

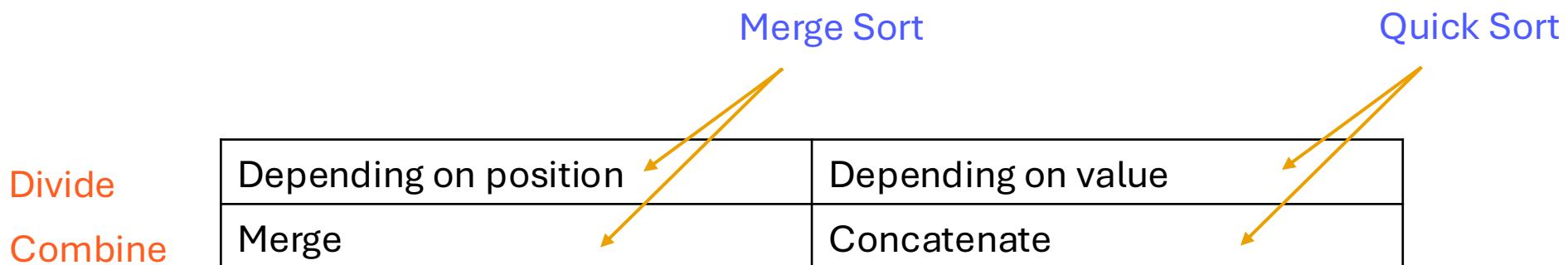
# ALGORITHMS AND DATA STRUCTURES I

Course 10

*Greedy Algorithms*

# Previous Course

- Elementary sorting methods belong to  $O(n^2)$
- Idea to streamline the sorting process:
  - Divide the initial sequence into two subsequences
  - Sort each subsequence
  - Combine sorted subsequences



# Today Course

- Technique of locally optimal choice - "greedy algorithms"
  - Structure
  - The basic idea of the locally optimal choice technique
  - Examples
  - Verification of correctness and analysis of efficiency
  - Applications

# Motivation

The stock portfolio problem

Input:

- Amount to be invested (available capital):  $C$
- Action set  $A = \{a_1, a_2, \dots, a_n\}$ ; each action is characterized by
  - Cost ( $c_1, c_2, \dots, c_n$ )
  - Profit ( $p_1, p_2, \dots, p_n$ )

Output:

- Subset of actions  $S$  having the property that:
  - The sum of the costs of shares in  $S$  does not exceed  $C$
  - The total profit of shares in  $S$  is maximum

What could be the stock selection criteria?

# Motivation

## Activity selection problem

Consider a set A of activities (e.g. exams) that require a resource (e.g. an exam room). Each activity is characterized by a performance interval (start time and end time). The problem arises of selecting a maximal subset of activities that can be performed using a single resource.

### Input:

- Start moments:  $b_1, b_2, \dots, b_n$
- Final moments:  $e_1, e_2, \dots, e_n$

### Output:

- Subset S of A having the property that:
  - There are no conflicts between activities: for any two activities i and j in S, their running intervals ( $[b_i, e_i]$ ) and ( $[b_j, e_j]$ ) are disjoint)
  - The number of elements in S is maximal

What could be the criteria for selecting activities?

# Structure

The general structure of a constrained optimization problem is:

To find  $x$  in  $X$  (the search space) such that :

- (i)  $x$  satisfies certain restrictions
- (ii)  $x$  optimizes (minimizes or maximizes) an optimality criterion

Special case:

- $X$  is a finite set – the problem is in the domain of discrete (or combinatorial) optimization
- At first glance such a problem seems simple to solve. However, since the search space has many elements, exhaustive analysis is impractical, so the problem can become difficult.

# Constrained optimization

**Example 1.** We consider a particular case of the stock portfolio problem when each stock has a cost equal to 1

The problem is equivalent to that of determining a subset of given cardinality and maximum sum

Let  $A = \{a_1, \dots, a_n\}$  and  $m \leq n$

Determine a subset  $S$  of  $A$  that satisfies :

- (i) The number of elements in  $S$  is  $m$  (**restriction of the problem**)
- (ii) The sum of the elements in  $S$  is maximal (**optimal criterion**)

## Remarks

1. The search space is  $X =$  the set of all  $2^n$  subsets of  $A$
2. A brute force approach based on generating all subsets and calculating the sum of their elements would have a complexity of the order of  $O(n2^n)$ .

