

## **Task: Implementing Q-Learning in a Hybrid Approach**

You will work in teams of up to **3** members to complete the following task. Your objective is to implement Q-Learning in two environments: one custom-built and one using a standardized library (gym). You will also prepare a PowerPoint presentation summarizing your work and findings. To be Presented in the LAB

**Additionally**, you will upload your model to Hugging Face and a video of your agent across the environment.

### **What to do**

#### **Part 1: Build a Custom Gridworld Environment**

##### **1. Create a 5x5 Gridworld:**

- Define the start state at (0, 0) and the goal state at (4, 4).
- Place obstacles at positions like (2, 2) and (3, 3).

##### **2. Set Rewards:**

- Goal: +100
- Obstacle: -10
- Each step: -1

##### **3. Implement Q-Learning:**

- Initialize a Q-table.
- Use the Bellman equation to update Q-values.
- Implement an epsilon-greedy policy for action selection.

##### **4. Train and Test:**

- Train the agent over multiple episodes.
  - Visualize the learned policy (optimal path).
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## **Part 2: Use a gym Environment**

### **1. Choose and Set Up the MountainCar-v0 Environment:**

- Use MountainCar-v0 from the gym library.
- In this environment, the agent must learn to drive a car up a steep hill, requiring it to learn to balance and gather enough speed to reach the goal.

### **2. Understand the Environment:**

- Visualize it using `env.render()`.
- Check the state and action spaces.

### **3. Implement Q-Learning:**

- Adapt your Q-Learning code from Part 1 to work with the MountainCar-v0 environment.

### **4. Train and Test:**

- Train the agent over multiple episodes.
- Visualize and evaluate the learned policy.

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## **Deliverables**

### **1. Presentation:** Prepare a PowerPoint (up to 6 slides) covering:

- Task overview and approach.
- Findings from the custom Gridworld.
- Findings from the MountainCar-v0 environment.
- Comparative analysis of performance.
- Challenges and insights.

### **2. Model Upload:**

- Upload your trained model to Hugging Face, including the code and the environment settings.