```
In [12]: import matplotlib.pyplot as plt
         import matplotlib.path as mpath
         import matplotlib
         from matplotlib.axes import Axes
         %matplotlib inline
         import numpy as np
         import pyvista as pv
         from pyvista import examples
         import pandas as pd
         import xarray as xr
         import time
         import cartopy.crs as ccrs
         pv.global theme.jupyter backend = 'pythreejs'
In [13]: ds = xr.open dataset('/scratch/project 2000789/muramarg/run 5 31/output WAOM check
         dt = xr.open dataset('/scratch/project 2000789/muramarg/run 5 31/output WAOM check
         #dd = xr.open_dataset('/scratch/project_2000789/muramarg/run_5_31/output_WAOM_che
         dg = xr.open dataset('/scratch/project 2000789/boeiradi/waom10 frc/waom10extend g
In [14]: | x = (ds.variables['Xgrid'].values)
         y = (ds.variables['Ygrid'].values)
         z = (ds.variables['Zgrid'].values)
In [15]: print(x.shape)
         (23521, 3675)
In [16]: def make points(i):
             """Helper to make XYZ points"""
             z1 = list(z[:,i])
             x1 = list(x[:,i])
             y1 = list(y[:,i])
             return np.column_stack((x1, y1, z1))
In [17]: def lines from points(points):
             """Given an array of points, make a line set"""
             poly = pv.PolyData()
             poly.points = points
             cells = np.full((len(points) - 1, 3), 2, dtype=np.int_)
             cells[:, 1] = np.arange(0, len(points) - 1, dtype=np.int )
             cells[:, 2] = np.arange(1, len(points), dtype=np.int_)
             poly.lines = cells
             return poly
         #line = lines from points(points)
         #Line
In [18]: # dt.variables['zice'].values
```

#### Attempts without looping

```
In [19]: | mask rho = dt.variables['mask rho']
          zice = dt.variables['zice']
          my xarr = zice*mask rho
          zpts = my_xarr.to_numpy()
          #poly = pv.PolyData(zpts)
          #grid = pv.create grid(zpts)
          #grid
          #zpts.texture_map_to_plane(use_bounds=True, inplace=True)
In [20]:
          # zice points
          def get_zice_points(zice):
              value = zice.to_numpy()
              x = np.arange(value.shape[0])
              y = np.arange(value.shape[1])
              xx, yy = np.meshgrid(x, y, sparse=False)
              xx = xx.reshape(-1, 1)
              xx = xx.flatten()
              yy = yy.reshape(-1, 1)
              yy = yy.flatten()
              value = value.reshape(-1, 1)
              value = value.flatten()
              value = (value)
              return (xx,yy,value)
          # test = dt.variables['zice'].values
          mask rho = dt.variables['mask rho']
          zice = dt.variables['zice']
          a = zice*mask_rho
          xz,yz,zz = get zice points(a)
In [21]: zz = zz/1000/10
In [22]: # print(xz,yz,zz)
          z_{mesh} = np.array([xz,yz,zz]).T
          print(z mesh.shape)
          (352800, 3)
In [23]: z nonzero = [i \text{ for } i \text{ in } z \text{ mesh } if i[2] != 0]
          z_nonzero = np.array(z_nonzero)
          z nonzero.shape
Out[23]: (19084, 3)
```

In [24]: myz = pv.PolyData(z\_mesh)
myz

Out[24]:	PolyData	Information
	N Cells	352800
	N Points	352800
	X Bounds	0.000e+00, 5.590e+02
	Y Bounds	0.000e+00, 6.290e+02
	Z Bounds	-2.134e-01, 0.000e+00
	N Arrays	0

In [25]: myz.plot()

/users/muramarg/.local/lib/python3.9/site-packages/pyvista/jupyter/pv\_pythreej s.py:436: UserWarning: Empty or unsupported dataset attached to actor warnings.warn('Empty or unsupported dataset attached to actor')

