

# Multiscale Inference in Nonparametric regression with Time Series Errors

---

Marina Khismatullina <sup>1</sup>   Michael Vogt <sup>1</sup>

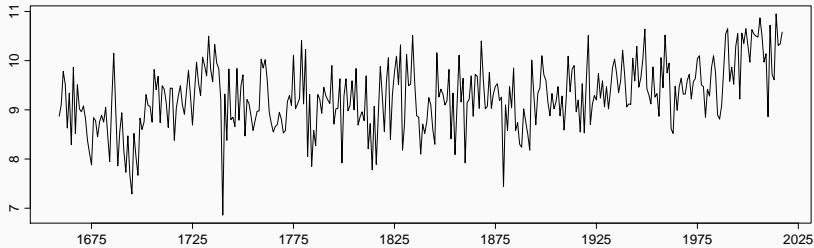
CFE-CMStatistics 2018

<sup>1</sup>University of Bonn

# Introduction

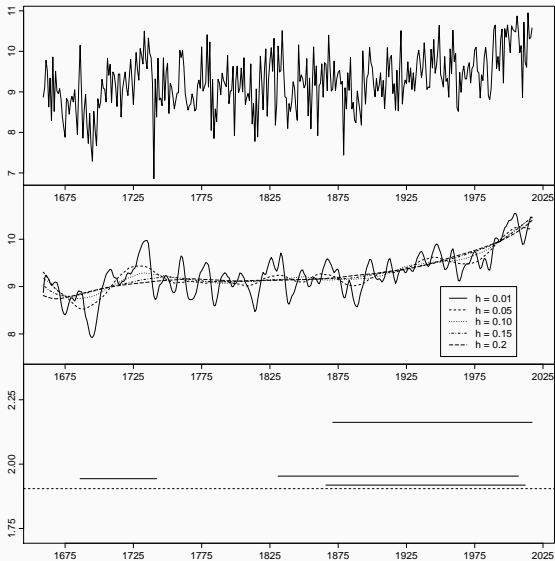
---

# Motivation



**Figure 1:** Yearly mean temperature in Central England from 1659 to 2017

# Motivation



# Model

---

We observe a single time series  $\{Y_t : 1 \leq t \leq T\}$  of length  $T$ . The observations come from the following model:

$$Y_t = m\left(\frac{t}{T}\right) + \varepsilon_t$$

- $m$  is an unknown trend function on  $[0, 1]$ ;
- $\{\varepsilon_t : 1 \leq t \leq T\}$  is a zero-mean stationary error process.

## Multiscale approaches for independent data

- SiZer method (Chaudhuri and Marron, 1999, 2000)
- Testing monotonicity of the trend function (Hall and Heckman, 2000)
- Testing qualitative hypotheses (Dümbgen and Spokoiny, 2001)

## Multiscale approaches for independent data

- SiZer method (Chaudhuri and Marron, 1999, 2000)
- Testing monotonicity of the trend function (Hall and Heckman, 2000)
- Testing qualitative hypotheses (Dümbgen and Spokoiny, 2001)

## Multiscale methods for dependent data

- Extensions to SiZer method (Park et al. 2004, 2009, Rondonotti et al. 2007)



# The multiscale method

---

Testing problem:

$$H_0 : m' = 0$$

$$H_1 : m' \neq 0$$

For a given location  $u \in [0, 1]$  and bandwidth  $h$  we construct the kernel averages

$$\hat{\psi}_T(u, h) = \sum_{t=1}^T w_{t,T}(u, h) Y_t,$$

where

$$w_{t,T}(u, h) = \frac{\Lambda_{t,T}(u, h)}{\{\sum_{t=1}^T \Lambda_{t,T}(u, h)^2\}^{1/2}},$$

$$\Lambda_{t,T}(u, h) = K\left(\frac{t/T - u}{h}\right) \left[ S_{T,0}(u, h) \left(\frac{t/T - u}{h}\right) - S_{T,1}(u, h) \right]$$

$$S_{T,\ell}(u, h) = \frac{1}{Th} \sum_{t=1}^T K\left(\frac{t/T - u}{h}\right) \left(\frac{t/T - u}{h}\right)^\ell$$

for  $\ell = 0, 1, 2$  and  $K$  is a kernel function.

Test statistic is defined as follows

$$\hat{\Psi}_T = \max_{(u,h) \in \mathcal{G}_T} \left\{ \left| \frac{\hat{\psi}_T(u,h)}{\hat{\sigma}} \right| - \lambda(h) \right\},$$

where

- $\lambda(h) = \sqrt{2 \log\{1/(2h)\}}$  is an additive correction term; Idea

Test statistic is defined as follows

$$\hat{\Psi}_T = \max_{(u,h) \in \mathcal{G}_T} \left\{ \left| \frac{\hat{\psi}_T(u,h)}{\hat{\sigma}} \right| - \lambda(h) \right\},$$

where

- $\lambda(h) = \sqrt{2 \log\{1/(2h)\}}$  is an additive correction term; Idea
- $\mathcal{G}_T$  is the set of points  $(u, h)$  that are taken into consideration;

Test statistic is defined as follows

$$\hat{\Psi}_T = \max_{(u,h) \in \mathcal{G}_T} \left\{ \left| \frac{\hat{\psi}_T(u,h)}{\hat{\sigma}} \right| - \lambda(h) \right\},$$

where

- $\lambda(h) = \sqrt{2 \log\{1/(2h)\}}$  is an additive correction term; Idea
- $\mathcal{G}_T$  is the set of points  $(u, h)$  that are taken into consideration;
- $\hat{\sigma}^2$  is an appropriate estimator of the long-run variance  $\sigma^2$ .

Gaussian version of the test statistic:

$$\Phi_T = \max_{(u,h) \in \mathcal{G}_T} \left\{ \left| \frac{\phi_T(u, h)}{\sigma} \right| - \lambda(h) \right\},$$

where

- $\phi_T(u, h) = \sum_{t=1}^T w_{t,T}(u, h) \sigma Z_t$ ;
- $Z_t$  are independent standard normal random variables;
- $q_T(\alpha)$  is  $(1 - \alpha)$  quantile of  $\Phi_T$ .

# Test procedure

Gaussian version of the test statistic:

$$\Phi_T = \max_{(u,h) \in \mathcal{G}_T} \left\{ \left| \frac{\phi_T(u, h)}{\sigma} \right| - \lambda(h) \right\},$$

where

- $\phi_T(u, h) = \sum_{t=1}^T w_{t,T}(u, h) \sigma Z_t$ ;
- $Z_t$  are independent standard normal random variables;
- $q_T(\alpha)$  is  $(1 - \alpha)$  quantile of  $\Phi_T$ .

## Test procedure

For a given significance level  $\alpha \in (0, 1)$ , we reject  $H_0$  if  $\hat{\Psi}_T > q_T(\alpha)$ .



