1. (i)

$$I_n - I_{n+1} = \int_0^\infty \frac{1}{(1+u^2)^n} du - \int_0^\infty \frac{1}{(1+u^2)^{n+1}} du = \int_0^\infty \frac{1+u^2-1}{(1+u^2)^{n+1}} du$$
$$= \int_0^\infty \frac{u^2}{(1+u^2)^{n+1}} du$$

**B1** 

$$= \int_{0}^{\infty} u \frac{u}{(1+u^{2})^{n+1}} du = \left[ u \frac{-1}{2n(1+u^{2})^{n}} \right]_{0}^{\infty} - \int_{0}^{\infty} \frac{-1}{2n(1+u^{2})^{n}} du$$

integrating by parts

M1 A1

$$= 0 + \frac{1}{2n} \int_{0}^{\infty} \frac{1}{(1+u^2)^n} du = \frac{1}{2n} I_n$$

A1\* (4)

$$I_{n+1} = I_n - \frac{1}{2n}I_n = \frac{2n-1}{2n}I_n$$
 M1

$$=\frac{(2n-1)(2n-3)...(1)}{(2n)(2n-2)...(2)}I_1 \hspace{1.5cm} \text{M1}$$

$$I_1 = \int_0^\infty \frac{1}{(1+u^2)} du = [\tan^{-1} u]_0^\infty = \frac{\pi}{2}$$
 B1

$$\frac{(2n-1)(2n-3)...(1)}{(2n)(2n-2)...(2)} = \frac{(2n)(2n-1)(2n-2)(2n-3)...(2)(1)}{[(2n)(2n-2)...(2)]^2} = \frac{(2n)!}{[2^n n!]^2} = \frac{(2n)!}{2^{2n}(n!)^2}$$
 M1

Thus 
$$I_{n+1} = \frac{(2n)!}{2^{2n}(n!)^2} \frac{\pi}{2} = \frac{(2n)!\pi}{2^{2n+1}(n!)^2}$$
 A1\*

(ii)

$$J = \int_{0}^{\infty} f((x - x^{-1})^{2}) dx = \int_{0}^{0} f((u^{-1} - u)^{2}) . -u^{-2} du = \int_{0}^{\infty} x^{-2} f((x - x^{-1})^{2}) dx$$

using the substitution  $u=x^{-1}$  ,  $\frac{du}{dx}=-x^{-2}$  and then the substitution u=x ,  $\frac{du}{dx}=1$  M1A1\*

$$2J = \int_{0}^{\infty} f((x - x^{-1})^{2}) dx + \int_{0}^{\infty} x^{-2} f((x - x^{-1})^{2}) dx = \int_{0}^{\infty} f((x - x^{-1})^{2}) (1 + x^{-2}) dx$$

So 
$$J = \frac{1}{2} \int_0^\infty f((x - x^{-1})^2) (1 + x^{-2}) dx$$
 M1A1\*

Using the substitution  $u = x - x^{-1}$ ,  $\frac{du}{dx} = 1 + x^{-2}$ ,

$$J = \frac{1}{2} \int_0^\infty f((x - x^{-1})^2) (1 + x^{-2}) dx = \frac{1}{2} \int_{-\infty}^\infty f(u^2) du = \int_0^\infty f(u^2) du$$
 M1A1\* (6)

$$\int_0^\infty \frac{x^{2n-2}}{(x^4-x^2+1)^n} dx = \int_0^\infty \frac{x^{-2}}{(x^2-1+x^{-2})^n} dx = \int_0^\infty \frac{x^{-2}}{((x-x^{-1})^2+1)^n} dx$$
 M1A1

$$=\int_0^\infty \frac{1}{(u^2+1)^n} du$$
 M1

$$\int_0^\infty \frac{x^{2n-2}}{(x^4-x^2+1)^n} dx = \int_0^\infty \frac{1}{(u^2+1)^n} du = I_n$$
 M1

$$=\frac{(2(n-1))!\pi}{2^{2(n-1)+1}((n-1)!)^2} = \frac{(2n-2)!\pi}{2^{2n-1}((n-1)!)^2}$$
 A1 (5)

$$m = 1000$$
 B1

If 
$$n \ge 1000$$
, then  $1000 \le n$ , so  $1000n \le n^2$ , i.e.  $(1000n) \le (n^2)$  M1A1 (4)

E. G. Let 
$$s_n=1$$
 and  $t_n=2$  for  $n$  odd, and  $s_n=2$  and  $t_n=1$  for  $n$  even.

Then 
$$\not\exists m$$
 for which for  $n \geq m$  ,  $s_n \leq t_n$  , nor  $t_n \leq s_n$ 

So it is not the case that 
$$(s_n) \leq (t_n)$$
 , but nor is it the case that  $(t_n) \leq (s_n)$ 

$$(s_n) \leq (t_n)$$
 means that there exists a positive integer, say  $\,m_1$  , for which for  $\,n \geq m_1\,$  ,  $\,s_n \leq t_n$  .   
 E1

$$(t_n) \leq (u_n)$$
 means that there exists a positive integer, say  $m_2$  , for which for  $n \geq m_2$  ,  $t_n \leq u_n$  . F1

Then if 
$$m = \max(m_1, m_2)$$
,

for 
$$n \ge m$$
,  $s_n \le t_n \le u_n$ , and so  $(s_n) \le (u_n)$ 

$$m=4$$

Assume 
$$k^2 \le 2^k$$
 for some value  $k \ge 4$ .

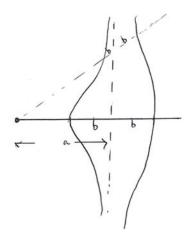
Then 
$$(k+1)^2 = \left(\frac{k+1}{k}\right)^2 k^2 = \left(1 + \frac{1}{k}\right)^2 k^2 \le \left(1 + \frac{1}{4}\right)^2 k^2 = \frac{25}{16}k^2 < 2k^2 \le 2 \times 2^k = 2^{k+1}$$

M1A1

$$4^2 = 2^4$$
 B1

so by the principle of mathematical induction,  $n^2 \le 2^n$  for  $n \ge 4$ , and thus  $(n^2) \le (2^n)$  A1 (7)

3. (i)



Symmetry about initial line

Two branches G1

Shape and labelling G1 (3)

If  $|r - a \sec \theta| = b$ , then  $r - a \sec \theta = b$  or  $r - a \sec \theta = -b$ 

So  $r = a \sec \theta + b$  or  $r = a \sec \theta - b$  M1A1

If  $\sec \theta < 0$ ,  $a \sec \theta + b < -a + b < 0$  as a > b and  $a \sec \theta - b < -a - b < 0$  as a and b are both positive, and thus in both cases, r < 0 which is not permitted.

