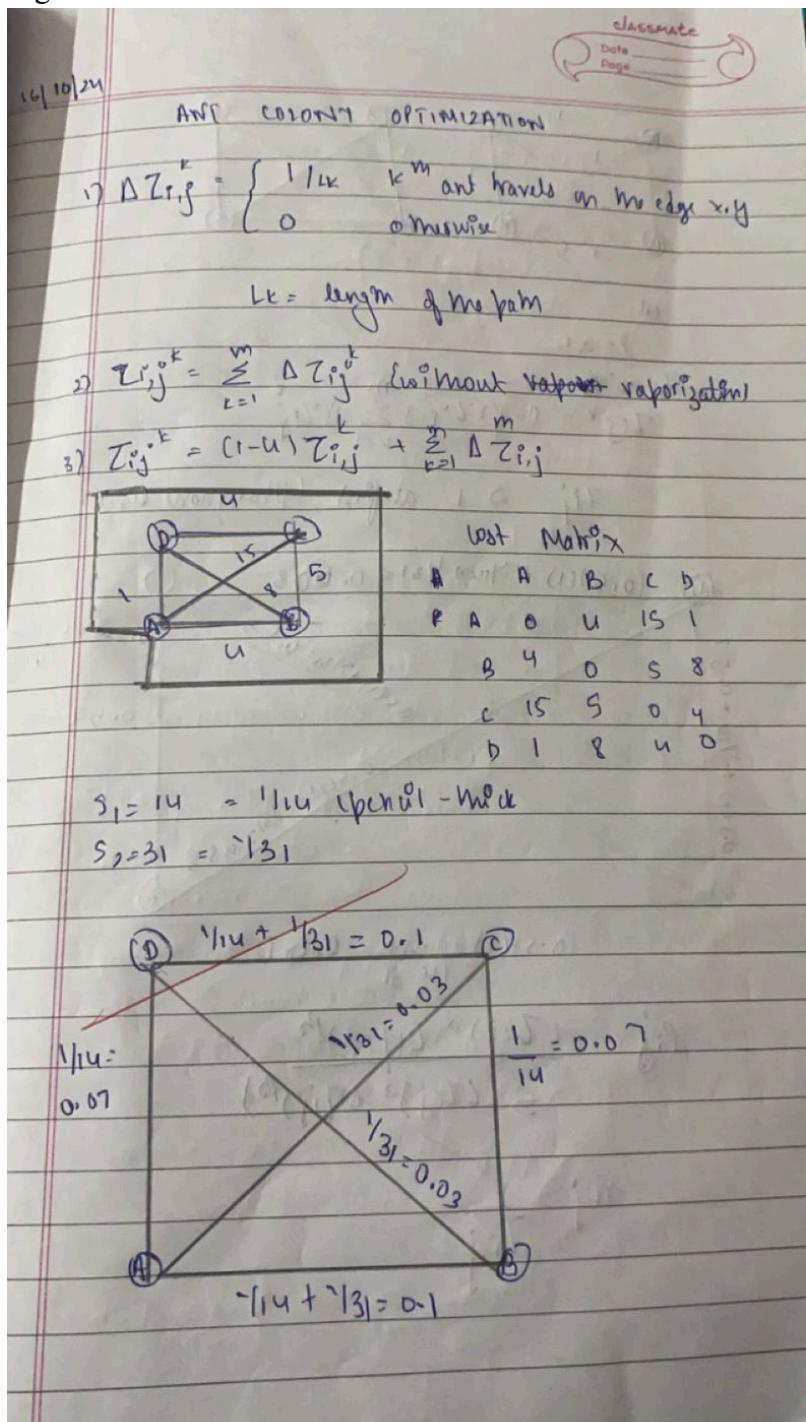
