

# Monocular depth estimation

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# Overview

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- 6 Results

# Depth estimation from a single image

- Ill posed problem
- Supervised learning works
- But requires ground truth depth
- Lidar sensors - expensive...

# Solution

- Self-supervised learning
- Image reconstruction is the supervisory signal
- Stereo
- Monocular video
  - We have to estimate camera pose

# In general

- No labels
- Supervision comes from data

# Example

ImageNet-trained CNNs are biased towards texture; increasing shape bias improves accuracy and robustness (2018.)



(a) Texture image  
81.4% **Indian elephant**  
10.3% indri  
8.2% black swan



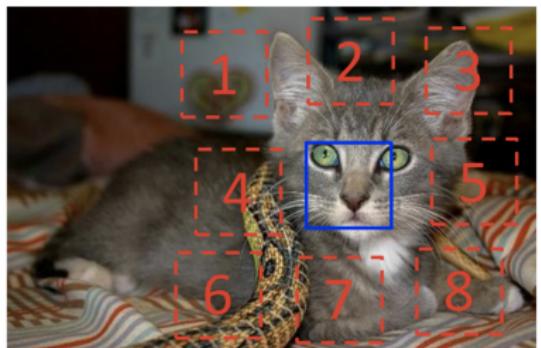
(b) Content image  
71.1% **tabby cat**  
17.3% grey fox  
3.3% Siamese cat



(c) Texture-shape cue conflict  
63.9% **Indian elephant**  
26.4% indri  
9.6% black swan

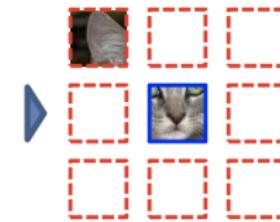
# Example

Unsupervised Visual Representation Learning by Context Prediction  
(2015.)



$$X = (\underset{\text{Image}}{\text{cat eye}}, \underset{\text{Image}}{\text{cat nose}}); Y = 3$$

Example:



Question 1:



?

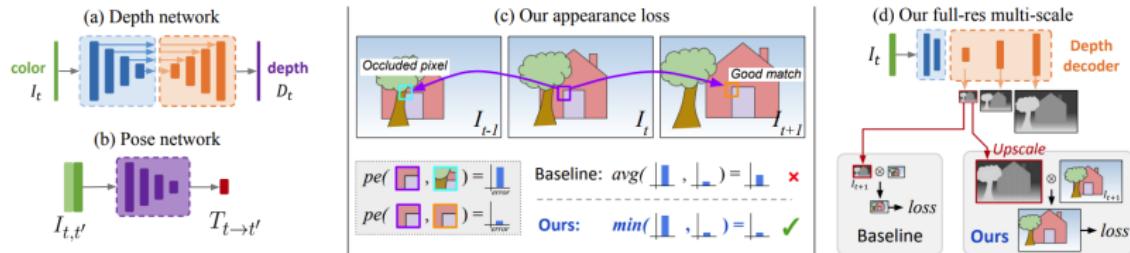
Question 2:



?

# Monodepth2

Digging Into Self-Supervised Monocular Depth Estimation (2018.)

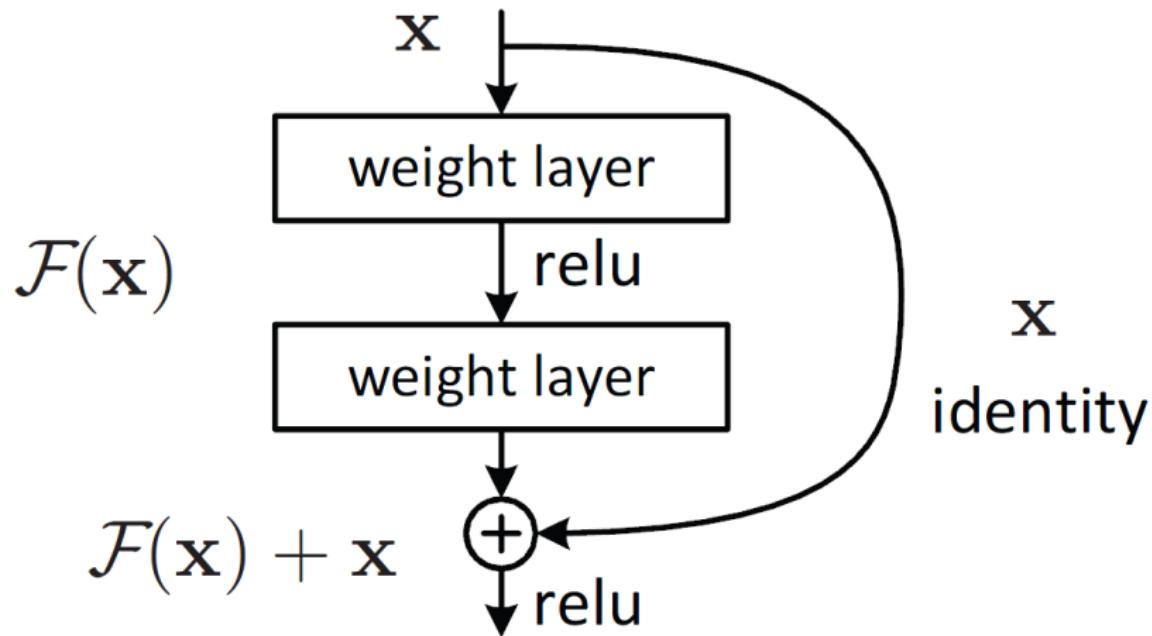


# Improvements

- Minimum reprojection loss
- Auto-masking stationary pixels
- Multi-scale estimation