In [27]: df

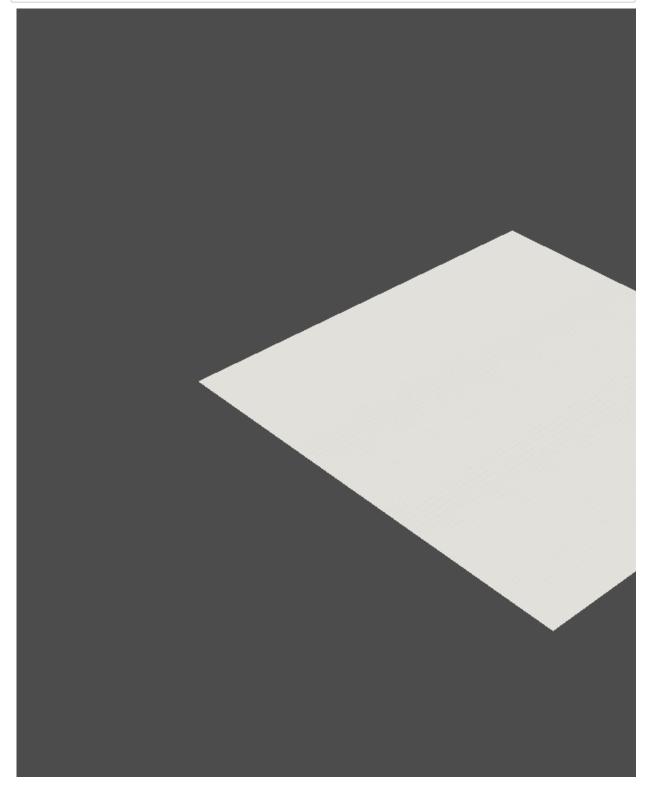
#### Out[27]:

	X	Y	Z
0	0.0	0.0	0.0
1	1.0	0.0	0.0
2	2.0	0.0	0.0
3	3.0	0.0	0.0
4	4.0	0.0	0.0
352795	555.0	629.0	0.0
352796	556.0	629.0	0.0
352797	557.0	629.0	0.0
352798	558.0	629.0	0.0
352799	559.0	629.0	0.0

352800 rows × 3 columns

```
In [28]: structured = pv.StructuredGrid()
    # Set coordinates
    structured.points = coords
    # Set the dimensions of the structured grid
    structured.dimensions = [560, 630, 1]

# Apply an Elevation filter
    # elevation = structured.elevation()
    # elevation.plot()
    structured.plot()
```



```
In [29]: p = pv.Plotter()
p.add_mesh(myz)
p.show()
#myz.plot()
```

/users/muramarg/.local/lib/python3.9/site-packages/pyvista/jupyter/pv\_pythreej s.py:436: UserWarning: Empty or unsupported dataset attached to actor warnings.warn('Empty or unsupported dataset attached to actor')



### **Plotting by looping**

In [32]: zpts = np.array([xz,yz,zz]).T

#print(zpts)

In [33]: point\_cloud = pv.PolyData(zpts)
point\_cloud

Out[33]:	PolyData	Information
	N Cells	119793
	N Points	119793
	X Bounds	4.600e+01, 5.740e+02
	Y Bounds	8.500e+01, 5.230e+02
	Z Bounds	-2.534e-05, -3.069e-14
	N Arrays	0

In [34]: pv.global\_theme.jupyter\_backend = 'pythreejs'
point\_cloud.plot()