# Theoretical properties

---

# Assumptions

$\mathcal{C}1$  The variables  $\varepsilon_t$  are weakly dependent.

# Assumptions

$\mathcal{C}1$  The variables  $\varepsilon_t$  are weakly dependent.

$\mathcal{C}2$  It holds that  $\|\varepsilon_t\|_q < \infty$  for some  $q > 4$ .

# Assumptions

- $\mathcal{C}1$  The variables  $\varepsilon_t$  are weakly dependent.
- $\mathcal{C}2$  It holds that  $\|\varepsilon_t\|_q < \infty$  for some  $q > 4$ .
- $\mathcal{C}3$  Standard assumptions on the kernel function  $K$ .

# Assumptions

- $\mathcal{C}1$  The variables  $\varepsilon_t$  are weakly dependent.
- $\mathcal{C}2$  It holds that  $\|\varepsilon_t\|_q < \infty$  for some  $q > 4$ .
- $\mathcal{C}3$  Standard assumptions on the kernel function  $K$ .
- $\mathcal{C}4$  Assume that  $\hat{\sigma}^2 = \sigma^2 + o_p(\rho_T)$  with  $\rho_T = o(1/\log T)$ .

# Assumptions

- $\mathcal{C}1$  The variables  $\varepsilon_t$  are weakly dependent.
- $\mathcal{C}2$  It holds that  $\|\varepsilon_t\|_q < \infty$  for some  $q > 4$ .
- $\mathcal{C}3$  Standard assumptions on the kernel function  $K$ .
- $\mathcal{C}4$  Assume that  $\hat{\sigma}^2 = \sigma^2 + o_p(\rho_T)$  with  $\rho_T = o(1/\log T)$ .
- $\mathcal{C}5$   $|\mathcal{G}_T| = O(T^\theta)$  for some arbitrarily large but fixed constant  $\theta > 0$ .

# Assumptions

- $\mathcal{C}1$  The variables  $\varepsilon_t$  are weakly dependent.
- $\mathcal{C}2$  It holds that  $\|\varepsilon_t\|_q < \infty$  for some  $q > 4$ .
- $\mathcal{C}3$  Standard assumptions on the kernel function  $K$ .
- $\mathcal{C}4$  Assume that  $\hat{\sigma}^2 = \sigma^2 + o_p(\rho_T)$  with  $\rho_T = o(1/\log T)$ .
- $\mathcal{C}5$   $|\mathcal{G}_T| = O(T^\theta)$  for some arbitrarily large but fixed constant  $\theta > 0$ .

$$\mathcal{G}_T = \{(u, h) : u = t/T \text{ for some } 1 \leq t \leq T \text{ and } h \in [h_{\min}, h_{\max}] \\ \text{with } h = t/T \text{ for some } 1 \leq t \leq T\},$$

# Assumptions

- $\mathcal{C}1$  The variables  $\varepsilon_t$  are weakly dependent.
- $\mathcal{C}2$  It holds that  $\|\varepsilon_t\|_q < \infty$  for some  $q > 4$ .
- $\mathcal{C}3$  Standard assumptions on the kernel function  $K$ .
- $\mathcal{C}4$  Assume that  $\hat{\sigma}^2 = \sigma^2 + o_p(\rho_T)$  with  $\rho_T = o(1/\log T)$ .
- $\mathcal{C}5$   $|\mathcal{G}_T| = O(T^\theta)$  for some arbitrarily large but fixed constant  $\theta > 0$ .
- $\mathcal{C}6$   $h_{\min} \gg T^{-(1-\frac{2}{q})} \log T$  and  $h_{\max} = o(1)$ .



## Proposition

*Under our assumptions and under  $H_0 : m' = 0$  it holds that*

$$P(\hat{\Psi}_T \leq q_T(\alpha)) = (1 - \alpha) + o(1).$$

## Proposition

*Under our assumptions and under  $H_0 : m' = 0$  it holds that*

$$P(\hat{\Psi}_T \leq q_T(\alpha)) = (1 - \alpha) + o(1).$$

## Proposition

*Under our assumptions and under local alternatives, we have*

$$P(\hat{\Psi}_T \leq q_T(\alpha)) = o(1).$$

# Strategy of the proof

- Replace the statistic  $\widehat{\Psi}_T$  under  $H_0 : m = 0$  by a statistic  $\widetilde{\Phi}_T$  with the same distribution and the property that

$$|\widetilde{\Phi}_T - \Phi_T| = o_p(\delta_T),$$

where  $\delta_T = o(1)$ . To do so, we make use of strong approximation theory for dependent processes as derived in Berkes et al. (2014)

# Strategy of the proof

- Replace the statistic  $\widehat{\Psi}_T$  under  $H_0 : m = 0$  by a statistic  $\widetilde{\Phi}_T$  with the same distribution and the property that

$$|\widetilde{\Phi}_T - \Phi_T| = o_p(\delta_T),$$

where  $\delta_T = o(1)$ . To do so, we make use of strong approximation theory for dependent processes as derived in Berkes et al. (2014)

- Using the anti-concentration results for Gaussian random vectors (Chernozhukov et al. 2015), prove that  $\Phi_T$  does not concentrate too strongly in small regions of the form  $[x - \delta_T, x + \delta_T]$ , i.e.

$$\sup_{x \in \mathbb{R}} \mathbb{P}(|\Phi_T - x| \leq \delta_T) = o(1).$$

# Strategy of the proof

- Replace the statistic  $\widehat{\Psi}_T$  under  $H_0 : m = 0$  by a statistic  $\widetilde{\Phi}_T$  with the same distribution and the property that

$$|\widetilde{\Phi}_T - \Phi_T| = o_p(\delta_T),$$

where  $\delta_T = o(1)$ . To do so, we make use of strong approximation theory for dependent processes as derived in Berkes et al. (2014)

- Using the anti-concentration results for Gaussian random vectors (Chernozhukov et al. 2015), prove that  $\Phi_T$  does not concentrate too strongly in small regions of the form  $[x - \delta_T, x + \delta_T]$ , i.e.

$$\sup_{x \in \mathbb{R}} \mathbb{P}(|\Phi_T - x| \leq \delta_T) = o(1).$$

- Show that

$$\sup_{x \in \mathbb{R}} |\mathbb{P}(\widetilde{\Phi}_T \leq x) - \mathbb{P}(\Phi_T \leq x)| = o(1).$$

Define

$$\Pi_T^+ = \{I_{u,h} = [u-h, u+h] : (u,h) \in \mathcal{A}_T^+ \text{ and } I_{u,h} \subseteq [0,1]\}$$

with

$$\mathcal{A}_T^+ = \left\{ (u,h) \in \mathcal{G}_T : \frac{\hat{\psi}_T(u,h)}{\hat{\sigma}} > q_T(\alpha) + \lambda(h) \right\}$$

