STEP II 2017 Mark Scheme

Question 1

(i)
$$I_n = \int_0^1 \arctan x \cdot x^n \, dx$$

M1 Use of intgrn. by parts (parts correct way round)

$$= \left[\arctan x \cdot \frac{x^{n+1}}{n+1}\right]_0^1 - \int_0^1 \frac{1}{1+x^2} \cdot \frac{x^{n+1}}{n+1} dx$$

A1 Correct to here

$$= \left(\frac{\pi}{4} \cdot \frac{1}{n+1} - 0\right) - \frac{1}{n+1} \int_{0}^{1} \frac{x^{n+1}}{1+x^{2}} dx$$

$$\Rightarrow (n+1)I_n = \frac{\pi}{4} - \int_0^1 \frac{x^{n+1}}{1+x^2} dx$$

A1 Given Answer legitimately established 3

Setting n = 0, $I_0 = \frac{\pi}{4} - \int_0^1 \frac{x}{1+x^2} dx$ M1 Attempt to solve this using recognition/ substitution $= \frac{\pi}{4} - \left[\frac{1}{2}\ln(1+x^2)\right]$ M1 Log integral involved $= \frac{\pi}{4} - \frac{1}{2}\ln 2$ A1 CAO

(ii) $n \rightarrow n + 2$ in given result:

$$(n+3)I_{n+2} = \frac{\pi}{4} - \int_{0}^{1} \frac{x^{n+3}}{1+x^{2}} dx$$

B1 Noted or used somewhere

$$(n+3)I_{n+2} + (n+1)I_n = \frac{\pi}{2} - \int_0^1 \frac{x^{n+1}(1+x^2)}{1+x^2} dx$$
$$= \frac{\pi}{2} - \frac{1}{n+2}$$

M1 Adding and cancelling ready to integrate

Setting n = 0 and then n = 2 in this result (or equivalent involving integrals):

$$3I_2 + I_0 = \frac{\pi}{2} - \frac{1}{2}$$
 and $5I_4 + 3I_2 = \frac{\pi}{2} - \frac{1}{4}$

M1

Eliminating I_2 and using value for I_0 to find I_4 $I_4 = \frac{1}{20} (1 + \pi - 2 \ln 2)$

M1 By subtracting, or equivalent

A1 FT from their I_0 value

3

(iii) For n = 1, $5I_4 = A - \frac{1}{2} \left(-1 + \frac{1}{2} \right) = A + \frac{1}{4}$ = $\frac{1}{4} + \frac{1}{4}\pi - \frac{1}{2}\ln 2$

M1 Comparing formula with found I_4 value

and the result is true for n = 1 provided $A = \frac{1}{4}\pi - \frac{1}{2}\ln 2$

A1 FT from their I_4 value

Assuming $(4k+1)I_{4k+1} = A - \frac{1}{2}\sum_{r=1}^{2k} (-1)^r \frac{1}{r}$

M1 For a clearly stated induction hypothesis

(or a fully explained "if ... then ..." at end)

$$(4k+5)I_{4k+4} + (4k+3)I_{4k+2} = \frac{\pi}{2} - \frac{1}{4k+4}$$
 B1

$$(4k+3)I_{4k+2} + (4k+1)I_{4k} = \frac{\pi}{2} - \frac{1}{4k+2}$$
 B1

Subtracting:

$$(4k+5)I_{4k+4} = (4k+1)I_{4k} + \frac{1}{4k+2} - \frac{1}{4k+4}$$
 M1 Use of assumed result
$$= A - \frac{1}{2} \sum_{r=1}^{2k} (-1)^r \frac{1}{r} + \frac{1}{4k+2} - \frac{1}{4k+4}$$
 M1 Use of assumed result
$$= A - \frac{1}{2} \sum_{r=1}^{2k} (-1)^r \frac{1}{r} - \frac{1}{2} (-1)^{2k+1} \frac{1}{2k+1} - \frac{1}{2} (-1)^{2k+2} \frac{1}{2k+2}$$

$$= A - \frac{1}{2} \sum_{r=1}^{2(k+1)} (-1)^r \frac{1}{r}$$
 A1 A clear demonstration of how the two extra terms fit must be given

Let
$$x_n = X$$
. Then $x_{n+1} = \frac{aX - 1}{X + b}$ and $x_{n+2} = \frac{a\left(\frac{aX - 1}{X + b}\right) - 1}{\left(\frac{aX - 1}{X + b}\right) + b}$ M1 A1 Correct, unsimplified

i.e.
$$x_{n+2} = \frac{(a^2-1)X - (a+b)}{(a+b)X + (b^2-1)}$$

M1 Attempt to remove "fractions within fractions"

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(i) If
$$x_{n+1} = x_n$$
 then $aX - 1 = X^2 + bX$ M1
 $\Rightarrow 0 = X^2 - (a-b)X + 1$ A1

If
$$x_{n+2} = x_n$$
 then

$$(a^2-1)X-(a+b)=(a+b)X^2+(b^2-1)X$$
 M1

$$\Rightarrow 0 = (a+b)\{X^2 - (a-b)X + 1\}$$

M1 A1 Factorisation

and so, for $x_{n+2} = x_n$ but $x_{n+1} \neq x_n$

we must have
$$a + b = 0$$

A1 Given Answer fully justified & clearly stated

(No marks for setting b = -a, for instance, and showing sufficiency)

For "comparing coefficients" approach (must be all 3 terms) max. 3/4

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(ii)
$$x_{n+4} = \frac{(a^2 - 1)x_{n+2} - (a+b)}{(a+b)x_{n+2} + (b^2 - 1)}$$
$$= \frac{(a^2 - 1)\left[\frac{(a^2 - 1)X - (a+b)}{(a+b)X + (b^2 - 1)}\right] - (a+b)}{(a+b)\left[\frac{(a^2 - 1)X - (a+b)}{(a+b)X + (b^2 - 1)}\right] + (b^2 - 1)}$$

M1 Use of the two-step result from earlier

A1 Correct, unsimplified, in terms of X

If
$$x_{n+4} = x_n$$
 then $(a^2 - 1)^2 X - (a + b) (a^2 - 1) - (a + b)^2 X - (a + b) (b^2 - 1)$ A1 LHS correct $= (a + b) (a^2 - 1)X^2 - (a + b)^2 X + (a + b) (b^2 - 1)X^2 + (b^2 - 1)^2 X$ A1 RHS correct $\Rightarrow 0 = (a + b) (a^2 + b^2 - 2)X^2 - [(a^2 - 1)^2 - (b^2 - 1)^2]X + (a + b) (a^2 + b^2 - 2)$

$$\Rightarrow 0 = (a+b)(a^2+b^2-2)\{X^2-(a-b)X+1\}$$

M1 Good attempt to simplify

M1 Factorisation attempt

A1 A1 Partial; complete

and the sequence has period 4 if and only if

$$a^2 + b^2 = 2$$
, $a + b \ne 0$, $X^2 - (a - b)X + 1 \ne 0$

B1 CAO Correct final statement

[Ignore any discussion or confusion regarding issues of necessity and sufficiency]

NB Some candidates may use the one-step result repeatedly and get to x_{n+4} via x_{n+3} :

$$x_{n+3} = \frac{(a^3 - 2a - b)X - (a^2 + ab + b^2 - 1)}{(a^2 + ab + b^2 - 1)X - (a + 2b + b^3)} \text{ and } x_{n+4} = \frac{ax_{n+3} - 1}{x_{n+3} + b} \text{ starts the process; then as above.}$$

ALT. Consider the two-step sequence $\{\ldots, x_n, x_{n+2}, x_{n+4}, \ldots\}$ given by (assuming $a + b \neq 0$)

$$x_{n+2} = \frac{\left(\frac{a^2 - 1}{a + b}\right)X - 1}{X + \left(\frac{b^2 - 1}{a + b}\right)} = \frac{AX - 1}{X + B}, \text{ which is clearly of exactly the same form as before.}$$

Then $x_{n+4} = x_n$ if and only if $a + b \ne 0$, $X^2 - (a - b)X + 1 \ne 0$ (from $x_{n+4} \ne x_{n+2}$ and $x_{n+4} \ne x_n$ as before), together with the condition A + B = 0 (also from previous work);

i.e.
$$\frac{a^2-1}{a+b} + \frac{b^2-1}{a+b} = 0$$
, which is equivalent to $a^2+b^2-2=0$ since $a+b \ne 0$.

