

# Multiscale inference for nonparametric time trends

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Marina Khismatullina   Michael Vogt

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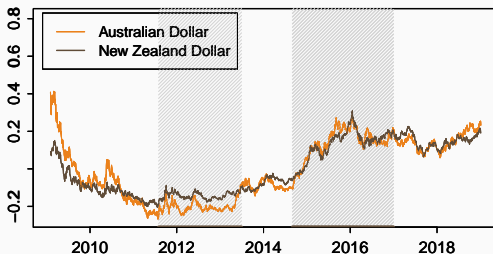
# Introduction

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# Motivation

## Aim of the paper

To develop new inference methods that allow to *identify* and *locate* differences between nonparametric trend curves with dependent errors.



**Research question:** Out of many given intervals, how to find those where the trends are significantly different?

## **Why is it relevant?**

Finding systematic differences between trends = basis for further research

## **Why is it difficult?**

Testing many hypotheses at the same time = multiple testing problem

⇒ large probability of one true null hypothesis being rejected.

## **Is it limited to one application?**

No! Our method = general method for comparing nonparametric trends

⇒ new statistical test for equality of nonparametric trend curves.

Comparison of deterministic trends:

- Park et al. (2009), Degras et al. (2012), Zhang et al. (2012), Hidalgo and Lee (2014), Chen and Wu (2019).

Multiscale tests:

- Chaudhuri and Marron (1999, 2000), Hall and Heckman (2000), Dümbgen and Spokoiny (2001), Park et al. (2009).

Comparison of volatility trends:

- Nyblom and Harvey (2000), ...

# Model

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We observe a panel of  $n$  time series  $\mathcal{Z}_i = \{(Y_{it}, \mathbf{X}_{it}) : 1 \leq t \leq T\}$  of length  $T$ , where  $Y_{it} \in \mathbb{R}$  and  $\mathbf{X}_{it} \in \mathbb{R}^d$ . We assume that  $n$  is fixed.

We assume the following model:

$$Y_{it} = m_i\left(\frac{t}{T}\right) + \beta_i^T \mathbf{X}_{it} + \alpha_i + \varepsilon_{it},$$

where

- $m_i$  are unknown trend functions on  $[0, 1]$ ;
- $\beta_i$  is  $d \times 1$  vector of unknown parameters;
- $\alpha_i$  are so-called fixed effect error terms;
- $\mathcal{E}_i = \{\varepsilon_{it} : 1 \leq t \leq T\}$  is a zero-mean stationary and causal error process.



$$Y_{it} = m_i\left(\frac{t}{T}\right) + \beta_i^\top \mathbf{X}_{it} + \alpha_i + \varepsilon_{it},$$

If we knew  $\alpha_i$  and  $\beta_i$ , then the model becomes much simpler:

$$\begin{aligned} Y_{it} - \alpha_i - \beta_i^\top \mathbf{X}_{it} &=: Y_{it}^\circ \\ &= m_i\left(\frac{t}{T}\right) + \varepsilon_{it}. \end{aligned}$$

In reality the variables  $Y_{it}^\circ$  are **not** observed.

But given  $\hat{\alpha}_i$  and  $\hat{\beta}_i$ , we can consider

$$\hat{Y}_{it} := Y_{it} - \hat{\alpha}_i - \hat{\beta}_i^\top \mathbf{X}_{it} = (\beta_i - \hat{\beta}_i)^\top \mathbf{X}_{it} + m_i\left(\frac{t}{T}\right) + (\alpha_i - \hat{\alpha}_i) + \varepsilon_{it}.$$

## Model, part 3

1. We estimate  $\beta_i$ :

$$\hat{\beta}_i = \left( \sum_{t=2}^T \Delta \mathbf{x}_{it} \Delta \mathbf{x}_{it}^\top \right)^{-1} \sum_{t=2}^T \Delta \mathbf{x}_{it} \Delta Y_{it}$$

### Theorem

Under certain regularity assumptions,  $\hat{\beta}_i$  is a consistent estimator of  $\beta_i$  with the property  $\beta_i - \hat{\beta}_i = O_P(T^{-1/2})$ .