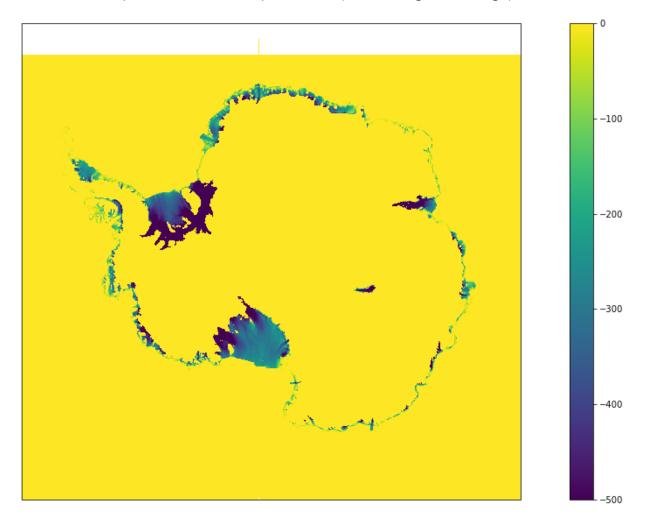
## Plotting with ccrs normally

```
In [35]: #plt.figure(figsize=(10, 10))
# masking land points
mask_rho = dt.variables['mask_rho']
zice = dt.variables['zice']

proj = ccrs.SouthPolarStereo(central_longitude=0.0, true_scale_latitude=None, glough fig = plt.figure(figsize=(20,10))
ax = fig.add_subplot(1, 1, 1, projection=proj)
#plt.scatter(zpts[:, 0], zpts[:, 1], c=zpts[:, 2])
# another way
plt.pcolormesh(dg.lon_rho,dg.lat_rho, zice*mask_rho,transform=ccrs.PlateCarree(), plt.axis("image")
plt.xlabel("X Coordinate")
plt.ylabel("Y Coordinate")
plt.colorbar()
plt.show()
```

/CSC\_CONTAINER/miniconda/envs/env1/lib/python3.9/site-packages/cartopy/mpl/geoa xes.py:1797: UserWarning: The input coordinates to pcolormesh are interpreted a s cell centers, but are not monotonically increasing or decreasing. This may le ad to incorrectly calculated cell edges, in which case, please supply explicit cell edges to pcolormesh.

result = matplotlib.axes.Axes.pcolormesh(self, \*args, \*\*kwargs)



```
In [36]: # point_cloud = pv.PolyData(zpts)
          point_cloud = pv.PolyData(zpts)
          point_cloud
Out[36]:
           PolyData
                             Information
             N Cells
                                 119793
            N Points
                                 119793
                     4.600e+01, 5.740e+02
           X Bounds
           Y Bounds
                    8.500e+01, 5.230e+02
           Z Bounds -2.534e-05, -3.069e-14
            N Arrays
                                     0
 In [ ]:
In [37]: # pv.global_theme.jupyter_backend = 'pythreejs'
          pv.global_theme.jupyter_backend = 'pythreejs'
```

### plotting splines without addition of zice

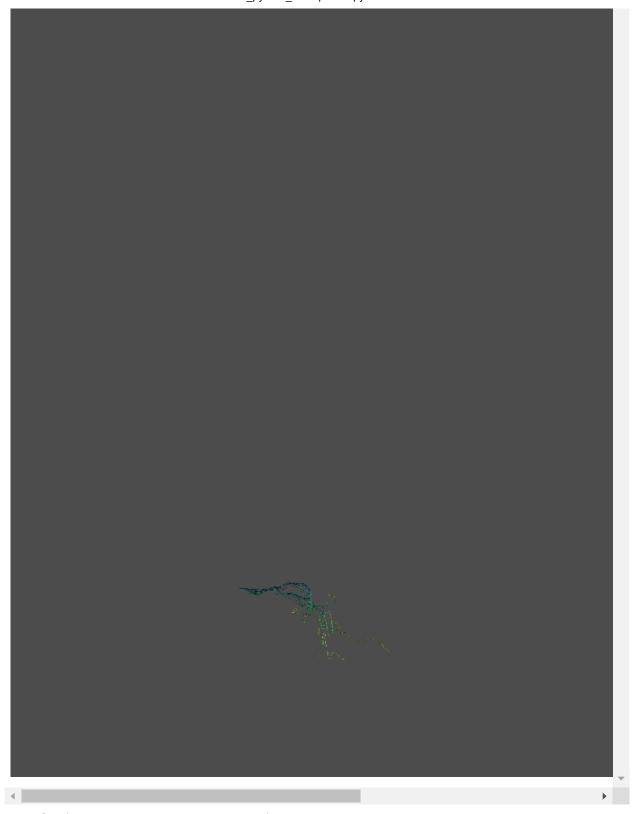
```
In [38]: | def cast_all points():
             #pv.start xvfb()
             start time = time.time()
             network = pv.MultiBlock()
             network.add field data(np.arange(x.shape[0]/900), "time")
             # add backend
             for i in range(0,10):
                 if (i%5 ==0):
                     print(i,'/ 105','in',(time.time()-start_time)/60)
                 points = make points(i)
                 line = lines from points(points)
                 line["days since start"] = np.arange(line.n points)
                 tube = line.tube(radius=0.1)
                 network.append(tube)
                 #Line['time'] = np.arange(x.shape[0])
                 #tube.plot(smooth shading=True)
             # create the scalar bars and plot
             print('ok')
             p = pv.Plotter()
             sargs = dict(
                 n labels=0,
                 label font size = 14
             )
             annotations = {
                 0:'0',2820: '30', 5640: '60', 8460:'90',11280: '120', 14100:'150', 16920:
                 19740: '210', 22560: '240',
             # = p.add mesh(network, smooth shading=True,annotations=annotations, scalar
              = p.add mesh(network, smooth shading=True,show scalar bar=True,annotations=
             #network.plot(show scalar bar=True)
             # = p.add scalar bar(n labels=0, label font size=14, above label=annotations)
             # add the zice shape
             print('plotting')
             # add the plot axes
             _ = p.add_axes(line_width=5, xlabel='x',ylabel='y',zlabel='z',viewport=(0,0,1
             p.show(auto close=False)
             #p.save graphic("testing.svg")
             print('total time:',(time.time()-start time)/60,'min')
         cast all points()
         0 / 105 in 0.00039312044779459633
         5 / 105 in 0.01955617666244507
         ok
         plotting
```