Note that it is not necessary to consider $x_{n+4} \neq x_{n+3}$ since if $x_{n+4} = x_{n+3} = X$ then the sequence would be constant.

(i)
$$\sin y = \sin x \implies y = n\pi + (-1)^n x$$

$$n = -1$$
: $y = -\pi - x$

B1

$$n = 0$$
:

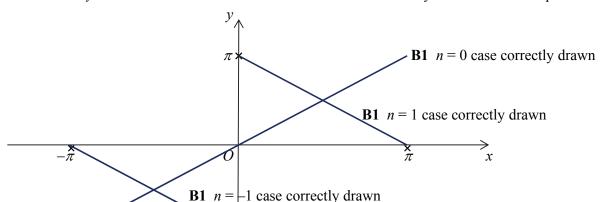
$$y = x$$

B1

$$n=1$$

$$n = 1$$
: $y = \pi - x$

B1 Withhold final B mark for any number of extra eqns.



 $\sin y = \frac{1}{2}\sin x \implies \cos y \frac{\mathrm{d}y}{\mathrm{d}x} = \frac{1}{2}\cos x$ (ii)

Withhold final B mark for any number of extra lines Ignore "endpoint" issues

(ii)
$$\sin y = \frac{1}{2}\sin x \implies \cos y \frac{dy}{dx} = \frac{1}{2}\cos x$$

M1 Implicit diffn. attempt (or equivalent)

$$\frac{\mathrm{d}y}{\mathrm{d}x} = \frac{\cos x}{2\cos y}$$

$$= \frac{\cos x}{2\sqrt{1 - \frac{1}{4}\sin^2 x}} \quad \text{or} \quad \frac{\cos x}{\sqrt{4 - \sin^2 x}}$$

A1 Correct and in terms of x only

3

6

$$\frac{d^2 y}{dx^2} = \frac{\left(4 - \sin^2 x\right)^{\frac{1}{2}} - \sin x - \cos x \cdot \frac{1}{2} \left(4 - \sin^2 x\right)^{-\frac{1}{2}} - 2\sin x \cos x}{4 - \sin^2 x}$$

M1 For use of the *Quotient Rule* (or equivalent)

M1 For use of the *Chain Rule* for d/dx(denominator)

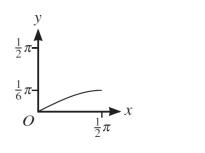
A1

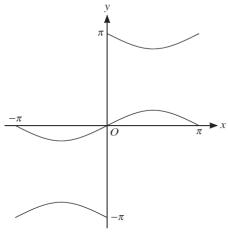
$$= \frac{-\sin x (4 - \sin^2 x) + \cos^2 x \cdot \sin x}{(4 - \sin^2 x)^{\frac{3}{2}}}$$
$$= \frac{\sin x (\cos^2 x - 4 + \sin^2 x)}{(4 - \sin^2 x)^{\frac{3}{2}}}$$

M1 Method for getting correct denominator

$$= \frac{\sin x \{\cos^2 x - 4 + \sin^2 x\}}{(4 - \sin^2 x)^{\frac{3}{2}}}$$
$$= \frac{-3\sin x}{(4 - \sin^2 x)^{\frac{3}{2}}}$$

A1 Given Answer correctly obtained from
$$c^2 + s^2 = 1$$



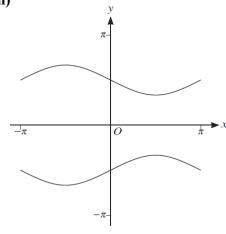


Initially, $\frac{dy}{dx} = \frac{1}{2}$ at (0, 0) increasing to a maximum at $(\frac{\pi}{2}, \frac{\pi}{6})$ since $\frac{d^2y}{dx^2} < 0$

- **B1** (Gradient and coordinate details unimportant unless graphs look silly as a result)
- **B1** Reflection symmetry in $x = \frac{\pi}{2}$
- ${\bf B1}$ Rotational symmetry about O
- **B1** Reflection symmetry in $y = \pm \frac{\pi}{2}$

4

(iii)



- **B1** RHS correct
- **B1** LHS correct

(i) Setting f(x) = 1 in (*) gives

$$\left(\int_{a}^{b} g(x) dx\right)^{2} \leq \left(\int_{a}^{b} 1 dx\right) \left(\int_{a}^{b} [g(x)]^{2} dx\right)$$

B1 Clearly stated

Let
$$g(x) = e^x : \left(\int_a^b e^x dx\right)^2 \le (b - a) \left(\int_a^b e^{2x} dx\right)$$

M1

$$\Rightarrow \left(e^b - e^a \right)^2 \le (b - a) \cdot \frac{1}{2} \left(e^{2b} - e^{2a} \right)$$

$$\Rightarrow (e^b - e^a)^2 \le (b - a) \cdot \frac{1}{2} (e^b - e^a) (e^b + e^a)$$

A1

$$\Rightarrow$$
 $e^b - e^a \le \frac{1}{2}(b-a)(e^b + e^a)$
Choosing $a = 0$ and $b = t$ gives

M1

$$e^{t} - 1 \le \frac{1}{2}t\left(e^{t} + 1\right) \implies \frac{e^{t} - 1}{e^{t} + 1} \le \frac{1}{2}t$$

A1 Given Answer legitimately obtained

(ii) Setting f(x) = x, a = 0 and b = 1 in (*) gives

$$\left(\int_{0}^{1} x g(x) dx\right)^{2} \leq \left(\int_{0}^{1} x^{2} dx\right) \left(\int_{0}^{1} [g(x)]^{2} dx\right)$$

B1 Clearly stated

Choosing $g(x) = e^{-\frac{1}{4}x^2}$ gives

M1

$$\left(\int_{0}^{1} x e^{-\frac{1}{4}x^{2}} dx\right)^{2} \le \frac{1}{3} \left(1^{3} - 0^{3}\right) \left(\int_{0}^{1} e^{-\frac{1}{2}x^{2}} dx\right)$$

$$\left(\left[-2e^{-\frac{1}{4}x^2} \right]_0^1 \right)^2 \le \frac{1}{3} \left(\int_0^1 e^{-\frac{1}{2}x^2} dx \right)$$

A1 A1 LHS, RHS correct

$$\Rightarrow \int_{0}^{1} e^{-\frac{1}{2}x^{2}} dx \ge 3 \left(-2 \left[-e^{-\frac{1}{4}} + 1 \right] \right)^{2}$$

i.e. $\int_{0}^{1} e^{-\frac{1}{2}x^{2}} dx \ge 12 \left(1 - e^{-\frac{1}{4}}\right)^{2}$

A1 Given Answer legitimately obtained 5

(iii) With f(x) = 1, $g(x) = \sqrt{\sin x}$, a = 0, $b = \frac{1}{2}\pi$,

M1 Correct choice for f, g (or v.v.)

M1 Any sensible f, g used in (*)

(*) becomes

 $\left(\int_{0}^{\frac{1}{2}\pi} \sqrt{\sin x} \, \mathrm{d}x\right)^{2} \le \frac{1}{2}\pi \left(\int_{0}^{\frac{1}{2}\pi} \sin x \, \mathrm{d}x\right)$

RHS is
$$\frac{1}{2}\pi \left[-\cos x \right]_{0}^{1} = \frac{1}{2}\pi$$

A1

(and since LHS is positive) we have
$$\int_{0}^{\frac{1}{2}\pi} \sqrt{\sin x} \, dx \le \sqrt{\frac{\pi}{2}}$$

A1 RH half of **Given** inequality obtained from fully correct working

With
$$f(x) = \cos x$$
, $g(x) = \sqrt[4]{\sin x}$, $a = 0$, $b = \frac{1}{2}\pi$, M1 Correct choice for f, g (or v.v.) (*) gives

$$\left(\int_{0}^{\frac{1}{2}\pi} \cos x \cdot (\sin x)^{\frac{1}{4}} dx\right)^{2} \leq \left(\int_{0}^{\frac{1}{2}\pi} \cos^{2} x dx\right) \left(\int_{0}^{\frac{1}{2}\pi} \sqrt{\sin x} dx\right) \mathbf{A1}$$

