

# Multiscale testing for equality of nonparametric trend curves

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Workshop on panel data

Tinbergen Institute & University of Amsterdam

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# Introduction

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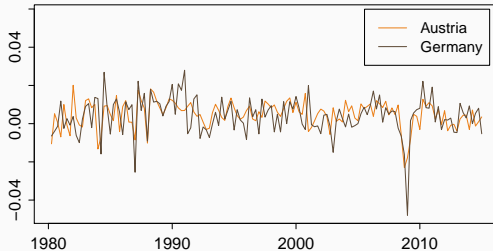
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To develop new inference methods that allow to *identify* and *locate* differences between nonparametric trend curves with dependent errors.

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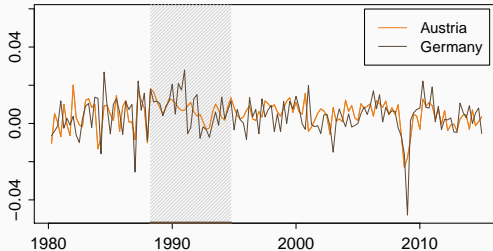
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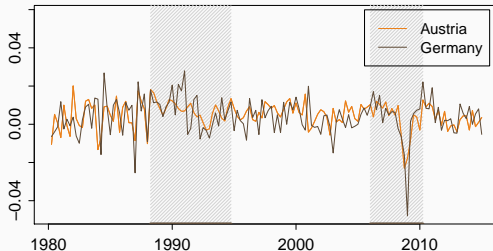
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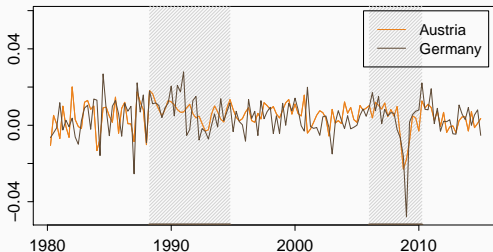
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# Motivation

## Aim of the paper

To develop new inference methods that allow to *identify* and *locate* differences between nonparametric trend curves with dependent errors.



**Research question:** Out of many given intervals, how to find those where the trends are significantly different?



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Finding systematic differences between trends = basis for further research.

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Testing many hypotheses at the same time = multiple testing problem  
⇒ large probability of one true null hypothesis being rejected.

## **Is it limited to a particular application?**

No! Our method = general method for comparing nonparametric trends  
⇒ new statistical test for equality of nonparametric trend curves.

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- Targeted students
  - Strong background in mathematics (statistics)
  - Interest for developing new statistical methods

# Model

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We observe a panel of  $n$  time series  $\mathcal{Z}_i = \{(Y_{it}, \mathbf{X}_{it}) : 1 \leq t \leq T\}$  of length  $T$ , where  $Y_{it} \in \mathbb{R}$  and  $\mathbf{X}_{it} \in \mathbb{R}^d$ .

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- $\mathcal{E}_i = \{\varepsilon_{it} : 1 \leq t \leq T\}$  is a zero-mean stationary and causal error process.

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If we knew  $\alpha_i$  and  $\beta_i$ , then the model becomes much simpler:

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But given  $\hat{\alpha}_i$  and  $\hat{\beta}_i$ , we can consider

$$\hat{Y}_{it} := Y_{it} - \hat{\alpha}_i - \hat{\beta}_i^\top \mathbf{X}_{it} = (\beta_i - \hat{\beta}_i)^\top \mathbf{X}_{it} + m_i\left(\frac{t}{T}\right) + (\alpha_i - \hat{\alpha}_i) + \varepsilon_{it}.$$

## Model, part 3

1. We estimate  $\beta_i$ :

$$\hat{\beta}_i = \left( \sum_{t=2}^T \Delta \mathbf{x}_{it} \Delta \mathbf{x}_{it}^\top \right)^{-1} \sum_{t=2}^T \Delta \mathbf{x}_{it} \Delta Y_{it}$$