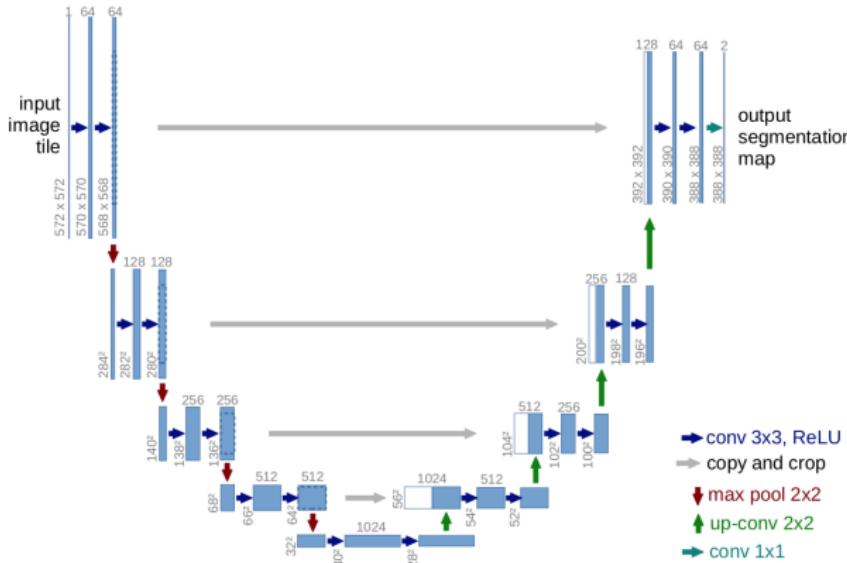
## Resnet

Deep Residual Learning for Image Recognition (2015.)



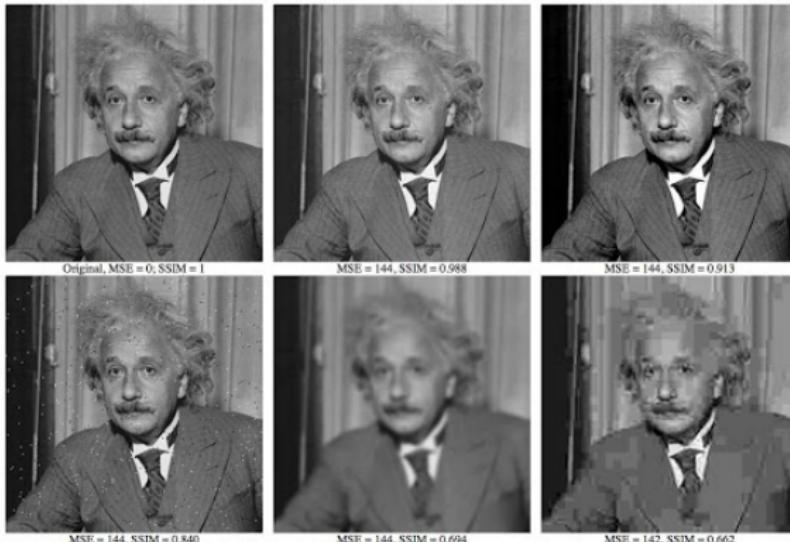
# U-Net

## U-Net: Convolutional Networks for Biomedical Image Segmentation (2015.)



# SSIM

## Image Quality Assessment: From Error Visibility to Structural Similarity (2004.)



# Bilinear sampling

Spatial Transformer Networks (2015.)

$$V_i^c = \sum_n^H \sum_m^W U_{nm}^c k(x_i^s - m; \Phi_x) k(y_i^s - n; \Phi_y) \quad \forall i \in [1 \dots H'W'] \quad \forall c \in [1 \dots C]$$

# KITTI

- Raw dataset 175 GB
- Odometry dataset 65 GB
- ...

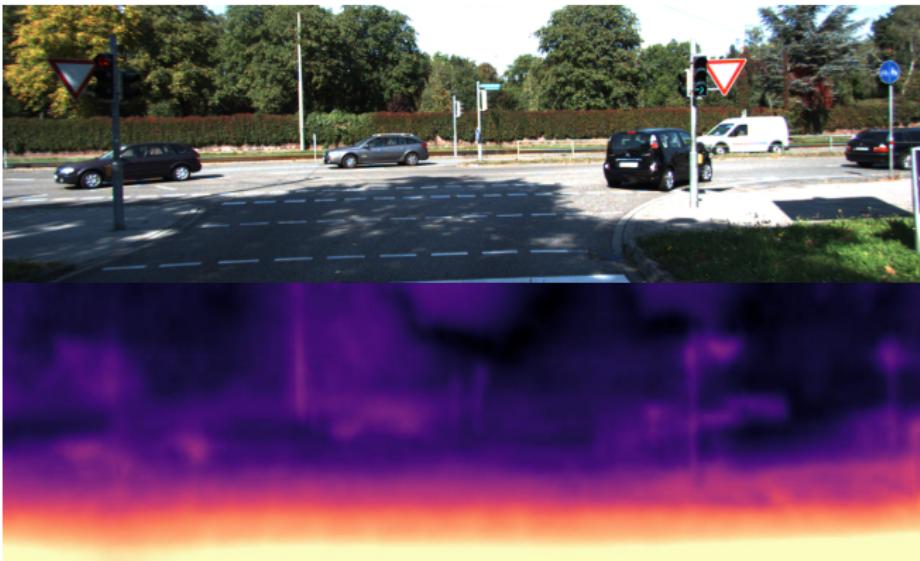
# Keras problems

- No ResNet 18 (github?)
- U-Net architecture
- ...

# Pytorch

- Original implementation
- Our adaptation
- Split

# Example



# Comparison