LHS =
$$\left[\left[\frac{4}{5} (\sin x)^{\frac{5}{4}} \right]_{0}^{\frac{1}{2} \pi} \right]^{2} = \frac{16}{25}$$
 M1 A1 By recognition/substitution integration

and
$$\int_{0}^{\frac{1}{2}\pi} \cos^{2} x \, dx = \int_{0}^{\frac{1}{2}\pi} \left(\frac{1}{2} + \frac{1}{2}\cos 2x\right) dx$$

$$= \left(\left[\frac{1}{2}x - \frac{1}{4}\sin 2x\right]^{\frac{1}{2}\pi}\right)^{2} = \frac{1}{4}\pi$$

Giving the required LH half of the **Given** inequality:

$$\frac{16}{25} \le \frac{1}{4} \pi \left(\int_{0}^{\frac{1}{2}\pi} \sqrt{\sin x} \, dx \right) \text{ i.e. } \int_{0}^{\frac{1}{2}\pi} \sqrt{\sin x} \, dx \ge \frac{64}{25\pi}$$

A1

Withhold the last A mark if final result is not arrived at

(i)
$$\frac{\mathrm{d}y}{\mathrm{d}x} = \frac{\frac{\mathrm{d}y}{\mathrm{d}t}}{\frac{\mathrm{d}x}{\mathrm{d}t}} = \frac{2a}{2at} = \frac{1}{t}$$

 \Rightarrow Grad. nml. at P is -p

 \Rightarrow Eqn. nml. to C at P is $x - 2ap = -p(x - ap^2)$

Nml. meets C again when $x = an^2$, y = 2an

$$\Rightarrow 2an = -pan^2 + ap(2 + p^2)$$

$$\Rightarrow 0 = pn^2 + 2n - p(2 + p^2)$$

$$\Rightarrow$$
 0 = $(n-p)(pn+[2+p^2])$

Since n = p at P, it follows that $n = -\frac{2 + p^2}{p}$ at N

i.e.
$$n = -\left(p + \frac{2}{p}\right)$$

M1 Solving attempt

M1 Substd. into nml. eqn.

A1

M1

A1 Given Answer legitimately obtained

A1 Given Answer legitimately obtained 2

M1 Finding gradt. of tgt. (or by implicit diffn.)

B1 FT any form, e.g. $y = -px + ap(2 + p^2)$

(ii) Distance $P(ap^2, 2ap)$ to $N(an^2, 2an)$ is given by $PN^2 = \left[a(p^2 - n^2)\right]^2 + \left[2a(p - n)\right]^2$ $= a^2(p - n)^2 \left\{(p + n)^2 + 4\right\}$ $= a^2 \left(2p + \frac{2}{p}\right)^2 \left\{\left(\frac{-2}{p}\right)^2 + 4\right\}$ $= 16a^2 \left(\frac{p^2 + 1}{p}\right)^2 \left\{\frac{1 + p^2}{p}\right\} = 16a^2 \frac{(p^2 + 1)^3}{p^4}$

M1 Substituting for *n*

 $\frac{d(PN^2)}{dp} = 16a^2 \frac{d(p^2 + 3 + 3p^{-2} + p^{-4})}{dp}$

$$= 16a^{2}(2p - 6p^{-3} - 4p^{-5})$$

$$= 32a^{2} \frac{p^{6} - 3p^{2} - 2}{p^{5}}$$

$$= \frac{32a^{2}}{p^{5}}(p^{2} + 1)^{2}[p^{2} - 2]$$

M1 Differentiation directly,

or by the Quotient Rule

A1 Correct, unsimplified

Note that $\frac{d(PN^2)}{dp} = 16a^2 \left\{ \frac{p^4 \cdot 3(p^2 + 1)^2 \cdot 2p - (p^2 + 1)^3 \cdot 4p^3}{p^8} \right\}$ $= \frac{32a^2}{p^8} \cdot p^3 (p^2 + 1)^2 \left[3p^2 - 2(p^2 + 1) \right] \text{ by the Quotient Rule}$

 $\frac{d(PN^2)}{dp} = 0 \text{ only when } p^2 = 2$

A1 Given Answer fully shown

Justification that it is a minimum

E1

(either by examining the sign of $\frac{d(PN^2)}{dp}$

or by explaining that PN^2 cannot be maximised

(iii) Grad.
$$PQ$$
 is $\frac{2}{p+q}$

Grad.
$$NQ$$
 is $\frac{2}{n+q}$ or $\frac{2}{q-p-\frac{2}{p}}$

Since $\angle PQN = 90^{\circ}$ (by " \angle in a semi-circle"; i.e. *Thales Theorem*)

$$\frac{2}{p+q} \times \frac{2}{q-p-\frac{2}{p}} = -1$$
 M1

$$\Rightarrow 4 = (p+q)\left(p-q+\frac{2}{p}\right) = p^2-q^2+2+\frac{2q}{p}$$

$$\Rightarrow 2 = p^2 - q^2 + \frac{2q}{p}$$

 $\Rightarrow q = 0 \text{ or } q = \frac{2}{p} = \pm \sqrt{2}$

M1 Substituted into given expression

A1 Given Answer legitimately obtained 4

PN minimised when
$$p^2 = 2 \implies q^2 = \frac{2q}{p}$$

But
$$q = \pm \sqrt{2} \implies q = p$$
 (which is not the case)

Special Case: 1/3 for substg.
$$q = 0$$
 and verifying that $p^2 = 2$

(i)		
When $n = 1$		Clear verification.
$S_1 = 1 \le 2\sqrt{1} - 1$	B1	
Assume that the statement is true when $n = k$:	B1	Must be clear that this is
S _k $\leq 2\sqrt{k} - 1$		assumed.
Then		Linking S_{k+1} and S_k
_	M1	
$S_{k+1} = S_k + \frac{1}{\sqrt{k+1}}$		
$\leq 2\sqrt{k} - 1 + \frac{1}{\sqrt{k+1}}$	M1	Using assumed result
Sufficient to prove:	M1	
$2\sqrt{k} - 1 + \frac{1}{\sqrt{k+1}} \le 2\sqrt{k+1} - 1$		
i.e. $2\sqrt{k(k+1)} + 1 \le 2(k+1)$	A1	Multiplying by $\sqrt{k+1}$ or putting over a common
		denominator
i.e. $2\sqrt{k(k+1)} \le 2k+1$ i.e. $4k^2 + 4k \le 4k^2 + 4k + 1$		
	A1	
Which is clearly true. Therefore by induction the statement is true for all $n \ge 1$.	B1	Clear conclusion showing logic of induction.
-	[8]	
(ii)		
Required to prove:		Squaring given inequality
$(4k+1)^2(k+1) > (4k+3)^2k$ i.e. $16k^3 + 24k^2 + 9k + 1 > 16k^3 + 24k^2 + 9k$	M2	
	A1	
which is clearly true.	[2]	
When $n = 1$:	[3] M1	
$S_1 = 1 \ge 2 + \frac{1}{2} - c$	1417	
	A1	
So we need $c \ge \frac{3}{2}$ Prove $c = \frac{3}{2}$ works using induction	M1	
Assume holds when $n = k$:	M1	Allow a general c.
$S_k \ge 2\sqrt{k} + \frac{1}{2\sqrt{k}} - \frac{3}{2}$		
Then	M1	
$S_{k+1} = S_k + \frac{1}{\sqrt{k+1}} \ge 2\sqrt{k} + \frac{1}{2\sqrt{k}} + \frac{1}{\sqrt{k+1}} - c$		
Sufficient to prove:	A1	
$2\sqrt{k} + \frac{1}{2\sqrt{k}} + \frac{1}{\sqrt{k+1}} - c \ge 2\sqrt{k+1} + \frac{1}{2\sqrt{k+1}} - c$ i.e. $4k\sqrt{k+1} + \sqrt{k+1} + 2\sqrt{k} \ge 4\sqrt{k}(k+1) + \sqrt{k}$		
i.e. $4k\sqrt{k+1} + \sqrt{k+1} + 2\sqrt{k} \ge 4\sqrt{k}(k+1) + \sqrt{k}$	A1A1	
Which simplifies to the previously proved inequality.	B1	
No further restrictions on c, so the minimum value is $c = \frac{3}{2}$		
	[9]	

(i) For $0 \le x \le 1$, x is positive and $\ln x$ is negative

so
$$0 > x \ln x > \ln x$$

$$\Rightarrow$$
 $e^0 > e^{x \ln x} > e^{\ln x}$ or $\ln 1 > \ln x^x > \ln x$

$$\Rightarrow$$
 (1 >) f(x) > x since ln is a strictly increasing fn. **B1**

Again, since $\ln x < 0$, it follows that

$$\ln x < f(x) \ln x < x \ln x$$

$$\Rightarrow \ln x < \ln\{g(x)\} < \ln\{f(x)\}$$

$$\Rightarrow x < g(x) < f(x)$$

For x > 1, $\ln x > 0$ and so x < f(x) < g(x)

- M1 Suitably coherent justification
- A1 Given Answer legitimately obtained

M1 Taking logs and attempting implicit diffn.