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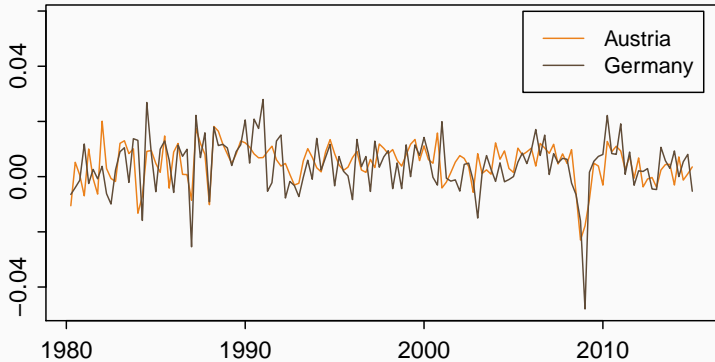
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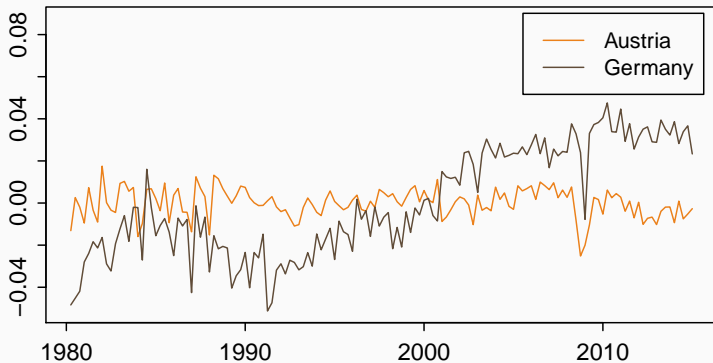
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We then work with the augmented time series  $\hat{Y}_{it} = Y_{it} - \hat{\alpha}_i - \hat{\beta}_i^\top \mathbf{x}_{it}$ .

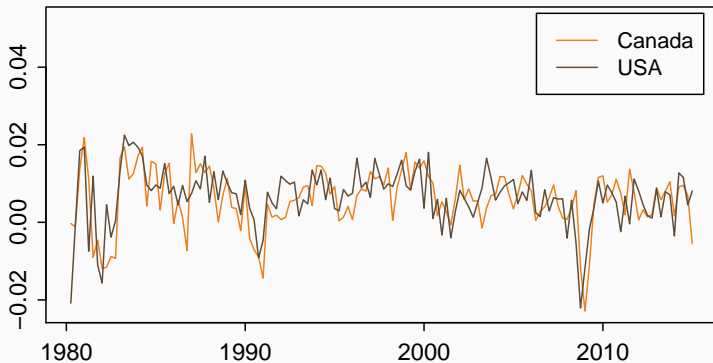
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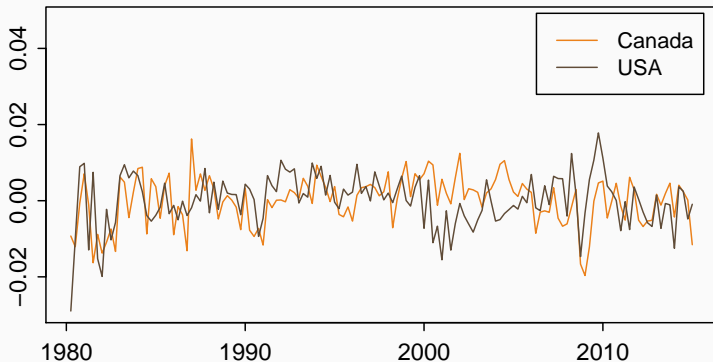
# Augmented time series: Austria and Germany



# Original time series: Canada and USA



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# Testing procedure

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$$H_0^{[i,j]}(u, h) : m_i(w) = m_j(w) \text{ for all } w \in [u - h, u + h].$$

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Then the global null  $H_0 : m_1 = m_2 = \dots = m_n$  can be reformulated as

$$H_0 : \text{The hypotheses } H_0^{[i,j]}(u, h) \text{ hold true for all intervals } [u - h, u + h], (u, h) \in \mathcal{G}_T, \text{ and for all } 1 \leq i < j \leq n.$$

