# Lecture 13: Change of Variables Part 1

October 9, 2018

# Review of Single Variable Case

In the univariate case we have:

$$\int_{a}^{b} f(g(x))g'(x)dx = \int_{g(a)}^{g(b)} f(u)du$$

Where

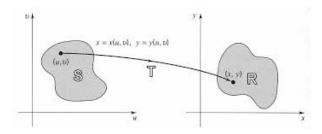
- (i) g'(x) is continuous on [a, b].
- (ii) f(x) is continuous on a range of g.
- (iii) u = g(x) is the transformation

This process is also called u-substitution.

#### **Example:**

(a) 
$$\int_0^4 \sqrt{3x+4} \, dx$$

### Transformations in Two Variables



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We consider a change of variables given by the transformation T from the (u, v) plane to the (x, y) plane.

$$\iint\limits_R f(x,y)dx\,dy = \iint\limits_S g(u,v)dv\,du$$

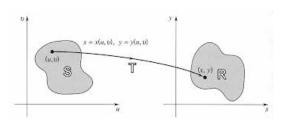
#### **Transformations**

- A function F that maps  $R^2 \to R^2$  is called "one-to-one" if  $\forall (u, v)$  in the domain of F on the (u, v) plane,  $\exists$  only one (x, y) in the (x, y) plane.
- The transformation T is given by

$$T(u, v) = (x, y) \text{ or } x = g(u, v), y = h(u, v)$$

- If T(u, v) = (x, y), then  $(x_1, y_1)$  is the image of  $(u_1, v_1)$  under the transformation T. If no two points have the same image, T is one-to-one.
- T is a  $C^1$  transformation which means that g and h have continuous 1st order partials.

### **Transformations**



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- T transforms S into a region R in the (x, y) plane called the image of S.
- T is said to be "onto" R if each point in R is the image of some point in S.
- A transformation T that is one-to-one and onto is invertable, denoted by  $T^{-1}$ .

$$T^{-1}(x, y) = (u, v) \text{ or } u = G(x, y), v = H(x, y)$$



### Is T Invertible?

#### How do you tell if *T* is invertible

- (1) Given that x = g(u, v) and y = h(u, v), take all the partial derivatives of x and y with respect to u and v.
- (2) Form the Jacobian, J = |M|, of the transformation which is the determinate of the matrix

$$M = \begin{bmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{bmatrix} \text{ giving } J = |M| = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u}$$

(3) If  $J \neq 0$  then  $T^{-1}$  exists.

#### **Example:**

(a) *T* is given by  $x = u^2 - v^2$  and y = 2uv. If  $S = \{(u, v) | 0 \le u \le 1, 0 \le v \le 1\}$ . Is *T* invertible?



# Finding the Image of S Under T

#### How do we find R?

- Need to find new limits of integration
- Process is to work along the boundaries of S and determine what happens on the (x, y) plane.

#### **Example:**

- (a) *T* is given by  $x = u^2 v^2$  and y = 2uv. If  $S = \{(u, v) | 0 \le u \le 1, 0 \le v \le 1\}$ . Find region *R*.
- (b) T is given by u = x + y and v = x y. If  $R = \{(x, y) | 0 \le x \le 1, 0 \le y \le 1\}$ . Find region S.

### Change of Variables Formula

If the following applies:

- (i) T is invertible. (Namely  $J \neq 0$ .)
- (ii) T is  $C^1$ .
- (iii) T maps region S in (u, v) plane onto region R in (x, y) plane.
- (iv) f is continuous in R.
- (v) R and S are Type I or Type II regions

Then we can apply the change of variables formula:

$$\iint\limits_R f(x,y)dy\,dx = \iint\limits_S f[g(u,v),h(u,v)]|J|dv\,du$$

#### **Example:**

(a) T is given by  $x = u^2 - v^2$  and y = 2uv. If  $S = \{(u, v) | 0 \le u \le 1, 0 \le v \le 1\}$ . Express and evaluate the integral  $\iint_{\Omega} y dy \, dx$  in terms of (u, v).