Alt. Writing $y = e^{x \ln x}$ and diffg.

B1 No justification required

- (ii) $ln\{f(x)\} = x ln x$
 - $\frac{1}{f(x)} f'(x) = x \cdot \frac{1}{x} + 1 \cdot \ln x$ i.e. $f'(x) = (1 + \ln x) f(x)$

$$f'(x) = 0$$
 when $1 + \ln x = 0$, $\ln x = -1$, $x = e^{-1}$

3

- $\mathcal{L}im\left(\mathbf{f}(x)\right) = \mathcal{L}im\left(\mathbf{e}^{x \ln x}\right) = \mathcal{L}im\left(\mathbf{e}^{0}\right) = 1$ (iii)
- B1 Suitably justified

A1

A1

- $\mathcal{L}im\left(\mathbf{g}(x)\right) = \mathcal{L}im\left(x^{\mathbf{f}(x)}\right) = \mathcal{L}im\left(x^{\mathbf{1}}\right) = 0$
- **B1** May just be stated

Alt.
$$\underset{x\to 0}{\text{Lim}} (g(x)) = \underset{x\to 0}{\text{Lim}} (e^{f(x)\ln x}) = \underset{x\to 0}{\text{Lim}} (e^{\ln x}) = \underset{x\to 0}{\text{Lim}} (x) = 0$$

2

(iv) For $y = \frac{1}{x} + \ln x$ (x > 0),

$$\frac{dy}{dx} = -\frac{1}{x^2} + \frac{1}{x}$$
 or $\frac{x-1}{x^2} = 0$...

For
$$x = 1-$$
, $\frac{dy}{dx} < 0$ and for $x = 1+$, $\frac{dy}{dx} > 0$

(1, 1) is a MINIMUM of $y = \frac{1}{x} + \ln x$

M1 Diffg. and equating to zero

A1 From correct derivative

M1 Method for deciding

(Since there are no other TPs or discontinuities)

$$y \ge 1$$
 for all $x > 0$

Conclusion must be made for all 4 marks

ln(g(x)) = f(x) ln x

$$\frac{1}{g(x)} \cdot g'(x) = f(x) \cdot \frac{1}{x} + \ln x \{ f(x) (1 + \ln x) \}$$

$$\Rightarrow g'(x) = f(x).g(x) \left\{ \frac{1}{x} + \ln x + (\ln x)^2 \right\}$$

$$\geq f(x).g(x) \left\{ 1 + (\ln x)^2 \right\}$$

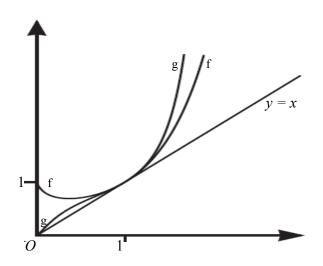
> 0 since f, g > 0 from (i)
and
$$1 + (\ln x)^2 \ge 1 > 0$$

M1 Taking logs and attempting implicit diffn.

A1 using f'(x) from (ii)

M1 using previous result of (iv)

A1 Given Answer fully justified



- **B1** One of f, g correct ...
- **B1** Both correct relative to y = x
- **B1** All three passing thro' (1, 1)

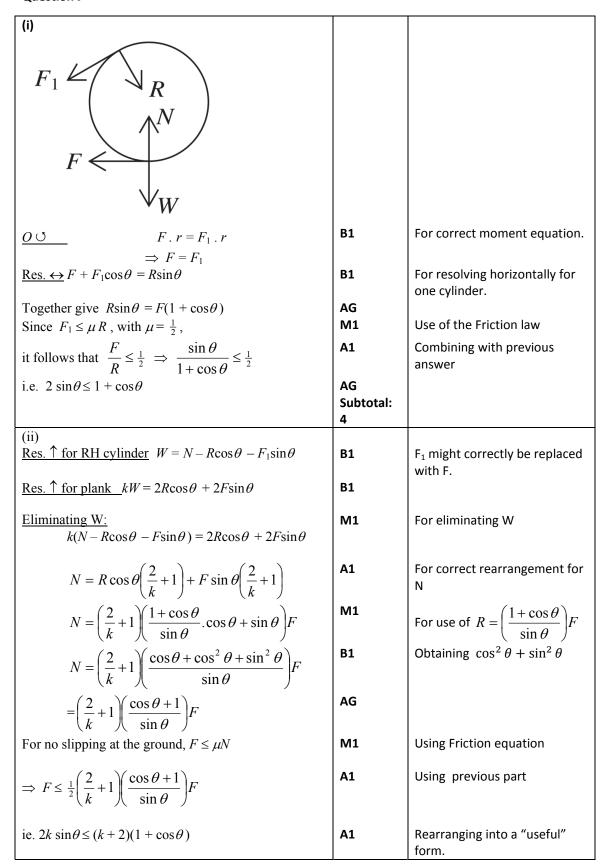
Since v is perpr. to CA , $(\mathbf{a} - \mathbf{b} + \lambda \mathbf{u}) \cdot (\mathbf{a} - \mathbf{c}) = 0$ $\Rightarrow (\mathbf{a} - \mathbf{b}) \cdot (\mathbf{a} - \mathbf{c}) + \lambda \mathbf{u} \cdot (\mathbf{a} - \mathbf{c}) = 0$	A1 Correctly multiplied out
$\Rightarrow \mathbf{v} = \frac{1}{\mu} (\mathbf{a} - \mathbf{b} + \lambda \mathbf{u})$	A1
Lines meet when $(\mathbf{r} = \mathbf{p} =) \mathbf{a} + \lambda \mathbf{u} = \mathbf{b} + \mu \mathbf{v}$	M1 Equated
Line thro' <i>B</i> perpr. to <i>CA</i> is $\mathbf{r} = \mathbf{b} + \mu \mathbf{v}$	B1
Line thro' A perpr. to BC is $\mathbf{r} = \mathbf{a} + \lambda \mathbf{u}$	B1

$\Rightarrow (\mathbf{a} - \mathbf{b}) \bullet (\mathbf{a} - \mathbf{c}) + \lambda \mathbf{u} \bullet (\mathbf{a} - \mathbf{c}) = 0$	AT Correctly multiplied out
$\Rightarrow \lambda = \frac{(\mathbf{b} - \mathbf{a}) \cdot (\mathbf{a} - \mathbf{c})}{\mathbf{u} \cdot (\mathbf{a} - \mathbf{c})}$	M1 Re-arranging for λ
, ,	A1 Correct (any sensible form)
$\Rightarrow p = a + \left(\frac{(b-a) \cdot (a-c)}{u \cdot (a-c)}\right) u$	A1 FT their λ (if only a , b , c , u involved)

$$\overrightarrow{CP} = \mathbf{p} - \mathbf{c} = \mathbf{a} - \mathbf{c} + \lambda \mathbf{u}$$
B1 FT their λ Attempt at $\overrightarrow{CP} \bullet \overrightarrow{AB}$ M1 $= (\mathbf{a} - \mathbf{c} + \lambda \mathbf{u}) \bullet (\mathbf{b} - \mathbf{a})$ A1 Correct to here $= (\mathbf{a} - \mathbf{c}) \bullet (\mathbf{b} - \mathbf{a}) + \lambda \mathbf{u} \bullet (\mathbf{b} - \mathbf{a})$ M1Now $\mathbf{u} \bullet (\mathbf{b} - \mathbf{c}) = 0$ since \mathbf{u} perpr. to BC M1 $\Rightarrow \mathbf{u} \bullet \mathbf{b} = \mathbf{u} \bullet \mathbf{c}$ A1so that $\overrightarrow{CP} \bullet \overrightarrow{AB} = (\mathbf{a} - \mathbf{c}) \bullet (\mathbf{b} - \mathbf{a}) + \lambda \mathbf{u} \bullet (\mathbf{c} - \mathbf{a})$ M1 Substituted in $= (\mathbf{a} - \mathbf{c}) \bullet (\mathbf{a} - \mathbf{b} + \lambda \mathbf{u})$ M1 A1 Factorisation attempt; correct $= 0$ from boxed line aboveA1 E1 Statement; justified $\Rightarrow CP$ is perpr. to AB E1 For final, justified statement

Notice that the "value" of is never actually required

Any candidate who states the result is true because P is the *orthocentre* of $\triangle ABC$ may be awarded **B2** for actually knowing something about triangle-geometry, but only in addition to any of the first 3 marks earned in the above solution: i.e. a maximum of 5/11 for the second part of the question.



