Enterprise-Grade Plugin-Based Simulation Engine in Advanced Modern C++

/*

File: SimulationEngine.cpp

Description: A highly modular, thread-safe, plugin-based simulation engine demonstrating advanced Modern C++ (C++17/20) features.

Keywords: Advanced C++, Modern C++, Multithreading, Design Patterns, OOP, Templates, Memory Management, Asynchronous Programming, STL, Smart Pointers, Factory Pattern, Visitor Pattern, Strategy Pattern, Singleton

*/

```
#include <iostream>
#include <vector>
#include <string>
#include <memory>
#include <map>
#include <mutex>
#include <future>
#include <future>
#include <future>
#include <chrono>
#include <functional>
#include <typeindex>
#include <typeinfo>
```

```
// ----- Logging Utility -----
class Logger {
public:
  static Logger& getInstance() {
    static Logger instance;
    return instance;
  }
  void log(const std::string& msg) {
    std::lock_guard<std::mutex> lock(mutex_);
    std::cout << "[LOG] " << msg << std::endl;
  }
private:
  Logger() = default;
  std::mutex mutex_;
};
// ----- Abstract Plugin Interface -----
class IPlugin {
public:
  virtual void initialize() = 0;
  virtual void execute() = 0;
  virtual void shutdown() = 0;
  virtual ~IPlugin() = default;
};
```

```
// ----- Plugin Factory ------
class PluginFactory {
public:
  using Creator = std::function<std::unique_ptr<IPlugin>()>;
  static PluginFactory& getInstance() {
    static PluginFactory instance;
    return instance;
  }
  void registerPlugin(const std::string& name, Creator creator) {
    creators_[name] = creator;
  }
  std::unique_ptr<IPlugin> createPlugin(const std::string& name) {
    if (creators_.count(name)) {
       return creators_[name]();
     }
    Logger::getInstance().log("Plugin not found: " + name);
    return nullptr;
  }
private:
  std::map<std::string, Creator> creators_;
```

```
};
// ----- Sample Plugin (Physics Module) -----
class PhysicsPlugin : public IPlugin {
public:
  void initialize() override {
    Logger::getInstance().log("PhysicsPlugin Initialized");
  }
  void execute() override {
    Logger::getInstance().log("PhysicsPlugin Executing Physics Simulation...");
    std::this_thread::sleep_for(std::chrono::milliseconds(100));
  }
  void shutdown() override {
    Logger::getInstance().log("PhysicsPlugin Shutdown");
  }
};
// Register Plugin Automatically
struct PhysicsPluginRegistrar {
  PhysicsPluginRegistrar() {
    PluginFactory::getInstance().registerPlugin("Physics", []() {
       return std::make_unique<PhysicsPlugin>();
     });
  }
} physicsRegistrar;
```

```
// ----- Strategy Pattern for Simulation Modes -----
class SimulationMode {
public:
  virtual void run() = 0;
  virtual ~SimulationMode() = default;
};
class FastMode : public SimulationMode {
public:
  void run() override {
    Logger::getInstance().log("Running in Fast Mode");
  }
};
class AccurateMode : public SimulationMode {
public:
  void run() override {
    Logger::getInstance().log("Running in Accurate Mode");
  }
};
// ----- Visitor Pattern for Entity Processing ------
class SimulationEntity;
```

```
class EntityVisitor {
public:
  virtual void visit(SimulationEntity& entity) = 0;
  virtual ~EntityVisitor() = default;
};
class SimulationEntity {
public:
  virtual void accept(EntityVisitor& visitor) = 0;
  virtual std::string getName() const = 0;
  virtual ~SimulationEntity() = default;
};
class CarEntity : public SimulationEntity {
public:
  void accept(EntityVisitor& visitor) override {
     visitor.visit(*this);
  }
  std::string getName() const override {
     return "Car";
  }
};
class EntityLoggerVisitor : public EntityVisitor {
public:
```

```
void visit(SimulationEntity& entity) override {
