FYS3150 - Project 4 - The ising model

Mari Dahl Eggen

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Abstract

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1 Introduction

2 Theory

2.1 The ising model in 2x2-lattice

In the 2x2 Ising model we can find the analytical expression for the systems partition function, and its mean expressions for energy, specific heat capacity, magnetization and susceptibility, in a feasible way. For bigger systems this is also possible, but it will take quite some time to finish, because the possible spin combinations in the system will grow rapidly with the size of the system.

2.1.1 Energy states and partition function

We are looking at the Ising model in two dimensions without an external magnetic field. An energy state on its simplest form is expressed as

$$E_i = -J \sum_{\langle kl \rangle}^N s_k s_l,\tag{1}$$

where $s_{k,l} = \pm 1$ is a given spin, N = 4 is the total number of spins and J is a coupling constant expressing the strength of the interaction between neighboring spins. We assume that J > 0, that is, the system has a ferromagnetic ordering. The symbol $\langle kl \rangle$ means that we in the sum just sums over the spins $s_{k,l}$ that are nearest neighbors. We will use periodic boundary conditions, which means that spin s_{N+1} corresponds to spin number s_1 in a one dimensional system. Then, by use of Eq. (1), the energy for the 2x2 Ising model is given by

$$E_i = -J \sum_{\langle kl \rangle}^4 s_k s_l = -J \left(s_1 s_2 + s_1 s_3 + s_2 s_1 + s_2 s_4 + s_3 s_1 + s_3 s_4 + s_4 s_3 + s_4 s_2 \right)$$
$$-J \left(2s_1 s_2 + 2s_2 s_3 + 2s_3 s_4 + 2s_4 s_1 \right),$$

where $s_i = 1$ corresponds to spin up and $s_i = -1$ corresponds to spin down. All the possible combinations of spin, which corresponds to all the possible energy states, are listed in Figure 1. We can see that there is 16 possible energy states, and each of those is listed in Table 1. Now that we know what the possible energy states are, we can find the partition function for the 2x2 spin system. In general the partition function is given by

$$Z = \sum_{i=1}^{M} e^{-\beta E_i} = \sum_{E} \Omega(E_i) e^{-\beta E_i},$$
(2)

where M=16 is the number of microstates, which corresponds to the number of possible energy states in the system. $e^{-\beta E_i}$ is a given probability distribution where $\beta=\frac{1}{kT}$, where k is the Boltzmann constant and T is the temperature of the system. The first sum in Eq. (2) is the same as summing over the possible energies -8J,0,8J, and multiply by the corresponding multiplicity $\Omega(E_i)$ of the given energy. Then we have

$$Z = \sum_{E} \Omega(E_i)e^{-\beta E_i} = 2e^{8J\beta} + 12e^0 + 2e^{-8J\beta}.$$

If we use that $\cosh(x) = \frac{1}{2} (e^{-x} + e^x)$, we get

$$Z = 4\cosh(8J\beta) + 12. \tag{3}$$

† † † †	† †	† †	† † †
† †	†	† †	† †
↑ ↓	† †	† †	† †
↓ ↑	↑ ↓	† † †	↓ ↑ †

Figure 1: All the possible spin combinations for a 2x2 spin system.

Row	Column	Energy	Row	Column	Energy
1	1	-8J	3	1	0
1	2	-8J	3	2	0
1	3	0	3	3	0
1	4	0	3	4	0
2	1	0	4	1	0
2	2	0	4	2	0
2	3	0	4	3	8J
2	4	0	4	4	8J

Table 1: The possible energy sates in the 2x2 spin system listed for the different spin combinations in Figure 1.