However, we already have that	E1	Properly justified
$2k\sin\theta \le k(1+\cos\theta) \le (k+2)(1+\cos\theta)$		l reperty jacomea
so there are no extra restrictions on θ .		
	Subtotal:	
	10	
(iii)		
$4\sin^2\theta \le 1 + 2\cos\theta + \cos^2\theta$	M1	Squaring up an appropriate trig inequality
$4(1-\cos^2\theta) \le 1 + 2\cos\theta + \cos^2\theta$		ang megaanty
$0 \le 5\cos^2\theta + 2\cos\theta - 3$	M1	Creating and simplifying
$0 \le (5\cos\theta - 3)(\cos\theta + 1)$		quadratic inequality in one trig
Since $\cos \theta \ge 0$ we have $\cos \theta \ge \frac{3}{5}$	A1	1.40.0
3	E1	A graphical argument is
For appropriate angles $\cos \theta$ is decreasing and $\sin \theta$ is increasing.	EI	A graphical argument is perfectly acceptable here.
increasing.		N.b It is possible that
		inequalities like $2s - 1 \le c$
		are squared. If this is done
		without justifying that both
		sides are positive then
		withhold this final E1 .
Therefore $\sin \theta \leq \frac{4}{\epsilon}$	AG	
r-a	B1	
$\sin\theta = \frac{r - a}{r}$		
So $5r - 5a \le 4r$	M1	Combining with previous
		result
$r \le 5a$	AG	
	Subtotal:	
	6	

T (1 2 m)	1	T
$ma = F - (Av^2 + R)$	B1	Clear use of N2L
d f	M1	
$WD = \int_{0}^{d} F dx$		
0		
d C	AG	
$= \int_{0}^{d} \left(ma + Av^{2} + R \right) dx$		
0		
dv	B1	
Since $a = v \frac{dv}{dx}$		
	M1	Attempting to change variable of
$WD = \int_{x=0}^{x=d} (ma + Av^2 + R) \frac{dx}{dv} dv$	IVIT	Attempting to change variable of
$\int_{0}^{\infty} \frac{dv}{dv} dv$		integration.
$= \int_{x=0}^{x=d} (ma + Av^2 + R) \frac{v}{a} dv$		
$-\int (ma + Av + K) - dv$		
x=0		
Using $v^2 = u^2 + 2as$ with $v = w$, $u = 0$, $s = d \Rightarrow$	B1	Justifying limits. Ignore absence of
$w = \sqrt{2ad}$		<u>±</u>
Therefore:	AG	
	-	
$WD = \int_{a}^{v=w} \frac{(ma + Av^2 + R)v}{a} dv$		
$\int_{v=0}^{J} a$		
	[5]	
(i)	£-3	
	M1	Performing integration
$WD = \left[\left(m + \frac{R}{a} \right) \frac{v^2}{2} + \frac{Av^4}{4a} \right]^{\sqrt{2}ad}$	1417	i cirorining integration
$ WD = \left \left \frac{m+-}{a} \right = \frac{1}{2} + \frac{1}{4a} \right $		
(R)	A1	Correct answer in terms of d.
$=\left(m+\frac{R}{a}\right)ad+Aad^{2}$		
(<i>u</i>)		
For second half-journey,	B1B1	B1 for correct limits
$WD = \int_{-a}^{0} \frac{\left(-ma + Av^2 + R\right)v}{-a} dv$		B1 for correct integrand
$WD = \int \frac{dv}{dx} dv$		
w		
$=-mad+Rd+Aad^{2}$	A1	
Summing gives $2dR + 2Aad^2$	AG	N.b. integrals may be combined to
		get to the same result.
$R > ma \implies F = Av^2 + R - ma > 0$ always	E1	
	[6]	

(ii)		
If $R < ma$ then F is zero when $Av^2 = ma - R$	B1	Finding an expression for the
$\sqrt{ma-R}$		critical speed.
i.e. when $v = V = \sqrt{\frac{ma - R}{A}}$		
For F to fall to zero during motion, $V < w$	E1	
i.e. when $\frac{ma-R}{A} < 2ad$ i.e. $R > ma - 2Aad$	E1	
In this case, $WD = mad + Rd + Aad^2$,	B1	
as before, for the first half-journey		
For the second half $WD = \int_{-a}^{v} \frac{(-ma + Av^2 + R)v}{-a} dv$	M2	
$\left[\left(ma-R\right)\frac{v^2}{2a}-\frac{Av^4}{4a}\right]_w^V$	A1	
$=\frac{1}{2a}(ma-R)\left(\frac{ma-R}{A}\right)-\frac{A}{4a}\left(\frac{ma-R}{A}\right)^{2}-$	M1	Substituting expressions for V and w.
$\frac{1}{2a}(ma-R)(2ad) + \frac{A}{4a}(4a^2d^2)$		
$\begin{vmatrix} = \frac{1}{2Aa}(ma - R)^2 - \frac{1}{4Aa}(ma - R)^2 - (ma - R)d + \\ Aad^2 \end{vmatrix}$		
	A1 CAC	Without wrong working
$= \frac{1}{4Aa}(ma - R)^2 - mad + Rd + Aad^2$	A1 CAO	Without wrong working
So total WD = $\frac{1}{4Aa}(ma - R)^2 + 2Rd + 2Aad^2$	AG	
	[9]	