# Test statistic

For a given location  $u \in [0, 1]$  and bandwidth  $h$  and a given pair  $(i, j)$  we construct the kernel averages

$$\hat{\psi}_{ij,T}(u, h) = \sum_{t=1}^T w_{t,T}(u, h) (\hat{Y}_{it} - \hat{Y}_{jt}),$$

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where

$$w_{t,T}(u, h) = \frac{\Lambda_{t,T}(u, h)}{\{\sum_{t=1}^T \Lambda_{t,T}^2(u, h)\}^{1/2}},$$

$$\Lambda_{t,T}(u, h) = K\left(\frac{t/T - u}{h}\right) \left[ S_{T,2}(u, h) - S_{T,1}(u, h) \left(\frac{t/T - u}{h}\right) \right],$$

$$S_{T,\ell}(u, h) = \frac{1}{Th} \sum_{t=1}^T K\left(\frac{t/T - u}{h}\right) \left(\frac{t/T - u}{h}\right)^\ell$$

for  $\ell = 1, 2$  and  $K$  is a kernel function.

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Instead with working directly with  $\widehat{\psi}_{ij,\tau}(u, h)$ , we replace them by

$$\widehat{\psi}_{ij,\tau}^0(u, h) = \left\{ \left| \frac{\widehat{\psi}_{ij,\tau}(u, h)}{(\widehat{\sigma}_i^2 + \widehat{\sigma}_j^2)^{1/2}} \right| - \lambda(h) \right\},$$



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- $\hat{\sigma}_i^2$  is an appropriate estimator of the long-run variance  $\sigma_i^2$ ;
- $\lambda(h) = \sqrt{2 \log\{1/(2h)\}}$  is an additive correction term (Dümbgen and Spokoiny (2001)).

To test the global null, we aggregate the individual test statistics for all  $(i, j)$  and all location-bandwidth pairs  $(u, h) \in \mathcal{G}_T$ :

$$\hat{\Psi}_{n,T} = \max_{1 \leq i < j \leq n} \max_{(u,h) \in \mathcal{G}_T} \hat{\psi}_{ij,T}^0(u, h).$$

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### Main theoretical result

Under certain conditions and under the null,  $\widehat{\psi}_{ij,T}^0(u, h)$  and  $\widehat{\Psi}_{n,T}$  can be approximated by the corresponding Gaussian versions of the test statistics.

Gaussian version of the individual test statistics:

$$\phi_{ij,T}^0(u, h) = \max_{(u,h) \in \mathcal{G}_T} \left\{ \left| \frac{\phi_{ij,T}(u, h)}{(\sigma_i^2 + \sigma_j^2)^{1/2}} \right| - \lambda(h) \right\},$$

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Aggregated Gaussian test statistics:

$$\Phi_{n,T} = \max_{1 \leq i < j \leq n} \max_{(u,h) \in \mathcal{G}_T} \phi_{ij,T}^0(u, h).$$

1. Consider the Gaussian test statistic

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4. For each  $i, j$ , and each  $(u, h) \in \mathcal{G}_T$ , carry out the test for the local null hypothesis  $H_0^{[i,j]}(u, h)$ : reject  $H_0^{[i,j]}(u, h)$  if  $\hat{\psi}_{ij,T}^0(u, h) > q_{n,T}(\alpha)$ .

# Theoretical properties

---

$\mathcal{C}1$  For all  $i$  it holds that  $\mathbb{E}[\varepsilon_{it}] = 0$  and  $\|\varepsilon_{it}\|_q < \infty$  for some  $q > 4$ .



# Assumptions

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$\mathcal{C}2$  For each  $i$  the variables  $\varepsilon_{it}$  are weakly dependent. [Details](#)

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*Under C1 – C10 and under the null, it holds that*

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## Proposition

*Consider a sequence of functions  $m_i = m_{i,T}$ ,  $m_j = m_{j,T}$  such that*

$$\exists (u, h) \in \mathcal{G}_T : m_i(w) - m_j(w) \geq c_T \sqrt{\log T / (Th)} \quad \forall w \in [u - h, u + h],$$

*and  $c_T \rightarrow \infty$ . Then under  $\mathcal{C}1 - \mathcal{C}10$ , it holds that*