     Logger::getInstance().log("Entity: " + entity.getName());
  }
};
// ----- Thread Pool for Concurrent Tasks -----
class ThreadPool {
public:
  ThreadPool(size_t threads) : stop(false) {
     for (size_t i = 0; i < threads; ++i)
       workers.emplace_back([this] {
          for (;;) {
            std::function<void()> task;
            {
               std::unique_lock<std::mutex> lock(this->queue_mutex);
               this->condition.wait(lock, [this] {
                 return this->stop | !this->tasks.empty();
               });
               if (this->stop && this->tasks.empty())
                 return;
               task = std::move(this->tasks.front());
               this->tasks.pop_front();
            task();
          }
```

```
});
template <class F>
auto enqueue(F&& f) -> std::future<decltype(f())> {
  auto task = std::make_shared<std::packaged_task<decltype(f())()>>(std::forward<F>(f));
  std::future<decltype(f())> res = task->get_future();
  {
    std::unique_lock<std::mutex> lock(queue_mutex);
     tasks.emplace_back([task]() { (*task)(); });
  }
  condition.notify_one();
  return res;
}
~ThreadPool() {
    std::unique_lock<std::mutex> lock(queue_mutex);
    stop = true;
  }
  condition.notify_all();
  for (auto& worker: workers)
    worker.join();
}
```

```
private:
  std::vector<std::thread> workers;
  std::deque<std::function<void()>> tasks;
  std::mutex queue_mutex;
  std::condition_variable condition;
  bool stop;
};
// ----- Templated Config Manager (Type-safe) -----
class ConfigManager {
public:
  template <typename T>
  void set(const std::string& key, const T& value) {
    std::lock_guard<std::mutex> lock(mutex_);
    data_[key] = std::make_shared<Holder<T>>(value);
  }
  template <typename T>
  T get(const std::string& key) {
    std::lock_guard<std::mutex> lock(mutex_);
    return std::static_pointer_cast<Holder<T>>(data_.at(key))->value;
  }
private:
  struct Base {
```

```
virtual ~Base() = default;
  };
  template <typename T>
  struct Holder : Base {
    Holder(const T& value) : value(value) {}
    T value;
  };
  std::map<std::string, std::shared_ptr<Base>> data_;
  std::mutex mutex_;
};
// ----- Main Simulation Engine -----
class SimulationEngine {
public:
  SimulationEngine()
    : threadPool(std::make_unique<ThreadPool>(4)),
config(std::make_unique<ConfigManager>()) {
    Logger::getInstance().log("SimulationEngine Constructed");
  }
  void setMode(std::unique_ptr<SimulationMode> m) {
    mode = std::move(m);
  }
```

```
void addEntity(std::unique_ptr<SimulationEntity> entity) {
  entities.push_back(std::move(entity));
}
void run() {
  mode->run();
  auto physicsPlugin = PluginFactory::getInstance().createPlugin("Physics");
  if (physicsPlugin) {
     physicsPlugin->initialize();
    auto future = threadPool->enqueue([&]() {
       physicsPlugin->execute();
     });
    EntityLoggerVisitor visitor;
    for (auto& entity: entities) {
       entity->accept(visitor);
     }
    future.get(); // Wait for plugin execution
    physicsPlugin->shutdown();
  }
}
```

```
private:
  std::unique_ptr<ThreadPool> threadPool;
  std::unique_ptr<ConfigManager> config;
  std::vector<std::unique_ptr<SimulationEntity>> entities;
  std::unique_ptr<SimulationMode> mode;
};
// ----- Main Driver (Asynchronous, Demonstrates Futures) -----
int main() {
  Logger::getInstance().log("Initializing Simulation");
  SimulationEngine engine;
  engine.setMode(std::make_unique<AccurateMode>());
  engine.addEntity(std::make_unique<CarEntity>());
  auto future = std::async(std::launch::async, [&engine]() {
    engine.run();
  });
  future.get(); // Wait for simulation to finish
  Logger::getInstance().log("Simulation Completed");
  return 0;
```