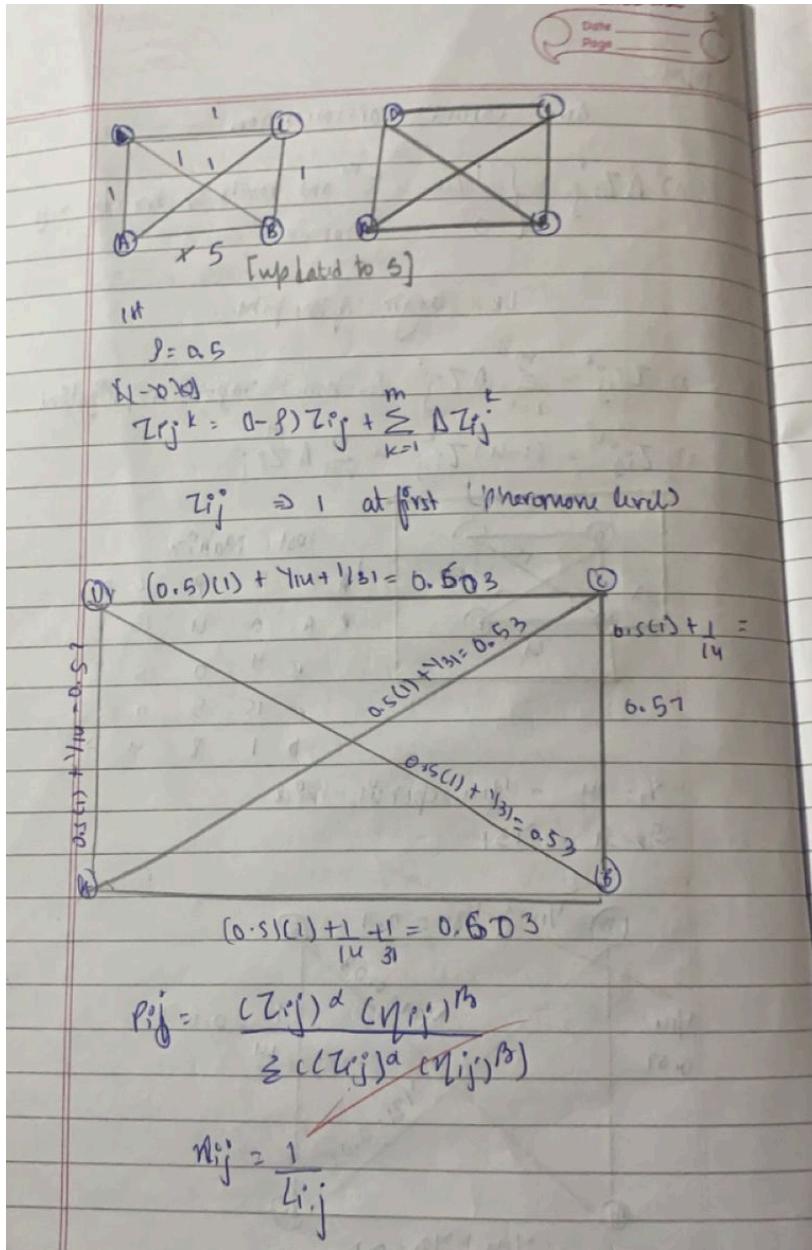