2. We estimate the fixed effects  $\alpha_i$ :

$$\hat{\alpha}_i = \frac{1}{T} \sum_{t=1}^T (Y_{it} - \hat{\beta}_i^\top \mathbf{x}_{it})$$

We then work with the augmented time series  $\hat{Y}_{it} = Y_{it} - \hat{\alpha}_i - \hat{\beta}_i^\top \mathbf{x}_{it}$ .

# Testing procedure

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# Testing problem

$$H_0 : m_1 = m_2 = \dots = m_n$$

**Question:** if we reject the global null, how to locate the differences between the trends?

Consider a grid  $\mathcal{G}_T = \{(u, h) : [u - h, u + h] \subseteq [0, 1]\}$  of location-bandwidth parameters. For each pair  $(i, j)$  and for each interval  $[u - h, u + h]$  we consider the null hypothesis

$$H_0^{[i,j]}(u, h) : m_i(w) = m_j(w) \text{ for all } w \in [u - h, u + h].$$

Then the global null  $H_0 : m_1 = m_2 = \dots = m_n$  can be reformulated as

$$H_0 : \text{The hypotheses } H_0^{[i,j]}(u, h) \text{ hold true for all intervals } [u - h, u + h], (u, h) \in \mathcal{G}_T, \text{ and for all } 1 \leq i < j \leq n.$$

# Test statistic

For a given location  $u \in [0, 1]$  and bandwidth  $h$  and a given pair  $(i, j)$  we construct the kernel averages

$$\hat{\psi}_{ij,T}(u, h) = \sum_{t=1}^T w_{t,T}(u, h) (\hat{Y}_{it} - \hat{Y}_{jt}),$$

where

$$w_{t,T}(u, h) = \frac{\Lambda_{t,T}(u, h)}{\{\sum_{t=1}^T \Lambda_{t,T}^2(u, h)\}^{1/2}},$$

$$\Lambda_{t,T}(u, h) = K\left(\frac{t/T - u}{h}\right) \left[ S_{T,2}(u, h) - S_{T,1}(u, h) \left(\frac{t/T - u}{h}\right) \right],$$

$$S_{T,\ell}(u, h) = \frac{1}{Th} \sum_{t=1}^T K\left(\frac{t/T - u}{h}\right) \left(\frac{t/T - u}{h}\right)^\ell$$

for  $\ell = 1, 2$  and  $K$  is a kernel function.

## Test statistic, part 2

The kernel averages  $\hat{\psi}_{ij,\tau}(u, h)$  measure the distance between two trend curves  $m_i$  and  $m_j$  on  $[u - h, u + h]$ .

Instead with working directly with  $\hat{\psi}_{ij,\tau}(u, h)$ , we replace them by

$$\hat{\psi}_{ij,\tau}^0(u, h) = \left\{ \left| \frac{\hat{\psi}_{ij,\tau}(u, h)}{(\hat{\sigma}_i^2 + \hat{\sigma}_j^2)^{1/2}} \right| - \lambda(h) \right\},$$

where

- $\hat{\sigma}_i^2$  is an appropriate estimator of the long-run variance  $\sigma_i^2$ ;
- $\lambda(h) = \sqrt{2 \log\{1/(2h)\}}$  is an additive correction term (Dümbgen and Spokoiny (2001)).

Explanation

To test the global null, we aggregate the individual test statistics for all  $(i, j)$  and all location-bandwidth pairs  $(u, h) \in \mathcal{G}_T$ :

$$\widehat{\Psi}_{n,T} = \max_{1 \leq i < j \leq n} \max_{(u,h) \in \mathcal{G}_T} \widehat{\psi}_{ij,T}^0(u, h).$$

### Note

Under certain conditions and under the null,  $\widehat{\psi}_{ij,T}^0(u, h)$  and  $\widehat{\Psi}_{n,T}$  can be approximated by the corresponding Gaussian versions of the test statistics.

