X_{n-1})}$$

No pivot!

$$A = LU$$

$$A = \begin{bmatrix} 1 & 0 & 0 \\ \frac{1}{2} & 1 & 0 \\ \frac{1}{3} & \frac{1}{3} & 1 \end{bmatrix} \begin{bmatrix} * & * & * \\ 0 & * & * \\ 0 & 0 & * \end{bmatrix}$$

L U

① find U first.

— remember k value.

③ L matrix is k-value.

partial pivoting = switching rows.
↳ find entry of largest magnitude

GEPP

① Forward Elimination

$$AX = B \Rightarrow UX = C \quad (\text{swap if necessary})$$

② get X using backward sub

$$PA = LU$$

~~or~~

P = permutation matrix

↳ matrix of every row switching