Education

2016–present Massachusetts Institute of Technology (MIT), Cambridge, United States.

- PhD student at the Mechanical Engineering department of MIT. GPA: 5.0.
- o Advisor: Prof. Alberto Rodriguez.
- 2015–2016 MIT, Cambridge, United States.
 - Visiting student at the MCube Lab supervised by Prof. Alberto Rodriguez.
- 2011–2016 Polytechnic University of Catalonia (UPC), Barcelona, Spain.
 - Dual Bachelors in Mathematics and Engineering Physics through CFIS.
 - CFIS is a talent center that selects some of the top technical students from Spain and provides them with a scholarship to simultaneously study two bachelor's degrees.

Research Experience

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2015—present Research assistant at MIT. I develop algorithms that make robots more reactive through accurate perception and feedback. In my work, I have studied both the power of closed-loop control in frictional systems and the capabilities of high-resolution tactile sensing for manipulation tasks, such as grasping and localization. My goal is to make robots reactive and dexterous at manipulation by effectively leveraging real-time tactile and visual feedback.

Summer 2016 Internship at Google: software engineer for three months at the SafeSearch team. Research and implementation of Deep Learning algorithms for a Computer Vision task.

Awards and Grants

- 2019 Selected to attend the **Global Young Scientists Summit**. Awarded to no more than 5 PhD students throughout all MIT departments.
- 2019 **Rising Stars in Mechanical Engineering.** Awarded to 30 graduate and postdoctoral women.
- 2019 **DeFlorez Travel Award in Design and Manufacturing.** Awarded to 1 MIT Mechanical Engineering Graduate Student annually.
- 2019 **Facebook Emerging Scholar Award**. Full funding for 2 years, only 21 awardees among more than 900 applications.
- 2018 **NVIDIA Graduate Fellowship** (declined). Awarded to 10 PhD students from more than 230 applications.
- 2018 **Best Paper Award on Cognitive Robotics** at IROS 2018 for the work "Augmenting Physical Simulators with Stochastic Neural Networks: Case Study of Planar Pushing and Bouncing".
- 2018 Amazon Robotics **Best Systems Paper Award** for the submission "Robotic pick-and-place of novel objects in clutter with multi-affordance grasping and cross-domain image matching".
- 2018 Travel Award to attend RSS 2018. The award is founded by the Women in Robotics Workshop.

- 2018 Best Poster Award at ICRA 2018 workshop on Active touch for perception and interaction.
- 2017 **1st Place Winners** (Stow Task) at the international competition **Amazon Robotics Challenge** (ARC) 2017 with the MIT-Princeton team.
- 2016 **Best Paper Finalist Award** at IROS 2016 for the work "More than a Million Ways to Be Pushed. A High-Fidelity Experimental Data Set of Planar Pushing".
- 2016 Proud recipient of 1 of just 45 prestigious **"La Caixa" Scholarships** for graduate studies. Full funding for 2 years in any graduate program of my choosing.
- 2016 3rd Place at the 2016 Amazon Robotics Challenge with the MIT-Princeton team.
- 2016 IROS 2016 NSF Travel Grant.
- 2015 UPC-Internship Program Grant to do research during one year at MIT.
- 2015 Google Grace Hopper Travel Award to attend the conference with all expenses paid.

Peer-reviewed Publications

- 2019 Alina Kloss, Maria Bauza et. al. "Accurate Vision-based Manipulation through Contact Reasoning", *submitted to ICRA 2019*.
- 2019 Yen-Chen Lin, Maria Bauza et. al. "Experience-Embedded Visual Foresight", CoRL 2019.
- 2019 Maria Bauza et. al. "Omnipush: accurate, diverse, real-world dataset of pushing dynamics with RGB-D video", *IROS 2019*.
- 2019 Ferran Alet, Adarsh K Jeewajee, Maria Bauza et. al. "Graph Element Networks: adaptive, structured computation and memory", *ICML 2019*.
- 2019 Maria Bauza, Oleguer Canal and Alberto Rodriguez, "Tactile Mapping and Localization from High-Resolution Tactile Imprints", *ICRA 2019*.
- 2019 Anurag Ajay, Maria Bauza et. al. "Combining Physical Simulators and Object-Based Networks for Control", *ICRA 2019*.
- 2018 Maria Bauza and Alberto Rodriguez, "GP-SUM. Gaussian Processes Filtering of non-Gaussian Beliefs", WAFR 2018.
- 2018 Maria Bauza*, Francois Hogan* et. al. "Learning vs. physics-based control of a planar push system", *CoRL 2018*.
- 2018 Maria Bauza*, Francois Hogan* et. al. "Tactile Regrasp: Grasp Adjustments via Simulated Tactile Transformations", *IROS 2018*.
- 2018 Anurag Ajay et. al., "Augmenting Physical Simulators with Stochastic Neural Networks: Case Study of Planar Pushing and Bouncing", *IROS 2018*.
- 2018 Andy Zeng et. al., "Active Perception of Novel Objects in Clutter with Multi-Affordance Grasping and Cross-Domain Image Matching" in *ICRA 2018, IJRR 2019*.
- 2017 Maria Bauza and Alberto Rodriguez, "A Probabilistic Data-Driven Model for Planar Pushing", in *ICRA 2017*.
- 2016 Kuan-Ting Yu, Maria Bauza, Nima Fazeli, and Alberto Rodriguez, "More than a Million Ways to Be Pushed. A High-Fidelity Experimental Data Set of Planar Pushing," in *IROS 2016*.

Press Coverage and Outreach

2019 MIT new article: Pushy robots learn the fundamentals of object manipulation .

- 2019 Selected poster at the MIT College of Computing Launch.
- 2019 Invited talk at Tec de Monterrey (Mexico).
- 2019 Selected talk at the ML across MIT retreat.
- 2019 ElMundo (spanish newspaper) Una mano robotica inteligente.
- 2019 El Iris (spanish newspaper, front page) Una ciutadellenca en el camp de la intelligencia artificial.
- 2018 Invited talk at IROS2018 Workshop on RoboTac: Tactile Perception and Learning in Robotics.
- 2018 MIT News Front page. Teaching robots how to move objects.
- 2018 Invited talk for broad audience (+100 attendees). First summer talk at Mercadal: Maria Bauza.
- 2018 MIT MechEConnects. Student Spotlight: Maria Bauza, PhD Candiate.
- 2018 MIT News Front page. Robo-picker grasps and packs.
- 2018 ExpressNews (spanish version). Maria Bauza, a spanish woman who makes history.
- 2018 La Vanguardia (spanish newspaper). MIT: the science paradise.
- 2017 Co-organized the workshop at RSS 2017 on Data-Driven Robotic Manipulation.
- 2016 Menorca (spanish newspaper). Maria Bauza, robotics researcher at MIT.