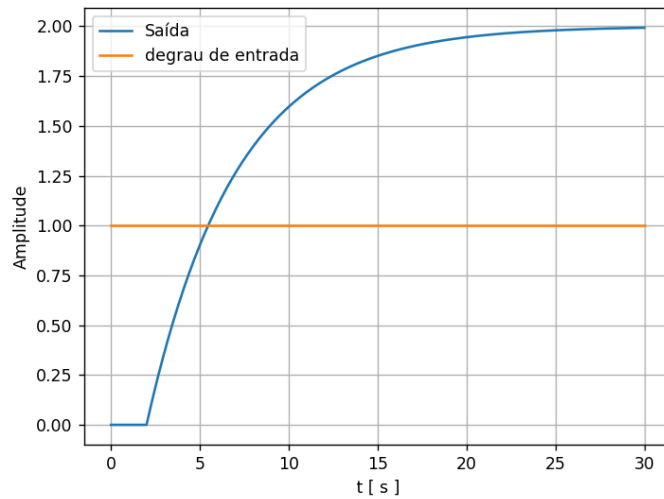


C213

1. Código Q01\_02.



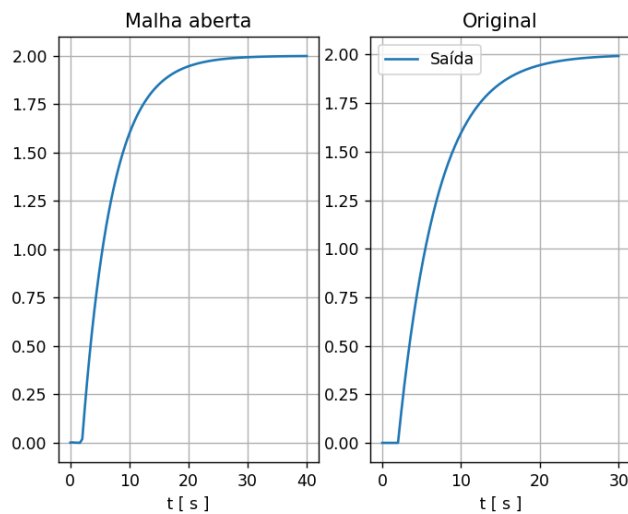
2.  $K = 2$

$$\tau = 1,5 * (t1 - t2) = 1,5 * (6,67 - 3,64) = 4,995$$

$$\theta = t2 - \tau = 6,67 - 4,995 = 1,975$$

$$H(s) = \frac{2e^{-1,975s}}{4,995s + 1}$$

3.



Código sendo plotado no arquivo Q03.py.

#### 4. Erro em malha aberta

$$e = \text{setpoint} - y$$

$$e = |1 - 2|$$

$$e = 1$$

Erro em malha fechada

$$e = \text{setpoint} - y$$

$$e = |1 - 0,66|$$

$$e = 0,34$$

#### 5. COHEN E COON

$$Kp = \frac{1 * \tau}{K * \theta} \left( \frac{4}{3} + \frac{\theta}{4\tau} \right) = \frac{4,995}{2 * 1,975} \left( \frac{4}{3} + \frac{1,975}{4 * 4,995} \right) = 1,256 * 1,432 = 1,81$$

$$Ti = \theta \left( \frac{32 + 6 \left( \frac{\theta}{\tau} \right)}{13 + 8 \left( \frac{\theta}{\tau} \right)} \right) = 1,995 * \left( \frac{32 + 6 \left( \frac{1,975}{4,995} \right)}{13 + 8 \left( \frac{1,975}{5,995} \right)} \right) = 1,995 * 2,127 = 4,2$$

$$Td = \theta * \left( \frac{4}{11 + 2 * \left( \frac{\theta}{\tau} \right)} \right) = 1,975 * \left( \frac{4}{11 + 2 * \left( \frac{\theta}{\tau} \right)} \right) = 1,975 * 0,339 = 0,67$$

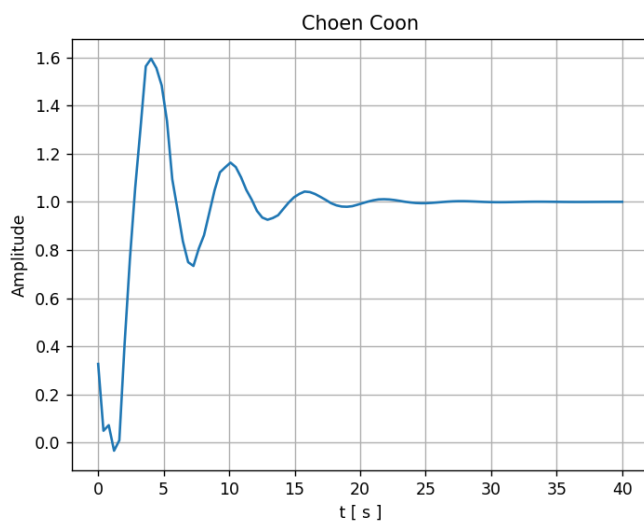
IMC

$$Kp = \frac{2 * \tau + \theta}{K * (2 * \lambda + \theta)} = \frac{2 * 4,995 + 1,975}{2 * (2 * 1,778 + 1,975)} = \frac{11,965}{11,062} = 1,082$$

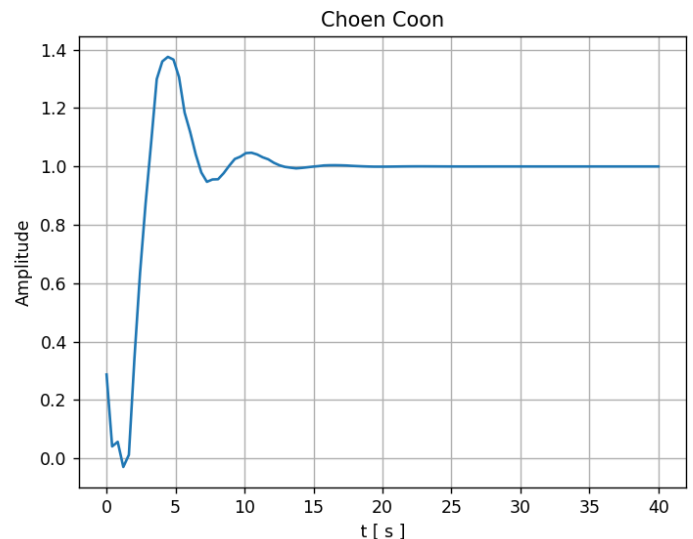
$$Td = \frac{\tau * \theta}{2 * \tau + \theta} = \frac{1,975 * 4,995}{2 * 4,995 + 1,975} = \frac{9,865}{11,965} = 0,824$$

$$Ti = \tau * \left( \frac{\theta}{2} \right) = 4,995 * \left( \frac{1,975}{2} \right) = 4,932$$

#### 6. Ajuste do Kp.



**Kp = 1,81**



**Kp = 1,5**

7. A desvantagem percebida foi que o método Cohen-Coon tem um cálculo mais complexo, um tempo menor de estabilização e mais oscilações.