

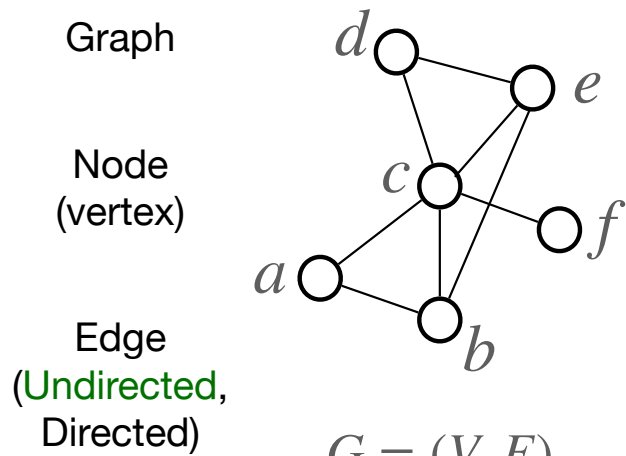
Algorithms

Lecture 6: Representation of Graphs, BFS

Anxiao (Andrew) Jiang

CH 22. Elementary Graph Algorithms

22.1 Representation of Graphs

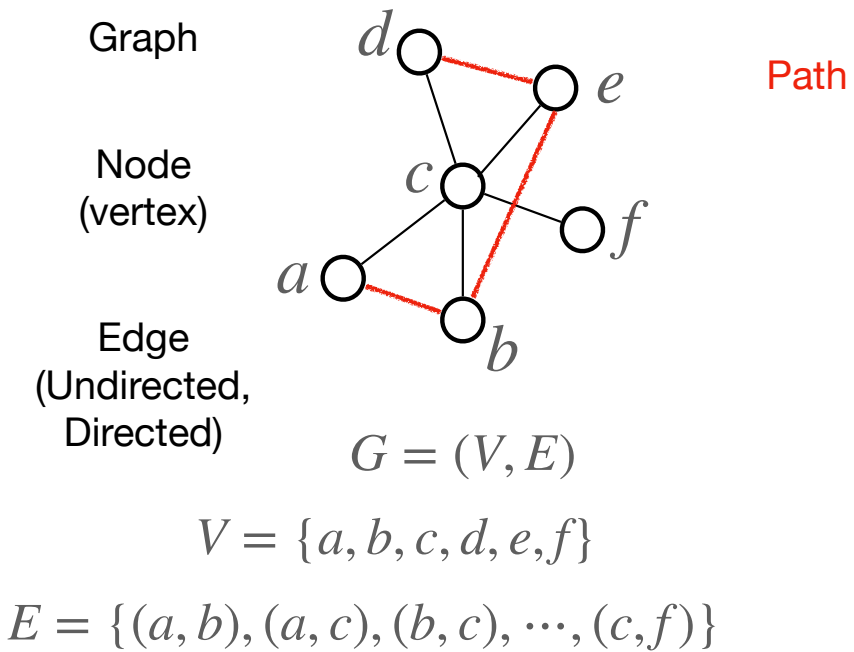


$$V = \{a, b, c, d, e, f\}$$

$$E = \{(a, b), (a, c), (b, c), \dots, (c, f)\}$$

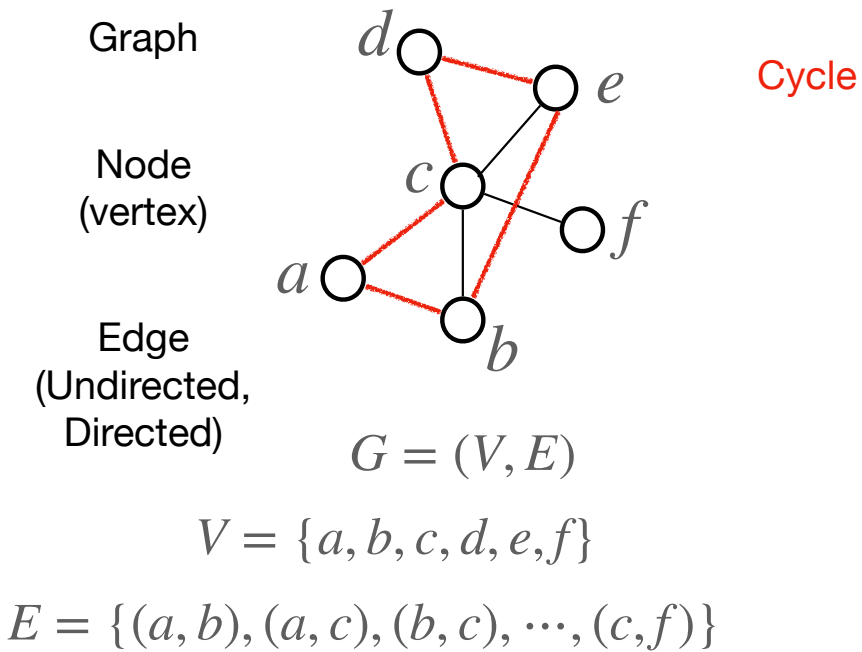
CH 22. Elementary Graph Algorithms

22.1 Representation of Graphs



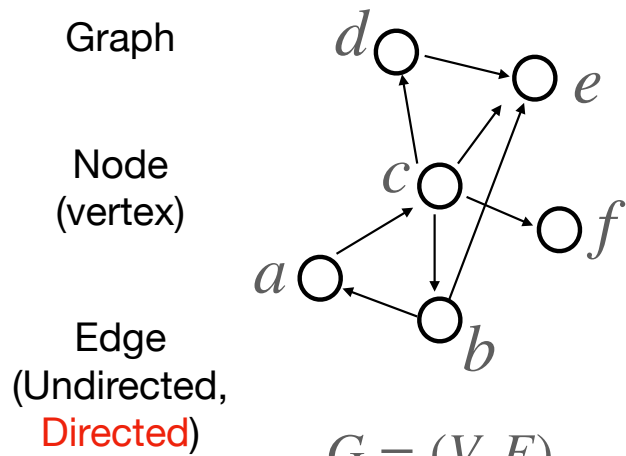
CH 22. Elementary Graph Algorithms

22.1 Representation of Graphs



CH 22. Elementary Graph Algorithms

22.1 Representation of Graphs

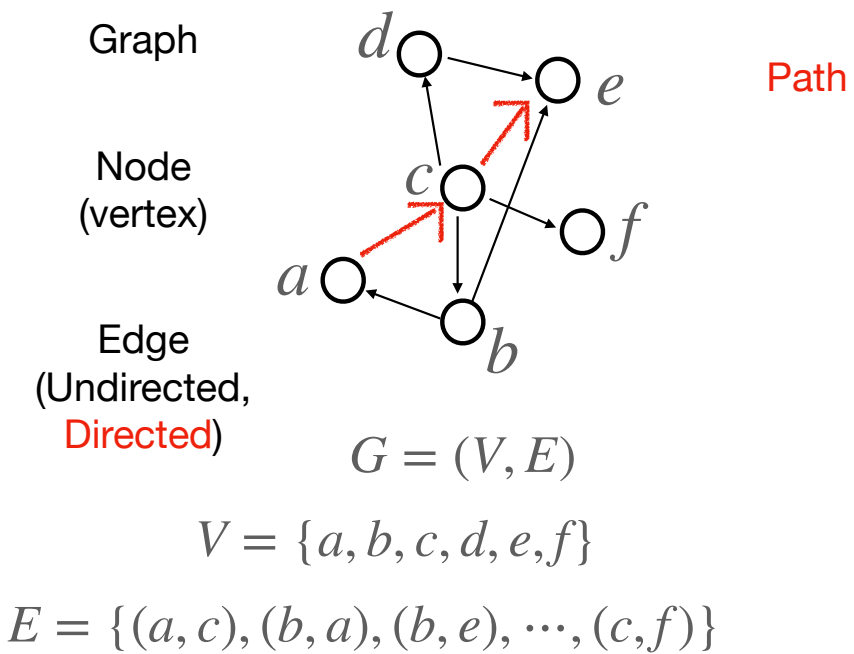


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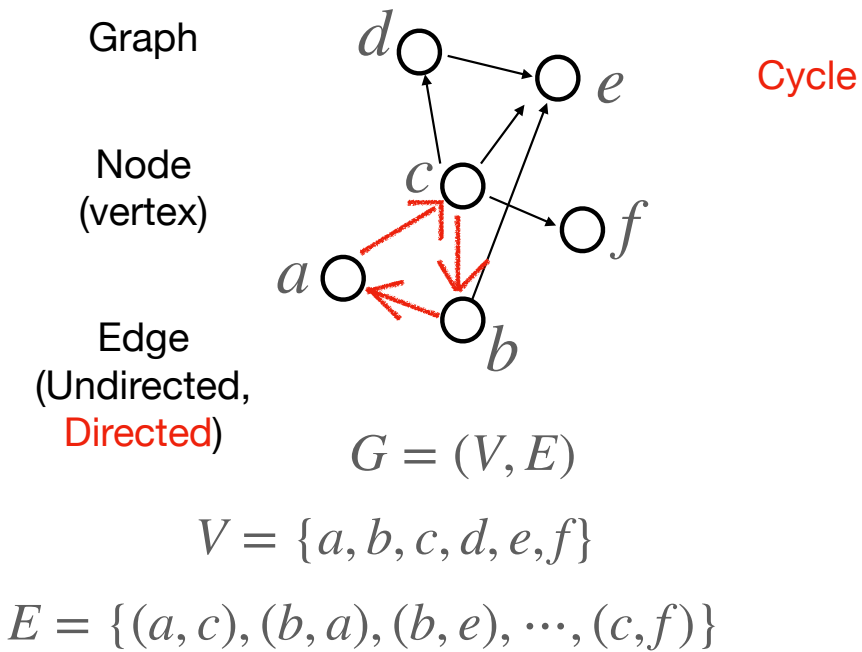
CH 22. Elementary Graph Algorithms

22.1 Representation of Graphs



CH 22. Elementary Graph Algorithms

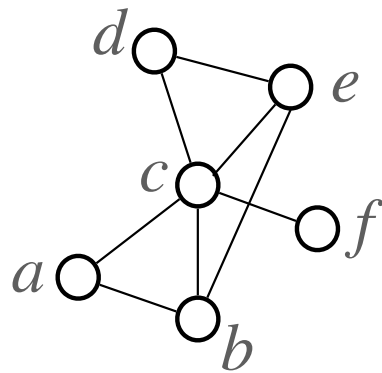
22.1 Representation of Graphs



CH 22. Elementary Graph Algorithms

22.1 Representation of Graphs

Graph
Node
(vertex)
Edge
(Undirected,
Directed)

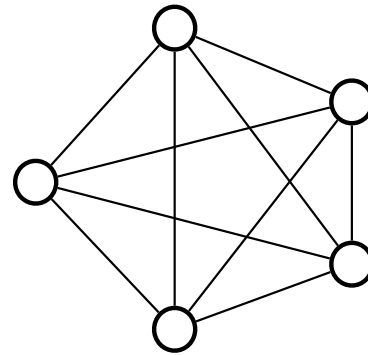


$$G = (V, E)$$