total time: 0.17574191490809124 min

# plotting with attempted addition of zice

```
In [40]: def cast all points(zpts):
             start time = time.time()
             network = pv.MultiBlock()
             network.add field data(np.arange(x.shape[0]/900), "time")
             #print(network)
             for i in range(0,10):
                 if (i%5 ==0):
                     print(i,'/ 105','in',(time.time()-start time)/60)
                 points = make points(i)
                 line = lines_from_points(points)
                 line["days since start"] = np.arange(line.n points)
                 tube = line.tube(radius=0.1)
                 network.append(tube)
                 #Line['time'] = np.arange(x.shape[0])
                 #tube.plot(smooth shading=True)
             # create the scalar bars and plot
             p = pv.Plotter()
             sargs = dict(
                 n_labels=0,
                 label_font_size = 14
             )
             annotations = {
                 0:'0',2820: '30', 5640: '60', 8460:'90',11280: '120', 14100:'150', 16920
                 19740: '210', 22560: '240',
             p.add_mesh(network, smooth_shading=True, annotations=annotations, scalar_bar_a
             # add the zice shape
             point cloud = pv.PolyData(zpts)
             p.add mesh(point cloud, smooth shading=True, color='#a8a8a8')
             # add the plot axes
             = p.add axes(line width=5, labels off=False)
             # = p.enable eye dome lighting()
             p.show()
             print('total time:',(time.time()-start time)/60,'min')
         cast all points(zpts)
         0 / 105 in 4.1604042053222655e-06
         5 / 105 in 0.01761853297551473
         /users/muramarg/.local/lib/python3.9/site-packages/pyvista/jupyter/pv pythreej
         s.py:436: UserWarning: Empty or unsupported dataset attached to actor
           warnings.warn('Empty or unsupported dataset attached to actor')
```



total time: 0.17025843461354573 min

```
In [ ]: # def make_points(i):
              """Helper to make XYZ points"""
              z1 = list(z[:,i])
              x1 = list(x[:,i])
              y1 = list(y[:,i])
              return np.column_stack((x1, y1, z1))
        # points = make_points(1)
        # line = lines_from_points(points)
In [ ]: |# line["scalars"] = np.arange(line.n_points)
        # tube = line.tube(radius=0.1)
        # tube.plot(smooth shading=True)
In [ ]: # p = pv.Plotter()
        # p.add_mesh(stream.tube(radius=0.0015))
        # p.view_xy()
        # p.show(cpos=cpos)
In [ ]:
```