Define

$$\Pi_T^+ = \{I_{u,h} = [u - h, u + h] : (u, h) \in \mathcal{A}_T^+ \text{ and } I_{u,h} \subseteq [0, 1]\}$$

$$\Pi_T^- = \{I_{u,h} = [u - h, u + h] : (u, h) \in \mathcal{A}_T^- \text{ and } I_{u,h} \subseteq [0, 1]\}$$

with

$$\mathcal{A}_T^+ = \left\{ (u, h) \in \mathcal{G}_T : \frac{\hat{\psi}_T(u, h)}{\hat{\sigma}} > q_T(\alpha) + \lambda(h) \right\}$$

$$\mathcal{A}_T^- = \left\{ (u, h) \in \mathcal{G}_T : -\frac{\hat{\psi}_T(u, h)}{\hat{\sigma}} > q_T(\alpha) + \lambda(h) \right\}$$

## Proposition

*Under our assumptions, for events*

$E_T^+ = \left\{ \forall I_{u,h} \in \Pi_T^+ : m'(v) > 0 \text{ for some } v \in I_{u,h} \right\}$  *it holds that*

$$\mathbb{P}(E_T^+) \geq (1 - \alpha) + o(1)$$



## Proposition

*Under our assumptions, for events*

$$E_T^+ = \left\{ \forall I_{u,h} \in \Pi_T^+ : m'(v) > 0 \text{ for some } v \in I_{u,h} \right\} \text{ and}$$

$$E_T^- = \left\{ \forall I_{u,h} \in \Pi_T^- : m'(v) < 0 \text{ for some } v \in I_{u,h} \right\} \text{ it holds that}$$

$$P(E_T^+) \geq (1 - \alpha) + o(1)$$

$$P(E_T^-) \geq (1 - \alpha) + o(1)$$

## Minimal intervals

An interval  $I_{u,h} \in \Pi_T^+$  is called **minimal** if there is no other interval  $I_{u',h'} \in \Pi_T^+$  with  $I_{u',h'} \subset I_{u,h}$ .

## Minimal intervals

An interval  $I_{u,h} \in \Pi_T^+$  is called **minimal** if there is no other interval  $I_{u',h'} \in \Pi_T^+$  with  $I_{u',h'} \subset I_{u,h}$ .

Define

$\Pi_T^{min,+}$  = set of minimal intervals from  $\Pi_T^+$ ,

$$E_T^{min,+} = \left\{ \forall I_{u,h} \in \Pi_T^{min,+} : m'(v) > 0 \text{ for some } v \in I_{u,h} \right\}$$

## Minimal intervals

An interval  $I_{u,h} \in \Pi_T^+$  is called **minimal** if there is no other interval  $I_{u',h'} \in \Pi_T^+$  with  $I_{u',h'} \subset I_{u,h}$ .

Define

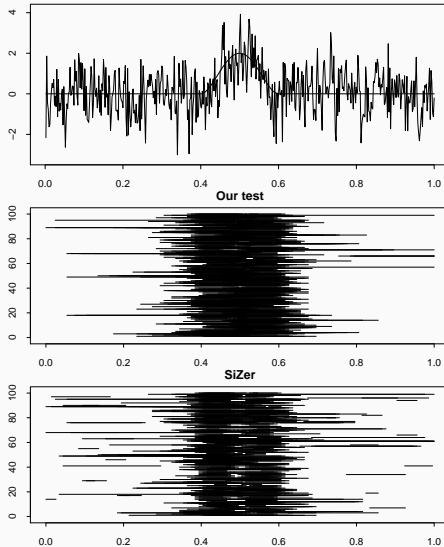
$\Pi_T^{min,+}$  = set of minimal intervals from  $\Pi_T^+$ ,

$$E_T^{min,+} = \left\{ \forall I_{u,h} \in \Pi_T^{min,+} : m'(v) > 0 \text{ for some } v \in I_{u,h} \right\}$$

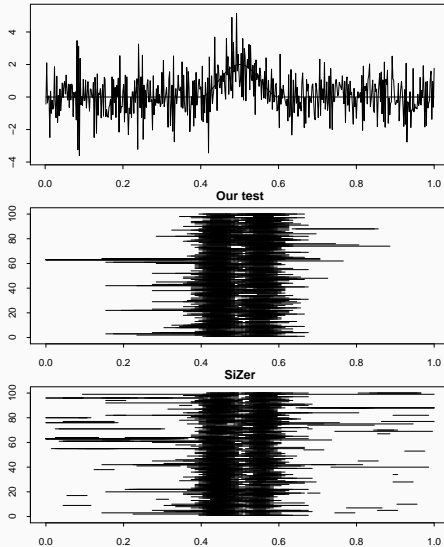
Since  $E_T^{min,+} = E_T^+$ , we have

$$P(E_T^{min,+}) \geq (1 - \alpha) + o(1).$$

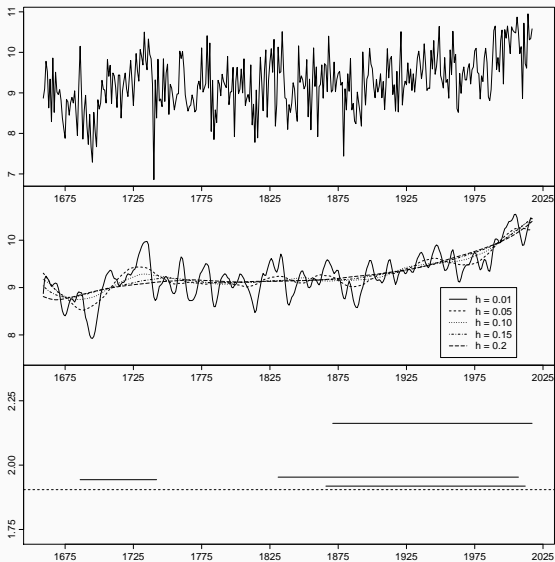
# Graphical representation, $a_1 = 0.25$



# Graphical representation, $a_1 = -0.5$



# Application



# Conclusion

---



We developed multiscale methods to test qualitative hypotheses about nonparametric time trends:

- whether the trend is present at all;
- whether the trend function is constant;
- in which time regions there is an upward/downward movement in the trend.

We derived asymptotic theory for the proposed tests.

As an application of our method, we analyzed the behavior of the yearly mean temperature in Central England from 1659 to 2017.