$$V = \{a, b, c, d, e, f\}$$

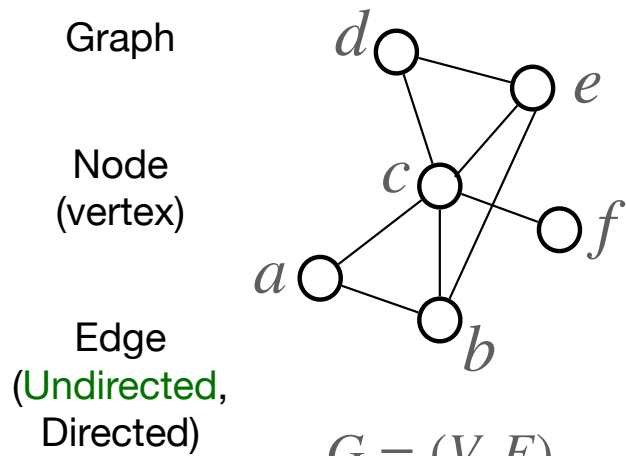
$$E = \{(a, b), (a, c), (b, c), \dots, (c, f)\}$$

Complete Graph:



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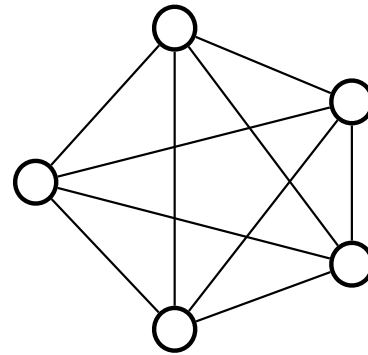
22.1 Representation of Graphs



$$V = \{a, b, c, d, e, f\}$$

$$E = \{(a, b), (a, c), (b, c), \dots, (c, f)\}$$

Complete Graph:



Tree: connected acyclic graph.

Number of edges = number of nodes - 1

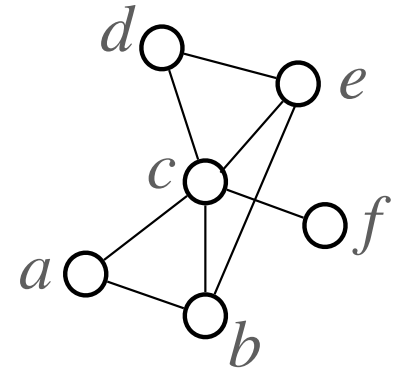
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22.1 Representation of Graphs

Adjacency List

$a : b, c$
 $b : a, c, e$
 $c : a, b, d, e, f$
 $d : c, e$
 $e : b, c, d$
 $f : c$

Size: $O(|V| + |E|)$
 $O(V + E)$



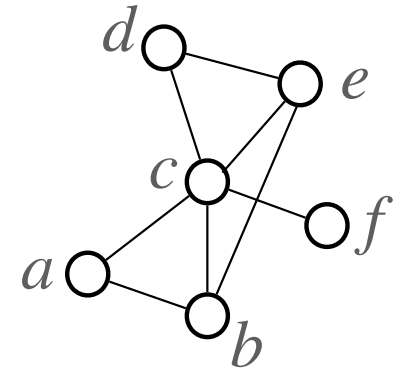
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22.1 Representation of Graphs

Adjacency List

$a : b, c$
 $b : a, c, e$
 $c : a, b, d, e, f$
 $d : c, e$
 $e : b, c, d$
 $f : c$

Size: $O(|V| + |E|)$
 $O(V + E)$



Adjacency Matrix

	a	b	c	d	e	f
a	0	1	1	0	0	0
b	1	0	1	0	1	0
c	1	1	0	1	1	1
d	0	0	1	0	1	0
e	0	1	1	1	0	0
f	0	0	1	0	0	0

