STEP MATHEMATICS 3 2021 Mark Scheme

1. (i)
$$x = -4\cos^3 t$$
 so $\frac{dx}{dt} = 12\cos^2 t \sin t$ M1

$$y = 12\sin t - 4\sin^3 t$$
 so $\frac{dy}{dt} = 12\cos t - 12\sin^2 t\cos t = 12\cos t (1 - \sin^2 t) = 12\cos^3 t$

So
$$\frac{dy}{dx} = \frac{12\cos^3 t}{12\cos^2 t \sin t} = \cot t$$

Thus the equation of the normal at $(-4\cos^3\varphi$, $12\sin\varphi-4\sin^3\varphi$) is

$$y - (12\sin\varphi - 4\sin^3\varphi) = -\frac{1}{\cot\varphi}(x - 4\cos^3\varphi)$$

M1 A1ft

This simplifies to $x \sin \varphi + y \cos \varphi = 12 \sin \varphi \cos \varphi - 4 \sin^3 \varphi \cos \varphi - 4 \sin \varphi \cos^3 \varphi$

That is
$$x \sin \varphi + y \cos \varphi = 8 \sin \varphi \cos \varphi$$
 A1 (6)

Alternative simplification $x \tan \varphi + y = 8 \sin \varphi$

For $x = 8\cos^3 t$, $\frac{dx}{dt} = -24\cos^2 t \sin t$ and for $y = 8\sin^3 t$, $\frac{dy}{dt} = 24\sin^2 t \cos t$

So
$$\frac{dy}{dx} = \frac{24\sin^2 t \cos t}{-24\cos^2 t \sin t} = -\tan t$$
 M1 A1ft

Thus the equation of the tangent to $x^{\frac{2}{3}} + y^{\frac{2}{3}} = 4$ at $(8\cos^3\varphi, 8\sin^3\varphi)$ is

$$y - 8 \sin^3 \varphi = -\tan \varphi (x - 8\cos^3 \varphi)$$

M1

This simplifies to

 $x\sin\varphi + y\cos\varphi = 8\sin^3\varphi\cos\varphi + 8\sin\varphi\cos^3\varphi = 8\sin\varphi\cos\varphi \,(\sin^2\varphi + \cos^2\varphi)$

That is $x \sin \varphi + y \cos \varphi = 8 \sin \varphi \cos \varphi$ as required.

A1 (4)

Alternative 1

the normal is a tangent to the second curve if it has the same gradient and the point $(8\cos^3\varphi$, $8\sin^3\varphi$) lies on the normal.

Gradient working as before M1A1ft

Substitution $x \sin \varphi + y \cos \varphi = 8 \sin \varphi \cos^3 \varphi + 8 \sin^3 \varphi \cos \varphi = 8 \sin \varphi \cos \varphi (\sin^2 \varphi + \cos^2 \varphi) = 8 \sin \varphi \cos \varphi$ as required or $x \tan \varphi + y = 8 \sin \varphi \cos \varphi (\sin^2 \varphi + \cos^2 \varphi)$ **A1**

Alternative 2

$$\frac{2}{3}x^{\frac{-1}{3}} + \frac{2}{3}y^{\frac{-1}{3}}\frac{dy}{dx} = 0$$

M1

(ii)
$$x = \cos t + t \sin t$$
 so $\frac{dx}{dt} = -\sin t + t \cos t + \sin t = t \cos t$
 $y = \sin t - t \cos t$ so $\frac{dy}{dt} = \cos t - \cos t + t \sin t = t \sin t$ M1
So $\frac{dy}{dx} = \tan t$ A1

Thus the equation of the normal at $(\cos \varphi + \varphi \sin \varphi, \sin \varphi - \varphi \cos \varphi)$ is

$$y - (\sin \varphi - \varphi \cos \varphi) = -\cot \varphi (x - (\cos \varphi + \varphi \sin \varphi))$$

M1 A1ft

This simplifies to $x \cos \varphi + y \sin \varphi = 1$

A1 (5)

Alternatives which can be followed through to perpendicular distance step, or alternative method #

$$x + y \tan \varphi = \sec \varphi$$
 and $x \cot \varphi + y = \csc \varphi$

The distance of (0,0) from
$$x\cos\varphi + y\sin\varphi = 1$$
 is $\left|\frac{-1}{\sqrt{\cos^2\varphi + \sin^2\varphi}}\right| = 1$

M1 A1ft A1

Alternatively, the perpendicular to $x\cos\varphi+y\sin\varphi=1$ through (0,0) is $y\cos\varphi-x\sin\varphi=0$, and these two lines meet at $(\cos\varphi$, $\sin\varphi$)

M1 A1ft

which is a distance $\sqrt{\cos^2 \varphi + \sin^2 \varphi} = 1$ from (0,0) . A1

So the curve to which this normal is a tangent is a circle centre (0,0), radius 1 which is thus $x^2+y^2=1$ M1 A1 (5)

2. (i)
$$\begin{pmatrix} 1 & -x & x \\ y & 1 & -y \\ -z & z & 1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} a - (b - c)x \\ b - (c - a)y \\ c - (a - b)z \end{pmatrix} = \begin{pmatrix} a - a \\ b - b \\ c - c \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$
 as required. **M1 A1***

As a, b and c are distinct, they cannot all be zero. If M^{-1} exists $\begin{pmatrix} a \\ b \\ c \end{pmatrix} = M^{-1} \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ which is a contradiction.

So,
$$M^{-1}$$
 does not exist and thus $det\begin{pmatrix} 1 & -x & x \\ y & 1 & -y \\ -z & z & 1 \end{pmatrix} = 0$, M1

i.e.
$$1 - xyz + xyz + yz + zx + xy = 0$$
, (Sarus)

or
$$1(1 + yz) - -x(y - yz) + x(yz + z) = 0$$
 (by co-factors) M1

which simplifies to

$$yz + zx + xy = -1$$
 A1 * (5)

$$(x+y+z)^2 \ge 0$$

So
$$x^2 + y^2 + z^2 + 2yz + 2zx + 2xy \ge 0$$
 M1

and so $x^2 + y^2 + z^2 \ge 2$ A1* (2)

(ii)
$$\begin{pmatrix} 2 & -x & -x \\ -y & 2 & -y \\ -z & -z & 2 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 2a - (b+c)x \\ 2b - (c+a)y \\ 2c - (a+b)z \end{pmatrix} = \begin{pmatrix} 2a - 2a \\ 2b - 2b \\ 2c - 2c \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