G1

If  $\sec \theta > 0$ ,  $a \sec \theta + b > a + b > 0$  and  $a \sec \theta - b > a - b > 0$  giving r > 0

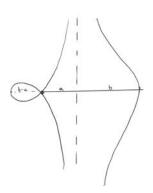
so  $\sec \theta > 0$  as required. B1 (4)

So  $r=a\sec\theta\pm b$  , thus points satisfying (\*) lie on a certain conchoid of Nicomedes with A being the pole (origin),

d being b,

and L being the line  $r = a \sec \theta$ . B1 (3)

(ii)



Symmetry about initial line G1

Two branches G1

Loop, shape and labelling G1

If a < b, then the curve has two branches,  $r = a \sec \theta + b$  with  $\sec \theta > 0$  and  $r = a \sec \theta + b$  with  $\sec \theta < 0$ , the endpoints of the loop corresponding to  $\sec \theta = \frac{-b}{a}$ . B1 (4)

In the case  $\ a=1$  and  $\ b=2$  ,  $\sec\theta=\frac{-2}{1}=-2$  so  $\ \theta=\pm\frac{2\pi}{3}$ 

Area of loop

$$=2\times\frac{1}{2}\int_{\frac{2\pi}{2}}^{\pi}(\sec\theta+2)^2d\theta$$
 M1A1

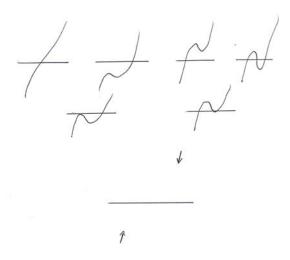
$$= \int_{\frac{2\pi}{3}}^{\pi} \sec^2 \theta + 4 \sec \theta + 4 d\theta = [\tan \theta + 4 \ln|\sec \theta + \tan \theta| + 4\theta]_{\frac{2\pi}{3}}^{\pi} \quad \mathbf{M1A1}$$

$$= 4\pi - \left(-\sqrt{3} + 4\ln\left|-2 - \sqrt{3}\right| + \frac{8\pi}{3}\right) = \frac{4\pi}{3} + \sqrt{3} - 4\ln\left|2 + \sqrt{3}\right|$$
 M1A1 (6)

4. (i) 
$$y = z^3 + az^2 + bz + c$$
 is continuous.

For 
$$z \to -\infty$$
,  $y \to -\infty$  and for  $z \to \infty$ ,  $y \to \infty$ .

So the sketch of this graph must be one of the following:-



### **B1**

Hence, it must intersect the z axis at least once, and so there is at least one real root of

$$z^3 + az^2 + bz + c = 0$$
 B1 (3)

(ii) 
$$z^3 + az^2 + bz + c = (z - z_1)(z - z_2)(z - z_3)$$
 M1

Thus 
$$a = (-z_1 - z_2 - z_3) = -S_1$$

$$b = (z_2 z_3 + z_3 z_1 + z_1 z_2) = \frac{(z_1 + z_2 + z_3)^2 - (z_1^2 + z_2^2 + z_3^2)}{2} = \frac{S_1^2 - S_2}{2}$$
A1

and, as 
$${z_1}^3 + a{z_1}^2 + b{z_1} + c = 0$$
 ,  ${z_2}^3 + a{z_2}^2 + b{z_2} + c = 0$  ,  ${z_3}^3 + a{z_3}^2 + b{z_3} + c = 0$ 

adding these three equations we have,

$$(z_1^3 + z_2^3 + z_3^3) + a(z_1^2 + z_2^2 + z_3^2) + b(z_1 + z_2 + z_3) + 3c = 0$$
 M1

(Alternatively,

$$(z_1 + z_2 + z_3)^3 =$$

$$({z_1}^3 + {z_2}^3 + {z_3}^3) + 3({z_1}^2 z_2 + {z_2}^2 z_3 + {z_3}^2 z_1 + {z_1}^2 z_3 + {z_2}^2 z_1 + {z_3}^2 z_2) + 6z_1 z_2 z_3$$

$$(z_1^2 + z_2^2 + z_3^2)(z_1 + z_2 + z_3) = (z_1^3 + z_2^3 + z_3^3) + (z_1^2 z_2 + z_2^2 z_3 + z_3^2 z_1 + z_1^2 z_3 + z_2^2 z_1 + z_3^2 z_2)$$

So 
$$S_3 - S_1 S_2 + \frac{S_1^2 - S_2}{2} S_1 + 3c = 0$$
 M1

Thus 
$$6c = (3S_1S_2 - S_1^3 - 2S_3)$$
 A1\* (6)

(iii) Let 
$$z_k = r_k(\cos \theta_k + i \sin \theta_k)$$
 for  $k = 1, 2, 3$ 

Then  $z_k^2 = r_k^2(\cos 2\theta_k + i \sin 2\theta_k)$  and  $z_k^3 = r_k^3(\cos 3\theta_k + i \sin 3\theta_k)$  by de Moivre M1

$$\sum_{k=1}^{3} r_k \sin \theta_k = 0$$

$$\sum_{k=1}^{3} r_k^2 \sin 2\theta_k = 0$$

$$\sum_{k=1}^{3} r_k^3 \sin 3\theta_k = 0$$

$$Im\left(\sum_{k=1}^{3} z_k\right) = 0$$

$$Im\left(\sum_{k=1}^{3} z_k^2\right) = 0$$

$$Im\left(\sum_{k=1}^{3} z_k^3\right) = 0$$

and so  $S_1$  ,  $S_2$  , and  $S_3$  are real ,

**M1** 

and therefore so are a , b , and c

**A1** 

Hence, as  $z_1$ ,  $z_2$ , and  $z_3$  are the roots of  $z^3+az^2+bz+c=0$  with a, b, and c real, by part (i), at least one of  $z_1$ ,  $z_2$ , and  $z_3$  is real.