**Thank you!**

**Long-run error variance estimator**

# Setting

Estimate the long-run error variance  $\sigma^2 = \sum_{\ell=-\infty}^{\infty} \text{Cov}(\varepsilon_0, \varepsilon_\ell)$  of the error terms  $\{\varepsilon_t\}$  in the model

$$Y_t = m\left(\frac{t}{T}\right) + \varepsilon_t,$$

where  $\{\varepsilon_t\}$  is a stationary and causal  $\text{AR}(p)$  process of the form

$$\varepsilon_t = \sum_{j=1}^p a_j \varepsilon_{t-j} + \eta_t.$$

# Setting

Estimate the long-run error variance  $\sigma^2 = \sum_{\ell=-\infty}^{\infty} \text{Cov}(\varepsilon_0, \varepsilon_\ell)$  of the error terms  $\{\varepsilon_t\}$  in the model

$$Y_t = m\left(\frac{t}{T}\right) + \varepsilon_t,$$

where  $\{\varepsilon_t\}$  is a stationary and causal  $\text{AR}(p)$  process of the form

$$\varepsilon_t = \sum_{j=1}^p a_j \varepsilon_{t-j} + \eta_t.$$

- $\mathbf{a} = (a_1, \dots, a_p)$  is a vector of the unknown parameters;

# Setting

Estimate the long-run error variance  $\sigma^2 = \sum_{\ell=-\infty}^{\infty} \text{Cov}(\varepsilon_0, \varepsilon_\ell)$  of the error terms  $\{\varepsilon_t\}$  in the model

$$Y_t = m\left(\frac{t}{T}\right) + \varepsilon_t,$$

where  $\{\varepsilon_t\}$  is a stationary and causal  $\text{AR}(p)$  process of the form

$$\varepsilon_t = \sum_{j=1}^p a_j \varepsilon_{t-j} + \eta_t.$$

- $\mathbf{a} = (a_1, \dots, a_p)$  is a vector of the unknown parameters;
- $\eta_t$  are i.i.d. innovations with  $\mathbb{E}[\eta_t] = 0$  and  $\mathbb{E}[\eta_t^2] = \nu^2$ ;

# Setting

Estimate the long-run error variance  $\sigma^2 = \sum_{\ell=-\infty}^{\infty} \text{Cov}(\varepsilon_0, \varepsilon_\ell)$  of the error terms  $\{\varepsilon_t\}$  in the model

$$Y_t = m\left(\frac{t}{T}\right) + \varepsilon_t,$$

where  $\{\varepsilon_t\}$  is a stationary and causal  $\text{AR}(p)$  process of the form

$$\varepsilon_t = \sum_{j=1}^p a_j \varepsilon_{t-j} + \eta_t.$$

- $\mathbf{a} = (a_1, \dots, a_p)$  is a vector of the unknown parameters;
- $\eta_t$  are i.i.d. innovations with  $\mathbb{E}[\eta_t] = 0$  and  $\mathbb{E}[\eta_t^2] = \nu^2$ ;
- $p$  is known.

## Estimator, first stage

Yule-Walker equations yield

$$\mathbf{\Gamma}_q \mathbf{a} = \gamma_q + \nu^2 \mathbf{c}_q,$$

where

- $\mathbf{c}_q = (c_{q-1}, \dots, c_{q-p})^\top$  are the coefficients from the  $\text{MA}(\infty)$  expansion of  $\{\varepsilon_t\}$ ;



## Estimator, first stage

Yule-Walker equations yield

$$\mathbf{\Gamma}_q \mathbf{a} = \gamma_q + \nu^2 \mathbf{c}_q,$$

where

- $\mathbf{c}_q = (c_{q-1}, \dots, c_{q-p})^\top$  are the coefficients from the  $\text{MA}(\infty)$  expansion of  $\{\varepsilon_t\}$ ;
- $\gamma_q = (\gamma_q(1), \dots, \gamma_q(p))^\top$  with  $\gamma_q(\ell) = \text{Cov}(\Delta_q \varepsilon_t, \Delta_q \varepsilon_{t-\ell})$ ;

## Estimator, first stage

Yule-Walker equations yield

$$\mathbf{\Gamma}_q \mathbf{a} = \boldsymbol{\gamma}_q + \nu^2 \mathbf{c}_q,$$

where

- $\mathbf{c}_q = (c_{q-1}, \dots, c_{q-p})^\top$  are the coefficients from the  $\text{MA}(\infty)$  expansion of  $\{\varepsilon_t\}$ ;
- $\boldsymbol{\gamma}_q = (\gamma_q(1), \dots, \gamma_q(p))^\top$  with  $\gamma_q(\ell) = \text{Cov}(\Delta_q \varepsilon_t, \Delta_q \varepsilon_{t-\ell})$ ;
- and  $\mathbf{\Gamma}_q$  is the  $p \times p$  covariance matrix  $\mathbf{\Gamma}_q = (\gamma_q(i-j) : 1 \leq i, j \leq p)$ .

## Estimator, first stage

Yule-Walker equations yield

$$\mathbf{\Gamma}_q \mathbf{a} = \gamma_q + \nu^2 \mathbf{c}_q,$$

where

- $\mathbf{c}_q = (c_{q-1}, \dots, c_{q-p})^\top$  are the coefficients from the  $\text{MA}(\infty)$  expansion of  $\{\varepsilon_t\}$ ;
- $\gamma_q = (\gamma_q(1), \dots, \gamma_q(p))^\top$  with  $\gamma_q(\ell) = \text{Cov}(\Delta_q \varepsilon_t, \Delta_q \varepsilon_{t-\ell})$ ;
- and  $\mathbf{\Gamma}_q$  is the  $p \times p$  covariance matrix  $\mathbf{\Gamma}_q = (\gamma_q(i-j) : 1 \leq i, j \leq p)$ .

### Note

$\mathbf{\Gamma}_q \mathbf{a} \approx \gamma_q$  for large values of  $q$ .

## Estimator, first stage

Yule-Walker equations yield

$$\mathbf{\Gamma}_q \mathbf{a} = \boldsymbol{\gamma}_q + \nu^2 \mathbf{c}_q,$$

where

- $\mathbf{c}_q = (c_{q-1}, \dots, c_{q-p})^\top$  are the coefficients from the  $\text{MA}(\infty)$  expansion of  $\{\varepsilon_t\}$ ;
- $\boldsymbol{\gamma}_q = (\gamma_q(1), \dots, \gamma_q(p))^\top$  with  $\gamma_q(\ell) = \text{Cov}(\Delta_q \varepsilon_t, \Delta_q \varepsilon_{t-\ell})$ ;
- and  $\mathbf{\Gamma}_q$  is the  $p \times p$  covariance matrix  $\mathbf{\Gamma}_q = (\gamma_q(i-j) : 1 \leq i, j \leq p)$ .

### Note

$\mathbf{\Gamma}_q \mathbf{a} \approx \boldsymbol{\gamma}_q$  for large values of  $q$ .