Size: $O(|V|^2)$
 $O(V^2)$

CH 22. Elementary Graph Algorithms

22.2 Breadth First Search (BFS)

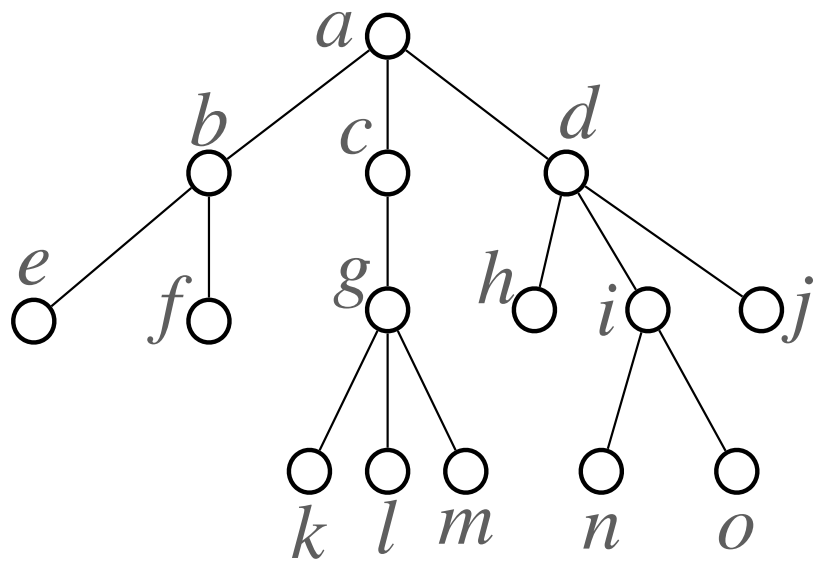
Basic idea:

Starting at a node,
We first check its 1-hop neighbors,
then check its 2-hop neighbors (neighbors of 1-hop neighbors),
then check its 3-hop neighbors (neighbors of 2-hop neighbors),
then check its 4-hop neighbors (neighbors of 3-hop neighbors),
.....,
until all reachable nodes are checked.

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22.2 Breadth First Search (BFS)

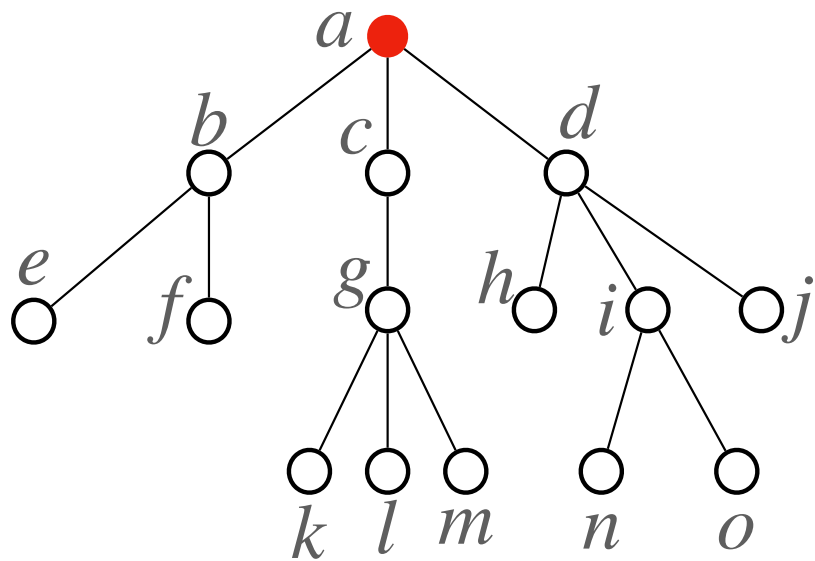
Example of BFS on a tree:



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22.2 Breadth First Search (BFS)

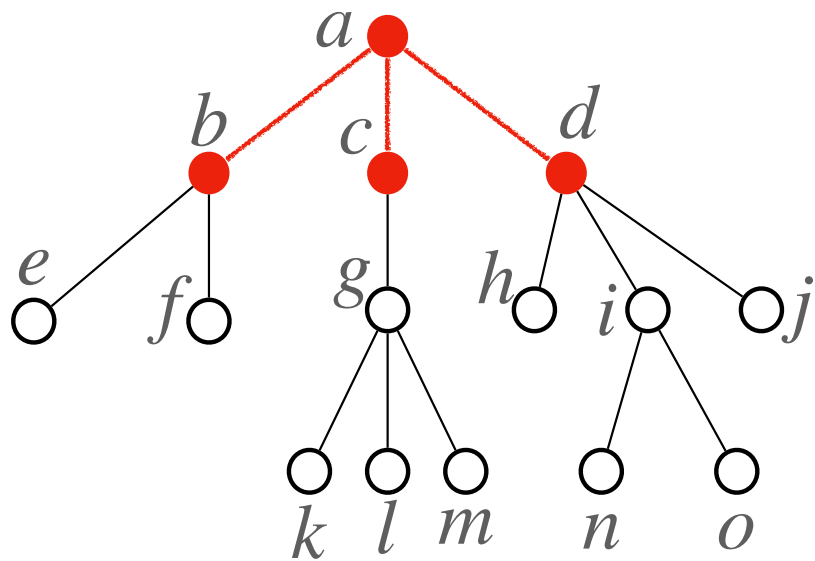
Example of BFS on a tree:



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22.2 Breadth First Search (BFS)

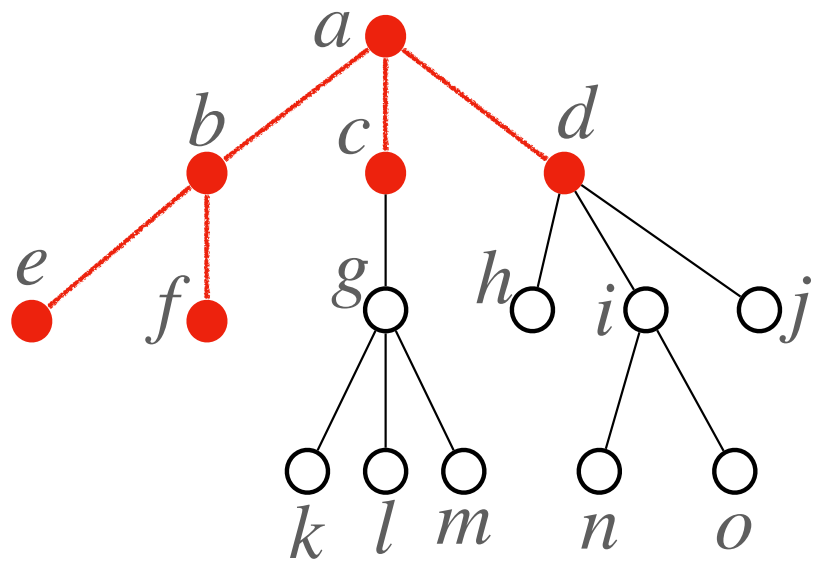
Example of BFS on a tree:



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22.2 Breadth First Search (BFS)

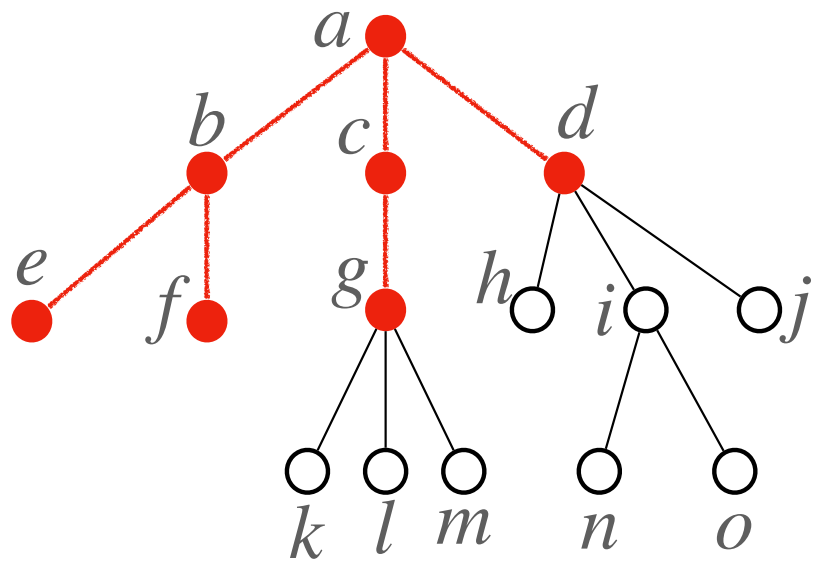
Example of BFS on a tree:



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22.2 Breadth First Search (BFS)

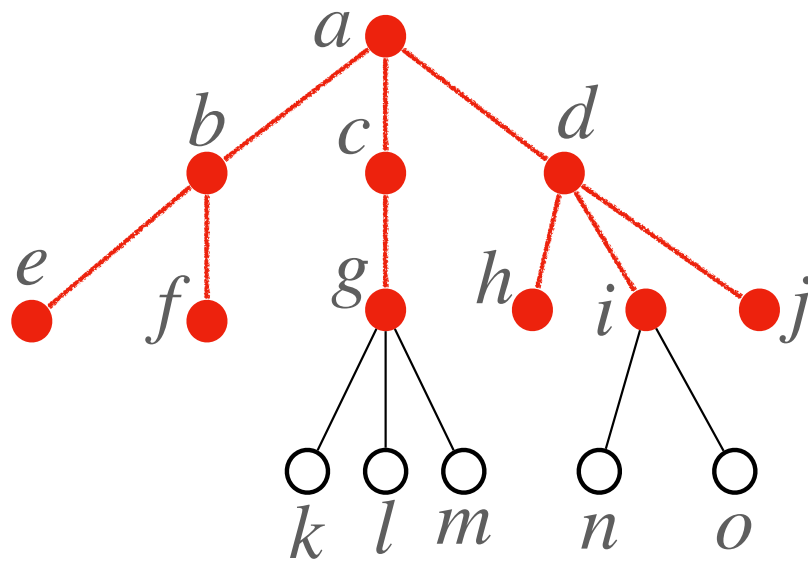
Example of BFS on a tree:



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22.2 Breadth First Search (BFS)

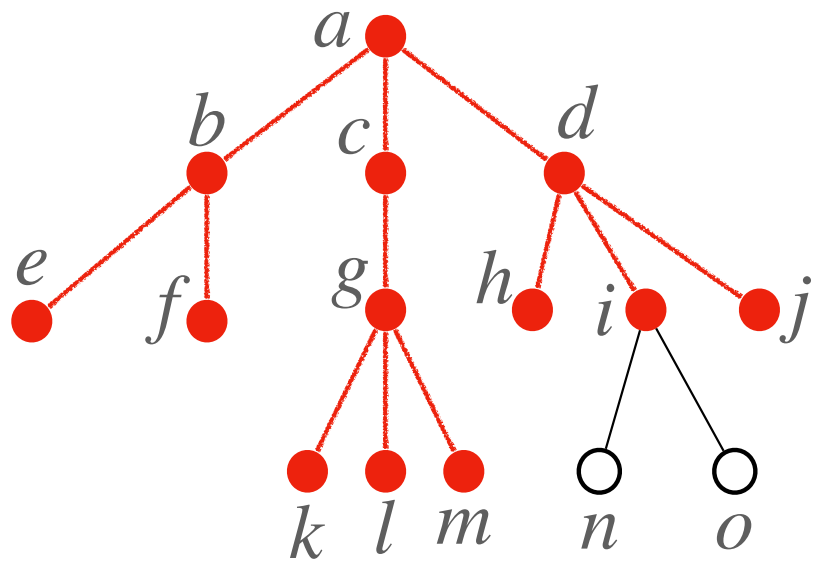
Example of BFS on a tree:



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22.2 Breadth First Search (BFS)

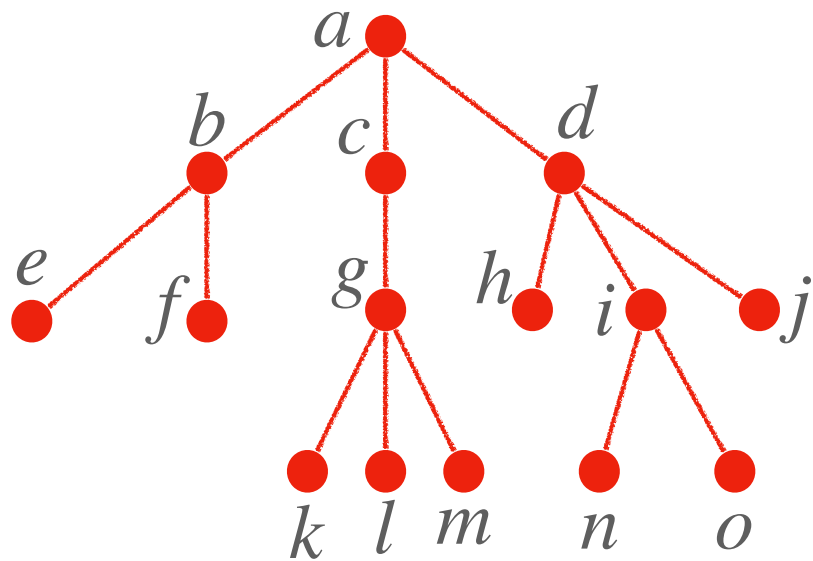
Example of BFS on a tree:



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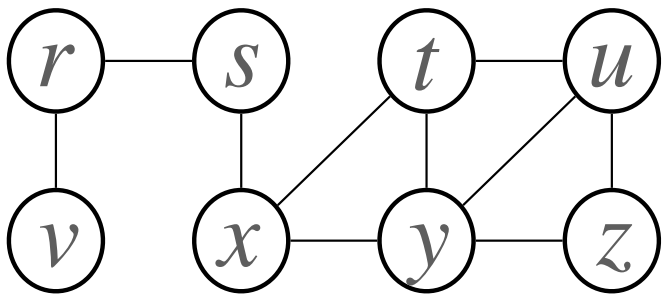
22.2 Breadth First Search (BFS)

Example of BFS on a tree:



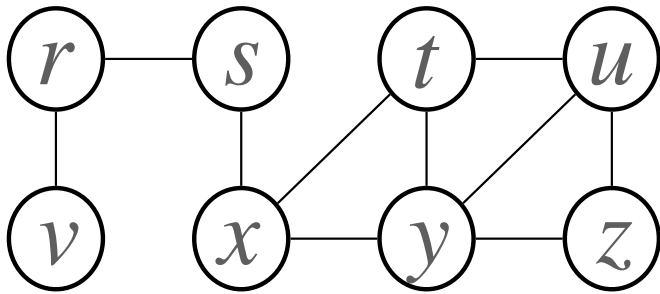
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22.2 Breadth First Search (BFS)



CH 22. Elementary Graph Algorithms

22.2 Breadth First Search (BFS)



Undiscovered nodes: white



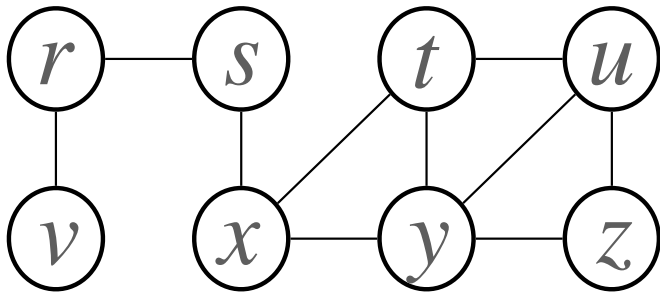
Discovered (but unfinished) nodes: gray



Finished nodes: black

CH 22. Elementary Graph Algorithms

22.2 Breadth First Search (BFS)



Undiscovered nodes: white



Discovered (but unfinished) nodes: gray



Finished nodes: black

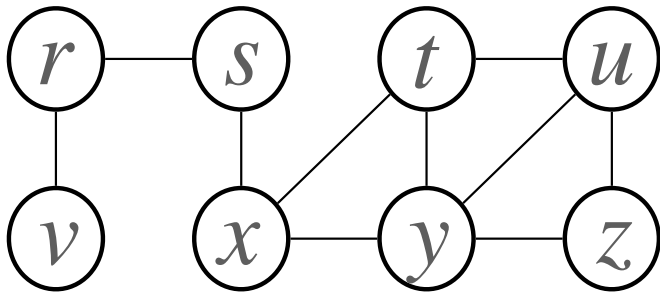
For each node v :