Gaussian version of the individual test statistics:

$$\phi_{ij,T}^0(u, h) = \max_{(u,h) \in \mathcal{G}_T} \left\{ \left| \frac{\phi_T(u, h)}{(\sigma_i^2 + \sigma_j^2)^{1/2}} \right| - \lambda(h) \right\},$$

where

- $\phi_T(u, h) = \sum_{t=1}^T w_{t,T}(u, h) \{ \sigma_i(Z_{it} - \bar{Z}_i) - \sigma_j(Z_{jt} - \bar{Z}_j) \};$
- $Z_{it}$  are independent standard normal random variables;
- $\bar{Z}_i$  is the empirical average of  $Z_{i1}, \dots, Z_{iT}$ .

Aggregated Gaussian test statistics:

$$\Phi_{n,T} = \max_{1 \leq i < j \leq n} \max_{(u,h) \in \mathcal{G}_T} \phi_{ij,T}^0(u, h).$$



## Test procedure, part 2

1. Consider the Gaussian test statistic

$$\Phi_{n,T} = \max_{1 \leq i < j \leq n} \max_{(u,h) \in \mathcal{G}_T} \phi_{ij,T}^0(u,h),$$

where  $\phi_{ijk}^0$  are weighted averages of the differences of standard normal random variables.

2. Compute a  $(1 - \alpha)$ -quantile  $q_{n,T}(\alpha)$  of  $\Phi_{n,T}$  by Monte Carlo simulations.
3. Perform the test for the global hypothesis  $H_0$ : reject  $H_0$  if  $\hat{\Psi}_{n,T} > q_{n,T}(\alpha)$ .
4. For each  $i, j$ , and each  $(u, h) \in \mathcal{G}_T$ , carry out the test for the local null hypothesis  $H_0^{[i,j]}(u, h)$ : reject  $H_0^{[i,j]}(u, h)$  if  $\hat{\psi}_{ij,T}^0(u, h) > q_{n,T}(\alpha)$ .

# Theoretical properties

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# Assumptions

- $\mathcal{C}1$  For all  $i$  it holds that  $\mathbb{E}[\varepsilon_{it}] = 0$  and  $\|\varepsilon_{it}\|_q < \infty$  for some  $q > 4$ .
- $\mathcal{C}2$  For each  $i$  the variables  $\varepsilon_{it}$  are weakly dependent. [Details](#)
- $\mathcal{C}3$  For each  $i$  we have that  $\mathbf{X}_{it}$  is stationary and causal with all the necessary moments and no asymptotic multicollinearity.
- $\mathcal{C}4$  For each  $i$  the variables  $\mathbf{X}_{it}$  are weakly dependent. [Details](#)
- $\mathcal{C}5$   $\mathbf{X}_{it}$  (elementwise) and  $\varepsilon_{is}$  are uncorrelated for each  $t, s$ .
- $\mathcal{C}6$  All of the variables in the model are short-range dependent. [Details](#)

## Assumptions, part 2

C7 Standard assumptions on the kernel function  $K$ .

C8  $|\mathcal{G}_T| = O(T^\theta)$  for some arbitrarily large but fixed constant  $\theta > 0$ .

$$\mathcal{G}_T = \{(u, h) : u = t/T \text{ for some } 1 \leq t \leq T \text{ and } h \in [h_{\min}, h_{\max}] \\ \text{with } h = t/T \text{ for some } 1 \leq t \leq T\},$$

C9  $h_{\min} \gg T^{-(1-\frac{2}{q})} \log T$  and  $h_{\max} < 1/2$ .

C10 Assume that  $\sigma_i^2 = \sigma_j^2$  for all  $i, j$  and  $\hat{\sigma}_i^2 = \sigma_i^2 + o_p(\rho_T)$  with  $\rho_T = o(1/\log T)$ .