So for at least one value of k ,  $r_k(\cos\theta_k+i\sin\theta_k)$  is real and thus,  $\sin\theta_k=0$  ,

and as  $-\pi < \theta_k < \pi$  ,  $\theta_k = 0$  as required. A1 (6)

If  $\theta_1=0$  then  $z_1$  is real.  $z_2$  and  $z_3$  are the roots of  $(z-z_2)(z-z_3)=0$ 

which is  $z^2 + (-z_2 - z_3)z + z_2z_3 = 0$  (say  $z^2 + pz + q = 0$ )

 $p=-z_2-z_3=a+z_1$  and  $q=z_2z_3=-rac{c}{z_1}$  and so the quadratic of which  $z_2$  and  $z_3$  are the roots has real coefficients. Thus  $z_2$ ,  $z_3=rac{-p\pm\sqrt{p^2-4q}}{2}$ . (  $z_1\neq 0$  because  $r_k>0$ )

If 
$$p^2 - 4q < 0$$
, M1

Thus  $\cos \theta_2 = \cos \theta_3$ , and so  $\theta_2 = \pm \theta_3$ , as  $-\pi < \theta_k < \pi$ .

But 
$$\sin \theta_2 = -\sin \theta_3$$
 and so  $\theta_2 = -\theta_3$ .

If  $p^2-4q\geq 0$ , then  $z_2$  and  $z_3$  are real roots, so  $\sin\theta_2=\sin\theta_3=0$ , and thus  $\theta_2=\theta_3=0$ , so  $\theta_2=-\theta_3$ .

5. (i) Having assumed that  $\sqrt{2}$  is rational (step 1),  $\sqrt{2} = p/q$ , where  $p, q \in \mathbb{Z}, q \neq 0$  B1

Thus from the definition of S (step 2), as  $q \in \mathbb{Z}$  and  $\sqrt{2} = q \times p/q = p \in \mathbb{Z}$ , so  $q \in S$  proving step 3. B1 (2)

If  $k \in S$ , then k is an integer and  $k\sqrt{2}$  is an integer.

So 
$$(\sqrt{2}-1)k = k\sqrt{2}-k$$
 is an integer,

and  $(\sqrt{2}-1)k\sqrt{2}=2k-k\sqrt{2}$  which is an integer and so  $(\sqrt{2}-1)k\in S$  proving step 5. **B1 (3)** 

 $1 < \sqrt{2} < 2$  and so **M1** 

$$0 < \sqrt{2} - 1 < 1$$
, and thus  $0 < (\sqrt{2} - 1)k < k$ 

and thus this contradicts step 4 that k is the smallest positive integer in S as  $(\sqrt{2}-1)k$  has been shown to be a smaller positive integer and is in S.

(ii) If 
$$2^{2/3}$$
 is rational, then  $2^{2/3} = p/q$  , where  $p, q \in \mathbb{Z}, q \neq 0$ 

So 
$$\left(2^{2/3}\right)^2 = {p \choose q}^2$$
 , that is  $2^{4/3} = {p^2 \choose q^2}$  , which can be written  $2 \times 2^{1/3} = {p^2 \choose q^2}$  M1

and hence  $2^{1/3} = p^2/2q^2$  proving that  $2^{1/3}$  is rational. A1

If  $2^{1/3}$  is rational, then  $2^{1/3} = p/q$  , where  $p, q \in \mathbb{Z}, q \neq 0$ 

and so  $2^{2/_3} = p^2/_{q^2}$  proving that  $2^{2/_3}$  is rational and that  $2^{1/_3}$  is rational only if  $2^{2/_3}$  is rational. A1 (4)

Assume that  $2^{1/3}$  is rational.

Define the set T to be the set of positive integers with the following property: n is in T if and only if  $n2^{1/3}$  and  $n2^{2/3}$  are integers.

The set T contains at least one positive integer as if  $2^{1/_3}=p/_q$  , where  $p,q\in\mathbb{Z}$ ,  $q\neq 0$  , then  $q^22^{1/_3}=q^2\times p/_q=pq\in\mathbb{Z}$  and  $q^22^{2/_3}=q^2\times p^2/_{q^2}=p^2\in\mathbb{Z}$  , so  $q^2\in T$  . M1A1

Define t to be the smallest positive integer in T. Then  $t2^{1/3}$  and  $t2^{2/3}$  are integers. **B1** 

Consider  $t\left(2^{2/3}-1\right)$ .  $t\left(2^{2/3}-1\right)=t2^{2/3}-t$  which is the difference of two integers and so is itself an integer.  $t\left(2^{2/3}-1\right)\times 2^{1/3}=2t-t2^{1/3}$  which is an integer,

and  $t(2^{2/3}-1)\times 2^{2/3}=2^{4/3}t-t2^{2/3}=2\times 2^{1/3}t-t2^{2/3}$  which is an integer.

Thus  $t(2^{2/3}-1)$  is in T. M1A1

 $1 < 2^{2/_3} < 2$  and so  $0 < 2^{2/_3} - 1 < 1$ , and thus  $0 < t\left(2^{2/_3} - 1\right) < t$ , and thus this contradicts that t is the smallest positive integer in T as  $t\left(2^{2/_3} - 1\right)$  has been shown to be a smaller positive integer and is in T.

6. (i) 
$$w, z \in \mathbb{R} \implies u, v \in \mathbb{R}$$

**B1** 

For  $w, z \in \mathbb{R}$ , we require to solve w + z = u,  $w^2 + z^2 = v$  M1

$$w^{2} + (u - w)^{2} = v$$

$$2w^{2} - 2uw + (u^{2} - v) = 0$$

$$w = \frac{2u \pm \sqrt{4u^{2} - 8u^{2} + 8v}}{4} = \frac{u \pm \sqrt{2v - u^{2}}}{2}$$

$$z = \frac{u \mp \sqrt{2v - u^{2}}}{2}$$

#### **M1A1**

So for ,  $z \in \mathbb{R}$  , as u = w + z must be real,  $v = w^2 + z^2$  must be real, and  $2v - u^2 \ge 0$ 

i.e. 
$$u^2 \le 2v$$
 B1\* (5)