1) distance from root to v : $d(v)$

2) the node that discovered v : $\pi(v)$

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22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

Undiscovered nodes: white



Discovered (but unfinished) nodes: gray



Finished nodes: black

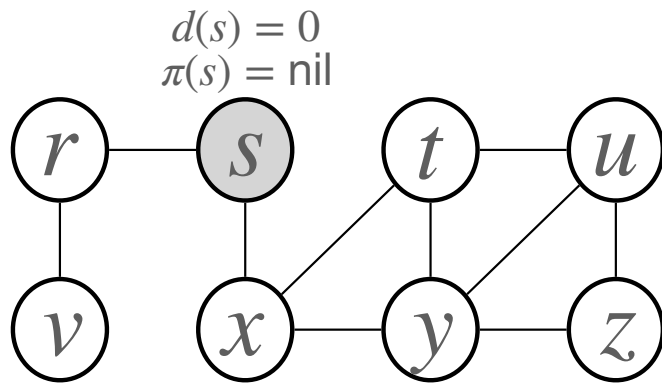
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CH 22. Elementary Graph Algorithms

22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

s

Undiscovered nodes: white



Discovered (but unfinished) nodes: gray



Finished nodes: black

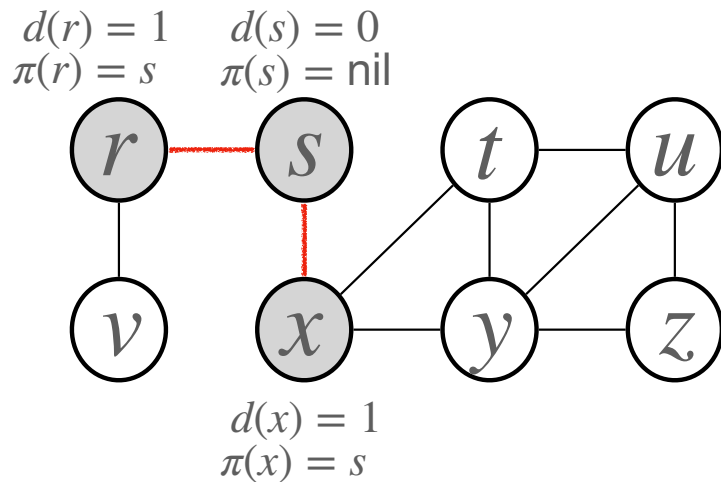
For each node v :

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22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

s r x

Undiscovered nodes: white



Discovered (but unfinished) nodes: gray



Finished nodes: black

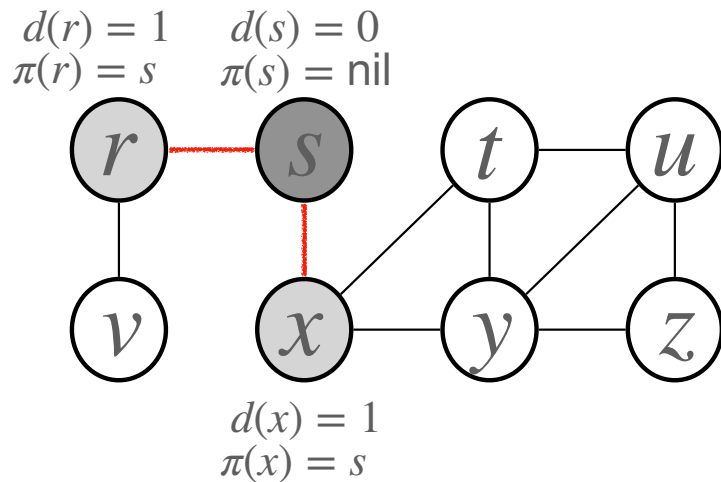
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22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

r x

Undiscovered nodes: white



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Finished nodes: black

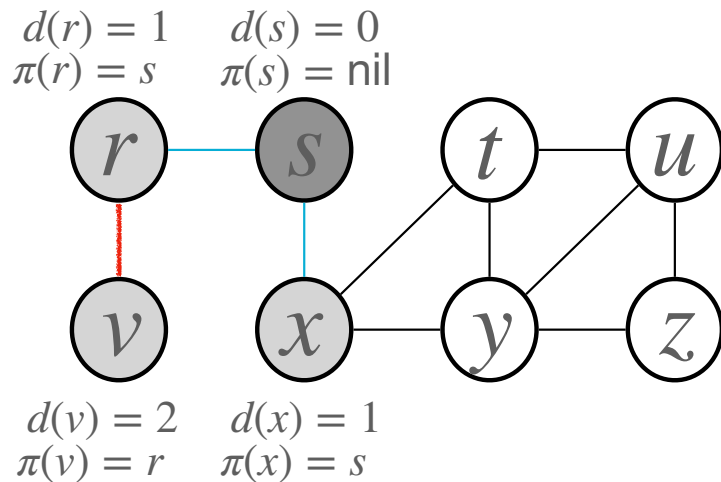
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22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

r x v

Undiscovered nodes: white



Discovered (but unfinished) nodes: gray



Finished nodes: black

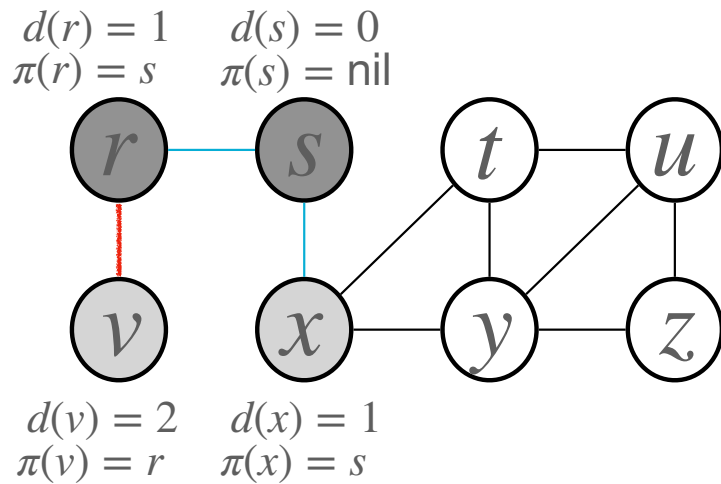
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22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

x v

Undiscovered nodes: white



Discovered (but unfinished) nodes: gray



Finished nodes: black

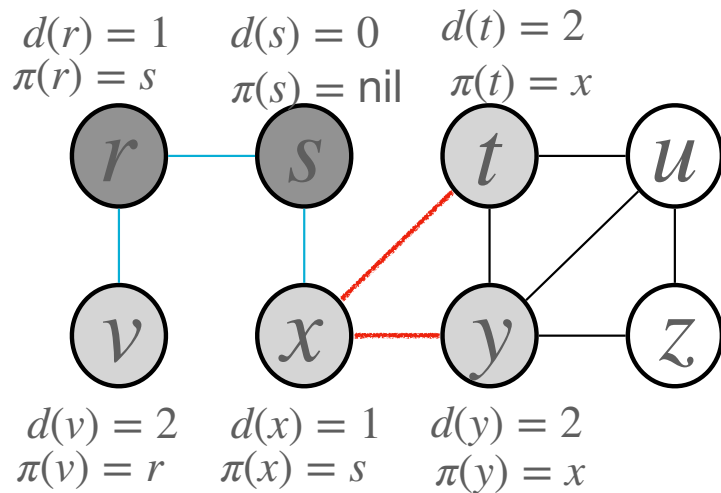
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22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