# Theoretical properties

## Proposition

Let  $\mathcal{M}_0$  be the set of triplets  $(i, j, k)$  for which  $H_0^{(ijk)}$  holds true. Then under  $\mathcal{C}1 - \mathcal{C}6$ , it holds that

$$\mathbb{P}\left(\forall (i, j, k) \in \mathcal{M}_0 : |\hat{\psi}_{ijk}| \leq c_{\text{Gauss}}(\alpha, h_k)\right) \geq 1 - \alpha + o(1)$$

## Proposition

Consider a sequence of functions  $\lambda_i = \lambda_{i,T}$ ,  $\lambda_j = \lambda_{j,T}$  such that

$$\exists \mathcal{I}_k : \lambda_i(w) - \lambda_j(w) \geq c_T \sqrt{\log T / (Th_k)} \quad \forall w \in \mathcal{I}_k, \quad (1)$$

and  $c_T \rightarrow \infty$  faster than  $\frac{\sqrt{\log T} \sqrt{\log \log T}}{\log \log \log T}$ . Let  $\mathcal{M}_1$  be the set of triplets  $(i, j, k)$  for which (1) holds true. Then under  $\mathcal{C}1 - \mathcal{C}6$ , it holds that

$$\mathbb{P}\left(\forall (i, j, k) \in \mathcal{M}_1 : |\hat{\psi}_{ijk}| > c_{\text{Gauss}}(\alpha, h_k)\right) = 1 - o(1)$$

# Strategy of the proof

- Replace the statistic  $\widehat{\Psi}_T$  under  $H_0 : m = 0$  by a statistic  $\widetilde{\Phi}_T$  with the same distribution and the property that

$$|\widetilde{\Phi}_T - \Phi_T| = o_p(\delta_T),$$

where  $\delta_T = o(1)$ . To do so, we make use of strong approximation theory for dependent processes as derived in Berkes et al. (2014)

- Using the anti-concentration results for Gaussian random vectors (Chernozhukov et al. 2015), prove that  $\Phi_T$  does not concentrate too strongly in small regions of the form  $[x - \delta_T, x + \delta_T]$ , i.e.

$$\sup_{x \in \mathbb{R}} P(|\Phi_T - x| \leq \delta_T) = o(1).$$

- Show that

$$\sup_{x \in \mathbb{R}} |P(\widetilde{\Phi}_T \leq x) - P(\Phi_T \leq x)| = o(1).$$

# Illustration

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# Graphical representation

How to represent the results of the test?

Plot the results of pairwise comparison  $\mathcal{F}_{\text{reject}}(i, j)$ :

$$P\left(\forall(i, j, k) \in \mathcal{M}_0 : \mathcal{I}_k \notin \mathcal{F}_{\text{reject}}(i, j)\right) \geq 1 - \alpha + o(1)$$

## Minimal intervals

An interval  $\mathcal{I}_k \in \mathcal{F}_{\text{reject}}(i, j)$  is called **minimal** if there is no other interval  $\mathcal{I}_{k'} \in \mathcal{F}_{\text{reject}}(i, j)$  with  $\mathcal{I}_{k'} \subset \mathcal{I}_k$ .

The set of minimal intervals is denoted  $\mathcal{F}_{\text{reject}}^{\min}(i, j)$ .

We can make similar confidence statements about minimal intervals:

$$P\left(\forall(i, j, k) \in \mathcal{M}_0 : \mathcal{I}_k \notin \mathcal{F}_{\text{reject}}^{\min}(i, j)\right) \geq 1 - \alpha + o(1)$$



We can claim, with confidence of about 95%, that the null hypothesis is violated for all intervals (and all pairs of time series) for which our test rejects the null.

However, we can not say anything about the causes of such differences. This question requires further (probably not purely statistical) analysis.