(ii) 
$$u = w + z \implies u^2 = w^2 + z^2 + 2wz$$
 so if  $w^2 + z^2 - u^2 = -\frac{2}{3}$ , then  $-2wz = -\frac{2}{3}$ 

so 
$$3wz = 1$$

**M1A1** 

$$w^3 + z^3 = (w + z)(w^2 + z^2 - wz) = u(u^2 - 3wz) = u(u^2 - 1)$$

**M1A1** 

Thus if 
$$w^3 + z^3 - \lambda u = -\lambda$$
,  $u(u^2 - 1) = \lambda(u - 1)$ 

**M1A1** 

Thus 
$$(u-1)(u(u+1) - \lambda) = 0$$
,

**M1** 

$$(u-1)(u^2+u-\lambda)=0$$

**M1A1** 

Thus 
$$u=1$$
 or  $u=\frac{-1\pm\sqrt{1+4\lambda}}{2}$ 

So as  $\lambda \in \mathbb{R}$  and  $\lambda > 0$ , the values of u are real. **B1** 

There are three distinct values of u unless  $\frac{-1\pm\sqrt{1+4\lambda}}{2}=1$  in which case  $\pm\sqrt{1+4\lambda}=3$ , i.e.  $\lambda=2$ 

#### M1A1 (12)

For  $w,z\in\mathbb{R}$  , from (i) we require  $u\in\mathbb{R}$  which it is,  $u^2-\frac{2}{3}\in\mathbb{R}$  which it is, and  $u^2\leq 2\left(u^2-\frac{2}{3}\right)$  in other words  $u^2\geq\frac{4}{3}$ .

So w and z need not be real. A counterexample would be u=1

for then w+z=1,  $w^2+z^2=\frac{1}{3}$ , so  $w^2+(1-w)^2=\frac{1}{3}$ , i.e.  $2w^2-2w+\frac{2}{3}=0$  in which case the discriminant is  $-\frac{4}{3}<0$  so  $w\notin\mathbb{R}$ .

7. 
$$D^2 x^a = D(D(x^a)) = D\left(x \frac{d}{dx}(x^a)\right) = D(xax^{a-1})$$
 M1

$$= D(ax^a) = x \frac{d}{dx}(ax^a) = xa^2x^{a-1} = a^2x^a$$
 M1A1 (3)

(i) Suppose  $D^k P(x)$  is a polynomial of degree r i.e.  $D^k P(x) = a_r x^r + a_{r-1} x^{r-1} + \dots + a_0$  for some integer k .

Then 
$$D^{k+1}P(x) = D(a_rx^r + a_{r-1}x^{r-1} + \dots + a_0) = x\frac{d}{dx}(a_rx^r + a_{r-1}x^{r-1} + \dots + a_0)$$

$$= x(ra_rx^{r-1} + (r-1)a_{r-1}x^{r-2} + \dots + a_1) = ra_rx^r + (r-1)a_{r-1}x^{r-1} + \dots + a_1x$$

which is a polynomial of degree r.

M1A1

Suppose  $P(x) = b_r x^r + b_{r-1} x^{r-1} + \dots + b_0$  , then

$$DP(x) = x \frac{d}{dx} (b_r x^r + b_{r-1} x^{r-1} + \dots + b_0) = r b_r x^r + (r-1) b_{r-1} x^{r-1} + \dots + b_1 x$$
 so the result is true for  $n=1$  , M1A1

and we have shown that if it is true for n=k, it is true for n=k+1. Hence by induction, it is true for any positive integer . B1 (6)

(ii) Suppose  $D^k(1-x)^m$  is divisible by  $(1-x)^{m-k}$  i.e.  $D^k(1-x)^m=f(x)(1-x)^{m-k}$  for some integer k, with k < m-1.

Then 
$$D^{k+1}(1-x)^m = D(f(x)(1-x)^{m-k}) = x \frac{d}{dx}(f(x)(1-x)^{m-k})$$

$$= x \left( f'^{(x)} (1-x)^{m-k} - (m-k) f(x) (1-x)^{m-k-1} \right)$$

$$=x(1-x)^{m-k-1}\left(f'^{(x)}(1-x)-(m-k)f(x)\right)$$
 which is divisible by  $(1-x)^{m-(k+1)}$ . M1A1

$$D(1-x)^m = x \frac{d}{dx}((1-x)^m) = -mx(1-x)^{m-1}$$
 so result is true for  $n = 1$ . M1A1

We have shown that if it is true for n=k , it is true for n=k+1 . Hence by induction, it is true for any positive integer < m . B1 (6)

(iii)

$$(1-x)^m = \sum_{r=0}^m {m \choose r} (-x)^r = \sum_{r=0}^m (-1)^r {m \choose r} x^r$$
 M3

So

$$D^{n}(1-x)^{m} = \sum_{r=0}^{m} (-1)^{r} {m \choose r} D^{n} x^{r} = \sum_{r=0}^{m} (-1)^{r} {m \choose r} r^{n} x^{r}$$
 M1A1

But by (ii),  $D^n(1-x)^m$  is divisible by  $(1-x)^{m-n}$  and so  $D^n(1-x)^m=g(x)(1-x)^{m-n}$ , and thus if x=1,  $D^n(1-x)^m=0$ , and hence

$$\sum_{r=0}^{m} (-1)^r {m \choose r} r^n = 0$$
 M1A1\* (5)

8. (i) 
$$x = r \cos \theta \implies \frac{dx}{d\theta} = -r \sin \theta + \frac{dr}{d\theta} \cos \theta$$
 M1A1

and 
$$y = r \sin \theta \implies \frac{dy}{d\theta} = r \cos \theta + \frac{dr}{d\theta} \sin \theta$$
 M1A1

Thus 
$$(y+x)\frac{dy}{dx} = y-x$$
 becomes  $(r\sin\theta + r\cos\theta)\frac{r\cos\theta + \frac{dr}{d\theta}\sin\theta}{-r\sin\theta + \frac{dr}{d\theta}\cos\theta} = r\sin\theta - r\cos\theta$  M1

That is 
$$(\sin \theta + \cos \theta) \left( r \cos \theta + \frac{dr}{d\theta} \sin \theta \right) = (\sin \theta - \cos \theta) \left( -r \sin \theta + \frac{dr}{d\theta} \cos \theta \right)$$

as 
$$r > 0$$
,  $r \neq 0$ 

Multiplying out and collecting like terms gives

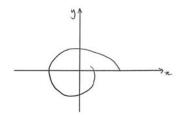
$$r(\cos^2\theta + \sin^2\theta) + \frac{dr}{d\theta}(\sin^2\theta + \cos^2\theta) = 0$$

which is 
$$r + \frac{dr}{d\theta} = 0$$
 . M1A1\* (7)

