

A (5 fields)

A. sup (54 fields)

- year frequency-kHz
- month sample rate - Hz
- day bins
- hour nbins
- minute binsize - cm
- second blank - cm

A. Nav (35 fields) (each field has

A. wate (17 fields) (29 rows x 358 columns x 4)

A. Sensor (5 fields)

A. Q (20 fields)

A. Wat

A. Sensor

buhrnatter,
correlation
bin depth

sensor-type
pitch - deg
roll - deg
heading - deg
temp - degC

V mag
V Mag - ms
V Div

V East
V East - ms
V North
V North - ms
V Vert
V Vert - ms

V Error
V Error - ms
beamfreq
Percent used

velocity correction source

A. Nav

bV East - lat - deg
bV Error long - deg
bV North n Satn
bV Vert htop

bV East - ms depth source
bV Error - ms performed depth source
bV North - ms bV Beam 1
bV Vert - ms bV Beam 2
bV Beam 3

depth
bS Depth

drag
length
tot dist north

altitude
altitude change
GPS to Dist

GPS Variable
GPS nearest
GPS North

GPS heading
GPS bearing

HH: mm:ss: Day

HH: mm:ss: Day

HH: mm:ss: Day

HH: mm:ss: Day

HH: mm:ss: Day

sum top end
Bottom track lat
Form, Formy Formy
Formy, direction
Bottom track, angle
avg - V Div
altitude - depth
Altitude - 2 - time stamp
bottom track - time stamp
no error in Sag

draft - cm
mounting depth - m
mounting angle
bin size - m
blacking - m
draft - m
error
ningo
358 columns
vector

avg - V Div
altitude - depth
Altitude - 2 - time stamp
bottom track - time stamp
no error in Sag

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