Estimation of the Long-run Error Variance in Nonparametric Regression with Time Series Errors

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Introduction

Model

We observe a single time series $\{Y_t : 1 \le t \le T\}$ of length T. The observations come from the following model:

$$Y_t = m\left(\frac{t}{T}\right) + \varepsilon_t$$

- *m* is an unknown trend function on [0, 1];
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Problem

Estimate the long-run error variance $\sigma^2 = \sum_{\ell=-\infty}^{\infty} \operatorname{Cov}(\varepsilon_0, \varepsilon_\ell)$.

Literature

Residual-based approach: estimate σ^2 from the residuals

$$\widehat{\varepsilon}_t = Y_t - \widehat{m}\left(\frac{t}{T}\right)$$

• AR(p) error processes (Truong, 1991; Shao and Yang, 2011; Qiu et al., 2013)

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Difference-based approach: estimate σ^2 from the ℓ -th differences $Y_t - Y_{t-\ell}$.

- AR(p) error processes (Hall and Van Keilegom, 2003)
- MA(m) error processes (Müller and Stadtmüller, 1988; Herrmann et al., 1992; Tecuapetla-Gómez and Munk, 2017)

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where $m(\cdot)$ is Lipshitz and $\{\varepsilon_t\}$ is an AR (p^*) process of the form

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- the error process $\{\varepsilon_t\}$ is stationary and causal;
- the coefficients a_1, a_2, a_3, \ldots decay to zero exponentially fast;
- $\{\varepsilon_t\}$ has an MA(∞) representation of the form $\varepsilon_t = \sum_{k=0}^{\infty} c_k \eta_{t-k}$.

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- $\{\varepsilon_t\}$ has an MA(∞) representation of the form $\varepsilon_t = \sum_{k=0}^{\infty} \frac{c_k}{n_{t-k}}$.

Estimation

Motivation for the estimator

If $\{\varepsilon_t\}$ is an AR (p^*) process, then the time series $\{\Delta_q \varepsilon_t\}$ of the differences $\Delta_q \varepsilon_t = \varepsilon_t - \varepsilon_{t-q}$ is an ARMA (p^*,q) process of the form

$$\Delta_q \varepsilon_t - \sum_{j=1}^{p^*} a_j \Delta_q \varepsilon_{t-j} = \eta_t - \eta_{t-q}.$$

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Then, since the trend function $m(\cdot)$ is Lipshitz, $\Delta_q Y_t = Y_t - Y_{t-q}$ is approximately an ARMA (p^*,q) process.

Yule-Walker equations

For any differencing order $q \ge 1$, we have

$$\gamma_q(\ell) - \sum_{j=1}^{p^\star} a_j \gamma_q(\ell-j) = egin{cases} -
u^2 c_{q-\ell} & ext{ for } 1 \leq \ell < q+1, \\ 0 & ext{ for } \ell \geq q+1. \end{cases}$$

where

- $c_q = (c_{q-1}, \dots, c_{q-p})^{\top}$ are the coefficients from the MA(∞) expansion of $\{\varepsilon_t\}$;
- $\gamma_q = (\gamma_q(1), \dots, \gamma_q(p))^{\top}$ with $\gamma_q(\ell) = \text{Cov}(\Delta_q \varepsilon_t, \Delta_q \varepsilon_{t-\ell});$
- and Γ_q is the $p \times p$ covariance matrix $\Gamma_q = (\gamma_q(i-j) : 1 \le i, j \le p)$.

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In vector notation

$$\mathbf{\Gamma}_{q}\mathbf{a} = \boldsymbol{\gamma}_{q} + \nu^{2}\mathbf{c}_{q}$$

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We construct the first-stage estimator by

$$\widetilde{\mathbf{a}}_q = \widehat{\mathbf{\Gamma}}_q^{-1} \widehat{\mathbf{\gamma}}_q,$$

where $\widehat{\mathbf{\Gamma}}_q$ and $\widehat{\gamma}_q$ are constructed from the sample autocovariances

$$\widehat{\gamma}_q(\ell) = (T-q)^{-1} \sum_{t=q+\ell+1}^T \Delta_q Y_t \Delta_q Y_{t-\ell}.$$

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- Compute estimators \widetilde{c}_k of c_k based on \widetilde{a}_q .
- Estimate the innovation variance ν^2 by $\widetilde{\nu}^2 = (2T)^{-1} \sum_{t=p+2}^T \widetilde{r}_t^2$, where $\widetilde{r}_t = \Delta_1 Y_t \sum_{j=1}^p \widetilde{a}_j \Delta_1 Y_{t-j}$.

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- Estimate **a** by

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• Average the estimators \hat{a}_r : $\hat{a} = \frac{1}{\bar{r} - \underline{r} + 1} \sum_{r=\underline{r}}^{r} \hat{a}_r$.

Problem

If the trend m is pronounced, the estimator \tilde{a}_q will have a strong bias.