So 
$$re^{\theta} + \frac{dr}{d\theta}e^{\theta} = 0$$
 M1

and thus 
$$re^{\, heta} = k$$
 ,

$$r = ke^{-\theta}$$
 A1



#### G1 (4)

(or alternatively  $\int \frac{1}{r} dr = \int -d\theta$  M1 so  $\ln |r| = -\theta + c$  A1 and hence  $r = ke^{-\theta}$  A1)

(ii) 
$$(y+x-x(x^2+y^2))\frac{dy}{dx} = y-x-y(x^2+y^2)$$

becomes 
$$(r\sin\theta + r\cos\theta - r^3\cos\theta)\frac{r\cos\theta + \frac{dr}{d\theta}\sin\theta}{-r\sin\theta + \frac{dr}{d\theta}\cos\theta} = r\sin\theta - r\cos\theta - r^3\sin\theta$$

that is

$$(\sin\theta + \cos\theta - r^2\cos\theta)\left(r\cos\theta + \frac{dr}{d\theta}\sin\theta\right) = (\sin\theta - \cos\theta - r^2\sin\theta)\left(-r\sin\theta + \frac{dr}{d\theta}\cos\theta\right)$$

Multiplying out and collecting like terms gives

$$r(\cos^2\theta + \sin^2\theta - r^2(\cos^2\theta + \sin^2\theta)) + \frac{dr}{d\theta}(\sin^2\theta + \cos^2\theta) = 0 \quad \mathbf{M1}$$

which is 
$$r - r^3 + \frac{dr}{d\theta} = 0$$
 .

Α1

$$\int \frac{1}{r^3 - r} dr = \int d\theta$$

$$\int \frac{1}{r^3 - r} dr = \int \frac{1}{r(r^2 - 1)} dr = \int \frac{1}{r(r - 1)(r + 1)} dr = \int d\theta$$

So 
$$\int d\theta = \int \frac{1/2}{r-1} + \frac{-1}{r} + \frac{1/2}{r+1} dr$$

Δ1

$$\theta + k = \frac{1}{2} \ln \left| \frac{(r-1)(r+1)}{r^2} \right|$$

**A1** 

So

$$\left|\frac{r^2 - 1}{r^2}\right| = Ce^{2\theta}$$

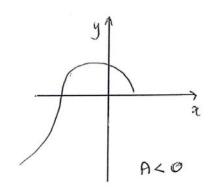
with C>0

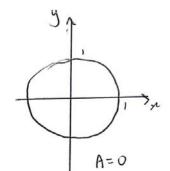
$$r^2 = \frac{1}{1 \mp Ce^{2\theta}}$$

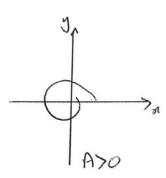
that is

$$r^2 = \frac{1}{1 + Ae^{2\theta}}$$

**A1**\*







G1 G1 G1 (9)

9. If the initial position of P is  $\alpha$ , then at time  $\alpha$ ,  $\alpha$ ,  $\alpha$ , so conserving energy,

$$\frac{1}{2}mv^2 = \frac{1}{2}m\dot{x}^2 + \frac{\lambda}{2a}\left(\sqrt{a^2 + x^2} - a\right)^2$$

M1 A1 A1

Thus,

$$\dot{x}^2 = v^2 - \frac{\lambda}{ma} \left( \sqrt{a^2 + x^2} - a \right)^2$$

**M1** 

i.e.

$$\dot{x}^2 = v^2 - k^2 \left( \sqrt{a^2 + x^2} - a \right)^2$$

A1\* (5)

The greatest value,  $x_0$  , attained by x , occurs when  $\dot{x}=0$ .

Thus 
$$v^2 = k^2 \left( \sqrt{a^2 + x_0^2} - a \right)^2$$

So  $\sqrt{a^2+{x_0}^2}-a=rac{v}{k}$  (negative root discounted as all quantities are positive)

Thus

$$x_0^2 = \left(\frac{v}{k} + a\right)^2 - a^2 = \frac{v^2}{k^2} + \frac{2av}{k}$$

and

$$x_0 = \sqrt{\frac{v^2}{k^2} + \frac{2av}{k}}$$

M1 A1 (3)

As

$$\dot{x}^2 = v^2 - k^2 \left( \sqrt{a^2 + x^2} - a \right)^2$$

differentiating with respect to t

$$2\dot{x}\ddot{x} = -2k^2\left(\sqrt{a^2 + x^2} - a\right)\frac{1}{2}(a^2 + x^2)^{\frac{-1}{2}}2x\dot{x}$$

M1 A1

Thus

$$\ddot{x} = -xk^2 \frac{\left(\sqrt{a^2 + x^2} - a\right)}{\sqrt{a^2 + x^2}}$$

**A1** 

So when  $x = x_0$  , the acceleration of P is

$$-x_0 k^2 \frac{\frac{v}{k}}{\frac{v}{k} + a} = -\sqrt{\frac{v^2}{k^2} + \frac{2av}{k}} k^2 \frac{\frac{v}{k}}{\frac{v}{k} + a} = -\frac{kv\sqrt{v^2 + 2akv}}{v + ak}$$

M1 A1 (5)

$$\dot{x} = \left[v^2 - k^2 \left(\sqrt{a^2 + x^2} - a\right)^2\right]^{\frac{1}{2}}$$

That is

$$\frac{dx}{dt} = \left[v^2 - k^2 \left(\sqrt{a^2 + x^2} - a\right)^2\right]^{\frac{1}{2}}$$

and thus

$$\int_{0}^{\tau/4} dt = \int_{0}^{x_{0}} \frac{1}{\left[v^{2} - k^{2}\left(\sqrt{a^{2} + x^{2}} - a\right)^{2}\right]^{\frac{1}{2}}} dx$$

where  $\tau$  is the period.