B1

M1

As a, b and c are positive, they cannot all be zero. Thus as $\begin{pmatrix} 2 & -x & -x \\ -y & 2 & -y \\ -z & -z & 2 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix},$

as in part (i),
$$\det\begin{pmatrix}2&-x&-x\\-y&2&-y\\-z&-z&2\end{pmatrix}=0\;,$$

i.e.
$$8 - xyz - xyz - 2yz - 2zx - 2xy = 0$$
, that is M1 A1

$$xyz + yz + zx + xy = 4$$
 A1* (6)

$$(x+1)(y+1)(z+1) = xyz + zx + xy + x + y + z + 1 = 4 + x + y + z + 1 > 5$$
M1

because as a, b, and c are all positive, so are x, y and z. E1

Thus
$$\left(\frac{2a}{b+c}+1\right)\left(\frac{2b}{c+a}+1\right)\left(\frac{2c}{a+b}+1\right) > 5$$

Multiplying by (b+c)(c+a)(a+b), all three factors of which are positive, gives

$$(2a+b+c)(a+2b+c)(a+b+c) > 5(b+c)(c+a)(a+b)$$
 as required. A1* (4)

$$x = \frac{2a}{b+c} > \frac{2a}{a+b+c}$$
 as a, b, and c are positive, and similarly both, $y > \frac{2b}{a+b+c}$ and $z > \frac{2c}{a+b+c}$

M1

Thus
$$4 + x + y + z + 1 > 4 + \frac{2a}{a+b+c} + \frac{2b}{a+b+c} + \frac{2c}{a+b+c} + 1 = 4 + \frac{2(a+b+c)}{a+b+c} + 1 = 7$$

dM1

and thus following the argument used to obtain the previous result

$$(2a + b + c)(a + 2b + c)(a + b + c) > 7(b + c)(c + a)(a + b)$$
 as required.

A1* (3)

$$\frac{1}{2} (I_{n+1} + I_{n-1}) = \frac{1}{2} \int_{0}^{\beta} (\sec x + \tan x)^{n+1} + (\sec x + \tan x)^{n-1} dx$$
$$= \frac{1}{2} \int_{0}^{\beta} (\sec x + \tan x)^{n-1} ((\sec x + \tan x)^{2} + 1) dx$$

M1

$$= \frac{1}{2} \int_{0}^{\beta} (\sec x + \tan x)^{n-1} (\sec^{2} x + 2 \sec x \tan x + \tan^{2} x + 1) dx$$
$$= \int_{0}^{\beta} (\sec x + \tan x)^{n-1} (\sec^{2} x + \sec x \tan x) dx$$

M1

$$= \left[\frac{1}{n}(\sec x + \tan x)^n\right]_0^\beta = \frac{1}{n}\left((\sec \beta + \tan \beta)^n - 1\right)$$
M1 A1
*A1 (5)

as required.

$$\frac{1}{2} (I_{n+1} + I_{n-1}) - I_n = \frac{1}{2} (I_{n+1} - 2I_n + I_{n-1})$$

$$= \frac{1}{2} \int_{0}^{\beta} (\sec x + \tan x)^{n+1} - 2(\sec x + \tan x)^n + (\sec x + \tan x)^{n-1} dx$$

M1

$$= \frac{1}{2} \int_{0}^{\beta} (\sec x + \tan x)^{n-1} \left((\sec x + \tan x) - 1 \right)^{2} dx$$

M1 A1

$$\left((\sec x + \tan x) - 1\right)^2 > 0 \text{ for all } x > 0$$

 $\sec x \ge 1$ for $0 \le x < \frac{\pi}{2}$ and hence for $0 \le x < \beta$ and similarly $\tan x \ge 0$, and thus also $(\sec x + \tan x)^{n-1} > 0$.

Therefore,
$$\frac{1}{2}\;(I_{n+1}+I_{n-1})-I_n>0$$
 , $\bf A1$

and so
$$I_n < \frac{1}{2} (I_{n+1} + I_{n-1}) = \frac{1}{n} ((\sec \beta + \tan \beta)^n - 1)$$
 as required. M1 *A1 (7)

Alternative 1: it has already been shown that

$$\frac{1}{2} (I_{n+1} + I_{n-1}) = \int_0^\beta (\sec x + \tan x)^{n-1} (\sec^2 x + \sec x \tan x) \, dx$$
$$= \int_0^\beta \sec x (\sec x + \tan x)^n \, dx$$

which is greater than I_n as the expression being integrated is greater than $(\sec x + \tan x)^n$ because $\sec x > 0$ over this domain.

Alternative 2:-

$$I_{n+1} - I_n = \int_0^\beta (\sec x + \tan x)^n (\sec x + \tan x - 1) \, dx$$

$$I_n - I_{n-1} = \int_0^\beta (\sec x + \tan x)^{n-1} (\sec x + \tan x - 1) \, dx$$

M1 A1 A1

For $0 < \mathbf{x} < \beta$, $\sec x > 1$, $\tan x > 0$ so $\sec x + \tan x > 1$ **E1** and thus $I_{n+1} - I_n > I_n - I_{n-1}$ **A1** and so $I_n \le \frac{1}{2} \left(I_{n+1} + I_{n-1} \right) = \frac{1}{n} \left((\sec \beta + \tan \beta)^n - 1 \right)$ **M1 *A1 (7)**

(ii)
$$\frac{1}{2} (J_{n+1} + J_{n-1}) = \frac{1}{2} \int_0^\beta (\sec x \cos \beta + \tan x)^{n+1} + (\sec x \cos \beta + \tan x)^{n-1} dx$$

$$= \frac{1}{2} \int_0^\beta (\sec x \cos \beta + \tan x)^{n-1} ((\sec x \cos \beta + \tan x)^2 + 1) dx$$

M1

$$= \frac{1}{2} \int_{0}^{\beta} (\sec x \cos \beta + \tan x)^{n-1} (\sec^{2} x \cos^{2} \beta + 2 \sec x \cos \beta \tan x + \tan^{2} x + 1) dx$$

$$= \frac{1}{2} \int_{0}^{\beta} (\sec x \cos \beta + \tan x)^{n-1} (\sec^{2} x (1 - \sin^{2} \beta) + 2 \sec x \cos \beta \tan x + \tan^{2} x + 1) dx$$

$$= \int_{0}^{\beta} (\sec x \cos \beta + \tan x)^{n-1} ((\sec^{2} x + \sec x \cos \beta \tan x) - \sec^{2} x \sin^{2} \beta) dx$$