2.1.2 Mean expressions of energy and specific heat capacity

It can be shown that the mean energy of a thermodynamic system is given by

$$\langle E \rangle = -\frac{\partial}{\partial \beta} \ln Z,\tag{4}$$

and that the mean value of the specific heat capacity is given by

$$\langle C_V \rangle = \frac{1}{kT^2} \frac{\partial^2}{\partial \beta^2} \ln Z,$$
 (5)

where Z is the partition function of the system and $\beta = \frac{1}{kT}$. We use Eq. (3) and (4) to find the mean energy of the 2x2 spin system.

$$\langle E \rangle = -\frac{\partial}{\partial \beta} \ln \left[4 \cosh(8J\beta) + 12 \right] = -\frac{1}{4 \cosh(8J\beta) + 12} \frac{\partial}{\partial \beta} \left[4 \cosh(8J\beta) + 12 \right]$$

$$= -\frac{4 \cdot 8J \sinh(8J\beta)}{4 \cosh(8J\beta) + 12} = -\frac{8J \sinh(8J\beta)}{\cosh(8J\beta) + 3}$$

Then we use Eq. (5) to find the mean of the systems specific heat capacity.

$$\langle C_V \rangle = \frac{1}{kT^2} \frac{\partial^2}{\partial \beta^2} \ln Z = \frac{1}{kT^2} \frac{\partial}{\partial \beta} \left[\frac{\partial}{\partial \beta} \ln Z \right]$$

$$= -\frac{1}{kT^2} \frac{\partial}{\partial \beta} \langle E \rangle = -\frac{1}{kT^2} \frac{\partial}{\partial \beta} \left[-\frac{8J \sinh(8J\beta)}{\cosh(8J\beta) + 3} \right]$$

$$= \frac{1}{kT^2} \left[\frac{64J^2 \cosh(8J\beta) \left(\cosh(8J\beta) + 3 \right) - 8J \sinh(8J\beta) 8J \sinh(8J\beta)}{\left(\cosh(8J\beta) + 3 \right)^2} \right]$$

$$= \frac{1}{kT^2} \left[\frac{64J^2 \cosh(8J\beta)}{\cosh(8J\beta) + 3} - \frac{64J^2 \sinh^2(8J\beta)}{(\cosh(8J\beta) + 3)^2} \right]$$

$$=\frac{64J^2}{kT^2\left(\cosh(8J\beta)+3\right)}\left[\cosh(8J\beta)-\frac{\sinh^2(8J\beta)}{\cosh(8J\beta)+3}\right]$$

2.1.3 Mean expressions of magnetization and susceptibility

The magnetization of a system is simply given by

$$M_i = \sum_{i=1}^{N} s_i,$$

where $s_i = \pm 1$ is a given spin and N = 4 is the total number of spins in the system. If we again use the given probability distribution $e^{-\beta E_i}$, the mean magnetization of the system is given by

$$\langle M \rangle = \frac{1}{Z} \sum_{i=1}^{n} M_i e^{-\beta E_i}, \tag{6}$$

where n = 16 is the number of microstates in the system. Again $s_i = 1$ corresponds to spin up and $s_i = -1$ corresponds to spin down. The magnetization for each of the 16 microstates is given in Table 2, and is linked to Figure 1.

Row	Column	Magnetization	Row	Column	Magnetization
1	1	4	3	1	2
1	2	-4	3	2	2
1	3	-2	3	3	0
1	4	-2	3	4	0
2	1	-2	4	1	0
2	2	-2	4	2	0
2	3	2	4	3	0
2	4	2	4	4	0

Table 2: The possible magnetization values in the 2x2 spin system listed for the different spin combinations in Figure 1.

By use of Eq. (6) and (3), Table 1 and Table 2, we can find the mean magnetization of the 2x2 spin system.

$$\langle M \rangle = \frac{1}{Z} \left[-4e^{8J\beta} - 8e^0 + 8e^0 + 4e^{8J\beta} \right] = 0$$

It is also interesting to look at the absolute value of the magnetization in the system. The mean value of the magnetization in the 2x2 spin system is given by

$$\langle |M| \rangle = \frac{1}{Z} \left[4e^{8J\beta} + 8e^0 + 8e^0 + 4e^{8J\beta} \right] = \frac{16 + 8e^{8J\beta}}{4\cosh(8J\beta) + 12} = \frac{4 + 2e^{8J\beta}}{\cosh(8J\beta) + 3}$$

