

Computacional study

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Carreguem les dades generades pel codi de matlab

```
X <- read.csv("uo_nn_batch_49784363-54409254.csv", sep=';', row.names=NULL, header
= TRUE)
X <- X[,-9]
colnames(X) <- c('num_target', 'la', 'isd', 'niter', 'tex', 'tr_acc', 'te_acc', 'L*
')

X$num_target <- as.numeric(X$num_target)
X[1:18,]
```

##	num_target	la	isd	niter	tex	tr_acc	te_acc	L*
## 1	1	0	1	4	0.1037	100.0	100.0	6.28e-09
## 2	1	0	3	4	0.0604	100.0	100.0	1.80e-10
## 3	1	0	7	1001	0.1111	78.0	70.4	5.00e-05
## 4	1	1	1	134	1.4203	100.0	100.0	3.47e+00
## 5	1	1	3	21	1.7346	100.0	100.0	3.47e+00
## 6	1	1	7	409	0.3439	94.0	95.2	7.45e-01
## 7	1	10	1	61	1.0335	100.0	100.0	1.43e+01
## 8	1	10	3	30	0.4431	100.0	100.0	1.43e+01
## 9	1	10	7	1001	0.1745	58.4	48.4	Inf
## 10	2	0	1	1001	5.5946	100.0	100.0	9.85e-04
## 11	2	0	3	92	0.7569	100.0	94.4	2.02e-07
## 12	2	0	7	87	0.0802	94.0	93.2	3.13e-10
## 13	2	1	1	118	1.9388	100.0	99.6	7.02e+00
## 14	2	1	3	26	0.3681	100.0	99.6	7.02e+00
## 15	2	1	7	542	0.1822	94.4	93.2	9.43e-01
## 16	2	10	1	112	2.2540	96.8	95.2	2.15e+01
## 17	2	10	3	29	0.4785	96.8	95.2	2.15e+01
## 18	2	10	7	1001	0.2726	55.2	50.8	Inf

Separem les dades segons la λ per obtenir representacions gràfiques

```
la0 <- X[X$la == 0,]
col<- rep("black",nrow(la0))
col[la0$isd == 1] <- "red"
col[la0$isd == 3] <- "dodgerblue"
col[la0$isd == 7] <- "green3"
la1 <- X[X$la == 1,]
la10 <- X[X$la == 10,]
```