М1

$$\int_{0}^{\beta} (\sec x \cos \beta + \tan x)^{n-1} (\sec^2 x + \sec x \cos \beta \tan x) dx = \left[\frac{1}{n} (\sec x \cos \beta + \tan x)^{n} \right]_{0}^{\beta}$$

$$=\frac{1}{n}((1+\tan\beta)^n-\cos^n\beta)$$

Δ1

$$\int_{0}^{\beta} (\sec x \cos \beta + \tan x)^{n-1} \sec^2 x \sin^2 \beta \, dx > 0$$

by a similar argument to part (i), namely $\sec^2 x \sin^2 \beta > 0$ for any x, and $\sec x \cos \beta + \tan x > 0$ as $\sec x > 0$ and $\tan x \ge 0$ for $0 \le x < \beta < \frac{\pi}{2}$

Hence
$$\frac{1}{2}(J_{n+1}+J_{n-1})<\frac{1}{n}((1+\tan\beta)^n-\cos^n\beta)$$
 A1

But

$$\frac{1}{2} (J_{n+1} + J_{n-1}) - J_n = \frac{1}{2} \int_0^\beta (\sec x \cos \beta + \tan x)^{n-1} ((\sec x \cos \beta + \tan x) - 1)^2 dx > 0$$

M1

as before, and thus $J_n < \frac{1}{2} (J_{n+1} + J_{n-1}) < \frac{1}{n} ((1 + \tan \beta)^n - \cos^n \beta)$ as required. *A1 (8)

4. (i)

 $m{m}.\ m{a} = rac{1}{2}(m{a} + m{b}).\ m{a} = rac{1}{2}(1 + m{a}.\ m{b}) = m\cos\alpha$ where α is the non-reflex angle between $m{a}$ and $m{m}$ $m{m}.\ m{b} = rac{1}{2}(m{a} + m{b}).\ m{b} = rac{1}{2}(1 + m{a}.\ m{b}) = m\cos\beta$ where α is the non-reflex angle between $m{b}$ and $m{m}$

Thus $\cos \alpha = \cos \beta$ and so $\alpha = \beta$ as for $0 \le \tau \le \pi$, there is only one value of τ for any given value of $\cos \tau$. **E1 (3)**

(ii)
$$a_1 \cdot c = (a - (a \cdot c)c) \cdot c = a \cdot c - a \cdot c \cdot c \cdot c = 0$$
 as required. *B1 $a \cdot c = \cos \alpha$, $b \cdot c = \cos \beta$, $a \cdot b = \cos \theta$ $a_1 = a - (a \cdot c)c$ and $b_1 = b - (b \cdot c)c$

M1 A1

$$|a_1|^2 = a_1 \cdot a_1 = (a - (a \cdot c)c) \cdot (a - (a \cdot c)c) = a \cdot a - 2a \cdot c \cdot a \cdot c + a \cdot c \cdot a \cdot c \cdot c \cdot c$$

= $1 - 2\cos^2 \alpha + \cos^2 \alpha = \sin^2 \alpha$

M1

and so. as α is acute, $|a_1| = \sin \alpha$ as required. *A1

$$a_1 \cdot b_1 = (a - (a \cdot c)c) \cdot (b - (b \cdot c)c) = a \cdot b - 2(a \cdot c)(b \cdot c) + (a \cdot c)(b \cdot c)(c \cdot c)$$

= $\cos \theta - \cos \alpha \cos \beta$

M1 A1

but also, $a_1 \cdot b_1 = \sin \alpha \sin \beta \cos \varphi$

B1 M1

and hence,

$$\cos \varphi = \frac{\cos \theta - \cos \alpha \cos \beta}{\sin \alpha \sin \beta}$$

as required.

*A1 (8)

(iii)
$$m_1 = m - (m.c)c = \frac{1}{2}(a+b) - (\frac{1}{2}(a+b).c)c = \frac{1}{2}(a_1+b_1)$$
 B1

 m_1 bisects the angle between $\,a_1\,$ and $\,b_1\,$ if and only if

$$\frac{\boldsymbol{m_1}.\,\boldsymbol{a_1}}{\sin\alpha} = \frac{\boldsymbol{m_1}.\,\boldsymbol{b_1}}{\sin\beta}$$

M₁

Thus, multiplying through by $2 \sin \alpha \sin \beta$,

$$(\boldsymbol{a_1} + \boldsymbol{b_1}).\,\boldsymbol{a_1}\sin\beta = (\boldsymbol{a_1} + \boldsymbol{b_1}).\,\boldsymbol{b_1}\sin\alpha$$

A1

$$(\sin^2 \alpha + \boldsymbol{a_1}.\boldsymbol{b_1})\sin \beta = (\sin^2 \beta + \boldsymbol{a_1}.\boldsymbol{b_1})\sin \alpha$$

So

$$(\boldsymbol{a_1}.\boldsymbol{b_1} - \sin\alpha\sin\beta)(\sin\alpha - \sin\beta) = 0$$

A1

and thus, $\sin\alpha=\sin\beta$ in which case $\alpha=\beta$ as both angles are acute, *A1 or $\cos\theta-\cos\alpha\cos\beta=\sin\alpha\sin\beta$, meaning that $\cos\theta=\cos\alpha\cos\beta+\sin\alpha\sin\beta=\cos(\alpha-\beta)$ M1 *A1 (9)

5. (i) The curves meet when $\alpha + 2\cos\theta = 2 + \cos 2\theta$

That is, $a + 2\cos\theta = 2 + 2\cos^2\theta - 1$ or as required, **B1** $2\cos^2\theta - 2\cos\theta + 1 - a = 0$

The curves touch if this quadratic has coincident roots, M1 i.e. if $4-8(1-a)=0 \Rightarrow a=\frac{1}{2}$, *A1 or if $\cos\theta=\pm1$, M1 in which cases a=1 A1 or a=5. A1 (6)

Alternatively, for the curves to touch, they must have the same gradient, so differentiating,

$$-2\sin\theta = -2\sin 2\theta = -4\sin\theta\cos\theta$$

M1

in which case, either $\sin\theta=0$ giving $\cos\theta=\pm1$, **M1** in which cases a=1 **A1** or a=5 , **A1** or $\cos\theta=\frac{1}{2}$ in which case $a=\frac{1}{2}$. *A1 (6)

(ii) If $a = \frac{1}{2}$ then at points where they touch, $\cos \theta = \frac{1}{2}$ so $\theta = \pm \frac{\pi}{3}$ and thus $(\frac{3}{2}, \pm \frac{\pi}{3})$. M1A1