We construct the first-stage estimator by

$$\tilde{\mathbf{a}}_q = \hat{\mathbf{\Gamma}}_q^{-1} \hat{\boldsymbol{\gamma}}_q,$$

where  $\hat{\mathbf{\Gamma}}_q$  and  $\hat{\boldsymbol{\gamma}}_q$  are constructed from the sample autocovariances

$$\hat{\gamma}_q(\ell) = (T - q)^{-1} \sum_{t=q+\ell+1}^T \Delta_q Y_{t,T} \Delta_q Y_{t-\ell,T}.$$

## Estimator, second stage

### Problem

If the trend  $m$  is pronounced, the estimator  $\tilde{\mathbf{a}}_q$  will have a strong bias.

## Estimator, second stage

### Problem

If the trend  $m$  is pronounced, the estimator  $\tilde{\mathbf{a}}_q$  will have a strong bias.

Solution:

- Compute estimators  $\tilde{c}_k$  of  $c_k$  based on  $\tilde{\mathbf{a}}_q$ .

## Estimator, second stage

### Problem

If the trend  $m$  is pronounced, the estimator  $\tilde{\mathbf{a}}_q$  will have a strong bias.

Solution:

- Compute estimators  $\tilde{c}_k$  of  $c_k$  based on  $\tilde{\mathbf{a}}_q$ .
- Estimate the innovation variance  $\nu^2$  by  $\tilde{\nu}^2 = (2T)^{-1} \sum_{t=p+1}^T \tilde{r}_{t,T}^2$ ,  
where  $\tilde{r}_{t,T} = \Delta_1 Y_{t,T} - \sum_{j=1}^p \tilde{a}_j \Delta_1 Y_{t-j,T}$ .

## Estimator, second stage

### Problem

If the trend  $m$  is pronounced, the estimator  $\tilde{\mathbf{a}}_q$  will have a strong bias.

Solution:

- Compute estimators  $\tilde{c}_k$  of  $c_k$  based on  $\tilde{\mathbf{a}}_q$ .
- Estimate the innovation variance  $\nu^2$  by  $\tilde{\nu}^2 = (2T)^{-1} \sum_{t=p+1}^T \tilde{r}_{t,T}^2$ ,  
where  $\tilde{r}_{t,T} = \Delta_1 Y_{t,T} - \sum_{j=1}^p \tilde{a}_j \Delta_1 Y_{t-j,T}$ .
- Estimate  $\mathbf{a}$  by

$$\hat{\mathbf{a}}_r = \hat{\mathbf{\Gamma}}_r^{-1} (\hat{\gamma}_r + \tilde{\nu}^2 \tilde{\mathbf{c}}_r).$$



## Estimator, second stage

### Problem

If the trend  $m$  is pronounced, the estimator  $\tilde{\mathbf{a}}_q$  will have a strong bias.

Solution:

- Compute estimators  $\tilde{c}_k$  of  $c_k$  based on  $\tilde{\mathbf{a}}_q$ .
- Estimate the innovation variance  $\nu^2$  by  $\tilde{\nu}^2 = (2T)^{-1} \sum_{t=p+1}^T \tilde{r}_{t,T}^2$ ,  
where  $\tilde{r}_{t,T} = \Delta_1 Y_{t,T} - \sum_{j=1}^p \tilde{a}_j \Delta_1 Y_{t-j,T}$ .

- Estimate  $\mathbf{a}$  by

$$\hat{\mathbf{a}}_r = \hat{\mathbf{\Gamma}}_r^{-1} (\hat{\gamma}_r + \tilde{\nu}^2 \tilde{\mathbf{c}}_r).$$

- Average the estimators  $\hat{\mathbf{a}}_r$ :  $\hat{\mathbf{a}} = \frac{1}{\bar{r}} \sum_{r=1}^{\bar{r}} \hat{\mathbf{a}}_r$ .

## Estimator, second stage

### Problem

If the trend  $m$  is pronounced, the estimator  $\tilde{\mathbf{a}}_q$  will have a strong bias.

Solution:

- Compute estimators  $\tilde{c}_k$  of  $c_k$  based on  $\tilde{\mathbf{a}}_q$ .
- Estimate the innovation variance  $\nu^2$  by  $\hat{\nu}^2 = (2T)^{-1} \sum_{t=p+1}^T \tilde{r}_{t,T}^2$ ,  
where  $\tilde{r}_{t,T} = \Delta_1 Y_{t,T} - \sum_{j=1}^p \tilde{a}_j \Delta_1 Y_{t-j,T}$ .

- Estimate  $\mathbf{a}$  by

$$\hat{\mathbf{a}}_r = \hat{\mathbf{\Gamma}}_r^{-1} (\hat{\gamma}_r + \hat{\nu}^2 \tilde{\mathbf{c}}_r).$$

- Average the estimators  $\hat{\mathbf{a}}_r$ :  $\hat{\mathbf{a}} = \frac{1}{\bar{r}} \sum_{r=1}^{\bar{r}} \hat{\mathbf{a}}_r$ .
- Estimate the long-run variance  $\sigma^2$  by

$$\hat{\sigma}^2 = \frac{\hat{\nu}^2}{(1 - \sum_{j=1}^p \hat{a}_j)^2}.$$

# Motivation for the estimator

If  $\{\varepsilon_t\}$  is an  $\text{AR}(p)$  process, then the time series  $\{\Delta_q \varepsilon_t\}$  of the differences  $\Delta_q \varepsilon_t = \varepsilon_t - \varepsilon_{t-q}$  is an  $\text{ARMA}(p, q)$  process of the form

$$\Delta_q \varepsilon_t - \sum_{j=1}^p a_j \Delta_q \varepsilon_{t-j} = \eta_t - \eta_{t-q}.$$

# Motivation for the estimator

If  $\{\varepsilon_t\}$  is an  $\text{AR}(p)$  process, then the time series  $\{\Delta_q \varepsilon_t\}$  of the differences  $\Delta_q \varepsilon_t = \varepsilon_t - \varepsilon_{t-q}$  is an  $\text{ARMA}(p, q)$  process of the form

$$\Delta_q \varepsilon_t - \sum_{j=1}^p a_j \Delta_q \varepsilon_{t-j} = \eta_t - \eta_{t-q}.$$

Then  $\Delta_q Y_{t,T} = Y_{t,T} - Y_{t-q,T}$  is approximately an  $\text{ARMA}(p, q)$  process.

# Theoretical properties of the estimator

Performance:

- Our estimator  $\hat{\mathbf{a}}$  produces accurate estimation results even when the AR polynomial  $A(z) = 1 - \sum_{j=1}^p a_j z^j$  has a root close to the unit circle.