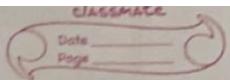
Program 2

Problem statement: Ant Colony Optimization for the Traveling Salesman Problem

Algorithm:







A to D

$$\frac{1^* \gamma_1}{(1^* \gamma_1 + 1^* \gamma_2 + 1^* \gamma_3 + 1^* \gamma_4)} = 0.195$$

A to B

$$\frac{1^* \gamma_1}{(1^* \gamma_1 + 1^* \gamma_2 + 1^* \gamma_3 + 1^* \gamma_4)} = 0.18$$

A to C

$$\frac{1^* \gamma_1}{(1^* \gamma_1 + 1^* \gamma_2 + 1^* \gamma_3 + 1^* \gamma_4)} = 0.02$$

Mating \rightarrow B pheromone levels

$$A \text{ to } B = \frac{5^* \gamma_4}{(1^* \gamma_1 + 1^* \gamma_2 + 1^* \gamma_3 + 5^* \gamma_4)} = 0.53$$

~~$$A \text{ to } C = \frac{1^* \gamma_1}{(1^* \gamma_1 + 1^* \gamma_2 + 1^* \gamma_3 + 5^* \gamma_4)} = 0.10$$~~

ANT DRITUM

Initialize parameters

N = no. of ants

T = max. no. of iterations

α = influence of pheromone

β = influence of heuristic information

γ = pheromone evaporation rate

δ = pheromone deposit constant

Z_{ij}^0 : initial pheromone level

n_{ij} : heuristic information

For $b=1 \dots T$

(for each ant $k=1 \dots N$)

initialize ant's tour

(for each step j of the ant's tour)

select the next node c_j based on transition probability

$$P_{ij} = (Z_{ij}^\alpha)^* (n_{ij}^\beta)^* / \text{sum_over_allowed_nodes} (Z_{ik}^\alpha)^* (n_{ik}^\beta)^*$$

choose the next node c_j using P_{ij}
favoring paths with more pheromone
and better heuristic info

Move the ant to selected node

for each edge (i, j)

apply pheromone evaporation:

$$Z_{ij}^{new} = (\alpha - \beta)^\gamma Z_{ij}$$

for each ant k :

calculate the tour length L_k

Deposit pheromone on the edges in ant's path:

$$\Delta \tau_{ij} = 0 / L_K$$

$\tau_{ij} = \tau_{ij}$ for all edges (i, j) in ant k 's tour

or Normally, keep track of the best solution so far
check stopping criteria:
of stopping condition met (e.g. maximum iterations or convergence, exit the loop)
return the best solution found.

Before updating the pheromone

$$P_1 = \frac{1^{*} \gamma_1}{1^{*} \gamma_1 + 1^{*} \gamma_5 + 1^{*} \gamma_4} = 0.75$$

$$P_2 = \frac{1^{*} \gamma_4}{1^{*} \gamma_1 + 1^{*} \gamma_5 + 1^{*} \gamma_4} = 0.18$$

$$P_3 = \frac{1^{*} \gamma_5}{1^{*} \gamma_1 + 1^{*} \gamma_5 + 1^{*} \gamma_4} = 0.05$$

After updating the pheromone

$$P_1 = \frac{1^{*} \gamma_1}{1^{*} \gamma_1 + 1^{*} \gamma_5 + 5^{*} \gamma_4} = 0.43$$

$$P_2 = \frac{5^{*} \gamma_4}{1^{*} \gamma_1 + 1^{*} \gamma_5 + 5^{*} \gamma_4} = 0.53$$

$$P_3 = \frac{1^{*} \gamma_5}{1^{*} \gamma_1 + 1^{*} \gamma_5 + 5^{*} \gamma_4} = 0.02$$

Code:

```
import numpy as np
import random
class AntColony:
    def __init__(self, graph, n_ants, n_best, n_iterations, decay, alpha=1, beta=1):
        self.graph = graph
```

```

self.n_ants = n_ants
self.n_best = n_best
self.n_iterations = n_iterations
self.decay = decay
self.alpha = alpha
self.beta = beta
self.pheromone = np.ones(self.graph.shape) / len(graph)
self.nodes = ['A', 'B', 'C', 'D']
def run(self):
    shortest_path = None
    shortest_distance = float('inf')
    for _ in range(self.n_iterations):
        all_paths = self.gen_all_paths()
        self.spread_pheromone(all_paths, shortest_path, shortest_distance)
        shortest_path, shortest_distance = self.best_path(all_paths)
    shortest_path = [(self.nodes[from_node], self.nodes[to_node]) for from_node, to_node in
shortest_path]
    return shortest_path, shortest_distance
def spread_pheromone(self, all_paths, shortest_path, shortest_distance):
    for path, dist in all_paths:
        for from_node, to_node in path:
            self.pheromone[from_node][to_node] += 1.0 / dist
            self.pheromone *= self.decay
def gen_path(self, start):
    path = []
    visited = set()
    visited.add(start)
    current = start
    while len(visited) < len(self.graph):
        next_node = self.pick_next_node(current, visited)
        path.append((current, next_node))
        visited.add(next_node)
        current = next_node
    path.append((current, start))
    return path
def gen_all_paths(self):
    all_paths = []
    for ant in range(self.n_ants):
        path = self.gen_path(random.randint(0, len(self.graph)-1))
        distance = self.calculate_distance(path)
        all_paths.append((path, distance))
    return all_paths
def calculate_distance(self, path):
    distance = 0
    for from_node, to_node in path:
        distance += self.graph[from_node][to_node]