 $r=a+2\cos\theta$ is symmetrical about the initial line which it intercepts at $\left(\frac{5}{2},0\right)$ and has a cusp at $\left(0,\pm\cos^{-1}\left(-\frac{1}{4}\right)\right)$. It passes through $\left(\frac{1}{2},\pm\frac{\pi}{2}\right)$ and only exists for

$$-\cos^{-1}\left(-\frac{1}{4}\right) < \theta < \cos^{-1}\left(-\frac{1}{4}\right).$$

 $r=2+\cos 2\theta$ is symmetrical about both the initial line, and its perpendicular. It passes through

$$(3,0)$$
 , $(3,\pi)$, and $\left(1,\pm\frac{\pi}{2}\right)$

Sketch G6 (8)

(iii) If a=1, then the curves meet where $2\cos^2\theta-2\cos\theta=0$, i.e. $\cos\theta=1$ at (3,0) where they touch, and $\cos\theta=0$ at $\left(1,\pm\frac{\pi}{2}\right)$

 $r=a+2\cos\theta$ is symmetrical about the initial line which it intercepts at $\left(3\,,0\right.$) and has a cusp at $\left(0\,,\pm\cos^{-1}\left(-\frac{1}{2}\right)\right.$) $=\left(0\,,\pm\frac{2\pi}{3}\right.$). It passes through $\left(1\,,\pm\frac{\pi}{2}\right.$) and only exists for

$$-\frac{2\pi}{3} < \theta < \frac{2\pi}{3}.$$

Sketch G3

If a=5, then the curves meet where $2\cos^2\theta-2\cos\theta-4=0$, i.e. only $\cos\theta=-1$ at $(3,\pi)$ where they touch, as $\cos\theta\neq 2$.

 $r=a+2\cos\theta$ is symmetrical about the initial line which it intercepts at (7,0) and $(3,\pi)$. It also passes through $\left(5,\pm\frac{\pi}{2}\right)$.

Sketch G3 (6)

$$f_{\alpha}(x) = \tan^{-1}\left(\frac{x\tan\alpha + 1}{\tan\alpha - x}\right)$$
$$f'_{\alpha}(x) = \frac{1}{1 + \left(\frac{x\tan\alpha + 1}{\tan\alpha - x}\right)^2} \frac{(\tan\alpha - x)\tan\alpha + (x\tan\alpha + 1)}{(\tan\alpha - x)^2}$$

M1 A1

as required.

Alternative

$$f_{\alpha}(x) = \tan^{-1}\left(\frac{x \tan \alpha + 1}{\tan \alpha - x}\right)$$

$$= \tan^{-1}\left(\frac{x + \cot \alpha}{1 - x \cot \alpha}\right)$$

$$= \tan^{-1}\left(\frac{\tan(\tan^{-1}x) + \tan\left(\frac{\pi}{2} - \alpha\right)}{1 - \tan(\tan^{-1}x) \tan\left(\frac{\pi}{2} - \alpha\right)}\right)$$

$$\mathbf{M1 A1}$$

$$= \tan^{-1}\left(\tan\left(\tan^{-1}x + \frac{\pi}{2} - \alpha\right)\right)$$

M1

= $\tan^{-1} x + \frac{\pi}{2} - \alpha$ if this is less than $\frac{\pi}{2}$, i.e. if $x < \tan \alpha$

or
$$= \tan^{-1} x - \frac{\pi}{2} - \alpha$$
 if $x > \tan \alpha$ M1

So
$$f'_{\alpha}(x) = \frac{d}{dx}(\tan^{-1}x) = \frac{1}{1+x^2}$$
 *A1 (5)

Thus $f_{\alpha}(x) = \tan^{-1} x + c$

$$f_{\alpha}(0) = \tan^{-1}\left(\frac{1}{\tan \alpha}\right) = \tan^{-1}(\cot \alpha) = \frac{\pi}{2} - \alpha$$

 $f_{\alpha}(x) = 0$ when $x = -\cot \alpha$

There is a discontinuity at $x = \tan \alpha$, with $f_{\alpha}(x)$ approaching $\frac{\pi}{2}$ from below and $-\frac{\pi}{2}$ from above.

As
$$x \to \pm \infty$$
, $f_{\alpha}(x) \to \tan^{-1}(-\tan \alpha) = -\alpha$

So $f_{\alpha}(x) = \tan^{-1} x + \frac{\pi}{2} - \alpha$ for $x < \tan \alpha$ and $f_{\alpha}(x) = \tan^{-1} x - \frac{\pi}{2} - \alpha$ for $x > \tan \alpha$ Sketch **G1 G1 G1 (3)**

$$y = f_{\alpha}(x) - f_{\beta}(x) =$$

$$\left(\frac{\pi}{2} - \alpha\right) - \left(\frac{\pi}{2} - \beta\right) = \beta - \alpha \text{ for } x < \tan \alpha$$

$$\left(-\frac{\pi}{2} - \alpha\right) - \left(\frac{\pi}{2} - \beta\right) = \beta - \alpha - \pi$$
 for $\tan \alpha < x < \tan \beta$

and
$$\left(-\frac{\pi}{2} - \alpha\right) - \left(-\frac{\pi}{2} - \beta\right) = \beta - \alpha$$
 for $x > \tan \beta$

Sketch **G1 G1 G1 (3)**

(ii) $g(x) = \tanh^{-1}(\sin x) - \sinh^{-1}(\tan x)$

$$g'(x) = \frac{1}{1 - \sin^2 x} \cos x - \frac{1}{\sqrt{1 + \tan^2 x}} \sec^2 x$$

M1 A1

AI

$$= \frac{\cos x}{\cos^2 x} - \frac{\sec^2 x}{|\sec x|} = \sec x - \frac{\sec^2 x}{-\sec x} = 2\sec x$$

11 *A1 (5)

as required, for $\sec x < 0$, i.e. for $\frac{\pi}{2} < x < \frac{3\pi}{2}$.

