



Elektrobit



UDACITY

Software Safety Requirements and Architecture

Lane Assistance

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Document history

Date	Version	Editor	Description
10/21/2018	1.0	Chunfeng Yang	Initial version.

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Purpose

The purpose of the Software Requirements and Architecture Document is to develop requirements and metrics against which the item can be verified, that will ensure its functional safety.

Inputs to the Software Requirements and Architecture Document

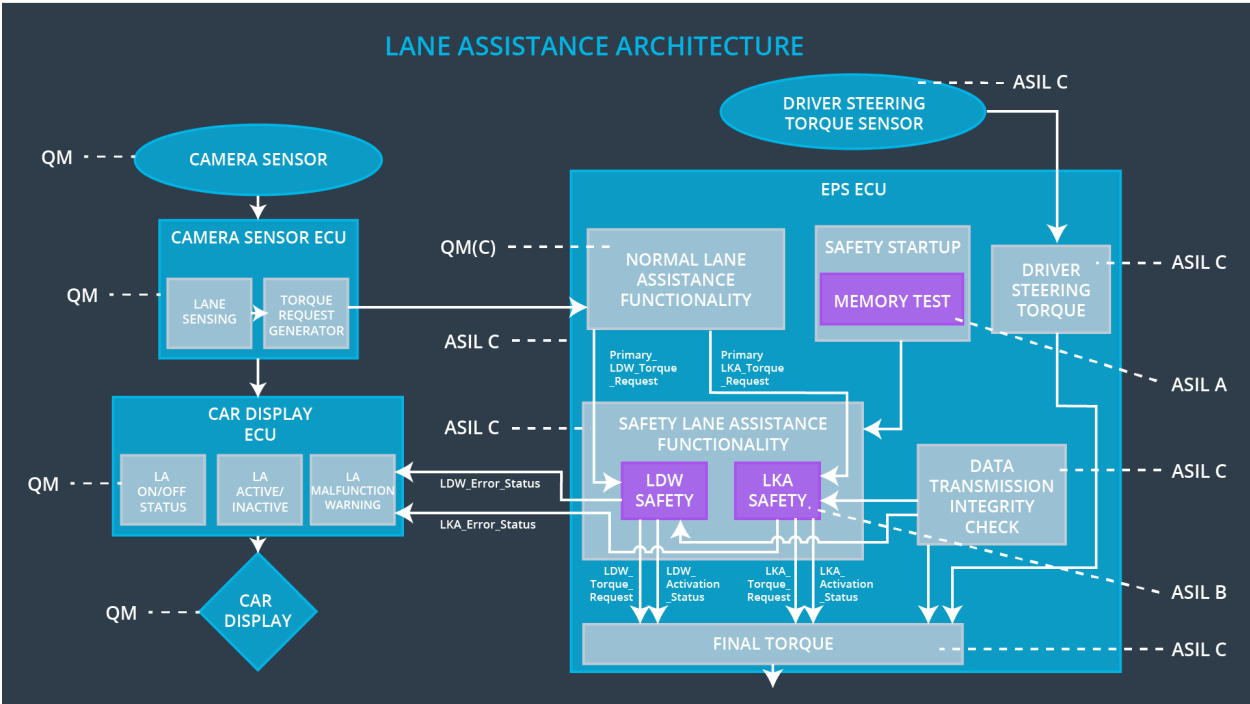
Technical safety requirements

Technical Safety Requirements related to Functional Safety Requirement 01-01 are:

ID	Technical Safety Requirement	ASIL	Fault Tolerant Time Interval	Architecture Allocation	Safe State
Technical Safety Requirement 01	The LDW safety component shall ensure that the amplitude of the 'LDW_Torque_Request' sent to the 'Final electronic power steering Torque' component is below 'Max_Torque_Amplitude'	C	50 ms	LDW safety	LDW shall set the oscillating torque to 0.
Technical Safety Requirement 02	The validity and integrity of the data transmission for 'LDW_Torque_Request' signal shall be ensured.	C	50 ms	Data Transmission Integrity Check	N/A
Technical Safety Requirement 03	As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and the 'LDW_Torque_Request' shall be set to zero.	C	50 ms	LDW Safety	LDW shall set the oscillating torque to 0.
Technical Safety Requirement	As soon as the LDW function deactivates the LDW feature, the 'LDW Safety' software	C	50 ms	LDW Safety	LDW Error Status is zero.

04	block shall send a signal to the car display ECU to turn on a warning light.				
Technical Safety Requirement 05	Memory test shall be conducted at startup of the EPS ECU to check for any faults in memory.	A	Ignition cycle	Memory Test	LDW shall set the oscillating torque to 0.

Refined Architecture Diagram from the Technical Safety Concept



Software Requirements

Lane Departure Warning (LDW) Amplitude Malfunction Software Requirements:

ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 01	The LDW safety component shall ensure that the amplitude of the LDW_Torque_Request sent to the Final Electronic Power Steering Torque component is below Max_Torque_Amplitude	C	50 ms	LDW Safety	LDW torque output is set to zero.