# Example 1

**Problem 1** (find subset with maximum sum under given condition)

Determine the subset S of the finite set A that has the property that :

- (i) S has  $m \leq \text{card } A$  elements
- (ii) The sum of the elements in S is maximal

**Example:**

Let  $A = \{5, 1, 7, 5, 4\}$  and  $m = 3$ .

**Which is the solution? In what order should the elements be selected?**

The solution is  $S = \{7, 5, 5\}$  - the elements are selected in DECREASING order

# Example 1

Greedy approach: the largest m elements of A are selected

```
Subset(A[1..n], m) //variant 1
FOR i ← 1,m DO
    k ← i
    FOR j ← i+1,n DO
        IF A[k]<A[j] THEN k ← j ENDIF
    ENDFOR
    IF k<>i THEN A[k] ↔ A[i] ENDIF
    S[i] ← A[i]
ENDFOR
RETURN S[1..m]
```

```
Subset(A[1..n],m) //variant 2
A[1..n] ← sort_decreasing(A[1..n])
FOR i ← 1,m DO
    S[i] ← A[i]
ENDFOR
RETURN S[1..m]

// less efficient than option 1 ( if A is not
already sorted and if m is small )
```

Remark. It can be shown that for this problem the "greedy" technique is better

# The basic idea of the locally optimal choice technique

The general optimization problem can be formulated in the form:

Let  $A = (a_1, \dots, a_n)$  be a multiset (a collection of elements that are not necessarily distinct). Find  $S = (s_1, \dots, s_k)$ , a subset of  $A$  such that,  $S$  satisfies certain restrictions and optimizes a criterion.

The idea of optimal local search (greedy search) :

- $S$  is built incrementally starting from the first element
- The most promising at that step is selected from  $A$  and added to  $S$ .
- Once a choice is made, it is irrevocable (cannot go back and replace a component with another value)

# The basic idea of the locally optimal choice technique

The general structure of a "greedy" type algorithm:

Greedy(A)

$S \leftarrow \emptyset$

**WHILE** "S is not completed " AND " there are unselected elements in A" **DO**

$a \leftarrow \text{choose } (A)$  // "choose the best element a, available in A"

**IF**  $S \cup \{a\}$  satisfies the constraints of the problem

**THEN**  $S \leftarrow S \cup \{a\}$  // " add a to S"

**ENDIF**

**ENDWHILE**

**RETURN** S

**Remark.** The main steps in building the solution : initialization , selection, expansion

# The basic idea of the locally optimal choice technique

It represents the most important element of "greedy" type algorithms: **the selection of the element that is added at each step.**

The selection is made based on a criterion that is established according to the specifics of the problem to be solved

The selection criterion is usually based on heuristics (**heuristic** = technique based more on experience and intuition than on a deep analysis of the problem = the art of discovering new knowledge (cf. DEX) )

# Exemple 2

## Problem 2 (coins problem)

Assume that we have at our disposal an unlimited number of coins with the values:  $\{v_1, v_2, \dots, v_n\}$ . Find a way to cover an amount  $C$  so that the number of coins used is as small as possible.

Let  $s$  be the number of coins of value  $v$  selected

**Restriction** :  $s_1 v_1 + \dots + s_n v_n = C$

**Optimum criterion**: the number of selected coins ( $s_1 + s_2 + \dots + s_n$ ) is as small as possible

**Greedy approach**: it starts from the coin with the highest value and covers as much of the amount as possible, for the rest of the amount it tries to use the next coin ( in descending order of values) ...

# Exemple 2

```
coins(v[1..n],C)
v[1..n] ← sort_descending(v[1..n])
FOR i ← 1,n DO S[i]:=0 ENDFOR
i ← 1
WHILE C>0 and i<=n DO
    S[i] ← C DIV v[i] // maximum number of coins of value v[i]
    C ← C MOD v[i] // the rest remains to be covered
    i ← i+1
ENDWHILE
IF C=0 THEN RETURN S[1..n]
ELSE RETURN "the problem has no solution "
ENDIF
```

# Exemple 2

Remarks :

1. Sometimes the problem has no solution:

Example:  $V=(20,10,5)$  and  $C=17$

However, if coins of value 1 are available, then the problem always has a solution

2. Sometimes the "greedy" technique does not lead to an optimal solution

Example :  $V=(25, 20, 10, 5, 1)$ ,  $C=40$

Greedy approach :  $(1, 0, 1, 1, 0)$

The optimal solution :  $(0, 2, 0, 0, 0)$

One condition for optimality :  $v_1 > v_2 > \dots > v_n = 1$  and  $v_{i-1} = d_{i-1} v_i$  ( $i = 2 \dots n$ )

# Characteristics of the technique

- It does not always lead to a solution optimal (optimal local choice may have global negative effects; what seems promising at a certain step is possible prove not to be globally optimal)
- Sometimes the solutions obtained by the greedy technique are sub-optimal that is the value CRITERIA is "enough" close to that optimal (an algorithm that leads to sub-optimal solutions it is called **approximation algorithm**)

Because the "greedy" technique does not guarantee optimal solutions, it is necessary to verify the optimality of the solution for each case (instance).