M1 A1

So

$$\tau = 4 \int_{0}^{x_0} \frac{1}{\left[v^2 - k^2 \left(\sqrt{a^2 + x^2} - a\right)^2\right]^{\frac{1}{2}}} dx$$

$$\tau = \frac{4}{v} \int_{0}^{\sqrt{\frac{v^{2}}{k^{2}}} + \frac{2av}{k}} \frac{1}{\left[1 - \frac{k^{2}(\sqrt{a^{2} + x^{2}} - a)^{2}}{v^{2}}\right]^{\frac{1}{2}}} dx$$

Let

$$u^2 = \frac{k\left(\sqrt{a^2 + x^2} - a\right)}{v}$$

**B1** 

then

$$a^2 + x^2 = \left(\frac{vu^2}{k} + a\right)^2$$

and so

$$x^2 = \frac{v^2 u^4 + 2kavu^2}{k^2}$$

$$x = \sqrt{2kav} \frac{u}{k} \left( 1 + \frac{v}{2ka} u^2 \right)^{\frac{1}{2}} \approx \sqrt{2kav} \frac{u}{k}$$

as  $v \ll ka$ 

Thus

$$\frac{dx}{du} \approx \frac{1}{k} \sqrt{2kav}$$

**M1A1** 

and so

$$\tau \approx \frac{4}{v} \int_{0}^{1} \frac{1}{\sqrt{1 - u^{4}}} \frac{1}{k} \sqrt{2kav} du = \sqrt{\frac{32a}{kv}} \int_{0}^{1} \frac{1}{\sqrt{1 - u^{4}}} du$$

as required. M1 A1\* (7)

10. The position vector of the upper particle is

$$\begin{pmatrix} x + a \sin \theta \\ y + a \cos \theta \end{pmatrix}$$

**B1 B1** 

so differentiating with respect to time, its velocity is

$$\begin{pmatrix} \dot{x} + a \,\dot{\theta} \cos\theta \\ \dot{y} - a \,\dot{\theta} \sin\theta \end{pmatrix}$$

E1\* (3)

Its acceleration, by differentiating with respect to time, is thus

$$\begin{pmatrix} \ddot{x} + a \ddot{\theta} \cos \theta - a \dot{\theta}^2 \sin \theta \\ \ddot{y} - a \ddot{\theta} \sin \theta - a \dot{\theta}^2 \cos \theta \end{pmatrix}$$

M1 A1 A1

so by Newton's second law resolving horizontally and vertically

$$\begin{pmatrix} -T\sin\theta \\ -T\cos\theta - mg \end{pmatrix} = m \begin{pmatrix} \ddot{x} + a\,\ddot{\theta}\cos\theta - a\dot{\theta}^{2}\sin\theta \\ \ddot{y} - a\,\ddot{\theta}\sin\theta - a\dot{\theta}^{2}\cos\theta \end{pmatrix}$$

M1 A1

That is

$$m\begin{pmatrix} \ddot{x} + a \ddot{\theta} \cos \theta - a \dot{\theta}^2 \sin \theta \\ \ddot{y} - a \ddot{\theta} \sin \theta - a \dot{\theta}^2 \cos \theta \end{pmatrix} = -T \begin{pmatrix} \sin \theta \\ \cos \theta \end{pmatrix} - mg \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

The other particle's equation is

$$m\begin{pmatrix} \ddot{x} - a \ddot{\theta} \cos \theta + a \dot{\theta}^2 \sin \theta \\ \ddot{y} + a \ddot{\theta} \sin \theta + a \dot{\theta}^2 \cos \theta \end{pmatrix} = T\begin{pmatrix} \sin \theta \\ \cos \theta \end{pmatrix} - mg\begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

**B1 (6)** 

Adding these two equations we find

$$2m\begin{pmatrix}\ddot{x}\\\ddot{y}\end{pmatrix} = -2mg\begin{pmatrix}0\\1\end{pmatrix}$$

i.e.  $\ddot{x}=0$  and  $\ddot{y}=-g$ 

M1 A1\*

Thus

$$m \begin{pmatrix} -a \ddot{\theta} \cos \theta + a\dot{\theta}^2 \sin \theta \\ a \ddot{\theta} \sin \theta + a\dot{\theta}^2 \cos \theta \end{pmatrix} = T \begin{pmatrix} \sin \theta \\ \cos \theta \end{pmatrix}$$

i.e.  $m(-a\ddot{\theta}\cos\theta + a\dot{\theta}^2\sin\theta) = T\sin\theta$  and  $m(a\ddot{\theta}\sin\theta + a\dot{\theta}^2\cos\theta) = T\cos\theta$ 

Multiplying the second of these by  $\sin\theta$  and the first by  $\cos\theta$  and subtracting,

$$ma\ddot{\theta} = 0$$
 and so  $\ddot{\theta} = 0$ . M1A1\* (4)

Thus  $\dot{\theta}=a\ constant$  and as initially  $2a\dot{\theta}=u$  ,  $\dot{\theta}=\frac{u}{2a}$ 

Therefore the time to rotate by  $\frac{1}{2}\pi$  is given by  $\tau\dot{\theta}=\frac{1}{2}\pi$  , so  $\tau=\frac{1}{2}\pi\div\frac{u}{2a}=\frac{\pi a}{u}$ 

As  $\ddot{y}=-g$  and initially  $\dot{y}=v$ , at time ,  $\dot{y}=v-gt$ , and so  $y=vt-\frac{1}{2}gt^2+h$  as the centre of the rod is initially h above the table.

Hence, given the condition that the particles hit the table simultaneously,

$$0 = v \pi a/u - 1/2 g(\pi a/u)^2 + h$$

.

Hence 
$$0 = 2\pi uva - \pi^2 a^2 g + 2hu^2$$
, or  $2hu^2 = \pi^2 a^2 g - 2\pi uva$  as required. M1 A1\* (7)

11. (i) Suppose that the force exerted by P on the rod has components X perpendicular to the rod and Y parallel to the rod. Then taking moments for the rod about the hinge, Xd = 0, M1

which as  $d \neq 0$  yields X = 0 and hence the force exerted on the rod by P is parallel to the rod. A1\* (2)

Resolving perpendicular to the rod for P,  $mg \sin \alpha = m(r - d \sin \alpha)\omega^2 \cos \alpha$  M1 A1

Dividing by  $m\omega^2 \sin \alpha$  ,  $\frac{g}{\omega^2} = (r - d \sin \alpha) \cot \alpha$ 

That is  $\alpha = r \cot \alpha - d \cos \alpha$  or in other words  $r \cot \alpha = a + d \cos \alpha$  as required. M1 A1\* (4)

The force exerted by the hinge on the rod is along the rod towards P, **B1** 

and if that force is F, then resolving vertically for P,  $F\cos\alpha=mg$  M1 A1

so 
$$F = mg \sec \alpha$$
.