# Theoretical properties of the estimator

Performance:

- Our estimator  $\hat{\mathbf{a}}$  produces accurate estimation results even when the AR polynomial  $A(z) = 1 - \sum_{j=1}^p a_j z^j$  has a root close to the unit circle.
- Our pilot estimator  $\tilde{\mathbf{a}}_q$  tends to have a substantial bias when the trend  $m$  is pronounced. Our estimator  $\hat{\mathbf{a}}$  reduces this bias considerably.

# Theoretical properties of the estimator

Performance:

- Our estimator  $\hat{\mathbf{a}}$  produces accurate estimation results even when the AR polynomial  $A(z) = 1 - \sum_{j=1}^p a_j z^j$  has a root close to the unit circle.
- Our pilot estimator  $\tilde{\mathbf{a}}_q$  tends to have a substantial bias when the trend  $m$  is pronounced. Our estimator  $\hat{\mathbf{a}}$  reduces this bias considerably.

## Proposition

*Our estimators  $\tilde{\mathbf{a}}_q$ ,  $\hat{\mathbf{a}}$  and  $\hat{\sigma}^2$  are  $\sqrt{T}$ -consistent.*

**Testing for equality of the time trends**



# Model

We observe  $n$  time series  $\mathcal{Y}_i = \{Y_{it} : 1 \leq t \leq T\}$  of length  $T$  for  $1 \leq i \leq n$

$$Y_{it} = m_i\left(\frac{t}{T}\right) + \varepsilon_{it}$$

# Model

We observe  $n$  time series  $\mathcal{Y}_i = \{Y_{it} : 1 \leq t \leq T\}$  of length  $T$  for  $1 \leq i \leq n$

$$Y_{it} = m_i\left(\frac{t}{T}\right) + \varepsilon_{it}$$

where

- $m_i$  is an unknown trend function on  $[0, 1]$ , that are Lipschitz continuous and normalized such that  $\int_0^1 m_i(u) du = 0$ ;
- $\mathcal{E}_i = \{\varepsilon_{it} : 1 \leq t \leq T\}$  is a zero-mean stationary error process;
- $\mathcal{E}_i$  are independent across  $i$ .

# Test Statistic

For a given location  $u \in [0, 1]$ , bandwidth  $h$  and a pair of time series  $i$  and  $j$  we construct the kernel averages

$$\hat{\psi}_{ij,T}(u, h) = \sum_{t=1}^T w_{t,T}(u, h)(Y_{it} - Y_{jt}),$$

# Test Statistic

For a given location  $u \in [0, 1]$ , bandwidth  $h$  and a pair of time series  $i$  and  $j$  we construct the kernel averages

$$\hat{\psi}_{ij,T}(u, h) = \sum_{t=1}^T w_{t,T}(u, h)(Y_{it} - Y_{jt}),$$

where

$$w_{t,T}(u, h) = \frac{\Lambda_{t,T}(u, h)}{\{\sum_{t=1}^T \Lambda_{t,T}^2(u, h)\}^{1/2}},$$

$$\Lambda_{t,T}(u, h) = K\left(\frac{t/T - u}{h}\right) \left[ S_{T,2}(u, h) - S_{T,1}(u, h) \left(\frac{t/T - u}{h}\right) \right],$$

$$S_{T,\ell}(u, h) = \frac{1}{Th} \sum_{t=1}^T K\left(\frac{t/T - u}{h}\right) \left(\frac{t/T - u}{h}\right)^\ell$$

for  $\ell = 0, 1, 2$  and  $K$  is a kernel function.

# Test Statistic

Our multiscale statistic is defined as follows

$$\begin{aligned}\widehat{\Psi}_{n,T} &= \max_{1 \leq i < j \leq n} \widehat{\Psi}_{ij,T}, \\ \widehat{\Psi}_{ij,T} &= \max_{(u,h) \in \mathcal{G}_T} \left\{ \left| \frac{\widehat{\psi}_{ij,T}(u,h)}{(\widehat{\sigma}_i^2 + \widehat{\sigma}_j^2)^{1/2}} \right| - \lambda(h) \right\},\end{aligned}$$

where

- $\lambda(h) = \sqrt{2 \log\{1/(2h)\}}$  is an additive correction term;
- $\mathcal{G}_T$  is the set of points  $(u, h)$  that are taken into consideration;
- $\widehat{\sigma}_i^2$  is an appropriate estimator of the long-run variance  $\sigma_i^2$ .

# Test Statistic

Our multiscale statistic is defined as follows

$$\hat{\Psi}_{n,T} = \max_{1 \leq i < j \leq n} \hat{\Psi}_{ij,T},$$
$$\hat{\Psi}_{ij,T} = \max_{(u,h) \in \mathcal{G}_T} \left\{ \left| \frac{\hat{\psi}_{ij,T}(u,h)}{(\hat{\sigma}_i^2 + \hat{\sigma}_j^2)^{1/2}} \right| - \lambda(h) \right\},$$

where

- $\lambda(h) = \sqrt{2 \log\{1/(2h)\}}$  is an additive correction term;
- $\mathcal{G}_T$  is the set of points  $(u, h)$  that are taken into consideration;
- $\hat{\sigma}_i^2$  is an appropriate estimator of the long-run variance  $\sigma_i^2$ .

# Test procedure

Testing problem:

$$H_0 : m_1 = m_2 = \dots = m_n$$

# Test procedure

Testing problem:

$$H_0 : m_1 = m_2 = \dots = m_n$$

Gaussian version of the test statistic:

$$\Phi_{n,T} = \max_{1 \leq i < j \leq n} \Phi_{ij,T},$$
$$\Phi_{ij,T} = \max_{(u,h) \in \mathcal{G}_T} \left\{ \left| \frac{\phi_{ij,T}(u,h)}{(\hat{\sigma}_i^2 + \hat{\sigma}_j^2)^{1/2}} \right| - \lambda(h) \right\},$$

where

$$\phi_{ij,T}(u,h) = \sum_{t=1}^T w_{t,T}(u,h) \left\{ \hat{\sigma}_i \left( Z_{it} - \frac{1}{T} \sum_{t=1}^T Z_{it} \right) - \hat{\sigma}_j \left( Z_{jt} - \frac{1}{T} \sum_{t=1}^T Z_{jt} \right) \right\};$$

$Z_t$  are independent standard normal random variables;

$q_{n,T}(\alpha)$  is  $(1 - \alpha)$  quantile of  $\Phi_{n,T}$ .