```

```

    return distance
def best_path(self, all_paths):
    best = min(all_paths, key=lambda x: x[1])
    return best
def pick_next_node(self, current, visited):
    pheromone = np.copy(self.pheromone[current])
    pheromone[list(visited)] = 0
    attractiveness = np.copy(self.graph[current])
    attractiveness[list(visited)] = 0
    pheromone = pheromone ** self.alpha
    attractiveness = attractiveness ** self.beta
    prob = pheromone * attractiveness
    prob /= prob.sum()
    return np.random.choice(range(len(self.graph)), p=prob)
graph = np.array([
    [0, 10, 15, 20],
    [10, 0, 35, 25],
    [15, 35, 0, 30],
    [20, 25, 30, 0]
])
aco = AntColony(graph, n_ants=5, n_best=2, n_iterations=100, decay=0.95, alpha=1, beta=2)
shortest_path, shortest_distance = aco.run()
print("Shortest path (in terms of nodes): ", shortest_path)
print("Shortest distance: ", shortest_distance)

```

```

import numpy as np
import random
class AntColony:
    def __init__(self, graph, n_ants, n_best, n_iterations, decay, alpha=1, beta=1):
        self.graph = graph
        self.n_ants = n_ants
        self.n_best = n_best
        self.n_iterations = n_iterations
        self.decay = decay
        self.alpha = alpha
        self.beta = beta
        self.pheromone = np.ones(self.graph.shape) / len(graph)
        self.nodes = ['A', 'B', 'C', 'D']
    def run(self):
        shortest_path = None
        shortest_distance = float('inf')
        for _ in range(self.n_iterations):
            all_paths = self.gen_all_paths()
            self.spread_pheromone(all_paths, shortest_path, shortest_distance)
            shortest_path, shortest_distance = self.best_path(all_paths)
        shortest_path = [(self.nodes[from_node], self.nodes[to_node]) for from_node, to_node in shortest_path]
        return shortest_path, shortest_distance
    def spread_pheromone(self, all_paths, shortest_path, shortest_distance):
        for path, dist in all_paths:
            for from_node, to_node in path:
                self.pheromone[from_node][to_node] += 1.0 / dist
        self.pheromone *= self.decay
    def gen_path(self, start):
        path = []
        visited = set()
        visited.add(start)
        current = start
        while len(visited) < len(self.graph):
            next_node = self.pick_next_node(current, visited)
            path.append((current, next_node))
            visited.add(next_node)
            current = next_node
        path.append((current, start))
        return path
    def gen_all_paths(self):
        all_paths = []
        for ant in range(self.n_ants):
            path = self.gen_path(random.randint(0, len(self.graph)-1))
            distance = self.calculate_distance(path)
            all_paths.append((path, distance))
        return all_paths
    def calculate_distance(self, path):
        distance = 0
        for from_node, to_node in path:
            distance += self.graph[from_node][to_node]
        return distance
    def best_path(self, all_paths):
        best = min(all_paths, key=lambda x: x[1])
        return best

```

```
    return best
def pick_next_node(self, current, visited):
    pheromone = np.copy(self.pheromone[current])
    pheromone[list(visited)] = 0
    attractiveness = np.copy(self.graph[current])
    attractiveness[list(visited)] = 0
    pheromone = pheromone ** self.alpha
    attractiveness = attractiveness ** self.beta
    prob = pheromone * attractiveness
    prob /= prob.sum()
    return np.random.choice(range(len(self.graph)), p=prob)
graph = np.array([
    [0, 10, 15, 20],
    [10, 0, 35, 25],
    [15, 35, 0, 30],
    [20, 25, 30, 0]
])
aco = AntColony(graph, n_ants=5, n_best=2, n_iterations=100, decay=0.95, alpha=1, beta=2)
shortest_path, shortest_distance = aco.run()
print("Shortest path (in terms of nodes): ", shortest_path)
print("Shortest distance: ", shortest_distance)
```

Output:



Shortest path: [(1, 2), (2, 3), (3, 0), (0, 1)]
Shortest distance: 95