(For $\sec x > 0$, g'(x) = 0)

Sketch G1 G1 G1 (4)

$$z = \frac{e^{i\theta} + e^{i\varphi}}{e^{i\theta} - e^{i\varphi}}$$
$$= \frac{\cos\theta + i\sin\theta + \cos\varphi + i\sin\varphi}{\cos\theta + i\sin\theta - \cos\varphi - i\sin\varphi}$$

M1

$$=\frac{2\cos\frac{\theta+\varphi}{2}\cos\frac{\theta-\varphi}{2}+2i\sin\frac{\theta+\varphi}{2}\cos\frac{\theta-\varphi}{2}}{-2\sin\frac{\theta+\varphi}{2}\sin\frac{\theta-\varphi}{2}+2i\cos\frac{\theta+\varphi}{2}\sin\frac{\theta-\varphi}{2}}$$

M1 A1 A1

$$= \frac{2\cos\frac{\theta - \varphi}{2}\left(\cos\frac{\theta + \varphi}{2} + i\sin\frac{\theta + \varphi}{2}\right)}{2\sin\frac{\theta - \varphi}{2}\left(i\cos\frac{\theta + \varphi}{2} - \sin\frac{\theta + \varphi}{2}\right)}$$
$$= -i\cot\frac{\theta - \varphi}{2}$$
$$= i\cot\frac{\varphi - \theta}{2}$$
*A1 (5)

as required.

Alternatively,

$$z = \frac{e^{i\theta} + e^{i\varphi}}{e^{i\theta} - e^{i\varphi}} = \frac{e^{i\left(\frac{\theta - \varphi}{2}\right)} + e^{-i\left(\frac{\theta - \varphi}{2}\right)}}{e^{i\left(\frac{\theta - \varphi}{2}\right)} - e^{-i\left(\frac{\theta - \varphi}{2}\right)}} = \frac{2\cos\frac{\theta - \varphi}{2}}{2i\sin\frac{\theta - \varphi}{2}} = -i\cot\frac{\theta - \varphi}{2} = i\cot\frac{\varphi - \theta}{2}$$

$$\mathbf{M1} \qquad \mathbf{M1} \quad \mathbf{A1} \quad \mathbf{A1} \quad \mathbf{A1}$$

$$|z| = \left|\cot\frac{\theta - \varphi}{2}\right|$$

$$\mathbf{M1} \quad \mathbf{A1} \quad \mathbf{A1}$$

$$|\arg z| = \frac{\pi}{2}$$

[or $\arg z = \frac{\pi}{2} \ or \ \frac{3\pi}{2}$]

M1 A1 (4)

(ii) Let
$$a=e^{i\alpha}$$
 and $b=e^{i\beta}$ M1 then $x=a+b=e^{i\alpha}+e^{i\beta}$ and $AB=b-a=e^{i\beta}-e^{i\alpha}$

$$\arg x - \arg AB = \arg \frac{x}{AB} = \arg \frac{e^{i\alpha} + e^{i\beta}}{e^{i\beta} - e^{i\alpha}}$$

so using (i), $|\arg x - \arg AB| = \frac{\pi}{2}$ A1 and thus OX and AB are perpendicular, since $x = a + b \neq 0$ and $a \neq b$ as A and B are distinct. E1 (3)

Alternative:- 0, a, a + b, b define a rhombus OAXB as |a| = |b| = 1. Diagonals of a rhombus are perpendicular (and bisect one another).

(iii) h = a + b + c so AH = a + b + c - a = b + c and BC = c - b and thus

$$\frac{AH}{BC} = \frac{b+c}{c-b}$$

B1

as $c - b \neq 0$

From (ii),

$$\left| \arg \frac{AH}{BC} \right| = \frac{\pi}{2}$$

so BC is perpendicular to AH E1

unless b + c = 0 E1 in which case h = a E1 (4)

(iv)
$$p = a + b + c$$
 $q = b + c + d$ $r = c + d + a$ $s = d + a + b$

The midpoint of AQ is $\frac{a+q}{2} = \frac{a+b+c+d}{2}$ and so by its symmetry it is also the midpoint of BR, CS, and DP, **B1 E1**

and thus ABCD is transformed to PQRS by a rotation of π radians about midpoint of AQ. E1 B1 (4)

Alternatively, ABCD is transformed to PQRS by an enlargement scale factor -1 , centre of enlargement midpoint of AQ.

8. (i) Suppose $x_k \ge 2 + 4^{k-1}(a-2)$ for some particular integer k (and this is positive as a>2)

E1

Then
$$x_{k+1} = x_k^2 - 2 \ge [2 + 4^{k-1}(a-2)]^2 - 2 = 4 + 4^k(a-2) + 4^{2k-2}(a-2)^2 - 2$$

$$= 2 + 4^k(a-2) + 4^{2k-2}(a-2)^2$$

$$> 2 + 4^k(a-2)$$

M1 A1

which is the required result for k + 1.

For n=1, $2+4^{n-1}(a-2)=2+a-2=a$ so in this case, $x_n=2+4^{n-1}(a-2)$ **B1** and thus by induction $x_n\geq 2+4^{n-1}(a-2)$ for positive integer n. **E1 (5)**

(ii) If $|x_k| \le 2$, then $0 \le |x_k|^2 \le 4$, so $-2 \le |x_k|^2 - 2 \le 2$, that is $-2 \le x_{k+1} \le 2$. M1A1

If $|a| \le 2$, $|x_1| \le 2$ and thus by induction $-2 \le x_n \le 2$, that is $x_n \nrightarrow \infty$ E1

Whether $a=\pm \alpha$, x_2 would equal the same value, namely $~\alpha^2-2$. E1

So to consider $|a| \ge 2$, we only need consider a>2 to discuss the behaviour of all terms after the first. Therefore, from part (i), we know $x_n \ge 2+4^{n-1}(|a|-2)$ for $n\ge 2$, and thus $x_n\to\infty$ as $n\to\infty$; **B1** hence we have shown $x_n\to\infty$ as $n\to\infty$ if and only if $|a|\ge 2$. (5)

(iii)

$$y_k = \frac{Ax_1x_2 \cdots x_k}{x_{k+1}}$$
$$y_{k+1} = \frac{Ax_1x_2 \cdots x_{k+1}}{x_{k+2}} = \frac{x_{k+1}^2}{x_{k+2}} y_k$$

Suppose that

$$y_k = \frac{\sqrt{x_{k+1}^2 - 4}}{x_{k+1}}$$

for some positive integer k, E1 then

$$y_{k+1} = \frac{x_{k+1}^2}{x_{k+2}} \frac{\sqrt{x_{k+1}^2 - 4}}{x_{k+1}} = \frac{x_{k+1}\sqrt{x_{k+1}^2 - 4}}{x_{k+2}}$$