1. Convergence of the algorithms

Convergència global - Número d'iteracions

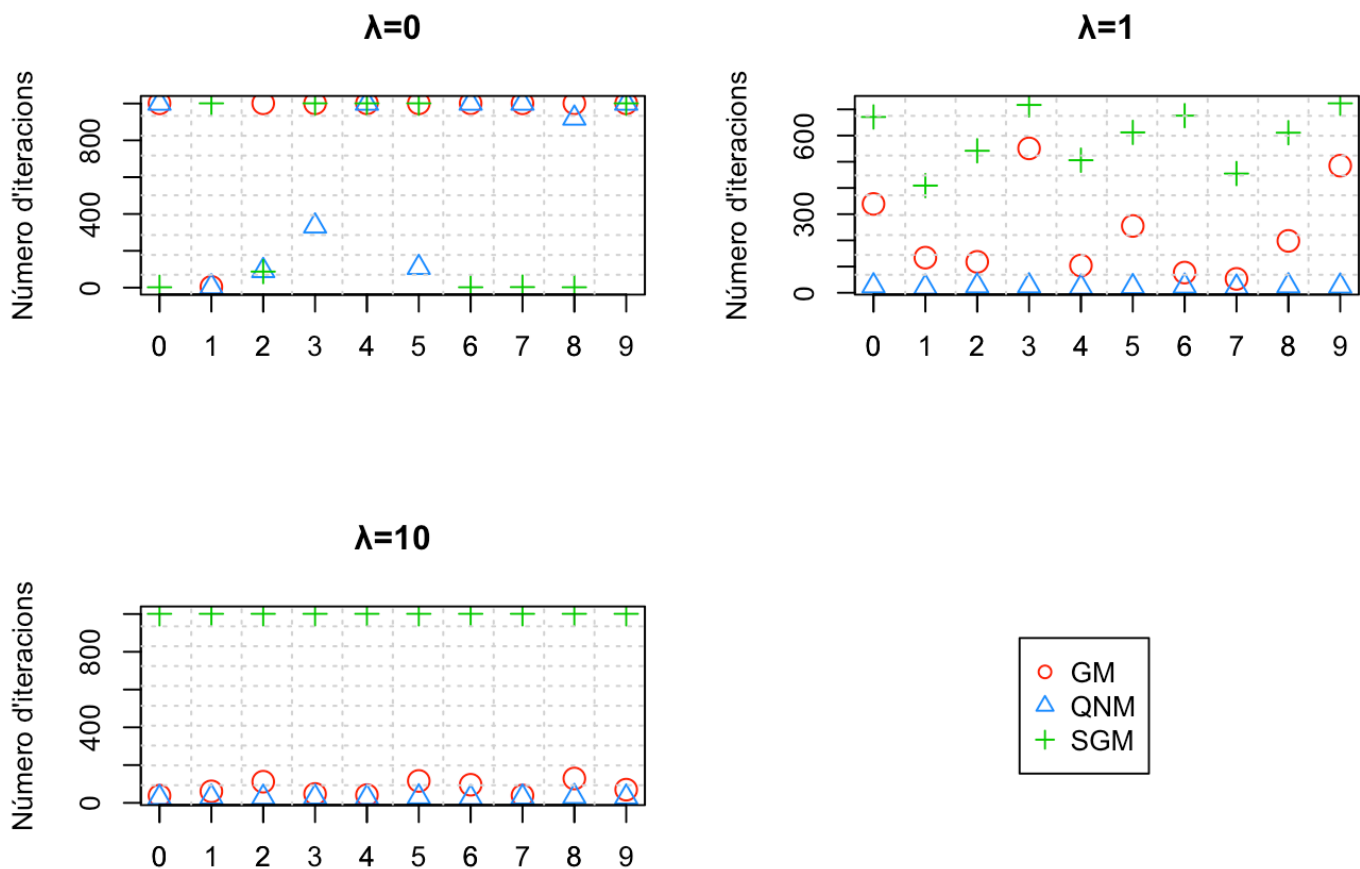
```
par(mfrow=c(2,2))

plot(la0$num_target ,la0$niter, col = col, cex=c(1.7,1.3,1.3), ylab="Número d'iteracions", xlab="", main="λ=0", pch=c(1,2,3))
axis(side=1, labels=NULL, at=0:9)
grid(10)

plot(la1$num_target ,la1$niter, col = col, cex=c(1.7,1.3,1.3), ylab="Número d'iteracions", xlab="", main="λ=1", pch=c(1,2,3))
axis(side=1, labels=NULL, at=0:9)
grid(10)

plot(la10$num_target ,la10$niter, col = col, cex=c(1.7,1.3,1.3), ylab="Número d'iteracions", xlab="", main="λ=10", pch=c(1,2,3))
axis(side=1, labels=NULL, at=0:9)
grid(10)

legend("right", legend = c("GM","QNM","SGM"), col = c("red","dodgerblue", "green3"),
, cex=1, pch=c(1,2,3),xpd=NA, inset=c(-1,0))
```