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 01-01	The input signal "Primary_LDW_Torq_Req" shall be read and pre-processed to determine the torque request coming from the "Basic/Main LAF functionality" Software Component. Signal "processed_LDW_Torq_Req" shall be generated at the end of the processing.	C	LDW_SAFETY_INPUT_P ROCESSING	N/A
Software Safety Requirement 01-02	In case the "processed_LDW_Torq_Req" signal has a value greater than "Max_Torque_Amplitude_LDW" (maximum allowed safe torque), the torque signal "limited_LDW_Torq_Req" shall be set to zero, else "limited_LDW_Torq_Req" shall take the value of "processed_LDW_Torq_Req".	C	TORQUE_LIMITER	"limited_LDW_T orq_Req" = 0 (Nm=Newton- meter)

Software Safety Requirement 01-03	The “limited_LDW_Torq_Req” shall be transformed into a signal “LDW_Torq_Req” which is suitable to be transmitted outside of the LDW Safety component(“LDW Safety”) to the “Final EPS Torque” component.	C	LDW_SAFETY_OUTPUT_GENERATOR	LDW_Torq_Req = 0 (Nm)
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ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 02	The validity and integrity of the data transmission for LDW_Torque_Request signal shall be ensured	C	50 ms	Data Transmission Integrity Check	N/A

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 02-01	Any data to be transmitted outside of the LDW Safety component ("LDW Safety") including "LDW_Torque_Req" and "activation_status" (see Software Safety Requirement 03-02) shall be reported by an End to End (E2E) protection mechanism.	C	E2ECalc	LDW_Torq_Re q = 0 (Nm)
Software Safety Requirement 02-02	The E2E protection protocol shall contain and attach the control data: alive counter (SQC) and CRC to the data to be transmitted.	C	E2ECalc	LDW_Torq_Re q = 0 (Nm)

ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 03	As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and the LDW_Torque_Request shall be set to zero	C	50 ms	LDW Safety	LDW_Activation_Status is zero.

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 03-01	Each of the Software elements shall output a signal to indicate any error which is detected by the element. Error signal = error_status_input (LDW_SAFETY_INPUT_PROCESSING), error_status_torque_limiter (TORQUE_LIMITER), error_status_output_gen (LDW_SAFETY_OUTPUT_GENERATOR)	C	All	N/A
Software Safety Requirement 03-02	A software element shall evaluate the error status of all the other software elements and in case any one of them indicates an error, it shall deactivate the LDW feature ("activation_status"=0).	C	LDW_SAFETY_ACTIVATION	Activation_status = 0 (LDW function deactivated)
Software Safety Requirement 03-03	In case of no errors from the software elements, the status of the LDW feature shall be set to activated ("activation_status"=1).	C	LDW_SAFETY_ACTIVATION	N/A
Software Safety Requirement 03-04	In case an error is detected by any of the software elements, it shall set the value of its corresponding torque to 0 so	C	All	LDW_Torq_Req = 0

	that "LDW_Torq_Req" is set to 0.			
Software Safety Requirement 03-05	Once the LDW functionality has been deactivated, it shall stay deactivated till the time the ignition is switched from off to on again.	C	LDW_SAFETY_ACTIVATION	Activation_status = 0 (LDW function deactivated)

ID	Technical Safety Requirement	ASIL	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 04	As soon as the LDW function deactivates the LDW feature, the LDW Safety software block shall send a signal to the car display ECU to turn on a warning light	C	50 ms	LDW Safety	LDW_Error_Status is 0

ID	Software Safety Requirement	ASIL	Allocation Software Elements	Safe State
Software Safety Requirement 04-01	When the LDW function is deactivated (activation_status is set to 0), the activation_status shall be sent to the car display ECU.	C	LDW_SAFETY_ACTIVATION, Car Display ECU	N/A

ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 05	Memory test shall be conducted at startup of the EPS ECU to check for any faults in memory	A	Ignition cycle	Memory Test	LDW_Activation_Status is 0

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 05-01	A CRC verification check over the software code in the Flash memory shall be done every time the ignition is switched from off to on to check for any corruption of content.	A	MEMORYTEST	Activation_status = 0
Software Safety Requirement 05-02	Standard RAM tests to check the data bus, address bus and device integrity shall be done every time the ignition is switched from off to on(e.g. walking 1s test, RAM pattern test. Refer to RAM and processor recommendations.)	A	MEMORYTEST	Activation_status = 0
Software Safety Requirement 05-03	The test result of the RAM or Flash memory shall be indicated to the LDW_Safety component via the "test_status" signal.	A	MEMORYTEST	Activation_status = 0
Software Safety Requirement 05-04	In case of any fault is indicated via the "test_status" signal the INPUT_LDW_PROCESSING shall set an error on error_status_input(=1) so that the LDW functionality is deactivated and the LDW Torque is set to 0.	A	LDW_SAFETY_INPUT_PROCESSING	Activation_status = 0

Refined Architecture Diagram