# Test procedure

Testing problem:

$$H_0 : m_1 = m_2 = \dots = m_n$$

Gaussian version of the test statistic:

$$\Phi_{n,T} = \max_{1 \leq i < j \leq n} \Phi_{ij,T},$$

$$\Phi_{ij,T} = \max_{(u,h) \in \mathcal{G}_T} \left\{ \left| \frac{\phi_{ij,T}(u,h)}{(\hat{\sigma}_i^2 + \hat{\sigma}_j^2)^{1/2}} \right| - \lambda(h) \right\},$$

where

$$\phi_{ij,T}(u,h) = \sum_{t=1}^T w_{t,T}(u,h) \left\{ \hat{\sigma}_i \left( Z_{it} - \frac{1}{T} \sum_{t=1}^T Z_{it} \right) - \hat{\sigma}_j \left( Z_{jt} - \frac{1}{T} \sum_{t=1}^T Z_{jt} \right) \right\};$$

$Z_t$  are independent standard normal random variables;

$q_{n,T}(\alpha)$  is  $(1 - \alpha)$  quantile of  $\Phi_{n,T}$ .

# Test procedure

Testing problem:

$$H_0 : m_1 = m_2 = \dots = m_n$$

Gaussian version of the test statistic:

$$\Phi_{n,T} = \max_{1 \leq i < j \leq n} \Phi_{ij,T},$$

$$\Phi_{ij,T} = \max_{(u,h) \in \mathcal{G}_T} \left\{ \left| \frac{\phi_{ij,T}(u,h)}{(\hat{\sigma}_i^2 + \hat{\sigma}_j^2)^{1/2}} \right| - \lambda(h) \right\},$$

where

$$\phi_{ij,T}(u,h) = \sum_{t=1}^T w_{t,T}(u,h) \left\{ \hat{\sigma}_i \left( Z_{it} - \frac{1}{T} \sum_{t=1}^T Z_{it} \right) - \hat{\sigma}_j \left( Z_{jt} - \frac{1}{T} \sum_{t=1}^T Z_{jt} \right) \right\};$$

$Z_t$  are independent standard normal random variables;

$q_{n,T}(\alpha)$  is  $(1 - \alpha)$  quantile of  $\Phi_{n,T}$ .

## Test procedure

For a given significance level  $\alpha \in (0, 1)$ , we reject  $H_0$  if  $\hat{\Psi}_{n,T} > q_{n,T}(\alpha)$ .

# Theoretical properties

## Proposition

*Suppose that  $\mathcal{E}_i$  are independent across  $i$  and satisfy  $\mathcal{C}1 - \mathcal{C}2$  for each  $i$ . Under our remaining assumptions and under  $H_0 : m_1 = m_2 = \dots = m_n$  it holds that*

$$P(\hat{\Psi}_{n,T} \leq q_{n,T}(\alpha)) = (1 - \alpha) + o(1).$$

# Theoretical properties

## Proposition

*Suppose that  $\mathcal{E}_i$  are independent across  $i$  and satisfy  $\mathcal{C}1 - \mathcal{C}2$  for each  $i$ . Under our remaining assumptions and under  $H_0 : m_1 = m_2 = \dots = m_n$  it holds that*

$$P(\hat{\Psi}_{n,T} \leq q_{n,T}(\alpha)) = (1 - \alpha) + o(1).$$

## Proposition

*Let the conditions of previous proposition be satisfied. Under local alternatives we have*

$$P(\hat{\Psi}_{n,T} \leq q_{n,T}(\alpha)) = o(1).$$

# Clustering, group structure

- The null hypothesis  $H_0 : m_1 = m_2 = \dots = m_n$  is violated.

# Clustering, group structure

- The null hypothesis  $H_0 : m_1 = m_2 = \dots = m_n$  is violated.
- There exist sets or groups of time series  $G_1, \dots, G_N$  with  $N \leq n$  and  $\{1, \dots, n\} = \dot{\bigcup}_{\ell=1}^N G_\ell$  such that for each  $1 \leq \ell \leq N$  we have  $m_i = g_\ell$  for all  $i \in G_\ell$ , where  $g_\ell$  are group-specific trend functions.

# Clustering, group structure

- The null hypothesis  $H_0 : m_1 = m_2 = \dots = m_n$  is violated.
- There exist sets or groups of time series  $G_1, \dots, G_N$  with  $N \leq n$  and  $\{1, \dots, n\} = \dot{\bigcup}_{\ell=1}^N G_\ell$  such that for each  $1 \leq \ell \leq N$  we have  $m_i = g_\ell$  for all  $i \in G_\ell$ , where  $g_\ell$  are group-specific trend functions.
- For any  $\ell \neq \ell'$ , the trends  $g_{\ell,T}$  and  $g_{\ell',T}$  differ in the following sense: There exists  $(u, h) \in \mathcal{G}_T$  with  $[u - h, u + h] \subseteq [0, 1]$  such that  $g_{\ell,T}(w) - g_{\ell',T}(w) \geq c_T \sqrt{\log T / (Th)}$  for all  $w \in [u - h, u + h]$  or  $g_{\ell',T}(w) - g_{\ell,T}(w) \geq c_T \sqrt{\log T / (Th)}$  for all  $w \in [u - h, u + h]$ , where  $0 < c_T \rightarrow \infty$ .

# Clustering, algorithm

Dissimilarity measure between two sets of time series  $S$  and  $S'$ :

$$\hat{\Delta}(S, S') = \max_{\substack{i \in S, \\ j \in S'}} \hat{\Psi}_{ij, T}.$$

## Clustering algorithm

*Step 0 (Initialization):* Let  $\hat{G}_i^{[0]} = \{i\}$  denote the  $i$ -th singleton cluster for  $1 \leq i \leq n$  and define  $\{\hat{G}_1^{[0]}, \dots, \hat{G}_n^{[0]}\}$  to be the initial partition of time series into clusters.

*Step  $r$  (Iteration):* Let  $\hat{G}_1^{[r-1]}, \dots, \hat{G}_{n-(r-1)}^{[r-1]}$  be the  $n - (r - 1)$  clusters from the previous step. Determine the pair of clusters  $\hat{G}_\ell^{[r-1]}$  and  $\hat{G}_{\ell'}^{[r-1]}$  for which

$$\hat{\Delta}(\hat{G}_\ell^{[r-1]}, \hat{G}_{\ell'}^{[r-1]}) = \min_{1 \leq k < k' \leq n-(r-1)} \hat{\Delta}(\hat{G}_k^{[r-1]}, \hat{G}_{k'}^{[r-1]})$$

and merge them into a new cluster.