Funció objectiu L^*

```

par(mfrow=c(2,2))

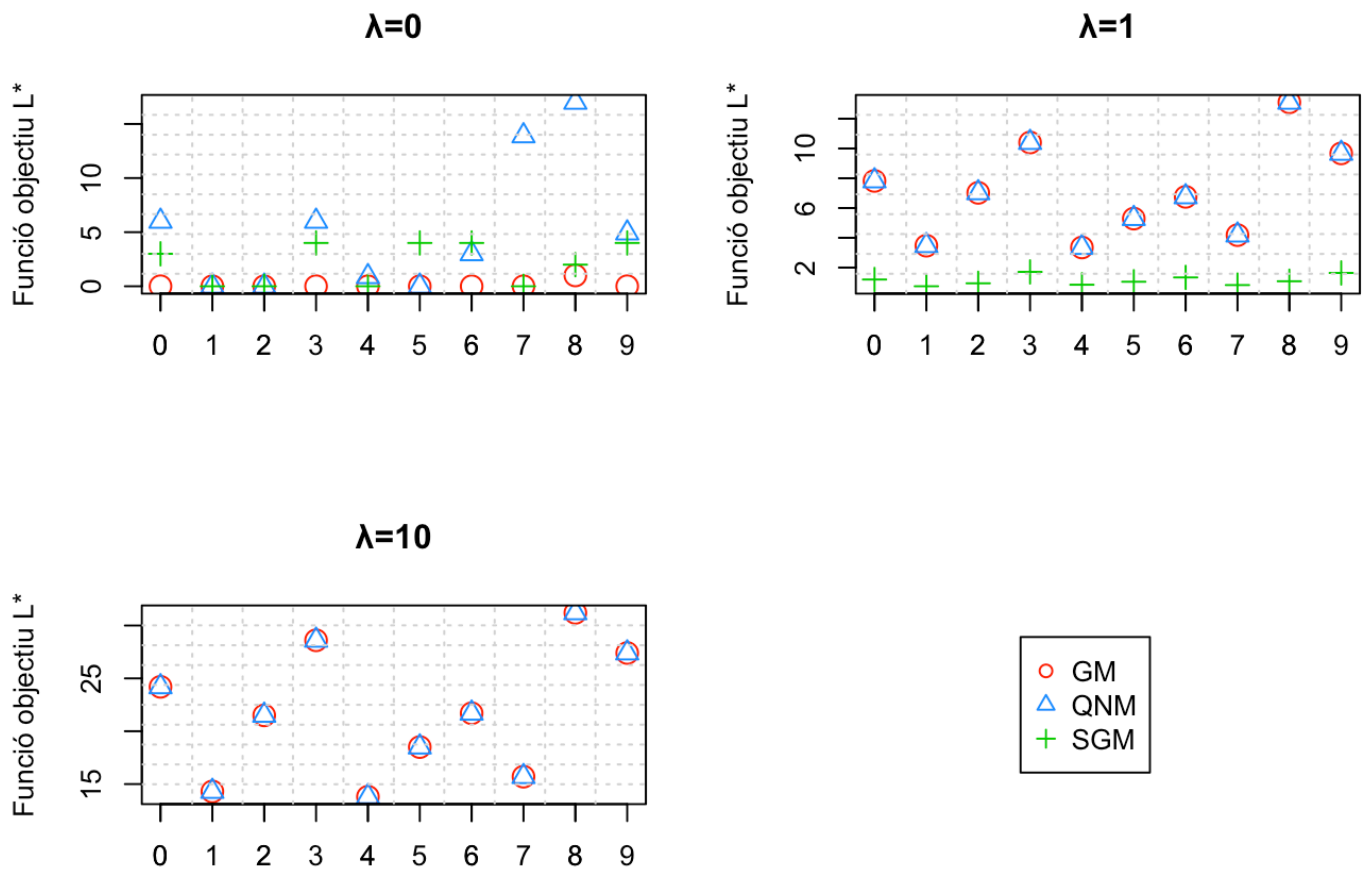
plot(la0$num_target ,la0$L*^, col = col, cex=c(1.7,1.3,1.3), ylab="Funció objectiu
L*", xlab="", main="λ=0", pch=c(1,2,3))
axis(side=1, labels=NULL, at=0:9)
grid(10)

plot(la1$num_target ,la1$L*^, col = col, cex=c(1.7,1.3,1.3), ylab="Funció objectiu
L*", xlab="", main="λ=1", pch=c(1,2,3))
axis(side=1, labels=NULL, at=0:9)
grid(10)

plot(la10$num_target ,la10$L*^, col = col, cex=c(1.7,1.3,1.3), ylab="Funció objectiu
L*", xlab="", main="λ=10", pch=c(1,2,3))
axis(side=1, labels=NULL, at=0:9)
grid(10)

legend("right", legend = c("GM","QNM","SGM"), col = c("red","dodgerblue", "green3")
, cex=1, pch=c(1,2,3),xpd=NA, inset=c(-1,0))