Solution:

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- Estimate the innovation variance ν^2 by $\widetilde{\nu}^2 = (2T)^{-1} \sum_{t=p+2}^T \widetilde{r}_t^2$, where $\widetilde{r}_t = \Delta_1 Y_t \sum_{j=1}^p \widetilde{a}_j \Delta_1 Y_{t-j}$.
- Estimate a by

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- Average the estimators \hat{a}_r : $\hat{a} = \frac{1}{\bar{r} \underline{r} + 1} \sum_{r=r}^{\bar{r}} \hat{a}_r$.
- Estimate the long-run variance σ^2 by

$$\widehat{\sigma}^2 = \frac{\widehat{\nu}^2}{(1 - \sum_{j=1}^p \widehat{a}_j)^2}.$$

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- (i) q should be large enough so that $\boldsymbol{c}_q = (c_{q-1}, \dots, c_{q-p})^{\top}$ is close to zero;
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For the consistency, we need log $T \ll q \ll \sqrt{T}$.

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We choose them to be fixed (small) natural numbers. Simulations in the paper.

Theoretical properties

Performance:

• Our estimator \widehat{a} produces accurate estimation results even when the AR polynomial $A(z) = 1 - \sum_{j=1}^{p^*} a_j z^j$ has a root close to the unit circle.

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Proposition

Our estimators \tilde{a}_q , \hat{a} and $\hat{\sigma}^2$ are \sqrt{T} -consistent.

Setting:

- data from the model $Y_t = m(t/T) + \varepsilon_t$, where ε_t is an AR(1) process of the form $\varepsilon_t = a_1 \varepsilon_{t-1} + \eta_t$;
- $a_1 \in \{-0.95, -0.75, -0.5, -0.25, 0.25, 0.5, 0.75, 0.95\};$
- sample size T is 500;
- the trend function is linear $m(u) = \beta u$;
- we generate S = 1000 data samples;
- $q = 25, \underline{r} = 1, \overline{r} = 10;$
- tuning parameters for the estimators from Hall and Van Keilegom (2003) are $m_1 = 20$ and $m_2 = 30$.

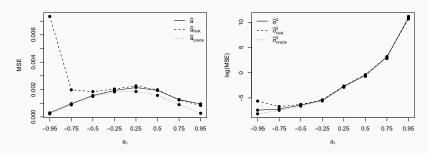


Figure 1: MSE values for the estimators \widehat{a} , \widehat{a}_{HvK} , \widehat{a}_{oracle} and $\widehat{\sigma}^2$, $\widehat{\sigma}^2_{HvK}$, $\widehat{\sigma}^2_{oracle}$ in the simulation scenarios for AR(1) with a moderate trend.

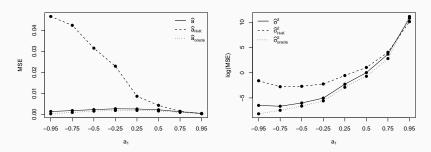


Figure 2: MSE values for the estimators \widehat{a} , \widehat{a}_{HvK} , \widehat{a}_{oracle} and $\widehat{\sigma}^2$, $\widehat{\sigma}^2_{HvK}$, $\widehat{\sigma}^2_{oracle}$ in the simulation scenarios for AR(1) with a pronounced trend.

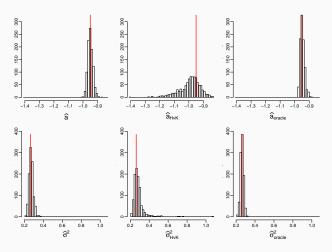


Figure 3: Histograms of the estimators \widehat{a} , \widehat{a}_{HvK} , \widehat{a}_{oracle} and $\widehat{\sigma}^2$, $\widehat{\sigma}^2_{HvK}$, $\widehat{\sigma}^2_{oracle}$ in the AR(1) model with $a_1=-0.95$ and moderate trend.

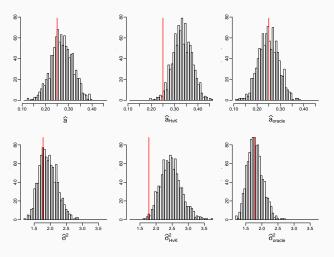


Figure 4: Histograms of the estimators \widehat{a} , \widehat{a}_{HvK} , \widehat{a}_{oracle} and $\widehat{\sigma}^2$, $\widehat{\sigma}^2_{HvK}$, $\widehat{\sigma}^2_{oracle}$ in the AR(1) model with $a_1=0.25$ and pronounced trend.

Conclusion

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- We constructed the long-run variance estimator for a wide range of error processes.
- We proved the \sqrt{T} -consistency for our estimators.
- Our estimator produces accurate estimation results even when the AR polynomial has a root close to the unit circle.
- In the simulations our estimators tend to perform well even in the presence of a strong trend.

References



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Thank you!