(i) $At \ A, KE = \frac{1}{2}mu^2 = \frac{5}{2}mag, PE = 0$ $At \ A_1, K = \frac{1}{2}mv^2, PE = 2mag$ $So \ respectively sin \ \beta \ t = \frac{1}{2}mv^2 + 2mag$ $B1$ $V^2 = ga$ $v = \sqrt{ga}$ $A1$ $If angle at \ A_1 \ is \ \beta \ and it just passes the second wall then we have: 0 = v \sin \theta \ t - \frac{1}{2}gt^2 So \ t = \frac{2v}{g} \sin \beta A1 Using \ s = ut + \frac{1}{2}at^2 So \ t = \frac{2v}{g} \sin \beta A1 Solving for \ t \ at second wall. A1 Considering horizontal distance \frac{2v^2 \sin \beta \cos \beta}{g} \frac{1}{g} \frac{2v^2 \sin \beta \cos \beta}{g} \frac{1}{g} \frac{2v^2 \sin \beta \cos \beta}{g} \frac{1}{g} \frac{1}$		1	
At A , $KE = \frac{1}{2}mu^2 = \frac{5}{2}mag$, $PE = 0$ At A_1 , $K = \frac{1}{2}mv^2$, $PE = 2mag$ Conservation of energy: $\frac{5}{2}mag = \frac{1}{2}mv^2 + 2mag$ M1 $v^2 = ga$ $v = \sqrt{ga}$ A1 If angle at A_1 is β and it just passes the second wall then we have: $0 = v \sin \theta \ t - \frac{1}{2}gt^2$ M1 Using $s = ut + \frac{1}{2}at^2$ So $t = \frac{2v}{g}\sin \beta$ A1 A1 A1 Solving for t at second wall. A1so, $a = v \cos \beta \ t$ M1 Considering horizontal distance $\frac{2v^2 \sin \beta \cos \beta}{g}$ A1 N.b. Some candidates may just quote this (or equivalent). Give full credit. $= 2a \sin \beta \cos \beta$ A1 Combining previous results. So $\sin(2\beta) = 1$ Therefore $\beta = 45^\circ$ A6 Condone absence of domain considerations. $x \text{ velocity is constant so}$ M1 Comparing $x \text{ velocities}$ A1 Comparing $x \text{ velocities}$	y 2a a		
At $A_1, K = \frac{1}{2}mv^2, PE = 2mag$ Conservation of energy: $\frac{5}{2}mag = \frac{1}{2}mv^2 + 2mag$ M1 $v^2 = ga$ $v = \sqrt{ga}$ A1 If angle at A_1 is β and it just passes the second wall then we have: $0 = v \sin \theta \ t - \frac{1}{2}gt^2$ M1 Using $s = ut + \frac{1}{2}at^2$ So $t = \frac{2v}{g}\sin \beta$ A1 Also, $a = v \cos \beta t$ M1 Considering horizontal distance N.b. Some candidates may just quote this (or equivalent). Give full credit. $= 2a \sin \beta \cos \beta$ A1 Therefore $\beta = 45^\circ$ AG Condone absence of domain considerations. $x \text{ velocity is constant so}$ M1 Comparing $x \text{ velocities}$ M1 Comparing $x \text{ velocities}$		54	
Conservation of energy: $\frac{5}{2}mag = \frac{1}{2}mv^2 + 2mag$ $v^2 = ga$ $v = \sqrt{ga}$ A1 If angle at A_1 is β and it just passes the second wall then we have: $0 = v \sin \theta \ t - \frac{1}{2}gt^2$ M1 Using $s = ut + \frac{1}{2}at^2$ So $t = \frac{2v}{g}\sin \beta$ A1 A1 Solving for t at second wall. Also, $a = v \cos \beta \ t$ M1 Considering horizontal distance $\frac{2v^2 \sin \beta \cos \beta}{g}$ A1 Combining previous results. So $\sin(2\beta) = 1$ Therefore $\beta = 45^\circ$ AG Condone absence of domain considerations. $v \cos \alpha = v \cos \beta$ M1 Comparing x velocities $\sqrt{5ag} \cos \alpha = \sqrt{ag} \frac{1}{\sqrt{g}}$ M1 Comparing x velocities		B1	
$\frac{5}{2} mag = \frac{1}{2} mv^2 + 2 mag$ $v^2 = ga$ $v = \sqrt{ga}$ A1 If angle at A_1 is β and it just passes the second wall then we have: $0 = v \sin \theta \ t - \frac{1}{2} gt^2$ M1 Using $s = ut + \frac{1}{2} at^2$ $5o \ t = \frac{2v}{g} \sin \beta$ A1 Solving for t at second wall. Also, $a = v \cos \beta \ t$ M1 Considering horizontal distance $\frac{2v^2 \sin \beta \cos \beta}{g}$ A1 N.b. Some candidates may just quote this (or equivalent). Give full credit. $= 2a \sin \beta \cos \beta$ A1 Combining previous results. $So \sin(2\beta) = 1$ Therefore $\beta = 45^\circ$ AG Condone absence of domain considerations. $x \text{ velocity is constant so}$ $y \text{ velocity is constant so}$ M1 Comparing $x \text{ velocities}$ A1	$At A_1, K = \frac{1}{2}mv^2, PE = 2mag$	B1	
If angle at A_1 is β and it just passes the second wall then we have: $0 = v \sin \theta \ t - \frac{1}{2}gt^2 \qquad \qquad \mathbf{M1} \qquad \text{Using } s = ut + \frac{1}{2}at^2$ So $t = \frac{2v}{g} \sin \beta$ A1 Solving for t at second wall. $Also, a = v \cos \beta \ t \qquad \qquad \mathbf{M1} \qquad \text{Considering horizontal distance} $ $= \frac{2v^2 \sin \beta \cos \beta}{g} \qquad \qquad \mathbf{M1} \qquad \text{Considering horizontal distance} $ N.b. Some candidates may just quote this (or equivalent). Give full credit. $= 2a \sin \beta \cos \beta \qquad \qquad \mathbf{A1} \qquad \text{Combining previous results.} $ So $\sin(2\beta) = 1$ A1 $= 2a \sin \beta \cos \beta \qquad \qquad \mathbf{A1} \qquad \mathbf{A2} \qquad \mathbf{A3} \qquad \mathbf{A4} \qquad \mathbf{A5} \qquad \mathbf{A6} \qquad A$		M1	
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If angle at A_1 is β and it just passes the second wall then we have: $0 = v \sin \theta \ t - \frac{1}{2}gt^2 \qquad \qquad \mathbf{M1} \qquad \text{Using } s = ut + \frac{1}{2}at^2$ So $t = \frac{2v}{g} \sin \beta$ A1 Solving for t at second wall. $Also, a = v \cos \beta \ t \qquad \qquad \mathbf{M1} \qquad \text{Considering horizontal distance} $ $= \frac{2v^2 \sin \beta \cos \beta}{g} \qquad \qquad \mathbf{M1} \qquad \text{Considering horizontal distance} $ N.b. Some candidates may just quote this (or equivalent). Give full credit. $= 2a \sin \beta \cos \beta \qquad \qquad \mathbf{A1} \qquad \text{Combining previous results.} $ So $\sin(2\beta) = 1$ A1 $= 2a \sin \beta \cos \beta \qquad \qquad \mathbf{A1} \qquad \mathbf{A2} \qquad \mathbf{A3} \qquad \mathbf{A4} \qquad \mathbf{A5} \qquad \mathbf{A6} \qquad A$	$v = \sqrt{ga}$	A1	
have: $0 = v \sin \theta t - \frac{1}{2}gt^2 \qquad \qquad \mathbf{M1} \qquad \text{Using } s = ut + \frac{1}{2}at^2$ So $t = \frac{2v}{g} \sin \beta$ $\mathbf{A1} \qquad \text{Solving for t at second wall.}$ Also, $a = v \cos \beta t$ $\mathbf{M1} \qquad \text{Considering horizontal distance}$ $N.b. \text{Some candidates may just quote this (or equivalent). Give full credit.}$ $= 2a \sin \beta \cos \beta \qquad \qquad \mathbf{A1} \qquad \text{Combining previous results.}$ So $\sin(2\beta) = 1$ $\text{Therefore } \beta = 45^\circ \qquad \qquad \mathbf{A6} \qquad \text{Condone absence of domain considerations.}$ $x \text{velocity is constant so} \qquad \qquad \mathbf{M1} \qquad \text{Comparing } x \text{velocities}$ $\sqrt{5ag} \cos \alpha = \sqrt{ag} \frac{1}{\sqrt{5}} \qquad \qquad \mathbf{A1} \qquad \mathbf{M1} \qquad \mathbf{Comparing } x \text{velocities}$	V G	[4]	
So $t = \frac{2v}{g} \sin \beta$ A1 Solving for t at second wall. Also, $a = v \cos \beta t$ M1 Considering horizontal distance $= \frac{2v^2 \sin \beta \cos \beta}{g}$ $= \frac{2v^2 \sin \beta \cos \beta}{g}$ N.b. Some candidates may just quote this (or equivalent). Give full credit. $= 2a \sin \beta \cos \beta$ A1 Combining previous results. So $\sin(2\beta) = 1$ A1 Therefore $\beta = 45^\circ$ AG Condone absence of domain considerations. [5] x velocity is constant so $u \cos \alpha = v \cos \beta$ M1 Comparing x velocities $\sqrt{5ag} \cos \alpha = \sqrt{ag} \frac{1}{\sqrt{5}}$ A1			
Also, $a = v \cos \beta t$ $= \frac{2v^2 \sin \beta \cos \beta}{g}$ $= \frac{2v^2 \sin \beta \cos \beta}{g}$ N.b. Some candidates may just quote this (or equivalent). Give full credit. $= 2a \sin \beta \cos \beta$ A1 Combining previous results. So $\sin(2\beta) = 1$ A1 Therefore $\beta = 45^\circ$ AG Condone absence of domain considerations. [5] x velocity is constant so $u \cos \alpha = v \cos \beta$ M1 Comparing x velocities $\sqrt{5ag} \cos \alpha = \sqrt{ag} \frac{1}{\sqrt{5}}$ A1	$0 = v \sin \theta t - \frac{1}{2} g t^2$	M1	Using $s = ut + \frac{1}{2}at^2$
$=\frac{2v^2\sin\beta\cos\beta}{g}$ $=\frac{2v^2\sin\beta\cos\beta}{g}$ N.b. Some candidates may just quote this (or equivalent). Give full credit. $=2a\sin\beta\cos\beta$ A1 Combining previous results. $So\sin(2\beta)=1$ A1 Therefore $\beta=45^\circ$ AG Condone absence of domain considerations. $[5]$ x velocity is constant so $u\cos\alpha=v\cos\beta$ M1 Comparing x velocities $\sqrt{5ag}\cos\alpha=\sqrt{ag}\frac{1}{\sqrt{5}}$ A1	So $t = \frac{2v}{g} \sin \beta$	A1	
$= 2a \sin \beta \cos \beta \qquad \qquad \text{equivalent). Give full} \\ = 2a \sin \beta \cos \beta \qquad \qquad \text{A1} \qquad \qquad \text{Combining previous} \\ \text{results.} \\ \text{So } \sin(2\beta) = 1 \qquad \qquad \text{A1} \qquad \qquad \\ \text{Therefore } \beta = 45^{\circ} \qquad \qquad \text{AG} \qquad \qquad \text{Condone absence of} \\ \text{domain considerations.} \\ \text{[5]} \qquad \qquad x \text{ velocity is constant so} \qquad \qquad$	Also, $a = v \cos \beta t$	M1	_
$= 2a \sin \beta \cos \beta \hspace{1cm} \textbf{A1} \hspace{1cm} \textbf{Combining previous} \\ \textbf{results.} \\ \textbf{So } \sin(2\beta) = 1 \hspace{1cm} \textbf{A1} \hspace{1cm} \\ \textbf{Therefore } \beta = 45^{\circ} \hspace{1cm} \textbf{AG} \hspace{1cm} \textbf{Condone absence of} \\ \textbf{domain considerations.} \\ \textbf{[5]} \\ x \hspace{1cm} \textbf{velocity is constant so} \hspace{1cm} \textbf{M1} \hspace{1cm} \textbf{Comparing } x \hspace{1cm} \textbf{velocities} \\ \hline \sqrt{5ag} \cos \alpha = \sqrt{ag} \frac{1}{\sqrt{2}} \hspace{1cm} \textbf{A1} \hspace{1cm} \\ \textbf{A1} \end{array}$	$=\frac{2v^2\sin\beta\cos\beta}{g}$		may just quote this (or equivalent). Give full
Therefore $\beta=45^\circ$ AG Condone absence of domain considerations. [5] $x \text{ velocity is constant so}$ M1 Comparing $x \text{ velocities}$ $\sqrt{5ag}\cos\alpha = \sqrt{ag}\frac{1}{\sqrt{2}}$ A1	$= 2a\sin\beta\cos\beta$	A1	
	So $\sin(2\beta) = 1$	A1	
x velocity is constant so $u\cos\alpha = v\cos\beta \qquad \qquad \text{M1} \qquad \text{Comparing } x \text{ velocities}$ $\sqrt{5ag}\cos\alpha = \sqrt{ag}\frac{1}{\sqrt{2}} \qquad \qquad \text{A1}$	Therefore $\beta=45^\circ$	AG	
$u\cos\alpha = v\cos\beta$ M1 Comparing x velocities $\sqrt{5ag}\cos\alpha = \sqrt{ag}\frac{1}{\sqrt{2}}$		[5]	
$u\cos\alpha = v\cos\beta$ $\sqrt{5ag}\cos\alpha = \sqrt{ag}\frac{1}{\sqrt{2}}$ $\cos\alpha = \frac{1}{\sqrt{10}}$ $\sin\alpha = \frac{3}{\sqrt{10}}, \tan\alpha = 3$ M1 Comparing x velocities A1 Converting to a more useful ratio	•		
$\sqrt{5ag}\cos\alpha = \sqrt{ag}\frac{1}{\sqrt{2}}$ $\cos\alpha = \frac{1}{\sqrt{10}}$ $\sin\alpha = \frac{3}{\sqrt{10}}, \tan\alpha = 3$ A1 Converting to a more useful ratio	$u\cos\alpha = v\cos\beta$	M1	Comparing x velocities
$\sin \alpha = \frac{3}{\sqrt{10}}, \tan \alpha = 3$ A1 Converting to a more	$\sqrt{5ag}\cos\alpha = \sqrt{ag}\frac{1}{\sqrt{2}}$ $\cos\alpha = \frac{1}{\sqrt{10}}$	A1	
γ_{10}	$\sin \alpha = \frac{3}{\sqrt{10}}, \tan \alpha = 3$	A1	Converting to a more useful ratio.

