

Convertendo do Espaço de Estados para uma Função de Transferência

Fundamentos de Controle

$$\dot{\mathbf{x}} = \mathbf{A}\mathbf{x} + \mathbf{B}\mathbf{u}$$

$$\mathbf{y} = \mathbf{C}\mathbf{x} + \mathbf{D}\mathbf{u}$$

$$s\mathbf{X}(s) = \mathbf{A}\mathbf{X}(s) + \mathbf{B}\mathbf{U}(s)$$

$$\mathbf{Y}(s) = \mathbf{C}\mathbf{X}(s) + \mathbf{D}\mathbf{U}(s)$$

$$(s\mathbf{I} - \mathbf{A})\mathbf{X}(s) = \mathbf{B}\mathbf{U}(s)$$

$$\mathbf{X}(s) = (s\mathbf{I} - \mathbf{A})^{-1}\mathbf{B}\mathbf{U}(s)$$

$$\mathbf{Y}(s) = \mathbf{C}(s\mathbf{I} - \mathbf{A})^{-1}\mathbf{B}\mathbf{U}(s) + \mathbf{D}\mathbf{U}(s) = [\mathbf{C}(s\mathbf{I} - \mathbf{A})^{-1}\mathbf{B} + \mathbf{D}]\mathbf{U}(s)$$

$$T(s) = \frac{Y(s)}{U(s)} = \mathbf{C}(s\mathbf{I} - \mathbf{A})^{-1}\mathbf{B} + \mathbf{D}$$

Exemplo 3.6

Representação no Espaço de Estados para Função de Transferência

PROBLEMA: Dado o sistema definido pelas Equações (3.74), obtenha a função de transferência $T(s) = Y(s)/U(s)$, em que $U(s)$ é a entrada e $Y(s)$ é a saída.

$$\dot{\mathbf{x}} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & -2 & -3 \end{bmatrix} \mathbf{x} + \begin{bmatrix} 10 \\ 0 \\ 0 \end{bmatrix} u \quad (3.74a)$$

$$y = [1 \quad 0 \quad 0] \mathbf{x} \quad (3.74b)$$

$$(s\mathbf{I} - \mathbf{A}) = \begin{bmatrix} s & 0 & 0 \\ 0 & s & 0 \\ 0 & 0 & s \end{bmatrix} - \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & -2 & -3 \end{bmatrix} = \begin{bmatrix} s & -1 & 0 \\ 0 & s & -1 \\ 1 & 2 & s+3 \end{bmatrix}$$

$$(s\mathbf{I} - \mathbf{A})^{-1} = \frac{\text{adj}(s\mathbf{I} - \mathbf{A})}{\det(s\mathbf{I} - \mathbf{A})} = \frac{\begin{bmatrix} (s^2 + 3s + 2) & s + 3 & 1 \\ -1 & s(s + 3) & s \\ -s & -(2s + 1) & s^2 \end{bmatrix}}{s^3 + 3s^2 + 2s + 1}$$

$$\mathbf{A} = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}$$

$$\text{cof}(A) = \begin{bmatrix} + \begin{vmatrix} e & f \\ h & i \end{vmatrix} & - \begin{vmatrix} d & f \\ g & i \end{vmatrix} & + \begin{vmatrix} d & e \\ g & h \end{vmatrix} \\ - \begin{vmatrix} b & c \\ h & i \end{vmatrix} & + \begin{vmatrix} a & c \\ g & i \end{vmatrix} & - \begin{vmatrix} a & b \\ g & h \end{vmatrix} \\ + \begin{vmatrix} b & c \\ e & f \end{vmatrix} & - \begin{vmatrix} a & c \\ d & f \end{vmatrix} & + \begin{vmatrix} a & b \\ d & e \end{vmatrix} \end{bmatrix}$$

$$\text{adj}(A) = \begin{bmatrix} + \begin{vmatrix} e & f \\ h & i \end{vmatrix} & - \begin{vmatrix} b & c \\ h & i \end{vmatrix} & + \begin{vmatrix} b & c \\ e & f \end{vmatrix} \\ - \begin{vmatrix} d & f \\ g & i \end{vmatrix} & + \begin{vmatrix} a & c \\ g & i \end{vmatrix} & - \begin{vmatrix} a & c \\ d & f \end{vmatrix} \\ + \begin{vmatrix} d & e \\ g & h \end{vmatrix} & - \begin{vmatrix} a & b \\ g & h \end{vmatrix} & + \begin{vmatrix} a & b \\ d & e \end{vmatrix} \end{bmatrix}$$

$$\mathbf{B} = \begin{bmatrix} 10 \\ 0 \\ 0 \end{bmatrix}$$

$$\mathbf{C} = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}$$

$$\mathbf{D} = 0$$

$$T(s) = \frac{10(s^2 + 3s + 2)}{s^3 + 3s^2 + 2s + 1}$$

```
syms s
```

```
A=[0 1 0;0 0 1;-1 -2 -3];
```

```
B=[10;0;0];
```

```
C=[1 0 0];
```

```
D=0;
```

```
I=[1 0 0;0 1 0;0 0 1];
```

```
'T(s)'
```

```
T=C*((s*I-A)^-1)*B+D;
```

```
pretty(T)
```

```
pause
```

```
% Construct symbolic object for  
% frequency variable 's'.
```

```
% Create matrix A.
```

```
% Create vector B.
```

```
% Create vector C.
```

```
% Create D.
```

```
% Create identity matrix.
```

```
% Display label.
```

```
% Find transfer function.
```

```
% Pretty print transfer function.
```

Exercício 3.4

PROBLEMA: Converta as equações de estado e de saída mostradas nas Equações (3.78) em uma função de transferência.

$$\dot{\mathbf{x}} = \begin{bmatrix} -4 & -1,5 \\ 4 & 0 \end{bmatrix} \mathbf{x} + \begin{bmatrix} 2 \\ 0 \end{bmatrix} u(t) \quad (3.78a)$$

$$y = [1,5 \quad 0,625] \mathbf{x} \quad (3.78b)$$

RESPOSTA:

$$G(s) = \frac{3s + 5}{s^2 + 4s + 6}$$

$A = \begin{bmatrix} -4 & -1.5 \\ 4 & 0 \end{bmatrix};$

$B = \begin{bmatrix} 2 & 0 \end{bmatrix}';$

$C = \begin{bmatrix} 1.5 & 0.625 \end{bmatrix};$

$D = 0;$

$T = \text{ss}(A, B, C, D);$

$T = \text{tf}(T)$