

## MT 3802 - Numerical Analysis:

### *Project on Iterative Methods*

#### *Programming language used: Python*

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## Overview

This project examines the basic properties of the three different iterative methods (Jacobi, Gauss-Seidel & Successive Relaxation). Two examples are analysed to discuss and compare the three methods and their rates of convergence.

## Implementation & Design

For all three of the methods there are some key arrays which are defined before defining the main functions. These are as follows:

A – matrix  $a[i][j]$  given from the examples

b – vector given from the examples

N – number of iterations

x – solution vector

Y – a n array consisting of the diagonal values of A (function used from numpy package)

empty – empty 6x6 arrays for later use

D – diagonal matrix with elements  $a[i][i]$

L – lower triangular matrix with  $l[i][j] = -a[i][j]$  for  $i > j$  and  $l[i][j] = 0$  elsewhere (for-loop going through A is used to fill in one of the empty arrays with the required values for a lower triangular matrix)

U – upper triangular matrix with  $u[i][j] = -a[i][j]$  for  $i < j$  and  $u[i][j] = 0$  elsewhere (for-loop going through A is used to fill in one of the empty arrays with the required values for an upper triangular matrix)

Result – L+U

Rho(1 to 3) - the spectral radiuses, calculated from the formula  $\rho(B) = \max(|\lambda_i|)$  for  $1 \leq i \leq n$ , where B is the Iteration matrix. The function for eigenvalues is from numpy.linalg.

## Jacobi Method

A function 'Jacobi' with parameters A, b, N and x is defined.

It starts with an initial guess for the vector x (in these examples the initial guess will be the (0,0,0,0,0,0)).

For every iteration the function calculates the solution vector from the formula given in the lecture notes, namely  $x(k+1) = D^{-1} * (L+U) * x(k) + D^{-1} * b$ .

The Iteration matrix is calculated from the formula in the lecture notes :  $B_J = D^{-1}(L+U)$ . The matrix multiplication is done using the `np.dot` function from the numpy package.

The spectral radius for Jacobi is calculated.

### Gauss-Seidel Method

A function 'GaussSeidel' with parameters A, b, DLIInv, IterMatrixGauss, N and x is defined. It starts with an initial guess for x and for every iteration it calculates the new solution vector from the formula  $x(k+1) = (D-L)^{-1}U * x(k) + (D-L)^{-1}b$ . The variable DLIInv is the calculated inverse of the matrix (D-L) and the Iteration matrix IterMatrixGauss is calculated from the formula  $B_{GS} = (D-L)^{-1}U$ . The function `np.linalg.inv` calculating the inverse of a matrix is used from the numpy package.

The spectral radius for Gauss-Seidel is calculated.

### Successive Relaxation Method

The successive relaxation method is used to accelerate the Gauss-Seidel method. In this project it is calculated in a different manner to the other two iteration methods. In order to be able to see the significance of the value of the relaxation parameter a for- loop is used to calculate the iterations for each different value of  $\omega$ . The loop takes the values of  $\omega$  in the range from 0 to 2 with a step = 0.05. A function `frange` is defined since the function `range` does not work with floats.

Formulas used:

$$X(k+1) = (D - \omega L)^{-1}[(1 - \omega)D + \omega U]x(k) + (D - \omega L)^{-1} \omega b.$$

$$B_{SOR} = (D - \omega L)^{-1}[(1 - \omega)D + \omega U]$$

The variable  $D - \omega L$  is the matrix  $(D - \omega L)$ , while  $D - \omega L$ Inv is its inverse.

The spectral radius for SOR is calculated.

The function SOR is defined to calculate the solution vector using the optimal value for  $\omega$  and using the formula from the lecture notes.

### **Tests**

The three algorithms were tested with the linear system from Example 2.3.1 from the lecture notes. All results were equal to these in the lecture notes.

### **Examples Analysis**

#### Example 1:

Comment: In order to work with the linear system from example 1, the code for the values of A and b needs to be de-hashed.

N=100

X guess = (0,0,0,0,0,0)

As it can be observed, the values for the solution vector are very similar in each case – approx.(1,2,1,2,1,2). The spectral radii in each case, however, are quite different.

The spectral radius of Jacobi method equals approximately 0.923 while the one of the Gauss-Seidel method equals approximately 0.282.

The rate of convergence of the successive relaxation method appears to be very sensitive to the value of  $\omega$ . From the values of  $\omega$  examined, we can observe a fastest rate of convergence when  $\omega=1.05$ , a value close to the one in the Gauss-Seidel method, but with spectral radius = approx. 0.152.

From these values, we can observe that the rate of convergence is fastest when using the successive relaxation method and slowest when using the Jacobi method.

Changing N:

In this example the Jacobi method is first most accurate when  $N=223$ , we get a solution vector [ 1.00000001 2.00000004 1.00000002 2.00000002 1.00000004 2.00000003]. The solution vector we get from Gauss-Seidel when  $N=16$  is [ 1. 2.00000001 1.00000001 2. 0.99999999 1.99999999]. Thus, we need much less iterations with the Gauss-Seidel method than we do for the Jacobi method.

### Example 2:

Comment: In order to work with the linear system from example 2, the code for the values of A and b of the previous example needs to be hashed, and the new values need to be de-hashed.

For:

$N=100$

As it can be observed, the values for the solution vector are very similar in each case – approx. ( [ 2. 3. 4. 2. 1. 2.]) The spectral radii in each case, however, are quite different.

The spectral radius of Jacobi method equals approximately 0.561 while the one of the Gauss-Seidel method equals approximately 0.314.

The rate of convergence of the successive relaxation method appears to be very sensitive to the value of  $\omega$ . From the values of  $\omega$  examined, we can observe a fastest rate of convergence when  $\omega=1.1$ , a value close to the one in the Gauss-Seidel method, but with spectral radius = 0.1.

From these values, we can observe that the rate of convergence is fastest when using the successive relaxation method and slowest when using the Jacobi method.

Changing N:

In this example the Jacobi matrix is first most accurate when  $N=36$ , we get a solution vector: [ 2. 3. 4. 2. 1. 2.]. The same solution vector we get from Gauss-Seidel when  $N=19$ . Here, the Gauss-Seidel method needs less iterations than the Jacobi one, but this time the difference is not as big as in example 1.

### **Conclusion**

From the analysed examples we can make the conclusion that the Jacobi Method has the slowest rate of convergence and it takes the most iterations to converge, while the Gauss-Seidel method had a faster rate of convergence and requires less iterations for greater accuracy. The

successive relaxation method can be used to accelerate the Gauss-Seidel method even more, having the fastest rate of convergence.