# Correctness check

Many of the problems for which the greedy solution is optimal are characterized by the following properties:

- The **optimal substructure** property
  - An optimal solution of the initial problem contains an optimal solution of a subproblem ( problem of the same type but of smaller size )
- Property of **greedy choice**
  - The components of an optimal solution have been chosen using the greedy selection criterion or can be replaced by elements chosen using this criterion without altering the optimality property

# The optimal substructure property

- When can a problem be said to have the optimal substructure property ?
  - When for an optimal solution  $S=(s_1, \dots, s_k)$  of the problem of dimension  $n$ , the subset  $S_{(2)} = (s_2, \dots, s_k)$  is an optimal solution of a subproblem of size  $(n-1)$ .
- How can one check if a problem has this property ?
  - Using proof by reduction to the absurd

# The "greedy" choice property

- When a problem has the "greedy" choice property ?
  - When the optimal solution of the problem is either constructed by a "greedy" strategy or can be transformed in another optimal solution built on the basis of the "greedy" strategy
- How can one check whether a problem possesses this property or not ?
  - It is proved that replacing the first element of an optimal solution with an element selected by the "greedy" technique, the solution remains optimal.

# Analysis of its effectiveness

- Greedy algorithms are efficient
- The dominant operation is the selection of the elements (if it is necessary to sort the elements of the set A then the sorting operation is the most expensive)
- So the order of complexity of "greedy" algorithms is  
 $O(n^2)$  or  $O(n \lg n)$  or  $O(n)$   
( depending on the nature of the elements in A and the sorting algorithm used)

# Applications

## Problem 3: knapsack problem

Consider a set of ( $n$ ) objects and a backpack of given capacity ( $C$ ). Each object is characterized by size ( $d$ ) and value or profit ( $p$ ). It is required to select a subset of objects so that the sum of their dimensions does not exceed the capacity of the backpack and the sum of the values is maximum.

- Variations:
  - **Fractional variant** : both whole objects and fractions of objects can be selected. The solution will consist of values belonging to  $[0,1]$ .
  - **Discrete variant (0-1)**: objects cannot be fragmented, they can only be included in the backpack as a whole.

# Knapsack problem

## Motivation

Many practical problems are similar to the knapsack problem

**Example.** Building the financial portfolio: a set of "financial operations"/actions is considered, each one being characterized by a cost and a profit; it is desired to select actions whose total cost does not exceed the amount available for investments and for which the profit is maximum

**Example.** The knapsack problem (the discrete variant) has applications in cryptography (it was the basis for the development of a public key encryption algorithm – nowadays it is no longer used because it is not secure enough).

# Knapsack problem

*Example*

Val(p)	Size(p)
6	2
5	1
12	3

*Selection criteria*

- In ascending order of size (select as many objects as possible)

$$5+6+12*2/3=11+8=19$$

C=5

# Knapsack problem

*Example*

Val(p)	Size(d)
6	2
5	1
12	3

C=5

*Selection criteria*

- In **ascending order of size** (select as many objects as possible)  
 $5+6+12*2/3=11+8=19$
- In **decreasing order of value** (select the most valuable objects ):  
 $12+6=18$

# Knapsack problem

*Example*

Val(p)	Size(p)	Relative profit (Val/Size)
6	2	3
5	1	5
12	3	4

C=5

*Selection criteria*

- In **ascending order of size** (select as many objects as possible)  
$$5+6+12*2/3=11+8=19$$
- In **decreasing order of value** (select the most valuable objects ):  
$$12+6=18$$
- In **descending order of relative profit** (select the small and valuable items):  
$$5+12+6*1/2=17+3=20$$

# Knapsack problem

Knapsack(d[1..n],p[1..n])

"sort item (d and p) in descending order by value of relative profit(d/p) "