(ii) Suppose that the force exerted by  $m_1$  on the rod has component  $X_1$  perpendicular to the rod towards the axis, that the force exerted by  $m_2$  on the rod has component  $X_2$  perpendicular to the rod towards the axis,

B1

then resolving perpendicular to the rod for  $m_1$  ,  $m_1g\sin\beta+X_1=m_1(r-d_1\sin\beta)\omega^2\cos\beta$  M1A1

and similarly for  $m_2$  ,  $m_2g\sin\beta+X_2=m_2(r-d_2\sin\beta)\omega^2\cos\beta$ 

### **M1A1**

Taking moments for the rod about the hinge,  $X_1d_1 + X_2d_2 = 0$  M1A1

So multiplying the first equation by  $\,d_1$  , the second by  $\,d_2\,$  and adding we have

 $m_1 g d_1 \sin \beta + m_2 d_2 g \sin \beta = m_1 d_1 (r - d_1 \sin \beta) \omega^2 \cos \beta + m_2 d_2 (r - d_2 \sin \beta) \omega^2 \cos \beta$ 

Dividing by 
$$(m_1 d_1 + m_2 d_2)\omega^2 \sin \beta$$
,  $\frac{g}{\omega^2} = r \cot \beta - \left(\frac{m_1 d_1^2 + m_2 d_2^2}{m_1 d_1 + m_2 d_2}\right) \cos \beta$  M1A1

That is  $r \cot \beta = a + b \cos \beta$ , where  $b = \frac{m_1 d_1^2 + m_2 d_2^2}{m_1 d_1 + m_2 d_2}$  A1 (10)

# 12. (i) The probability distribution function of $\mathcal{S}_{\mathbf{1}}$ is

$S_1$	1	2	3	4	5	6
p	1/6	1/6	1/6	1/6	<sup>1</sup> / <sub>6</sub>	1/6

so the probability distribution function of  $\,R_1$  is

$R_1$	0	1	2	3	4	5
р	1/6	1/6	1/6	1/6	1/6	1/6

and thus  $G(x) = \frac{1}{6}(1+t+t^2+t^3+t^4+t^5)$ .

The probability distribution function of  $\,S_2$  is

$S_2$	2	3	4	5	6	7	8	9	10	11	12
p	1/36	$^{2}/_{36}$	<sup>3</sup> / <sub>36</sub>	4/36	<sup>5</sup> / <sub>36</sub>	<sup>6</sup> / <sub>36</sub>	<sup>5</sup> / <sub>36</sub>	<sup>4</sup> / <sub>36</sub>	<sup>3</sup> / <sub>36</sub>	<sup>2</sup> / <sub>36</sub>	1/36

### **M1**

so the probability distribution function of  $\ensuremath{\mathit{R}}_2$  is

	$R_2$	0	1	2	3	4	5
-	p	6/36	6/36	6/36	6/36	6/36	6/36

### **A1**

which is the same as for  $\,R_1$  and hence its probability generating function is also  $\,G(x)$  . A1\*

Therefore, the probability generating function of  $R_n$  is also G(x)

and thus the probability that  $S_n$  is divisible by 6 is  $\frac{1}{6}$  . B1 (6)

# (ii) The probability distribution function of $T_1$ is

$T_1$	0	1	2	3	4
p	1/6	<sup>2</sup> / <sub>6</sub>	1/6	1/6	1/6

and thus 
$$G_1(x) = \frac{1}{6}(1 + 2x + x^2 + x^3 + x^4)$$
 M1 A1

 $G_2(x)$  would be  $(G_1(x))^2$  except that the powers must be multiplied congruent to modulus 5.

$$G_1(x) = \frac{1}{6}(1 + 2x + x^2 + x^3 + x^4) = \frac{1}{6}(x + 1 + x + x^2 + x^3 + x^4) = \frac{1}{6}(x + y)$$
 B1

Thus  $G_2(x)$  would be  $\frac{1}{36}(x+y)^2$ 

except 
$$xy = x(1 + x + x^2 + x^3 + x^4) = x + x^2 + x^3 + x^4 + 1 = y$$
 M1A1

and 
$$y^2 = (1 + x + x^2 + x^3 + x^4)(1 + x + x^2 + x^3 + x^4) = (1 + x + x^2 + x^3 + x^4) + (x + x^2 + x^3 + x^4 + 1) + (x^2 + x^3 + x^4 + 1 + x) + (x^3 + x^4 + 1 + x + x^2) + (x^4 + 1 + x + x^2 + x^3) = 5y$$

A1

So 
$$G_2(x) = \frac{1}{36}(x+y)^2 = \frac{1}{36}(x^2+2xy+y^2) = \frac{1}{36}(x^2+2y+5y) = \frac{1}{36}(x^2+7y)$$
 M1A1\* (8)

$$G_3(x) = \frac{1}{6^3}(x+y)^3 = \frac{1}{6^3}(x+y)(x^2+7y) = \frac{1}{6^3}(x^3+yx^2+7xy+7y^2)$$

That is

$$G_3(x) = \frac{1}{6^3}(x^3 + yx^2 + 7xy + 7y^2) = \frac{1}{6^3}(x^3 + y + 7y + 35y) = \frac{1}{6^3}(x^3 + 43y)$$

We notice that the coefficient of y inside the bracket in  $G_n(x)$  is  $(1+6+6^2+\cdots 6^{n-1})$ 

This can be shown simply by induction. It is true for n = 1 trivially.

Consider 
$$(x+y)(x^r + (1+6+6^2+\cdots+6^{k-1})y) = x^{r+1} + yx^r + (1+6+6^2+\cdots+6^{k-1})xy + (1+6+6^2+\cdots+6^{k-1})y^2$$

$$yx^{r} + (1+6+6^{2}+\cdots 6^{k-1})xy + (1+6+6^{2}+\cdots +6^{k-1})y^{2}$$
  
=  $y + (1+6+6^{2}+\cdots +6^{k-1})y + 5(1+6+6^{2}+\cdots +6^{k-1})y$ 

$$5(1+6+6^2+\cdots 6^{k-1})=(6-1)(1+6+6^2+\cdots 6^{k-1})=6^k-1$$

So 
$$y + (1 + 6 + 6^2 + \dots + 6^{k-1})y + 5(1 + 6 + 6^2 + \dots + 6^{k-1})y = (1 + 6 + 6^2 + \dots + 6^k)y$$

as required. M1

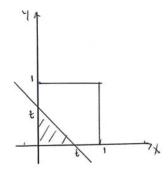
However, this coefficient is the sum of a GP and so  $G_n(x) = \frac{1}{6^n} \left( x^{n-5p} + \frac{6^n-1}{5} y \right)$  where p is an integer such that  $0 \le n-5p \le 4$ .