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# Illustration

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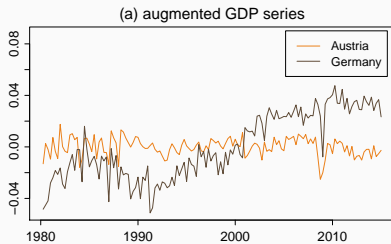
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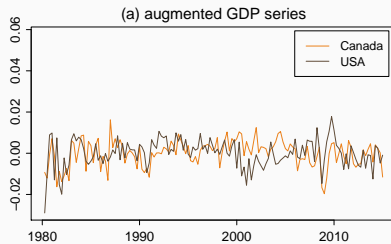
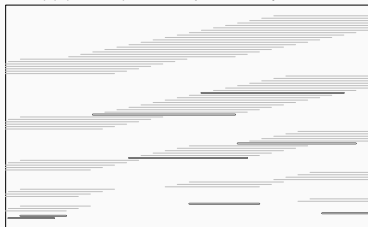
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An interval  $[u - h, u + h]$  is called **minimal** if the corresponding local null  $H_0^{[i,j]}(u, h)$  is rejected and there is no other interval  $[u' - h', u' + h']$  such that we reject  $H_0^{[i,j]}(u', h')$  and  $[u' - h', u' + h'] \subset [u - h, u + h]$ .

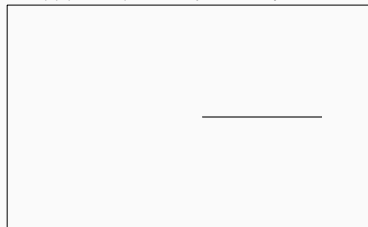
# Application results



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- introduce scaling factor in the trend function;
- include the dependence between covariates and error terms;
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**Thank you!**

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- Show that

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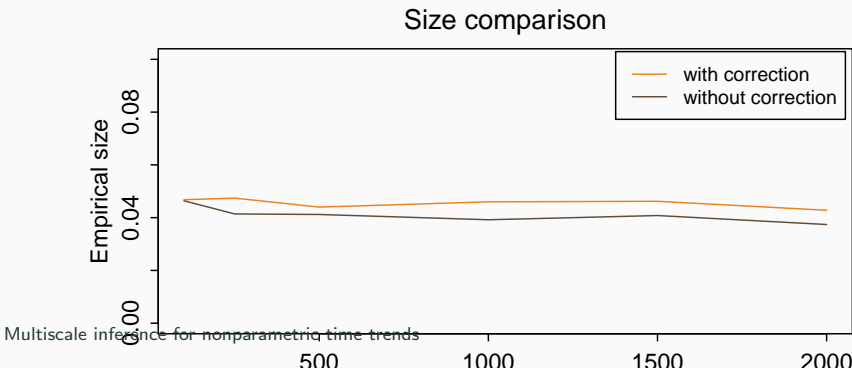
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Introduction of a scale-dependent parameter helps us balance the significance of hypotheses between the time intervals of different lengths  $h_k$ :



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Consider the uncorrected Gaussian statistic

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$\Rightarrow \max_m \dots = \sqrt{2 \log(1/h_l)} + o_P(1) \rightarrow \infty$  as  $h \rightarrow 0$  and the stochastic behavior of  $\Phi^{\text{uncor}}$  is dominated by the elements with small bandwidths  $h_l$ . [Go back](#)

# Dependence measure

Following Wu (2005), we define the *physical dependence measure* for the process  $\mathbf{L}(\mathcal{F}_t)$  as the following:

$$\delta_q(\mathbf{L}, t) = \|\mathbf{L}(\mathcal{F}_t) - \mathbf{L}(\mathcal{F}'_t)\|_q,$$

where  $\mathcal{F}_t = (\dots, \epsilon_{-1}, \epsilon_0, \epsilon_1, \dots, \epsilon_{t-1}, \epsilon_t)$  and  $\mathcal{F}'_t = (\dots, \epsilon_{-1}, \epsilon'_0, \epsilon_1, \dots, \epsilon_{t-1}, \epsilon_t)$  is a coupled process of  $\mathcal{F}_t$  with  $\epsilon'_0$  being an i.i.d. copy of  $\epsilon_0$ .