FOR i  $\leftarrow$  1,n DO S[i]  $\leftarrow$  0 ENDFOR

i  $\leftarrow$  1

WHILE C>0 AND i<=n DO

IF C $\geq$ d[i] THEN S[i]  $\leftarrow$  1; C  $\leftarrow$  C - d[i]

ELSE S[i]  $\leftarrow$  C / d[i]; C  $\leftarrow$  0

ENDIF

i  $\leftarrow$  i+1

ENDWHILE

RETURN S[1..n]

# Knapsack problem

## Correctness check:

In the case of the continuous (fractional) version of the problem, the greedy technique leads to the optimal solution

## Remark:

- A greedy solution satisfies :  $S=(1,1,\dots,1,f,0,\dots,0)$
- $s_1 d_1 + \dots + s_n d_n = C$  (the restriction can always be satisfied with equality )
- The objects are sorted in descending order according to the value of the relative profit:  $p_1/d_1 > p_2/d_2 > \dots > p_n/d_n$

## Demo

Let  $O=(o_1, o_2, \dots, o_n)$  be an optimal solution. It can be proven by reduction to the absurd that it is a greedy solution. Lets assume that  $O$  is not a greedy solution and consider it as a greedy solution  $O'=(o'_1, o'_2, \dots, o'_n)$

# Knapsack problem

Let  $B_+ = \{i | o'_i = o_i\}$  and  $B_- = \{j | o'_j < o_j\}$ ,  $k$  – the smallest index for which  $o'_k < o_k$ .

Due to the structure of a greedy solution, it follows that any index  $i$  in  $B_+$  is smaller than any index  $j$  in  $B_-$ .

On the other hand, both solutions must satisfy the restriction, that is:  $o_1 d_1 + \dots + o_n d_n = o'_1 d_1 + \dots + o'_n d_n$

$$\sum_{i \in B_+} (o'_i - o_i) d_i = \sum_{i \in B_-} (o_i - o'_i) d_i$$

$$P' - P = \sum_{i=1}^n (o'_i - o_i) d_i = \sum_{i \in B_+} (o'_i - o_i) d_i \frac{p_i}{d_i} - \sum_{i \in B_-} (o_i - o'_i) d_i \frac{p_i}{d_i}$$

$$P' - P \geq \frac{p_k}{d_k} \sum_{i \in B_+} (o'_i - o_i) d_i - \frac{p_k}{d_k} \sum_{i \in B_-} (o_i - o'_i) d_i = 0$$

So the greedy solution is at least as good as O (which is a solution optimum). The optimal substructure property is easy to prove by reduction to the absurd.

# Knapsack problem

*Remark* : the result is not valid for the discrete version of the problem

## Counterexample

	Val(p)	Size(p)	Relative profit
O1	10	6	5/3
O2	7	5	7/5
O3	6	4	3/2
O4	2	1	2

C=9

- Optimal solution: o2,o3 (total value: 13).
- Solution: dynamic programming technique

## Selection criteria

- In **ascending order of size** (select as many objects as possible)  
o3,o4 (total value: 8)
- In **decreasing order of value** (select the most valuable objects ):  
o1,o4 (total value: 12)
- In **descending order of relative profit** (select the small and valuable items):  
o4, o1 (total value: 12)

# Applications

## Problem 4: The task selection problem

Let  $A=\{a_1, \dots, a_n\}$  be a set of activities that share that resource. Each activity requires a time interval to be executed. Two activities are considered compatible if their execution intervals are disjoint and incompatible otherwise.

The problem asks to select as many compatible activities as possible.

### Example:

A1: [ 0,6)

A2: [1,5)

A3: [4,6)

A4: [5,8)

# The task selection problem

Let  $A=\{a_1, \dots, a_n\}$  be a set of activities that share that resource. Each activity requires a time interval to be executed. Two activities are considered compatible if their execution intervals are disjoint and incompatible otherwise.

The problem asks to select as many compatible activities as possible.

## Example:

A1: [0,6)

A2: [1,5)

A3: [4,6)

A4: [5,8)

There are several criteria for selecting activities:

- a) In ascending order of start time: a1
- b) In ascending order of duration: a3
- c) In ascending order of the moment of completion: a2, a4

# The task selection problem

```
// Assume that each element of a [ i ] contains two fields: a[i]. b - beginning moment (begin) and a[i]. e - moment of completion (end)

Select_activities(a[1..n])
    a[1..n] ← ascending sort by the value of e (a[1..n])
    s [1] ← 1 // s will contain indices of the elements selected from a
    k ← 1
    FOR i ← 2,n DO
        IF a[i].b>=a[s[k]].e THEN
            k ← k+1
            s[k] ← i
        ENDIF
    ENDFOR
    RETURN s [1..k]
```

# The task selection problem

Correctness check. Supposing that the set of activities is ordered increasing by the time of completion ( $a_1 e < a_2 e < \dots < a_k e$  ).