So if n is not divisible by 5, the probability that  $S_n$  is divisible by 5 will be the coefficient of  $x^0$  which in turn is the coefficient of y, namely  $\frac{1}{6^n} \left( \frac{6^n - 1}{5} \right) = \frac{1}{5} \left( 1 - \frac{1}{6^n} \right)$  as required.

If n is divisible by 5, the probability that  $S_n$  is divisible by 5 will be  $\frac{1}{6^n} \left( 1 + \frac{6^n - 1}{5} \right)$  as  $x^{n-5p} = x^0$ 

That is 
$$\frac{1}{5} \left( 1 + \frac{4}{6^n} \right)$$

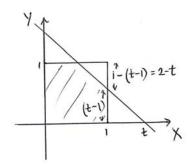
13. (i)



G1

$$P(X + Y < t) = \frac{1}{2}t^2 \text{ if } 0 \le t \le 1$$

**B1** 



**G1** 

and 
$$P(X + Y < t) = 1 - \frac{1}{2}(2 - t)^2$$
 if  $1 < t \le 2$ 

$$P(X + Y < t) = 0 \text{ if } t < 0 \text{ and } P(X + Y < t) = 1 \text{ if } t > 2$$

So 
$$F(t) = \begin{cases} 0 & for \ t < 0 \\ \frac{1}{2}t^2 & for \ 0 \le t \le 1 \\ 1 - \frac{1}{2}(2 - t)^2 & for \ 1 < t \le 2 \\ 1 & for \ t > 2 \end{cases}$$

B1 (5)

Thus 
$$P((X+Y)^{-1} < t) = P(X+Y > \frac{1}{t}) = 1 - P(X+Y < \frac{1}{t})$$

$$= \begin{cases} 1 - \frac{1}{2t^2} & \text{for } 1 \le t \\ \frac{1}{2} \left( 2 - \frac{1}{t} \right)^2 & \text{for } \frac{1}{2} \le t < 1 \\ 0 & \text{for } t < \frac{1}{2} \end{cases}$$

M1 A1

So as 
$$f(t) = \frac{dF(t)}{dt}$$
,

$$f(t) = \begin{cases} 0 & \text{for } t < \frac{1}{2} \\ \frac{1}{t^2} \left( 2 - \frac{1}{t} \right) & \text{for } \frac{1}{2} \le t < 1 \\ \frac{1}{t^3} & \text{for } 1 \le t \end{cases}$$

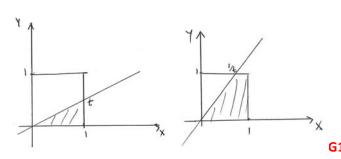
as required.

## M1A1\* (4)

$$E\left(\frac{1}{X+Y}\right) = \int_{\frac{1}{2}}^{1} t(2t^{-2} - t^{-3})dt + \int_{1}^{\infty} t \cdot t^{-3}dt = \left[2\ln t + t^{-1}\right]_{\frac{1}{2}}^{1} + \left[-t^{-1}\right]_{1}^{\infty}$$
$$= 1 - 2\ln\frac{1}{2} - 2 + 1 = 2\ln 2$$

### M1 A1 (2)

(ii)



$$P\left(\frac{Y}{X} < t\right) = \begin{cases} \frac{1}{2}t & for \ 0 \le t \le 1\\ 1 - \frac{1}{2}t^{-1} & for \ t > 1 \end{cases}$$

B1 (2)

Thus

$$P\left(\frac{X}{X+Y} < t\right) = P\left(\frac{X+Y}{X} > \frac{1}{t}\right) = P\left(1 + \frac{Y}{X} > \frac{1}{t}\right) = P\left(\frac{Y}{X} > \frac{1}{t} - 1\right) = 1 - P\left(\frac{Y}{X} < \frac{1}{t} - 1\right)$$

So

$$F(t) = \begin{cases} 1 - \frac{1}{2} \left( \frac{1}{t} - 1 \right) & \text{for } \frac{1}{2} \le t \le 1 \\ \frac{1}{2} \left( \frac{1}{t} - 1 \right)^{-1} & \text{for } 0 \le t < \frac{1}{2} \end{cases}$$

i.e.

$$F(t) = \begin{cases} \frac{1}{2}(3 - t^{-1}) & for \ \frac{1}{2} \le t \le 1\\ \frac{1}{2}(\frac{t}{1 - t}) & for \ 0 \le t < \frac{1}{2} \end{cases}$$

So as 
$$f(t) = \frac{dF(t)}{dt}$$
,

$$f(t) = \begin{cases} \frac{1}{2}t^{-2} & \text{for } \frac{1}{2} \le t \le 1\\ \frac{1}{2}(1-t)^{-2} & \text{for } 0 \le t < \frac{1}{2} \end{cases}$$

M1A1 (4)

$$E\left(\frac{X}{X+Y}\right) = \frac{1}{2}$$
 because, by symmetry,  $E\left(\frac{X}{X+Y}\right) = E\left(\frac{Y}{X+Y}\right)$ 

and 
$$E\left(\frac{X}{X+Y}\right) + E\left(\frac{Y}{X+Y}\right) = E\left(\frac{X+Y}{X+Y}\right) = E(1) = 1$$

$$E\left(\frac{X}{X+Y}\right) = \int_{0}^{\frac{1}{2}} \frac{1}{2}t(1-t)^{-2} dt + \int_{\frac{1}{2}}^{1} t \times \frac{1}{2}t^{-2} dt$$

$$\begin{split} &= \left[\frac{1}{2}t(1-t)^{-1}\right]_0^{\frac{1}{2}} - \int_0^{\frac{1}{2}} \frac{1}{2}(1-t)^{-1}dt + \left[\frac{1}{2}\ln t\right]_{\frac{1}{2}}^1 \\ &= \frac{1}{2} - \left[-\frac{1}{2}\ln(1-t)\right]_0^{\frac{1}{2}} - \frac{1}{2}\ln\frac{1}{2} \\ &= \frac{1}{2} + \frac{1}{2}\ln\frac{1}{2} - \frac{1}{2}\ln\frac{1}{2} = \frac{1}{2} \end{split}$$

as required. M1A1 (3)