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Intuitively,  $\delta_q(\mathbf{L}, t)$  measures the dependency of  $\mathbf{L}(\mathcal{F}_t)$  on  $\epsilon_0$ , i.e., how replacing  $\epsilon_0$  by an i.i.d. copy while keeping all other innovations in place affects the output  $\mathbf{L}(\mathcal{F}_t)$ .

# Technical assumptions

- $\mathcal{C}1'$  The variables  $\varepsilon_{it}$  are independent across  $i$  and allow for the representation  $\varepsilon_{it} = G_i(\dots, \eta_{it-1}, \eta_{it})$ , where  $\eta_{it}$  are i.i.d. random variables across  $t$  and  $G_i : \mathbb{R}^{\mathbb{Z}} \rightarrow \mathbb{R}$  is a measurable function..
- $\mathcal{C}1''$  Define  $\Theta_{i,t,q} = \sum_{s \geq t} \delta_q(G_i, s)$  for  $t \geq 0$ . For each  $i$  it holds that  $\Theta_{i,t,q} = O(t^{-\tau_q}(\log t)^{-A})$ , where  $A > \frac{2}{3}(1/q + 1 + \tau_q)$  and  $\tau_q = \{q^2 - 4 + (q - 2)\sqrt{q^2 + 20q + 4}\}/8q$ . [Go back](#)

## Technical assumptions, part 2

$\mathcal{C}3'$   $\mathbf{X}_{it}$  allow for the representation  $\mathbf{X}_{it} = \mathbf{H}_i(\dots, u_{it-1}, u_{it})$  with  $u_{it}$  being i.i.d. random variables and  $\mathbf{H}_i := (H_{i1}, H_{i2}, \dots, H_{id})^\top : \mathbb{R}^Z \rightarrow \mathbb{R}^d$  being a measurable function such that  $\mathbf{H}_i(\mathcal{U}_{it})$  is well defined.

$\mathcal{C}3''$  Let  $\mathbf{N}_i$  be the  $d \times d$  matrix with  $n_{i,kl} = \mathbb{E}[H_{ik}(\mathcal{U}_{i0})H_{il}(\mathcal{U}_{i0})]$  being  $kl$ -th entry. We assume that the smallest eigenvalue of  $\mathbf{N}_i$  is strictly bigger than 0.

$\mathcal{C}3'''$  Let  $\mathbb{E}[\mathbf{H}_i(\mathcal{U}_{i0})] = 0$  and  $\|\mathbf{H}_i(\mathcal{U}_{it})\|_{q'} < \infty$  for some  $q' > \max\{2\theta, 4\}$ , where  $\theta$  will be introduced further.

$\mathcal{C}4'$   $\sum_{s=0}^{\infty} \delta_{q'}(\mathbf{H}_i, s) < \infty$  for  $q'$  from Assumption  $\mathcal{C}3'''$ .

$\mathcal{C}4''$  For each  $i$  it holds that  $\sum_{s=t}^{\infty} \delta_{q'}(\mathbf{H}_i, s) = O(t^{-\alpha})$  for  $q'$  from Assumption  $\mathcal{C}3'''$  and for some  $\alpha > 1/2 - 1/q'$ . [Go back](#)

## Technical assumptions, part 3

C6 Let  $\zeta_{i,t} = (u_{it}, \eta_{it})^\top$ . Denote  $\mathcal{I}_{it} = (\dots, \zeta_{i,t-1}, \zeta_{i,t})$ ,  $\mathcal{J}_{it} = (\dots, \eta_{it-2}, \eta_{it-1}, \eta_{it})$ ,  $\mathcal{U}_{it} = (\dots, u_{it-1}, u_{it})$ , and  $U_i(\mathcal{I}_{it}) = \mathbf{H}_i(\mathcal{U}_{it})G_i(\mathcal{J}_{it})$ . With this notation at hand, we assume that  $\sum_{s=0}^{\infty} \delta_2(U_i, s) < \infty$ . [Go back](#)