As $x_{k+2} = {x_{k+1}}^2 - 2$, $x_{k+1} = \sqrt{{x_{k+2}} + 2}$, and $\sqrt{{x_{k+1}}^2 - 4} = \sqrt{{x_{k+2}} - 2}$,

and thus,

$$y_{k+1} = \frac{\sqrt{x_{k+2} + 2}\sqrt{x_{k+2} - 2}}{x_{k+2}} = \frac{\sqrt{x_{k+2}^2 - 4}}{x_{k+2}}$$

M1 A1

which is the required result for k + 1.

$$y_1 = \frac{Ax_1}{x_2}$$

and also we wish to have

$$y_1 = \frac{\sqrt{{x_2}^2 - 4}}{x_2}$$

M1

then
$$Ax_1=\sqrt{{x_2}^2-4}$$
 , that is $A^2x_1{}^2=x_2{}^2-4$, and as $x_1=a$, $x_2=x_1{}^2-2=a^2-2$ so
$$A^2a^2=(a^2-2)^2-4=a^4-4a^2$$
 , $A^2=a^2-4$, and thus $a=\sqrt{A^2+4}$, as $a\neq 0$ nor $-\sqrt{A^2+4}$ because $a>2$. **A1 E1**

So as the result is true for y_1 , and we have shown it to be true for y_{k+1} if it is true for y_k , it is true by induction for all positive integer $\,n\,$ that

$$y_n = \frac{\sqrt{x_{n+1}^2 - 4}}{x_{n+1}}$$
E1 (8)

As a>2 from (ii) $x_n\to\infty$ as $n\to\infty$ M1 and thus using result just proved, $y_n\to1$ as $n\to\infty$, i.e. the sequence converges. *A1 (2)

Using the sine rule, from triangle PQR

$$\frac{PR}{\sin \theta} = \frac{PQ}{\sin \left(\frac{2\pi}{3} - \varphi\right)}$$

M1 A1

From triangle PQC

$$\frac{PQ}{\sin\frac{\pi}{3}} = \frac{a - x}{\sin\left(\frac{2\pi}{3} - \theta\right)}$$

A1

From triangle PBR

$$\frac{PR}{\sin\frac{\pi}{3}} = \frac{x}{\sin\varphi}$$

Δ1

Eliminating PR and PQ between these three equations

$$x\sin\frac{\pi}{3}\sin\left(\frac{2\pi}{3}-\varphi\right)\sin\left(\frac{2\pi}{3}-\theta\right) = \sin\varphi\,\sin\theta\,(a-x)\sin\frac{\pi}{3}$$

M1 A1

Hence

$$x\left(\frac{\sqrt{3}}{2}\cos\varphi + \frac{1}{2}\sin\varphi\right)\left(\frac{\sqrt{3}}{2}\cos\theta + \frac{1}{2}\sin\theta\right) = (a - x)\sin\varphi\,\sin\theta$$

giving

$$(\sqrt{3}\cot\varphi + 1)(\sqrt{3}\cot\theta + 1)x = 4(a - x)$$

as required.

M1 *A1 (8)

If the ball has speed $\,v_1$ moving from P to Q, speed $\,v_2$ moving from Q to R, and speed $\,v_3$ moving from R to P,

then CLM at Q parallel to CA gives $v_1\cos\left(\frac{2\pi}{3}-\theta\right)=v_2\cos\frac{\pi}{3}$ and NELI perpendicular to CA gives $ev_1\sin\left(\frac{2\pi}{3}-\theta\right)=v_2\sin\frac{\pi}{3}$, and dividing these gives $e\tan\left(\frac{2\pi}{3}-\theta\right)=\tan\frac{\pi}{3}$

M1 A1

and similarly,

CLM at R parallel to AB gives $v_2\cos\frac{\pi}{3}=v_3\cos\varphi$ and NELI perpendicular to AB gives

$$ev_2\sin{\pi\over 3}=v_3\sin{arphi}$$
 , and dividing these gives $\,e an{\pi\over 3}=\, an{arphi}$. A1

$$e \tan\left(\frac{2\pi}{3} - \theta\right) = \tan\frac{\pi}{3}$$
 yields $e^{\frac{-\sqrt{3}-\tan\theta}{1-\sqrt{3}\tan\theta}} = \sqrt{3}$ M1 which simplifies to

 $e\big(\sqrt{3}+\tan\theta\big)=\sqrt{3}\left(\sqrt{3}\tan\theta-1\right)\text{ , or in turn, }(3-e)\tan\theta=\sqrt{3}(1+e)\text{ and so }\cot\theta=\frac{(3-e)}{\sqrt{3}(1+e)}\text{ A1}$

 $e \tan \frac{\pi}{3} = \tan \varphi$ yields $\cot \varphi = \frac{1}{e\sqrt{3}}$ A1

Substituting these two expressions into the first result of the question,

$$\left(\frac{1}{e} + 1\right) \left(\frac{(3-e)}{(1+e)} + 1\right) x = 4(a-x)$$

M1

This simplifies to

$$x \; \frac{1+e}{e} \frac{4}{1+e} = 4(a-x)$$

that is

$$x = e(a - x)$$

so

$$x = \frac{ae}{1 + e}$$

as required.

To continue the motion at P, then similarly to before, the third impact gives $e \tan \left(\frac{2\pi}{3} - \varphi\right) = \tan \theta$

M1

So

$$\tan \theta = e \frac{-\sqrt{3} - \tan \varphi}{1 - \sqrt{3} \tan \varphi} = e \frac{\sqrt{3}(e+1)}{3e-1}$$

and thus, using the previously found result for $\cot \theta$

$$\frac{(3-e)}{\sqrt{3}(1+e)} = \frac{3e-1}{\sqrt{3}(e+1)e}$$

M1 A1

That is e(3-e) = 3e-1, that is $e^2 = 1$ and as $e \ge 0$, e = 1 (and not -1) *B1 (4)

10. (i) At time t, the point where the string is tangential to the cylinder, M1 say T is at $(a\cos\theta, a\sin\theta)$, A1 the piece of string that remains straight is of length $b-a\theta$, M1, the vector representing the string is thus $(b-a\theta)\begin{pmatrix} -\sin\theta\\\cos\theta \end{pmatrix}$ dM1 A1 so the particle is at the point $(a\cos\theta-(b-a\theta)\sin\theta$, $a\sin\theta+(b-a\theta)\cos\theta$). M1 A1 (7)

$$\dot{x} = -a\dot{\theta}\sin\theta - (b - a\theta)\dot{\theta}\cos\theta + a\dot{\theta}\sin\theta = -(b - a\theta)\dot{\theta}\cos\theta$$
$$\dot{y} = a\dot{\theta}\cos\theta - (b - a\theta)\dot{\theta}\sin\theta - a\dot{\theta}\cos\theta = -(b - a\theta)\dot{\theta}\sin\theta$$

