

El código Processing® de abajo (<https://processing.org>) -del cual no me siento particularmente orgulloso- implementa el juego de la vida de Conway (https://en.wikipedia.org/wiki/Conway%27s_Game_of_Life), un juego uni-personal que es un referente en teoría de la computación (por ejemplo, en <https://www.ics.uci.edu/~welling/teaching/271fall09/Turing-Machine-Life.pdf> aparece una implementación de una máquina de Turing en el juego de la vida).

1 Lea el primer capítulo de "The Lifebox, the Seashell, and the Soul" titulado "computation everywhere" y modifique el código para reflejar la "Vichniac Vote Rule". Corra su código con diferentes imágenes iniciales y capture la imagen final después de algunos cientos de iteraciones. ¿aparece algún patrón? Documente sus hallazgos y repórtelos en la primera parte de un documento pdf.

2 Lea los artículos "Wicked Problems - Jay Rosen – In the US, rising health care costs are classic case of a wicked problem. No "right" way to view it" (<https://edge.org/response-detail/11091>) y "The World is Unpredictable - Rudy Rucker – Even if the world is as deterministic as a computer program, you still can't predict what you're going to do" (<https://edge.org/response-detail/10171>). Como practicante del área de seguridad de la información, escriba un ensayo de una página con sus propias conclusiones de los artículos y de su código.

El código... Ustedes sabrán excusarme.

```
/*
Conway game of life...

      NW   N   NE
      W    E
      SW   S   SE

Rules:
1. Death from isolation: Each live cell with less than two live neighbors dies
in the next generation
2. Death from overpopulation: Each cell with four or more live neighbors dies
in the next generation
3. Birth: Each dead cell with exactly three live neighbors comes to life in the
next generation
4. Survival: Each live cell with two live neighbors survives in the next
generation
*/

int[][] grid, futureGrid; // current state and next generation
int iterations = 0;

void setup() {
  size(800, 500);
  frameRate(8);
  grid = new int[width][height];
  futureGrid = new int[width][height];

  /* para llenado automático, lo que va por dentro
float density = 0.3 * width * height; // densidad inicial... que tan denso
es al principio
for (int i = 0; i < density; i=i+1) {
  grid[int(random(width))][int(random(height))] = 0; // en 0 para que no
ponga nada, en 1 para que llene aleatoriamente algunos
```

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    } // end for() del llenado inicial de la vaina

    */

    /* Voy a hacer un glider
    grid[1][1] = 0;
    grid[2][1] = 1;
    grid[3][1] = 0;
    grid[1][2] = 0;
    grid[2][2] = 0;
    grid[3][2] = 1;
    grid[1][3] = 1;
    grid[2][3] = 1;
    grid[3][3] = 1;
    */

    // este código imprime un patrón de 28 "live" pixels in a straight line that
    achieves infinite growth
    grid[401][250] = 1;
    grid[402][250] = 1;
    grid[403][250] = 1;
    grid[404][250] = 1;
    grid[405][250] = 1;
    grid[406][250] = 1;
    grid[407][250] = 1;
    grid[408][250] = 1;

    grid[409][250] = 0;

    grid[410][250] = 1;
    grid[411][250] = 1;
    grid[412][250] = 1;
    grid[413][250] = 1;
    grid[414][250] = 1;

    grid[415][250] = 0;
    grid[416][250] = 0;
    grid[417][250] = 0;

    grid[418][250] = 1;
    grid[419][250] = 1;
    grid[420][250] = 1;

    grid[421][250] = 0;
    grid[422][250] = 0;
    grid[423][250] = 0;
    grid[424][250] = 0;
    grid[425][250] = 0;
    grid[426][250] = 0;

    grid[427][250] = 1;
    grid[428][250] = 1;
    grid[429][250] = 1;
    grid[430][250] = 1;
    grid[431][250] = 1;
    grid[432][250] = 1;
    grid[433][250] = 1;

    grid[434][250] = 0;

    grid[435][250] = 1;
    grid[436][250] = 1;
    grid[437][250] = 1;
    grid[438][250] = 1;
    grid[439][250] = 1;

    background(255,255,255);

    for (int x = 1; x < width-1; x=x+1) {
        for (int y = 1; y < height-1; y=y+1) {
            if(grid[x][y] == 1) {
                set(x, y, color(255));
            } else {
                set(x, y, color(0));
            } // end if then else
        } //end for()
    } // end for()

    saveFrame("frames/first.png"); // el primero de todos...

} // end setup...

```

```

void draw() {
    iterations = iterations + 1;

    for (int x = 1; x < width-1; x=x+1) {
        for (int y = 1; y < height-1; y=y+1) {

/* Para "que pase el chorizo"
for (int x = 0; x < width; x=x+1) {
    for (int y = 0; y < height; y=y+1) {*/

        // Check the number of neighbors (adjacent cells)
        int nb = neighbors(x, y);

        if ((grid[x][y] == 1) && (nb < 2)) {
            futureGrid[x][y] = 0; // Isolation death
            set(x, y, color(0));
        } else if ((grid[x][y] == 1) && (nb > 3)) {
            futureGrid[x][y] = 0; // Overpopulation death
            set(x, y, color(0));
        } else if ((grid[x][y] == 0) && (nb == 3)) {
            futureGrid[x][y] = 1; // Birth
            set(x, y, color(255));
        } else {
            futureGrid[x][y] = grid[x][y]; // Survive
        } // end if-then-else
    } // end for()
} // end for()

// Swap current and future grids
int[][] temp = grid;
grid = futureGrid;
futureGrid = temp;

if(iterations % 1000000 == 0) {
    saveFrame("frames/glider-#####.png");
} // end if

} // end draw()

// Count the number of adjacent cells 'on'. Esta función "no pasa el chorizo"...
// el objeto llega al límite y muere...
int neighbors(int x, int y) {
    return grid[x][y-1] // North
        + grid[x+1][y-1] // Northeast
        + grid[x+1][y] // East
        + grid[x+1][y+1] // Southeast
        + grid[x][y+1] // South
        + grid[x-1][y+1] // Southwest
        + grid[x-1][y] // West
        + grid[x-1][y-1] // Northwest
        ;
} // end neighbors()

/*

Para que la figura pase el chorizo utilice mejor la función de abajo...
int neighbors(int x, int y) {
    int north = (y + height-1) % height;
    int south = (y + 1) % height;
    int east = (x + 1) % width;
    int west = (x + width-1) % width;
    return grid[x][north] // North
        + grid[east][north] // Northeast
        + grid[east][y] // East
        + grid[east][south] // Southeast
        + grid[x][south] // South
        + grid[west][south] // Southwest
        + grid[west][y] // West
        + grid[west][north] // Northwest
        ;
} // end neighbors()

*/

```