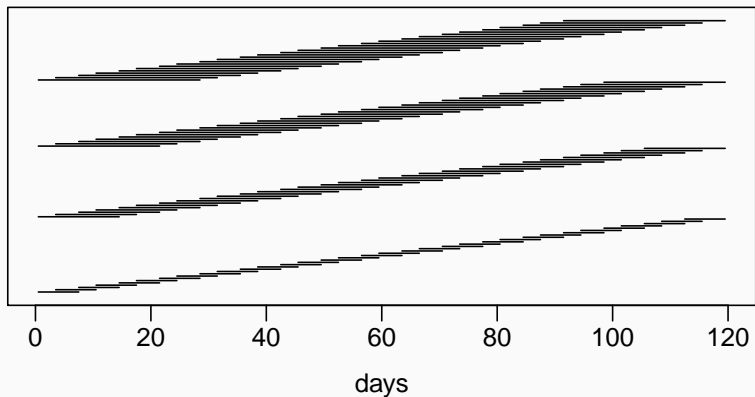
Further possible extensions:

- introduce scaling factor in the trend function, that will allow to adjust for the size of the country (population, density, testing regimes, etc.);
- include the dependence between covariates and error terms;
- cluster the time series based on the trends they exhibit.

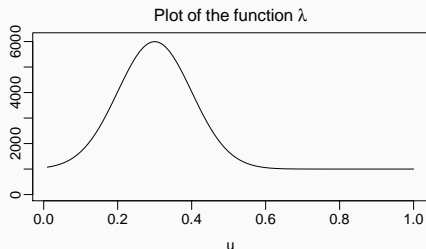
**Thank you!**

# Family of time intervals

The family of intervals  $F$



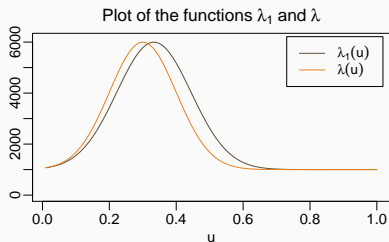
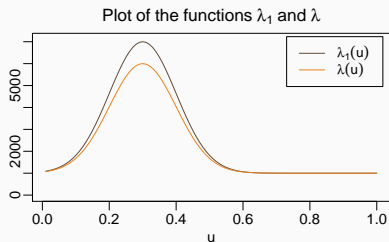
# Simulation results for the size of the test



**Table 1:** Size of the multiscale test

	$n = 5$			$n = 10$			$n = 50$		
	significance level $\alpha$			significance level $\alpha$			significance level $\alpha$		
	0.01	0.05	0.1	0.01	0.05	0.1	0.01	0.05	0.1
$T = 100$	0.011	0.047	0.093	0.010	0.044	0.087	0.008	0.037	0.075
$T = 250$	0.009	0.047	0.091	0.009	0.046	0.087	0.008	0.035	0.069
$T = 500$	0.010	0.044	0.083	0.008	0.048	0.093	0.007	0.035	0.077

# Simulation results for the power of the test



**Table 3:** Power of the multiscale test for scenario B

	$n = 5$			$n = 10$			$n = 50$		
	significance level $\alpha$			significance level $\alpha$			significance level $\alpha$		
	0.01	0.05	0.1	0.01	0.05	0.1	0.01	0.05	0.1
$T = 100$	0.835	0.918	0.993	0.800	0.873	0.895	0.232	0.852	0.852
$T = 250$	0.895	0.972	0.946	0.980	0.960	0.920	0.970	0.968	0.985
$T = 500$	0.996	0.905	0.947	0.998	0.964	0.928	0.996	0.989	0.932

# Estimator of $\sigma^2$

We estimate the overdispersion parameter  $\sigma^2$  by

$$\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n \hat{\sigma}_i^2 \text{ and } \hat{\sigma}_i^2 = \frac{\sum_{t=2}^T (X_{it} - X_{it-1})^2}{2 \sum_{t=1}^T X_{it}}$$

We assume that  $\lambda_i$  is Lipschitz continuous. Then

$$X_{it} - X_{it-1} = \sigma \sqrt{\lambda_i \left( \frac{t}{T} \right)} (\eta_{it} - \eta_{it-1}) + r_{it},$$

where  $|r_{it}| \leq C(1 + |\eta_{it-1}|)/T$  with a sufficiently large  $C$ . Hence,

$$\frac{1}{T} \sum_{t=2}^T (X_{it} - X_{it-1})^2 = 2\sigma^2 \left\{ \frac{1}{T} \sum_{t=2}^T \lambda_i(t/T) \right\} + o_p(1)$$

Together with

$$\frac{1}{T} \sum_{t=1}^T X_{it} = \frac{1}{T} \sum_{t=1}^T \lambda_i(t/T) + o_p(1),$$

we get that  $\hat{\sigma}_i^2 = \sigma^2 + o_p(1)$  for any  $i$  and thus  $\hat{\sigma}^2 = \sigma^2 + o_p(1)$ .