Mothod 1.	D.4.1	1 2
Method 1:	M1	Using $s = ut + \frac{1}{2}at^2$
$2a = \sqrt{5ag} \frac{3}{\sqrt{10}} t - \frac{1}{2} g t^2$		
$=\frac{3\sqrt{ag}}{\sqrt{2}}t-\frac{1}{2}gt^2$		
VZ Z		
So So		
$t^2 - \frac{3\sqrt{2}a}{1}t + \frac{4a}{1} = 0$		
$t^{2} - \frac{3\sqrt{2a}}{\sqrt{g}}t + \frac{4a}{g} = 0$ $\left(t - \sqrt{\frac{2a}{g}}\right)\left(t - 2\sqrt{\frac{2a}{g}}\right) = 0$		
$\left(\begin{array}{c} \overline{2a} \\ \end{array}\right)$		
$\left(t-\left \frac{2\alpha}{2}\right \right)\left(t-2\left \frac{2\alpha}{2}\right \right)=0$		
$\langle \sqrt{g} \rangle \langle \sqrt{g} \rangle$		
First time and the wall are and the total	A1	
First time over the wall means that $t = \sqrt{\frac{2a}{g}}$		
$\frac{1}{\sqrt{2a}}$	A1	
So $d = u\cos\theta \ t = \sqrt{5ag} \times \frac{1}{\sqrt{10}} \times \sqrt{\frac{2a}{g}} = a$		
Method 2:	M1	Using trajectory
$gx^2 \sec^2 \alpha$		equation
$y - x \tan \alpha - \frac{2u^2}{}$		
$y = x \tan \alpha - \frac{gx^2 \sec^2 \alpha}{2u^2}$ $2a = 3x - \frac{x^2}{a}$ $(x - a)(x - 2a) = 0$	A1	Combining with
$2a = 3x - \frac{1}{a}$		previous results
(x-a)(x-2a) = 0		·
x = a	A1	
	[6]	
If the speed at h above first wall is v then by conserving	M1	
energy,		
$\frac{1}{2}5ag = \frac{1}{2}v^2 + (2a+h)g$		
$\frac{2}{2}Say = \frac{1}{2}v + (2u + n)y$		
2		
$v^2 = ag - 2gh$	B1	
Hairan kuningkan yang kina wikina wikina adalah adalah adalah adalah dalah dal	B 4 4	11
Using trajectory equation with origin at top of first wall and angle β as particle moves over first wall:	M1	Use of trajectory
angle p as particle moves over first wall: $an^{2}(1 + ton^{2} p)$		equation (might be several kinematics
$y = h + x \tan \beta - \frac{gx^2(1 + \tan^2 \beta)}{2v^2}$		
When $x = a$ we need $y = 0$:		equations effectively leading to the same
		thing)
$0 = h + a \tan \beta - \frac{ga^2(1 + \tan^2 \beta)}{2v^2}$		10,101
20		
Treating this as a quadratic in $\tan \beta$:	M1	Considering the
$-\frac{ga^2}{2m^2}\tan^2\beta + a\tan\beta + h - \frac{ga^2}{2m^2} = 0$		quadratic (or
$ 2v^{2} + 3av^{2} + 3av^$		equivalently
$-ga^{-1}\tan^{2}\beta + 2av^{-1}\tan\beta + 2nv^{-1} - ga^{-1} = 0$ The discriminant is:		differentiating to find the max)
$4a^2v^4 + 4ga^2(2hv^2 - ga^2)$		uic iiiax)
iu v i tyu (211v — yu)		
$= 4a^{2}(g^{2}(a^{2} - 4ah + 4h^{2}) + 2g^{2}h(a - 2h) - g^{2}a^{2}))$	A1	Obtaining a clearly
$= 4a^{2}q^{2}(a^{2} - 4ah + 4h^{2} + 2ah - 4h^{2} - a^{2})$		negative discriminant –
$= -8a^3g^2h$		this might take many
< 0		alternative forms.
Therefore no solution.		
	[5]	