x v t y

Undiscovered nodes: white



Discovered (but unfinished) nodes: gray



Finished nodes: black

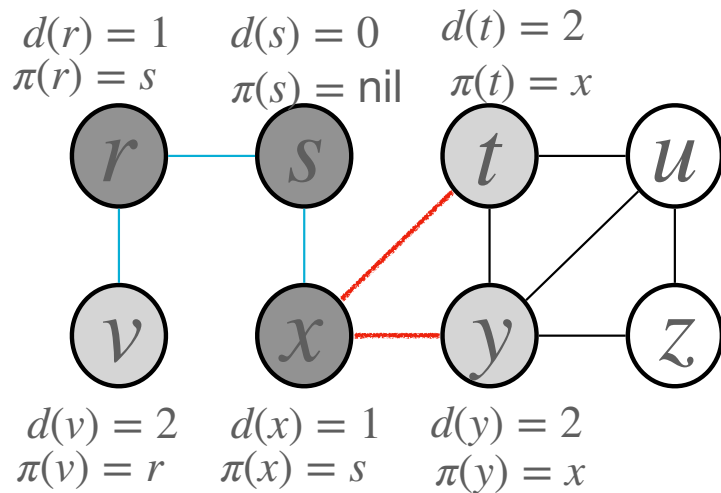
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22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

v t y

Undiscovered nodes: white



Discovered (but unfinished) nodes: gray



Finished nodes: black

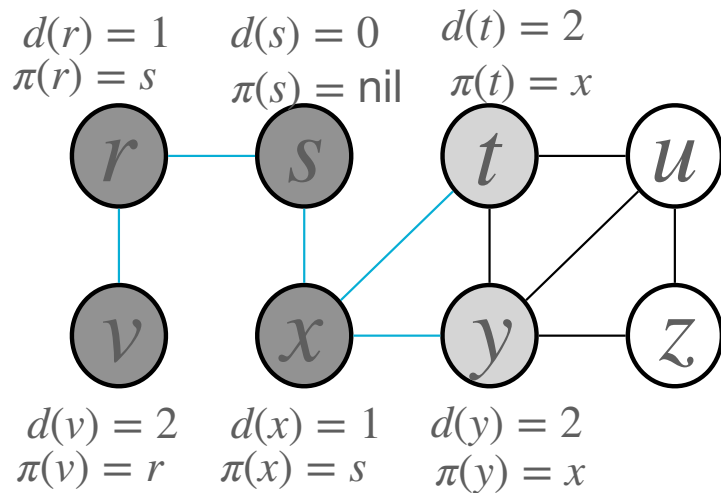
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22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

t y

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Discovered (but unfinished) nodes: gray



Finished nodes: black

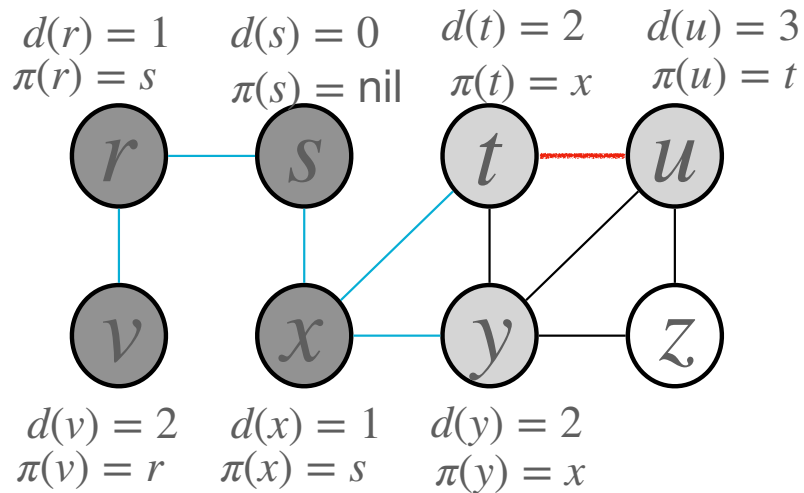
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22.2 Breadth First Search (BFS)



Undiscovered nodes: white



Discovered (but unfinished) nodes: gray



Finished nodes: black

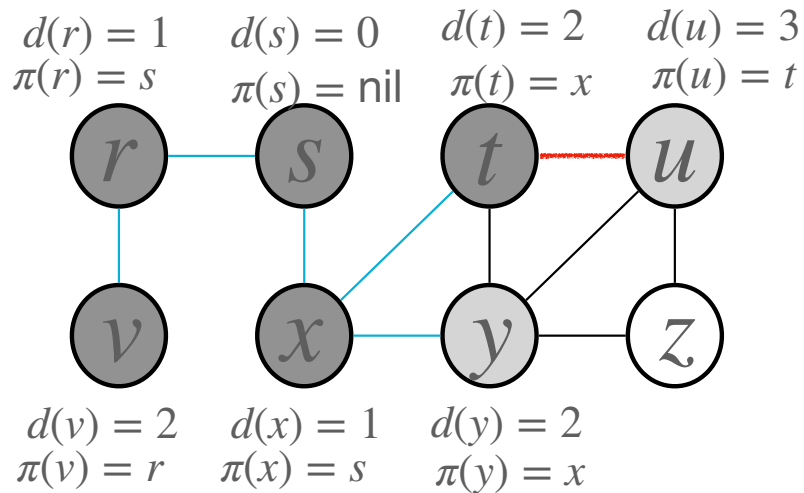
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22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

y u

Undiscovered nodes: white



Discovered (but unfinished) nodes: gray



Finished nodes: black

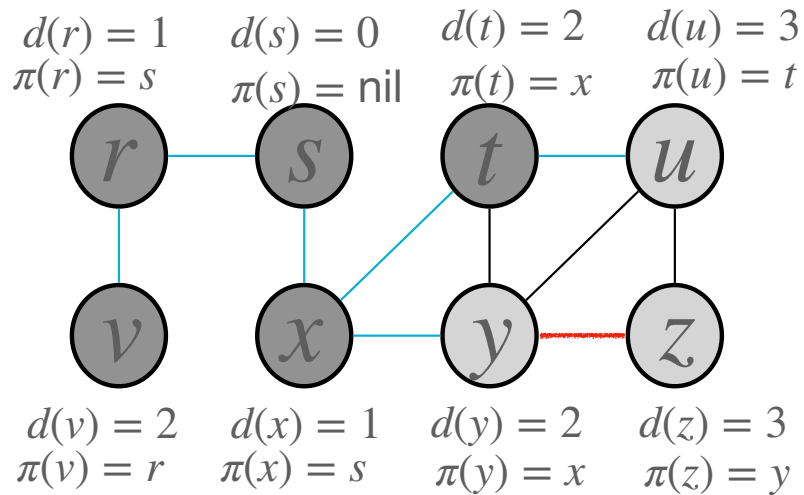
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22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

y u z

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Finished nodes: black

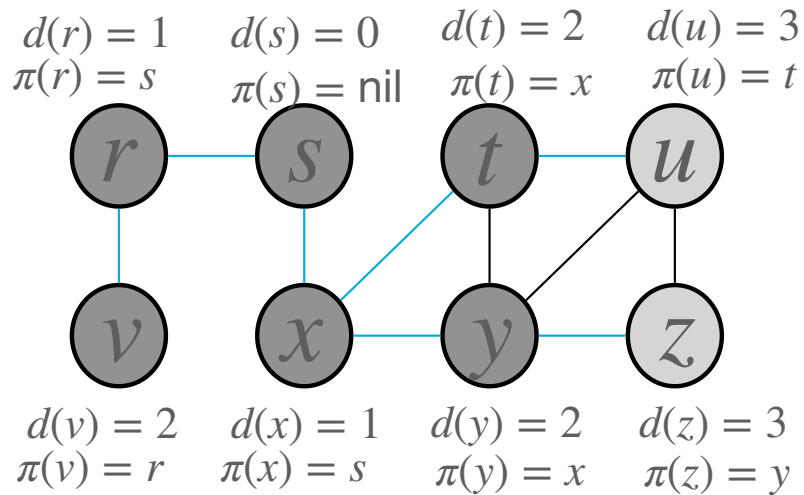
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22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

u z

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Discovered (but unfinished) nodes: gray