# Clustering, theoretical properties

The estimator of the number of groups is

$$\hat{N} = \min \left\{ r = 1, 2, \dots \mid \max_{1 \leq \ell \leq r} \hat{\Delta}(\hat{G}_\ell^{[n-r]}) \leq q_{n,T}(\alpha) \right\}.$$

# Clustering, theoretical properties

The estimator of the number of groups is

$$\hat{N} = \min \left\{ r = 1, 2, \dots \mid \max_{1 \leq \ell \leq r} \hat{\Delta}(\hat{G}_\ell^{[n-r]}) \leq q_{n,T}(\alpha) \right\}.$$

## Proposition

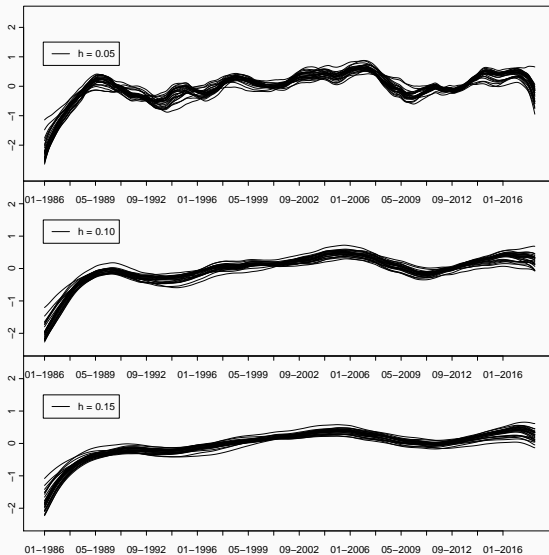
*Let the conditions of previous propositions be satisfied. Then*

$$P\left(\{\hat{G}_1, \dots, \hat{G}_{\hat{N}}\} = \{G_1, \dots, G_N\}\right) \geq (1 - \alpha) + o(1)$$

*and*

$$P(\hat{N} = N) \geq (1 - \alpha) + o(1).$$

# Testing for equality of different temperature time trends



# Idea behind the additive correction

Consider the uncorrected statistic

$$\hat{\Psi}_{T,\text{uncorrected}} = \max_{(u,h) \in \mathcal{G}_T} \left| \frac{\hat{\psi}_T(u, h)}{\hat{\sigma}} \right|$$

under the null hypothesis  $H_0 : m = 0$  and under simplifying assumptions:

- the errors  $\varepsilon_i$  are i.i.d. normally distributed;
- $\hat{\sigma} = \sigma$ ;
- $\mathcal{G}_T = \{(u_k, h_l) | u_k = (2k - 1)h_l \text{ for } 1 \leq k \leq 1/2h_l, 1 \leq l \leq L\}$ .

# Idea behind the additive correction

Consider the uncorrected statistic

$$\hat{\Psi}_{T,\text{uncorrected}} = \max_{(u,h) \in \mathcal{G}_T} \left| \frac{\hat{\psi}_T(u, h)}{\hat{\sigma}} \right|$$

under the null hypothesis  $H_0 : m = 0$  and under simplifying assumptions:

- the errors  $\varepsilon_i$  are i.i.d. normally distributed;
- $\hat{\sigma} = \sigma$ ;
- $\mathcal{G}_T = \{(u_k, h_l) | u_k = (2k - 1)h_l \text{ for } 1 \leq k \leq 1/2h_l, 1 \leq l \leq L\}$ .

$$\hat{\Psi}_{T,\text{uncorrected}} = \max_{1 \leq l \leq L} \max_{1 \leq k \leq 1/2h_l} \left| \frac{\hat{\psi}_T(u_k, h_l)}{\sigma} \right|$$

# Idea behind the additive correction

Consider the uncorrected statistic

$$\hat{\Psi}_{T,\text{uncorrected}} = \max_{(u,h) \in \mathcal{G}_T} \left| \frac{\hat{\psi}_T(u, h)}{\hat{\sigma}} \right|$$

under the null hypothesis  $H_0 : m = 0$  and under simplifying assumptions:

- the errors  $\varepsilon_i$  are i.i.d. normally distributed;
- $\hat{\sigma} = \sigma$ ;
- $\mathcal{G}_T = \{(u_k, h_l) | u_k = (2k - 1)h_l \text{ for } 1 \leq k \leq 1/2h_l, 1 \leq l \leq L\}$ .

$$\hat{\Psi}_{T,\text{uncorrected}} = \max_{1 \leq l \leq L} \max_{1 \leq k \leq 1/2h_l} \left| \frac{\hat{\psi}_T(u_k, h_l)}{\sigma} \right|$$

# Idea behind the additive correction

Consider the uncorrected statistic

$$\hat{\Psi}_{T,\text{uncorrected}} = \max_{(u,h) \in \mathcal{G}_T} \left| \frac{\hat{\psi}_T(u, h)}{\hat{\sigma}} \right|$$

under the null hypothesis  $H_0 : m = 0$  and under simplifying assumptions:

- the errors  $\varepsilon_i$  are i.i.d. normally distributed;
- $\hat{\sigma} = \sigma$ ;
- $\mathcal{G}_T = \{(u_k, h_l) | u_k = (2k - 1)h_l \text{ for } 1 \leq k \leq 1/2h_l, 1 \leq l \leq L\}$ .

$$\hat{\Psi}_{T,\text{uncorrected}} = \max_{1 \leq l \leq L} \max_{1 \leq k \leq 1/2h_l} \left| \frac{\hat{\psi}_T(u_k, h_l)}{\sigma} \right|$$

$\Rightarrow \max_k \frac{\hat{\psi}_T(u_k, h_l)}{\sigma} = \sqrt{2 \log(1/2h_l)} + o_P(1) \rightarrow \infty$  as  $h \rightarrow 0$  and the stochastic behavior of  $\hat{\Psi}_{T,\text{uncorrected}}$  is dominated by  $\frac{\hat{\psi}_T(u_k, h_l)}{\sigma}$  for small bandwidths  $h_l$ . [Go back](#)

# Idea behind the additive correction

Consider the uncorrected statistic

$$\hat{\Psi}_{T,\text{uncorrected}} = \max_{(u,h) \in \mathcal{G}_T} \left| \frac{\hat{\psi}_T(u,h)}{\hat{\sigma}} \right|$$

under the null hypothesis  $H_0 : m = 0$  and under simplifying assumptions:

- the errors  $\varepsilon_i$  are i.i.d. normally distributed;
- $\hat{\sigma} = \sigma$ ;
- $\mathcal{G}_T = \{(u_k, h_l) | u_k = (2k - 1)h_l \text{ for } 1 \leq k \leq 1/2h_l, 1 \leq l \leq L\}$ .

$$\hat{\Psi}_{T,\text{uncorrected}} = \max_{1 \leq l \leq L} \max_{1 \leq k \leq 1/2h_l} \left| \frac{\hat{\psi}_T(u_k, h_l)}{\sigma} \right|$$

$\Rightarrow \max_k \frac{\hat{\psi}_T(u_k, h_l)}{\sigma} = \sqrt{2 \log(1/2h_l)} + o_P(1) \rightarrow \infty$  as  $h \rightarrow 0$  and the stochastic behavior of  $\hat{\Psi}_{T,\text{uncorrected}}$  is dominated by  $\frac{\hat{\psi}_T(u_k, h_l)}{\sigma}$  for small bandwidths  $h_l$ . [Go back](#)