The susceptibility of a thermodynamic system is given by

$$\langle X \rangle = \frac{1}{kT} \left(\langle M^2 \rangle - \langle M \rangle^2 \right).$$
 (7)

To find $\langle X \rangle$ we have to find an expression for $\langle M^2 \rangle$ first. We can use Eq. (6) to find $\langle M^2 \rangle$, if we replace M with M^2 .

$$\langle M^2 \rangle = \frac{1}{Z} \left[16e^{8J\beta} + 16e^0 + 16e^0 + 16e^{8J\beta} \right] = \frac{32}{Z} \left(e^{8J\beta} + 1 \right)$$

$$= \frac{32 (e^{8J\beta} + 1)}{4 \cosh(8J\beta) + 12} = \frac{8 (e^{8J\beta} + 1)}{\cosh(8J\beta) + 3}$$

Now we can find the mean value of the susceptibility for the 2x2 spin system by use of Eq. (7).

$$\langle X \rangle = \frac{1}{kT} \left(\frac{8 \left(e^{8J\beta} + 1 \right)}{\cosh(8J\beta) + 3} - 0^2 \right) = \frac{8 \left(e^{8J\beta} + 1 \right)}{kT \left(\cosh(8J\beta) + 3 \right)},$$

or, if we use the mean of the absolute value of the magnetization, we get

$$\langle |X| \rangle = \frac{1}{kT} \left(\frac{8 \left(e^{8J\beta} + 1 \right)}{\cosh(8J\beta) + 3} - \left(\frac{4 + 2e^{8J\beta}}{\cosh(8J\beta) + 3} \right)^2 \right).$$

2.2 The Monte Carlo process

To pick the most appropriate selection of random states in the Monte Carlo simulation of a evolving system according to the given probability distribution $e^{-\beta E_i}$, Markov Chains and the Metropolis algorithm with detailed balance can be used.

2.2.1 Markov Chains

A Markov process generates random states by use of random walks that depends on a chosen probability distribution. A move from one random state to another is independent of the previous history of the system. This leads to that we reaches the most probable state of a system, if we choose a random state, and performs a Markov process for a long enough time. In our case the probability distribution is $w_i(t) = e^{-\beta E_i}$. The time development of our probability distribution, where t = 1 in this case is one Monte Carlo cycle, is given by

$$w_i(t=1) = W(j \to i)w_j(t=0) = W_{ji}w_j(t=0),$$

where W_{ji} is called the transition probability, and is represented by a matrix. Thus, in general vector-matrix representation we have that

$$\hat{\boldsymbol{w}}(t+1) = \hat{\boldsymbol{W}}\hat{\boldsymbol{w}}(t).$$

The system is said to be in the most probable state when $||\hat{\boldsymbol{w}}(t+1) - \hat{\boldsymbol{w}}(t)|| \to 0$. In this case, and in most other cases, the transition matrix is not known because of complicated behavior of the system. Then we have to use the Metropolis algorithm to get anywhere at all.

2.2.2 The Metropolis Algorithm and Detailed Balance

In thermodynamics, this means that after a certain number of Markov processes we reach an equilibrium distribution. This mimicks the way a real system reaches its most likely state at a given temperature of the surroundings.

To reach this distribution, the Markov process needs to obey two important conditions, that of ergodicity and detailed balance. These conditions impose constraints on our algorithms for accepting or rejecting new random states. The Metropolis algorithm discussed here abides to both these constraints and is discussed in more detail in Section 12.5. The Metropolis algorithm is widely used in Monte Carlo simulations of physical systems and the understand- ing of it rests within the interpretation of random walks and Markov processes. However, before we do that we discuss the intimate link between random walks, Markov processes and the diffusion

equation. In section 12.3 we show that a Markov process is nothing but the discretized version of the diffusion equation. Diffusion and random walks are discussed from a more experimental point of view in the next section. There we show also a simple algorithm for random walks and discuss eventual physical implications. We end this chapter with a discussion of one of the most used algorithms for generating new steps, namely the Metropolis algorithm. This algorithm, which is based on Markovian random walks satisfies both the ergodicity and detailed balance requirements and is widely in applications of Monte Carlo simulations in the natural sciences. The Metropolis algorithm is used in our studies of phase transitions in statistical physics and the simulations of quantum mechanical systems.