M1 A1

Thus the speed is $\sqrt{\left((b-a\theta)\dot{\theta}\cos\theta\right)^2+\left((b-a\theta)\dot{\theta}\sin\theta\right)^2}=(b-a\theta)\dot{\theta}$ as required. M1 A1 (4)

(ii) The only horizontal force on the particle is the tension in the string, which is perpendicular to the velocity at any time, so kinetic energy is conserved. **E1** Therefore,

$$\frac{1}{2}m\left((b-a\theta)\dot{\theta}\right)^2 = \frac{1}{2}mu^2$$

M1

and so, as $(b - a\theta)\dot{\theta}$ and u are both positive $(b - a\theta)\dot{\theta} = u$ *A1 (3)

(iii) The tension in the string, using instantaneous circular motion, at time t is

$$\frac{mu^2}{(b-a\theta)}$$

M1 A1

As $(b - a\theta)\dot{\theta} = u$, integrating with respect to t,

$$b\theta - \frac{a\theta^2}{2} = ut + c$$

M1

but when t=0 , $\theta=0$ so c=0 . M1 A1

Thus,
$$b\theta - \frac{a\theta^2}{2} = ut$$

i.e.

$$\theta^2 - \frac{2b\theta}{a} + \frac{b^2}{a^2} = \frac{b^2}{a^2} - \frac{2ut}{a} = \frac{b^2 - 2aut}{a^2}$$

Alternatively, integrating $(b - a\theta)\dot{\theta} = u$ with respect to t,

$$-\frac{(b-a\theta)^2}{2a} = ut + k$$

M1

When
$$t=0$$
 , $\theta=0$ so $k=-rac{b^2}{2a}$ M1 A1

$$\frac{(b-a\theta)^2}{2a} = \frac{b^2}{2a} - ut = \frac{b^2 - 2aut}{2a}$$

Thus, taking positive roots,

$$\frac{b-a\theta}{a} = \frac{\sqrt{b^2 - 2aut}}{a}$$

Hence, the tension is

$$\frac{mu^2}{\sqrt{b^2-2aut}}$$

*A1 (6)

$$P(Y = n) = P(n \le X < n + 1) = \int_{n}^{n+1} \lambda e^{-\lambda x} dx = \left[-e^{-\lambda x} \right]_{n}^{n+1} = -e^{-\lambda(n+1)} + e^{-\lambda n}$$

M1

M1

$$= (1 - e^{-\lambda})e^{-\lambda n}$$

as required.

*A1 (3

(ii)

$$P(Z < z) = \sum_{r=0}^{\infty} P(r \le X < r + z) = \sum_{r=0}^{\infty} \int_{r}^{r+z} \lambda e^{-\lambda x} dx = \sum_{r=0}^{\infty} \left[-e^{-\lambda x} \right]_{r}^{r+z}$$
M1
M1

$$= \sum_{r=0}^{\infty} \left(-e^{-\lambda(r+x)} + e^{-\lambda r} \right) = \sum_{r=0}^{\infty} \left(1 - e^{-\lambda z} \right) e^{-\lambda r}$$

M1 A1

$$= (1 - e^{-\lambda z}) \frac{1}{1 - e^{-\lambda}} = \frac{1 - e^{-\lambda z}}{1 - e^{-\lambda}}$$

using sum of an infinite GP with magnitude of common ratio less than one.

M1 *A1 (6)

(iii) As
$$P(Z < z) = \frac{1 - e^{-\lambda z}}{1 - e^{-\lambda}}$$
, $f_Z(z) = \frac{d}{dz} \left(\frac{1 - e^{-\lambda z}}{1 - e^{-\lambda}}\right) = \frac{\lambda e^{-\lambda z}}{1 - e^{-\lambda}}$ M1

SO

$$E(Z) = \int_{0}^{1} z \frac{\lambda e^{-\lambda z}}{1 - e^{-\lambda}} dz = \frac{1}{1 - e^{-\lambda}} \left\{ \left[-z e^{-\lambda z} \right]_{0}^{1} + \int_{0}^{1} e^{-\lambda z} dz \right\}$$

M1

M1

$$= \frac{1}{1 - e^{-\lambda}} \left\{ -e^{-\lambda} - \left[\frac{e^{-\lambda z}}{\lambda} \right]_0^1 \right\} = \frac{1}{1 - e^{-\lambda}} \left\{ -e^{-\lambda} - \frac{e^{-\lambda}}{\lambda} + \frac{1}{\lambda} \right\}$$

A1

$$=\frac{1}{\lambda}-\frac{e^{-\lambda}}{1-e^{-\lambda}}$$

or alternatively

$$\frac{1}{\lambda} \frac{\left(1 - (\lambda + 1)e^{-\lambda}\right)}{1 - e^{-\lambda}}$$

(iv)
$$P(Y = n \text{ and } z_1 < Z < z_2) = P(n + z_1 < X < n + z_2)$$

$$= \int_{n+z_1}^{n+z_2} \lambda \ e^{-\lambda x} \ dx = \left[-e^{-\lambda x} \right]_{n+z_1}^{n+z_2} = -e^{-\lambda(n+z_2)} + \ e^{-\lambda(n+z_1)} = e^{-\lambda n} \left(e^{-\lambda z_1} - e^{-\lambda z_2} \right)$$

$$\mathbf{M1}$$

$$P(Y = n \text{ and } z_1 < Z < z_2) = e^{-\lambda n} \left(e^{-\lambda z_1} - e^{-\lambda z_2} \right)$$

$$= \left(1 - e^{-\lambda} \right) e^{-\lambda n} \left(\frac{1 - e^{-\lambda z_2}}{1 - e^{-\lambda}} - \frac{1 - e^{-\lambda z_1}}{1 - e^{-\lambda}} \right)$$

$$\mathbf{M1} \mathbf{A1}$$

$$= P(Y = n) \times P(z_1 < Z < z_2) \quad \mathbf{M1}$$

so Y and Z are independent. E1 (6)

12. (i)

$$P(X_{12} = 1) = \frac{1}{6}$$
, $P(X_{12} = 0) = \frac{5}{6}$, $P(X_{23} = 1) = \frac{1}{6}$, $P(X_{23} = 0) = \frac{5}{6}$

If $X_{23}=1$, then players 2 and 3 score the same as one another. In that case, $X_{12}=1$ would mean that player 1 also obtained that same score so $P(X_{12}=1|X_{23}=1)=\frac{1}{6}=P(X_{12}=1)$.