**The “greedy” choice property:** Let  $(o_1, o_2, \dots, o_k) = (a_{i_1}, a_{i_2}, \dots, a_{i_k})$  be an optimal solution (supposing that the selected activities are specified in ascending order of completion time:  $i_1 < i_2 < \dots < i_k$  ).

In this case the activity of  $i_1$  can be replaced by  $a_1$ , the activity that finishes the fastest, without altering the problem restriction (the selected activities are all compatible) and keeping that and number (maximum) of selected activities

# The task selection problem

Correctness check. Supposing that the set of activities is ordered increasing by the time of completion ( $a_1 e < a_2 e < \dots < a_k e$  ).

**The optimal substructure property.** Consider the optimal solution :  $(a_1, o_2, \dots, o_k)$  (note: from the "greedy" choice property it follows that we can consider  $o_1 = a_1$  ) .

Supposing that  $(o_2, \dots, o_k)$  is not an optimal solution for the subproblem of selection from  $\{a_2, a_3, \dots, a_n\}$ .

It follows that there is  $o' = (o'_2, \dots, o'_{k'})$  another solution with  $k' > k$ . This would lead to a solution  $(a_1, o'_2, \dots, o'_{k'})$  better than  $(a_1, o_2, \dots, o_k)$  .

Contradiction

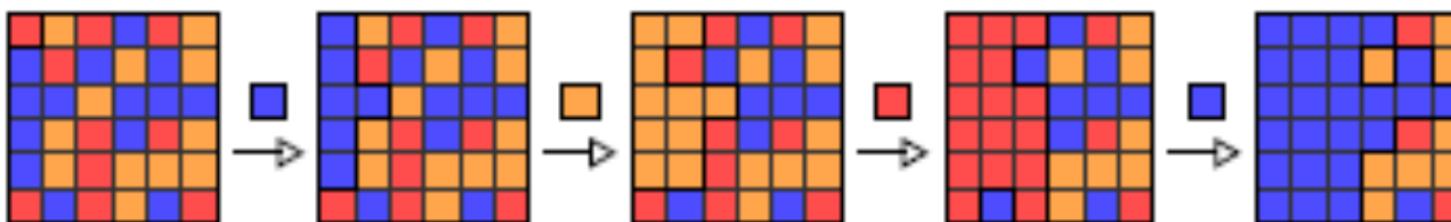
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# Next course

- Dynamic programming

# FloodIt Game [2006, LabPixies->Google]

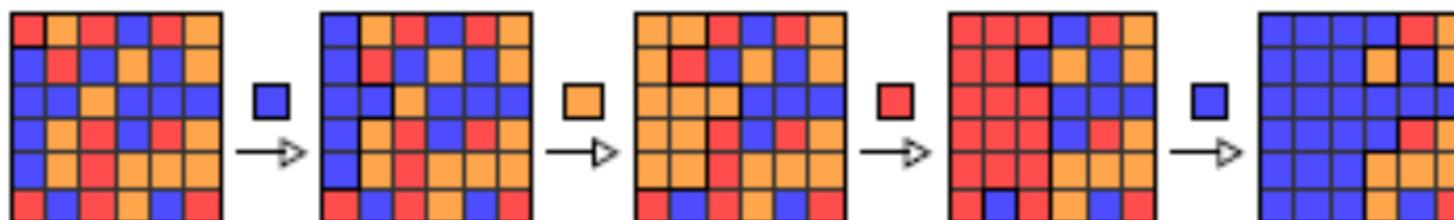
- Consider a  $n \times n$  grid containing initially randomly colored cells
- The cell in the upper left corner is considered the starting cell
- All cells that have the same color as the start cell and can be accessed by moving **horizontally** or **vertically** (but not diagonally) are considered connected to the start cell
- The problem is to successively change the color of the starting cell (and all those connected to it) so that the grid is completely covered with the **same color in as few steps as possible**



(R. Clifford, The Complexity of Flood Filling Games , 2011)

# FloodIt Game [2006, LabPixies->Google]

- Consider a  $n \times n$  grid containing initially randomly colored cells
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What would be a simple/intuitive game strategy?

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# Q&A