3 Method

3.1 Dimensionless variables

3.2 Evolution of the system

In order to reach the equilibrium state of the system in an efficient way, we choose to flip one spin at a time in the evolution of the system. We choose to do it this way because we then only have five possible changes in the energy per flip, namely $\Delta E = -8J, -4J, 0, 4J, 8J$. This comes from the fact that $\Delta E = E_2 - E_1$, and we can show it by use of Eq. (1).

$$\Delta E = E_2 - E_1 = J \sum_{\langle kl \rangle}^{N} s_k^1 s_l^1 - J \sum_{\langle kl \rangle}^{N} s_k^2 s_l^2$$

$$= -J \sum_{\langle kl \rangle}^{N} s_k^2 (s_l^2 - s_l^1),$$

where we have used that $s_l^1=1$ if $s_l^2=-1$, and vice versa. The nearest neighbors $s_k^1=s_k^2$ keeps their values because we only flips one spin at a time. Thus, if $s_l^1=1$ we have $s_l^1-s_l^2=2$, and if $s_l^1=-1$ we have $s_l^1-s_l^2=-2$, which gives us the relation

$$\Delta E = 2Js_l^1 \sum_{\langle kl \rangle}^N s_k.$$

From this relation we see that we only have the five possible values of change in energy per flip, which means that we can precalculate the possible values of the probability $e^{-\beta \Delta E_i}$. This relation also makes it easy to update the energy during the evolution of the simulated system. We can do a similar deriving for the new magnetization values of the simulated system, then vi get that

$$M_2 = M_1 + 2s_l^2.$$

4 Results and discussion

4.1 Comparison of data for low temperature

	Analytical data
$\langle E/J \rangle$	-1.99598
$\langle C_V/k \rangle$	0.0320823
$\langle M \rangle$	0.998661
$\langle X J\rangle$	0.00401074

Table 3: Analytically calculated data for dimensionless energy, specific heat capacity, absolute magnetization and absolute susceptibility respectively. Low temperature corresponds to $\frac{kT}{I} = 1$.

$\# ext{ MC cycles} = 10^2$			$\# ext{ MC cycles} = 10^5$			
	Data	Relative error		Data	Relative error	
E/J	-2	0.0020	E/J	-1.996	8.9680e - 06	
C_V/k	0	-1	C_V/k	0.031936	-0.0046	
M	1	0.0013	M	0.99873	6.9363e - 05	
X J	0	-1	X J	0.00361355	-0.0990	
	# MC cycl	$ m es=10^3$	$\# ext{ MC cycles} = 10^6$			
E/J	-1.998	0.0010	E/J	-1.99566	-1.5937e - 04	
C_V/k	0.015984	-0.50	C_V/k	0.0346128	0.0789	
M	0.999	0.00034	M	0.998557	-1.0337e - 04	
X J	0.003996	-0.0037	X J	0.00431068	0.0748	
	$\# ext{ MC cycles} = 10^4$			$\# ext{ MC cycles} = 10^7$		
E/J	-1.993	-0.0015	E/J	-1.99596	-9.5692e - 06	
C_V/k	0.055804	0.7394	C_V/k	0.032234	0.0047	
M	0.99765	-0.0010	M	0.998653	-7.7904e - 06	
X J	0.00707791	0.7647	X J	0.00403824	0.0069	

Table 4: Numerically calculated data for dimensionless energy, specific heat capacity, absolute magnetization and absolute susceptibility respectively. Low temperature corresponds to $\frac{kT}{J} = 1$. The data is calculated for different number of Monte Carlo cycles (MC cycles), and the relative error for all data are listed.

5 Conclusion