Finished nodes: black

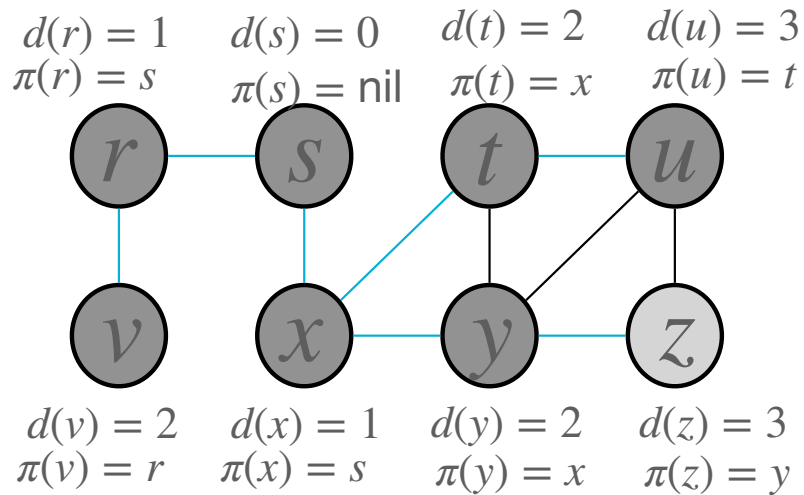
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22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

z

Undiscovered nodes: white



Discovered (but unfinished) nodes: gray



Finished nodes: black

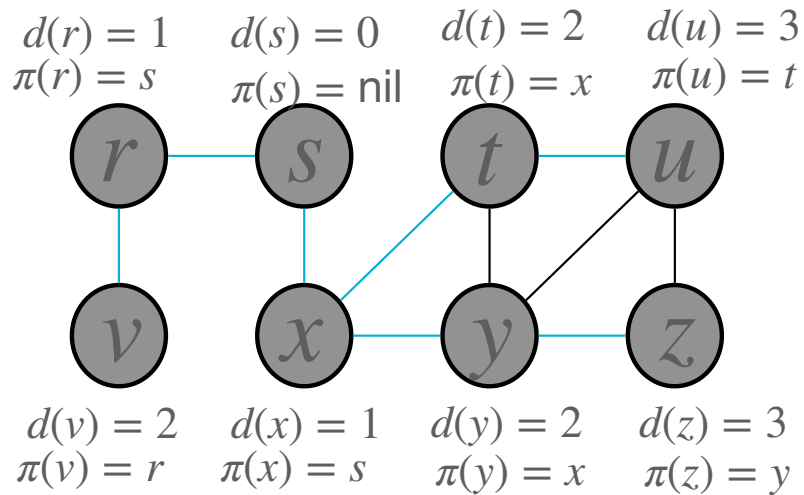
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22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

Undiscovered nodes: white



Discovered (but unfinished) nodes: gray



Finished nodes: black

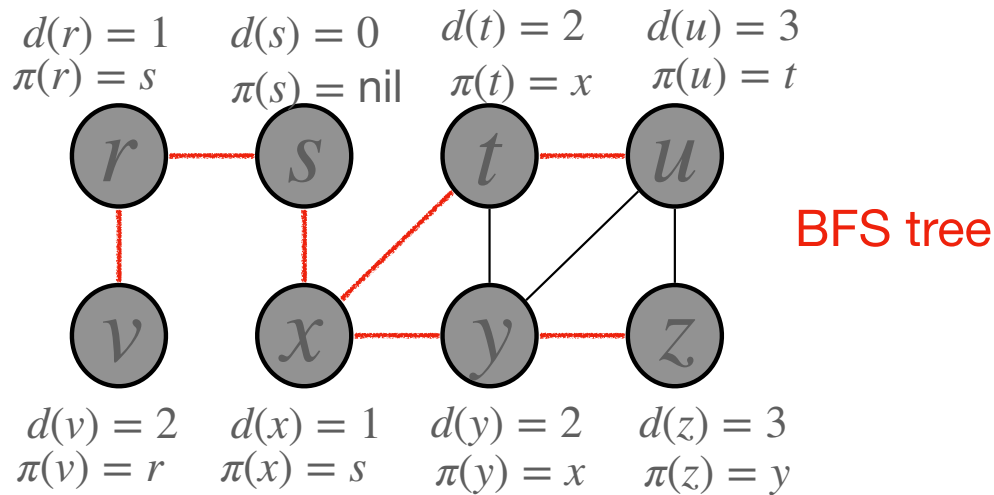
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Queue (for remembering the discovered nodes):

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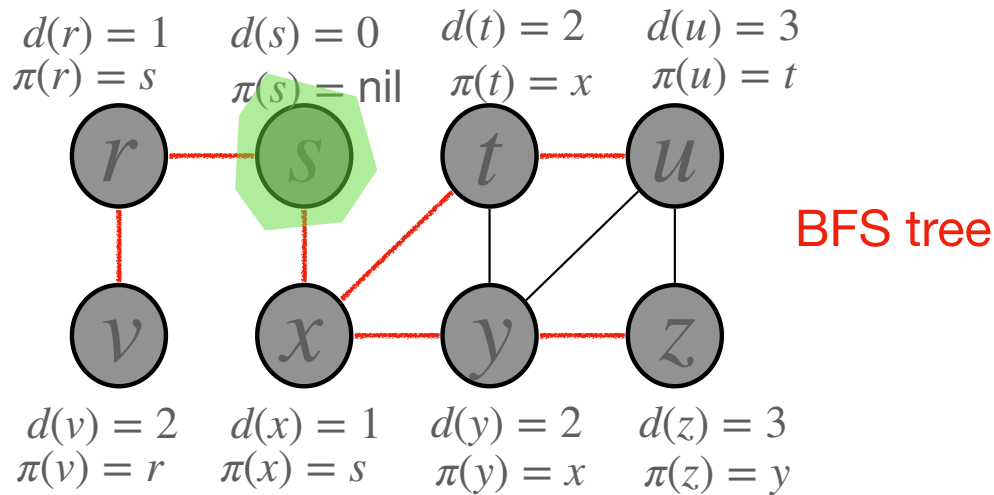
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22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

Undiscovered nodes: white



Discovered (but unfinished) nodes: gray



Finished nodes: black

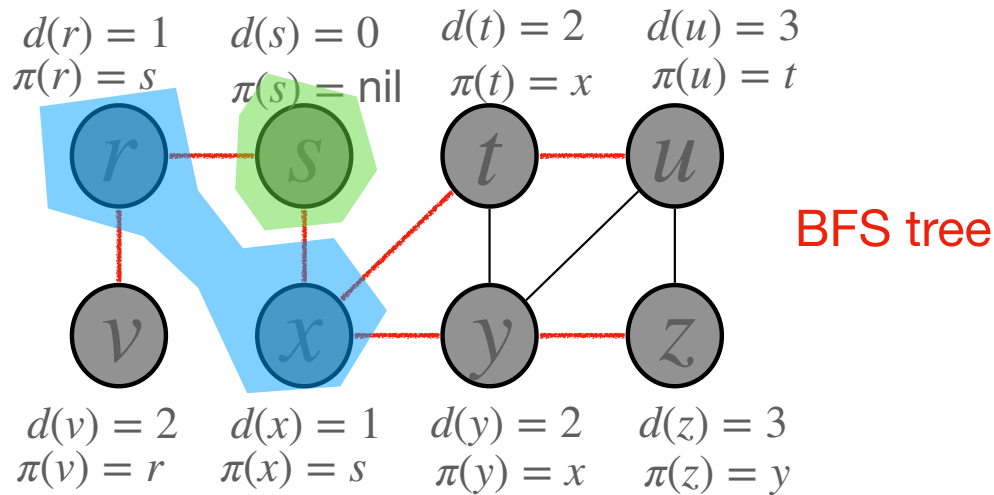
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Queue (for remembering the discovered nodes):