If $X_{23} = 1$, $X_{12} = 0$ would mean that player 1 obtained a different score so

$$P(X_{12} = 0 | X_{23} = 1) = \frac{5}{6} = P(X_{12} = 0)$$

If $X_{23}=0$, then players 2 and 3 score differently to one another. In that case, $X_{12}=1$ would mean that player 1 also obtained the same score as player 2 so $P(X_{12}=1|X_{23}=0)=\frac{1}{6}=P(X_{12}=1)$

If $\mathit{X}_{23} = 0$, $\mathit{X}_{12} = 0$ would mean that player 1 obtained a different score to player 2 so

$$P(X_{12} = 0 | X_{23} = 0) = \frac{5}{6} = P(X_{12} = 0)$$

Hence X_{12} is independent of X_{23} . M1 A1 (2)

Alternatively,

 X_{12} X_{23}

1 requires players 2 and 3 to both score same as player 1 so

$$P(X_{12} = 1 \text{ and } X_{23} = 1) = \frac{1}{36} = \frac{1}{6} \times \frac{1}{6} = P(X_{12} = 1) \times P(X_{23} = 1)$$

1 0 requires player 2 to score the same as player as player 1, and player 3 score differently so

$$P(X_{12} = 1 \text{ and } X_{23} = 0) = \frac{5}{36} = \frac{1}{6} \times \frac{5}{6} = P(X_{12} = 1) \times P(X_{23} = 0)$$

0 1 requires players 2 and 3 to score the same as one another, and player 1 score differently so

$$P(X_{12} = 0 \text{ and } X_{23} = 1) = \frac{5}{36} = \frac{5}{6} \times \frac{1}{6} = P(X_{12} = 0) \times P(X_{23} = 1)$$

0 0 requires both player 1 and 3 to score differently to player 2 so

$$P(X_{12} = 0 \text{ and } X_{23} = 0) = \frac{25}{36} = \frac{5}{6} \times \frac{5}{6} = P(X_{12} = 0) \times P(X_{23} = 0)$$

Hence X_{12} is independent of X_{23} . M1 A1 (2)

If total score is T , then

$$T = \sum_{i < j} X_{ij}$$

$$E(T) = E\left(\sum_{i < j} X_{ij}\right) = \sum_{i < j} E(X_{ij}) = {}^{n}C_{2} E(X_{12}) = {}^{n}C_{2} \left(1 \times \frac{1}{6} + 0 \times \frac{5}{6}\right) = \frac{n(n-1)}{12}$$

11 A

$$Var(T) = Var\left(\sum_{i < j} X_{ij}\right) = \sum_{i < j} Var(X_{ij}) = {}^{n}C_{2} Var(X_{12}) = {}^{n}C_{2} \left(1^{2} \times \frac{1}{6} + 0^{2} \times \frac{5}{6} - \frac{1}{6}^{2}\right)$$

M1

$$=\frac{5n(n-1)}{72}$$

A1 (5)

(ii)
$$Var(Y_1 + Y_2 + \dots + Y_m) = E((Y_1 + Y_2 + \dots + Y_m)^2) - [E(Y_1 + Y_2 + \dots + Y_m)]^2$$

$$= E(Y_1^2 + Y_2^2 + \dots + Y_m^2 + 2Y_1Y_2 + 2Y_1Y_3 + \dots + 2Y_{n-1}Y_n) - [E(Y_1) + E(Y_2) + \dots + E(Y_m)]^2$$

$$= E\left(\sum_{i=1}^m Y_i^2\right) + 2E\left(\sum_{i=1}^{m-1} \sum_{j=i+1}^m Y_iY_j\right) - (0 + 0 + \dots + 0)^2$$

$$= \sum_{i=1}^m E(Y_i^2) + 2\sum_{i=1}^{m-1} \sum_{j=i+1}^m E(Y_iY_j)$$

M1 *A1 (2)

(iii)

$$P(Z_{12} = 1) = \frac{1}{2} \times \frac{1}{6} = \frac{1}{12}$$

If $Z_{23}=1$ then player 2 has rolled an even score and player 3 has scored the same so, in this case, for $Z_{12}=1$, require player 1 to roll the score that player has so $P(Z_{12}=1|Z_{23}=1)=\frac{1}{6}$.

Therefore, $P(Z_{12}=1) \neq P(Z_{12}=1|Z_{23}=1)$ and thus Z_{12} and Z_{23} are not independent.

Alternatively,

$$P(Z_{12} = 1) = \frac{1}{12}$$
, $P(Z_{23} = 1) = \frac{1}{12}$

For $Z_{12}=1$ and $Z_{23}=1$ we require all three players to score the same even number so

$$P(Z_{12} = 1 \text{ and } Z_{23} = 1) = \frac{3}{6} \times \frac{1}{6} \times \frac{1}{6} = \frac{1}{72} \neq \frac{1}{12} \times \frac{1}{12} = P(Z_{12} = 1) \times P(Z_{23} = 1)$$

and thus they are not independent. M1 A1 (2)

Using part (ii), let $Y_1=Z_{12}$, let $Y_2=Z_{13}$, ... let $Y_m=Z_{(n-1)n}$

(and with
$$m = {}^{n}C_{2} = \frac{n(n-1)}{2}$$
).

 $P(Z_{12}=1)=\frac{1}{12}$, $P(Z_{12}=-1)=\frac{1}{12}$, $P(Z_{12}=0)=\frac{5}{6}$ so $E(Z_{12})=0$ and $E(Z_{12}^2)=\frac{1}{6}$ and likewise for all other Z (Y!).

If total score is U, then

$$U = \sum_{i < j} Z_{ij}$$

SO

$$E(U) = E\left(\sum_{i < j} Z_{ij}\right) = \sum_{i < j} E(Z_{ij}) = 0$$

B1

which means we can apply the result of (ii).

If
$$Z_{12}=1$$
 then $Z_{13}=1$ or $Z_{13}=0$

If
$$Z_{12}=-1$$
 then $Z_{13}=-1$ or $Z_{13}=0$

Otherwise $Z_{12} = 0$

So
$$E(Z_{12}Z_{13}) = 1 \times 1 \times \frac{1}{72} + -1 \times -1 \times \frac{1}{72} = \frac{1}{36}$$
 M1 A1

So

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