(i)	B2	-
l n	BZ	
$P(X + Y = n) = \sum_{r=0}^{n} P(X = r)(P(Y = n - r))$		
r=0		
$\frac{n}{n}$ $-\lambda_2 r$ $-\mu$ $n-r$	B1	
$=\sum_{r=0}^{n}\frac{e^{-\lambda}\lambda^{r}}{r!}\times\frac{e^{-\mu}\mu^{n-r}}{(n-r)!}$	51	
$\underset{r=0}{\angle}$ r! $(n-r)!$		
$a^{-\lambda}a^{-\mu}$	M1	Attempting to manipulate
$=\frac{e^{-\lambda}e^{-\mu}}{n!}\sum_{r=0}^{n}\frac{n!}{r!(n-r)!}\lambda^{r}\mu^{n-r}$		factorials towards a binomial
$n! \underset{r=0}{{\angle}} r! (n-r)!$		coefficient
$\rho^{-\lambda}\rho^{-\mu}\sum_{n=0}^{n} (n)$	B1	Identifying correct binomial
$=\frac{e^{-\lambda}e^{-\mu}}{n!}\sum_{r=0}^{n}\binom{n}{r}\lambda^{r}\mu^{n-r}$		coefficient
n: Z= (1)		
$\rho^{-(\lambda+\mu)}$	B1	
$=\frac{e^{-(\lambda+\mu)}}{n!}(\lambda+\mu)^n$		
16.		
Which is the the formula for $Po(\lambda + \mu)$	E1	Recognising result. Must state
	[-1	parameters
\(\text{i:1} \)	[7]	
(ii) $P(X=r) \times P(Y=k-r)$	M2	(may be implied by following
$P(X = r X + Y = k) = \frac{P(X = r) \times P(Y + Y = k)}{P(Y + Y = k)}$	1412	line)
$P(X = r X + Y = k) = \frac{P(X = r) \times P(Y = k - r)}{P(X + Y = k)}$ $= \frac{\frac{e^{-\lambda} \lambda^r}{r!} \times \frac{e^{-\mu} \mu^{k-r}}{(k-r)!}}{\frac{e^{-(\lambda+\mu)}}{k!} (\lambda + \mu)^k}$	A1	inie,
$\frac{e^{-\lambda}}{r!} \times \frac{e^{-\lambda}\mu}{(k-r)!}$	\ \frac{1}{2}	
$=\frac{1}{a^{-(\lambda+\mu)}}$		
$\frac{e^{-k}}{k!}(\lambda+\mu)^k$		
	A1	
$= \frac{k!}{r! (k-r)!} \left(\frac{\lambda}{\lambda+\mu}\right)^r \left(\frac{\mu}{\lambda+\mu}\right)^{k-r}$ Which is a $B\left(k, \frac{\lambda}{\lambda+\mu}\right)$ distribution.	AI	
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	E1	Darameters must be stated
Which is a $B\left(k, \frac{\kappa}{\lambda + \mu}\right)$ distribution.	ET	Parameters must be stated.
	[5]	
(iii) This corresponds to r=1, k=1 from (ii)	M2	Can be implied by correct
		answer.
So probability is $\frac{\lambda}{\lambda + \mu}$.	A1	
(iv)	[3]	
Expected waiting time given that Adam is first is waiting time	B2	Also accept waiting time given
for first fish plus waiting time for Eve $\left(=\frac{1}{\lambda+\mu}+\frac{1}{\mu}\right)$		Eve is first. Must be clearly
101 max man plus watering time for Eve $\left(-\frac{1}{\lambda + \mu} + \frac{1}{\mu}\right)$		identified.
Expected waiting time is:	M2	
E(Waiting time Adam first)P(Adam first)+E(Waiting time Eve		
first)P(Eve first)		
$= \left(\frac{1}{\lambda + \mu} + \frac{1}{\mu}\right) \times \frac{\lambda}{\lambda + \mu} + \left(\frac{1}{\lambda + \mu} + \frac{1}{\lambda}\right) \times \frac{\mu}{\lambda + \mu}$	A1	
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		No need for this algebraic
$=\frac{1}{\lambda}+\frac{1}{\mu}-\frac{1}{\lambda+\mu}$		simplification.
η μ π ι μ	[5]	
	[-]	

(;)		1
(i)	D/1 A 1	NA1 for any attempt relating to
$P(\text{correct key on } k^{\text{th}} \text{attempt}) = \frac{1}{n} \left(1 - \frac{1}{n}\right)^{k-1}$	M1A1	M1 for any attempt relating to
n = n		the geometric distribution –
		e.g. missing first factor or
		power slightly wrong.
$=pq^{k-1}$		Although not strictly necessary,
Where $p = \frac{1}{n}$, $q = 1 - \frac{1}{n}$		you may see this substitution
n n n		frequently
Expected number of attempts is given by	M1	May be written in sigma
$p + 2pq + 3pq^2 \dots$		notation
$p + 2pq + 3pq^{2} \dots$ $= p(1 + 2q + 3q^{2} \dots)$ $= p(1 - q)^{-2}$ $= \frac{p}{p^{2}} = \frac{1}{p}$		
$= p(1-q)^{-2}$	M1	Linking to binomial expansion
p 1		
$=\frac{1}{n^2}=\frac{1}{n}$		
= n	A1	
	[5]	
(ii)	r-1	
	B1	
$P(\text{correct key on } k^{\text{th}} \text{attempt}) = \frac{1}{n} \text{ for } k = 1n$	01	
Expected number of attempts is given by	M1	
$\frac{1}{n} + \frac{2}{n} + \frac{3}{n} \dots + \frac{n}{n}$		
n n n n n n		
$=\frac{n+1}{2}$	M1A1	M1 for clearly recognising sum
2		of integers / arithmetic series.
	[4]	
(iii)		
$P(\text{correct key on } k^{\text{th}} \text{attempt})$	M1	M1 for an attempt at this,
$= \frac{n-1}{n} \times \frac{n}{n+1} \times \frac{n+1}{n+2} \dots \times \frac{1}{n+k-1}$	A1	possibly by pattern spotting the
$-\frac{n}{n} \wedge \frac{n+1}{n+2} \wedge \frac{n+2}{n+k-1}$		first few cases. Condone
		absence of checking $k=1$ case
		explicitly.
$= \frac{n-1}{(n+k-2)(n+k-1)}$	M1	M1 for attempting telescoping
-(n+k-2)(n+k-1)	AG	(may be written as an
		induction)
$= (n-1)\left(\frac{-1}{n+k-1} + \frac{1}{n+k-2}\right)$	M2	Attempting partial fractions
$= (n-1)\left(\frac{n+k-1}{n+k-2}\right)$	A1	(This may be seen later)
	[6]	
Expected number of attempts is given by	M1	
$\sum_{k=0}^{\infty} \langle k \rangle \langle k \rangle$		
$(n-1)\sum_{1}^{\infty}\left(\frac{k}{n+k-2}-\frac{k}{n+k-1}\right)$		
$= (n-1)\left[\left(\frac{1}{n-1} - \frac{1}{n}\right) + \left(\frac{2}{n} - \frac{2}{n+1}\right)\right]$		
$= (n-1)\left[\left(\frac{n-1}{n-1} - \frac{1}{n}\right) + \left(\frac{n-1}{n-1}\right)\right]$		
$\begin{bmatrix} & & & & & & & & & & & & & & & & & & &$		
$+\left(\frac{3}{n+1}-\frac{3}{n+2}\right)$		
	M1A1	M1 for attempting telescoping
$= (n-1) \left[\frac{1}{n-1} + \frac{1}{n} + \frac{1}{n+1} \dots \right]$ $= (n-1) \left(\sum_{r=1}^{\infty} \frac{1}{r} - \sum_{r=1}^{n-2} \frac{1}{r} \right)$		ma for accompania colescoping
$\left(\sum_{i=1}^{\infty} 1, \sum_{i=1}^{n-2} 1\right)$	B1	
$=(n-1)\left(\begin{array}{c} \sum_{i=1}^{n}-\sum_{i=1}^{n}\end{array}\right)$		
$\left\langle \frac{1}{r-1}r \frac{1}{r-1}r\right\rangle$		
In the brackets there is an infinite sum minus a finite sum, so	E1	
the result is infinite.		
	[5]	