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## Idea behind $a_k$ and $b_k$

Dümbgen and Spokoiny (2001): the critical values  $c_{ijk}(\alpha)$  depend on the scale of the testing problem, i.e. the length  $h_k$  of the time interval.

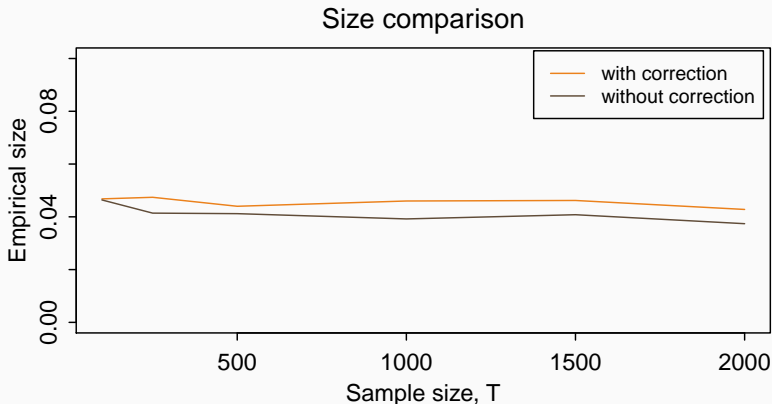
Specifically,

$$c_{ijk}(\alpha) = c(\alpha, h_k) := b_k + q(\alpha)/a_k,$$

where  $a_k = \{\log(e/h_k)\}^{1/2} / \log \log(e^e/h_k)$  and  $b_k = \sqrt{2 \log(1/h_k)}$  are scale-dependent constants and  $q(\alpha)$  is chosen such that we control FWER.

## Idea behind $a_k$ and $b_k$ , part 2

This choice of scale-dependent constants helps us balance the significance of hypotheses between the time intervals of different lengths  $h_k$ :



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# Idea behind the additive correction

Consider the uncorrected Gaussian statistic

$$\Phi^{\text{uncor}} = \max_{(i,j,k)} |\phi_{ijk}|$$

and let the family of intervals be

$$\mathcal{F} = \{[(m-1)h_l, mh_l] \text{ for } 1 \leq m \leq 1/h_l, 1 \leq l \leq L\}$$

Then we can rewrite the uncorrected test statistic as

$$\Phi^{\text{uncor}} = \max_{i,j} \max_{\substack{1 \leq l \leq L, \\ 1 \leq m \leq 1/h_l}} \left| \frac{1}{\sqrt{2Th_l}} \sum_{t=1}^T 1\left(\frac{t}{T} \in [(m-1)h_l, mh_l]\right) (Z_{it} - Z_{jt}) \right|$$

$\Rightarrow \max_m \dots = \sqrt{2 \log(1/h_l)} + o_P(1) \rightarrow \infty$  as  $h \rightarrow 0$  and the stochastic behavior of  $\Phi^{\text{uncor}}$  is dominated by the elements with small bandwidths  $h_l$ . [Go back](#)

# Dependence measure

Following Wu (2005), we define the *physical dependence measure* for the process  $\mathbf{L}(\mathcal{F}_t)$  as the following:

$$\delta_q(\mathbf{L}, t) = \|\mathbf{L}(\mathcal{F}_t) - \mathbf{L}(\mathcal{F}'_t)\|_q,$$

where  $\mathcal{F}_t = (\dots, \epsilon_{-1}, \epsilon_0, \epsilon_1, \dots, \epsilon_{t-1}, \epsilon_t)$  and  $\mathcal{F}'_t = (\dots, \epsilon_{-1}, \epsilon'_0, \epsilon_1, \dots, \epsilon_{t-1}, \epsilon_t)$  is a coupled process of  $\mathcal{F}_t$  with  $\epsilon'_0$  being an i.i.d. copy of  $\epsilon_0$ .