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Finished nodes: black

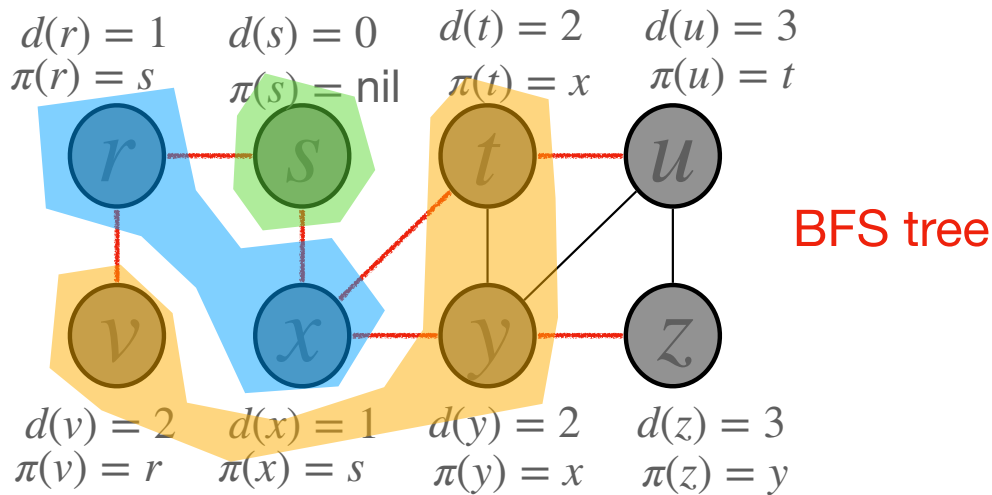
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22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

Undiscovered nodes: white



Discovered (but unfinished) nodes: gray



Finished nodes: black

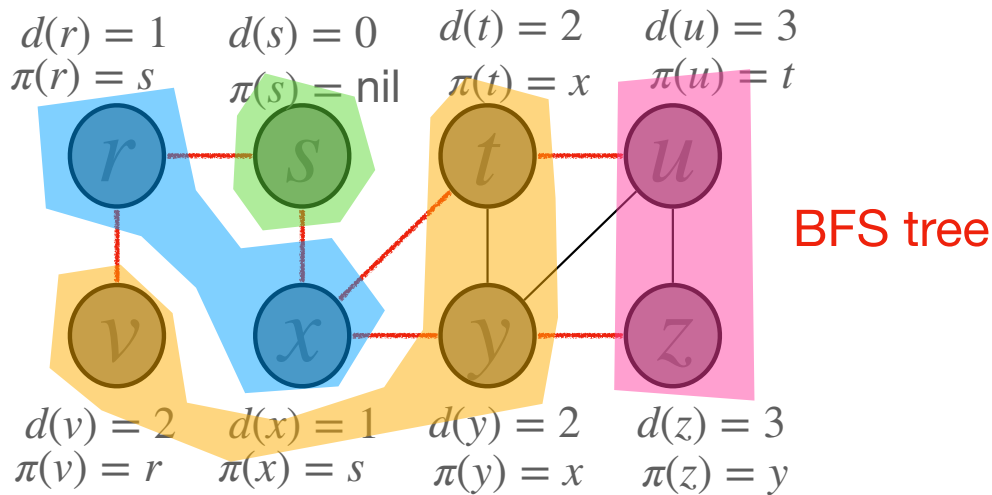
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22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

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Finished nodes: black

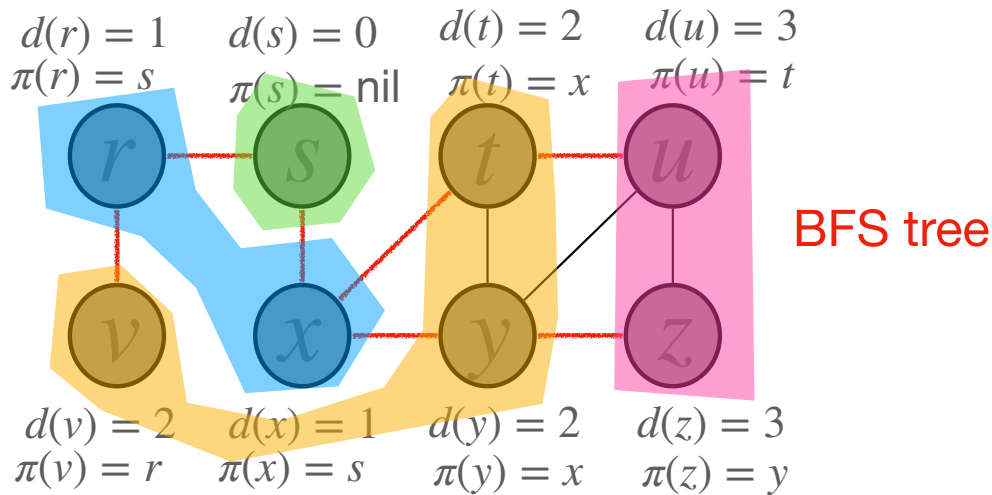
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22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

s , r , x , v , t , y , u , z

0 1 2 3

Undiscovered nodes: white



Discovered (but unfinished) nodes: gray



Finished nodes: black

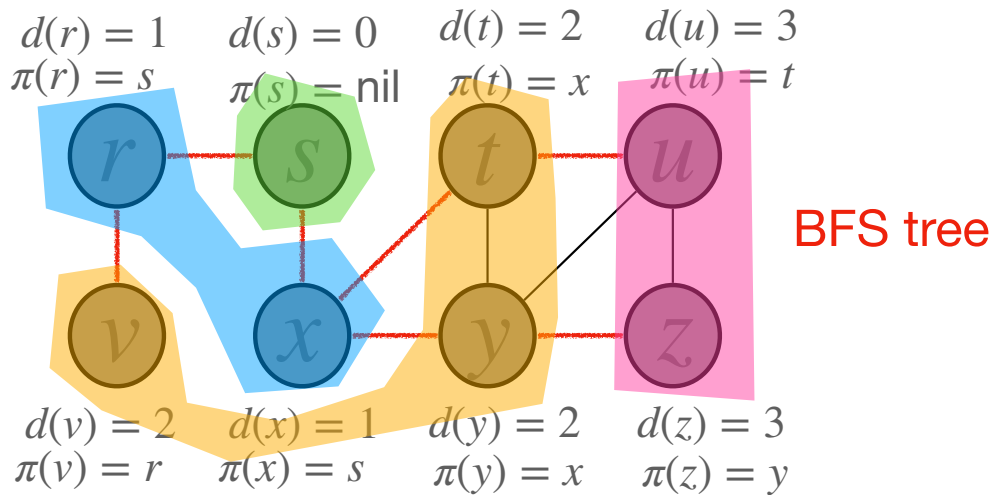
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22.2 Breadth First Search (BFS)



Queue (for remembering the discovered nodes):

s , r , x , v , t , y , u , z

0 1 2 3

Time complexity: $O(V + E)$

Undiscovered nodes: white



Discovered (but unfinished) nodes: gray



Finished nodes: black

For each node v :

1) distance from root to v : $d(v)$

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