Intuitively,  $\delta_q(\mathbf{L}, t)$  measures the dependency of  $\mathbf{L}(\mathcal{F}_t)$  on  $\epsilon_0$ , i.e., how replacing  $\epsilon_0$  by an i.i.d. copy while keeping all other innovations in place affects the output  $\mathbf{L}(\mathcal{F}_t)$ .

# Technical assumptions

$\mathcal{C1}'$  The variables  $\varepsilon_{it}$  allow for the representation  $\varepsilon_{it} = G_i(\dots, \eta_{it-1}, \eta_{it})$ , where  $\eta_{it}$  are i.i.d. random variables across  $t$  and  $G_i : \mathbb{R}^{\mathbb{Z}} \rightarrow \mathbb{R}$  is a measurable function. Denote  $\mathcal{J}_{it} = (\dots, \eta_{it-2}, \eta_{it-1}, \eta_{it})$ .

$\mathcal{C1}'''$  Define  $\Theta_{i,t,q} = \sum_{s \geq t} \delta_q(G_i, s)$  for  $t \geq 0$ . For each  $i$  it holds that  $\Theta_{i,t,q} = O(t^{-\tau_q}(\log t)^{-A})$ , where  $A > \frac{2}{3}(1/q + 1 + \tau_q)$  and  $\tau_q = \{q^2 - 4 + (q - 2)\sqrt{q^2 + 20q + 4}\}/8q$ . [Go back](#)

## Technical assumptions, part 2

$\mathcal{C}3'$   $\mathbf{X}_{it}$  allow for the representation  $\mathbf{X}_{it} = \mathbf{H}_i(\dots, u_{it-1}, u_{it})$  with  $u_{it}$  being i.i.d. random variables and  $\mathbf{H}_i := (H_{i1}, H_{i2}, \dots, H_{id})^\top : \mathbb{R}^Z \rightarrow \mathbb{R}^d$  being a measurable function such that  $\mathbf{H}_i(\mathcal{U}_{it})$  is well defined. Denote  $\mathcal{U}_{it} = (\dots, u_{it-1}, u_{it})$ .

$\mathcal{C}3''$  Let  $\mathbf{N}_i$  be the  $d \times d$  matrix with  $n_{i,kl} = \mathbb{E}[H_{ik}(\mathcal{U}_{i0})H_{il}(\mathcal{U}_{i0})]$  being  $kl$ -th entry. We assume that the smallest eigenvalue of  $\mathbf{N}_i$  is strictly bigger than 0.

$\mathcal{C}3'''$  Let  $\mathbb{E}[H_i(\mathcal{U}_{i0})] = 0$  and  $\|H_i(\mathcal{U}_{it})\|_{q'} < \infty$  for some  $q' > \max\{2\theta, 4\}$ , where  $\theta$  will be introduced further.

$\mathcal{C}4'$   $\sum_{s=0}^{\infty} \delta_{q'}(H_i, s) < \infty$  for  $q'$  from Assumption  $\mathcal{C}3'''$ .

$\mathcal{C}4''$  For each  $i$  it holds that  $\sum_{s=t}^{\infty} \delta_{q'}(H_i, s) = O(t^{-\alpha})$  for  $q'$  from Assumption  $\mathcal{C}3'''$  and for some  $\alpha > 1/2 - 1/q'$ . [Go back](#)

## Technical assumptions, part 3

C6 Let  $\zeta_{i,t} = (u_{it}, \eta_{it})^\top$ . Define  $\mathcal{I}_{it} = (\dots, \zeta_{i,t-1}, \zeta_{i,t})$  and  $U_i(\mathcal{I}_{it}) = H_i(\mathcal{U}_{it})G_i(\mathcal{J}_{it})$ . With this notation at hand, we assume that  $\sum_{s=0}^{\infty} \delta_2(U_i, s) < \infty$ . [Go back](#)