```



Convergència local - Temps d'execució

```

par(mfrow=c(2,2))

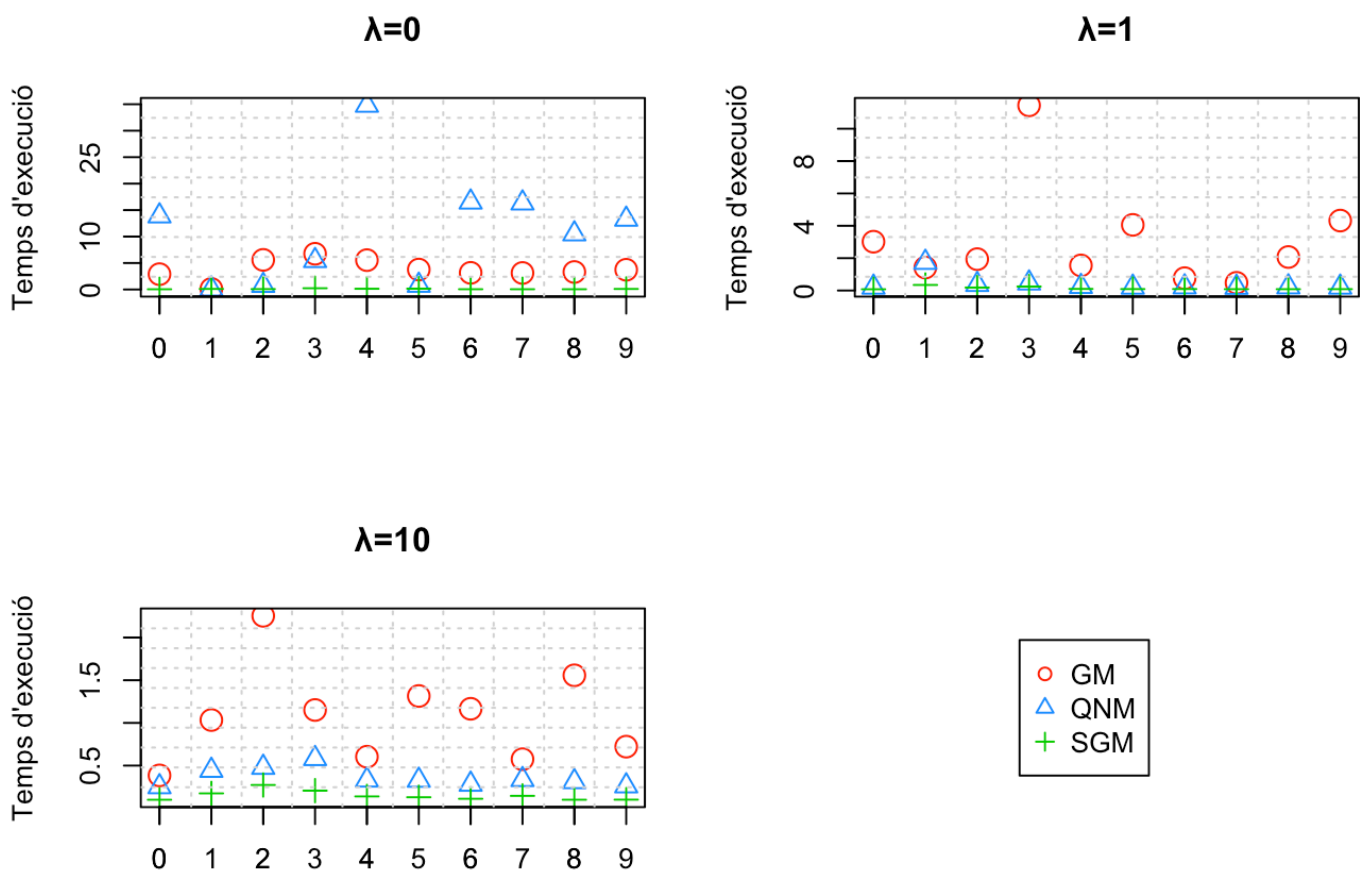
plot(la0$num_target ,la0$tex, col = col, cex=c(1.7,1.3,1.3), ylab="Temps d'execució",
     xlab="", main="λ=0", pch=c(1,2,3))
axis(side=1, labels=NULL, at=0:9)
grid(10)

plot(la1$num_target ,la1$tex, col = col, cex=c(1.7,1.3,1.3), ylab="Temps d'execució",
     xlab="", main="λ=1", pch=c(1,2,3))
axis(side=1, labels=NULL, at=0:9)
grid(10)

plot(la10$num_target ,la10$tex, col = col, cex=c(1.7,1.3,1.3), ylab="Temps d'execució",
     xlab="", main="λ=10", pch=c(1,2,3))
axis(side=1, labels=NULL, at=0:9)
grid(10)

legend("right", legend = c("GM","QNM","SGM"), col = c("red","dodgerblue", "green3"),
      , cex=1, pch=c(1,2,3),xpd=NA, inset=c(-1,0))

```



Comparativa detallada del temps d'execució de Quasi Newton amb $\lambda=1$ i $\lambda=10$

```
la1qn <- la1[la1$isd==3,]
la10qn <- la10[la10$isd==3,]
la1qn$tex
```

```
## [1] 1.7346 0.3681 0.4578 0.2433 0.1985 0.2176 0.1902 0.2178 0.2003 0.1991
```

```
la10qn$tex
```

```
## [1] 0.4431 0.4785 0.5811 0.3294 0.3270 0.2805 0.3350 0.3107 0.2613 0.2513
```

2. Recognition accuracy

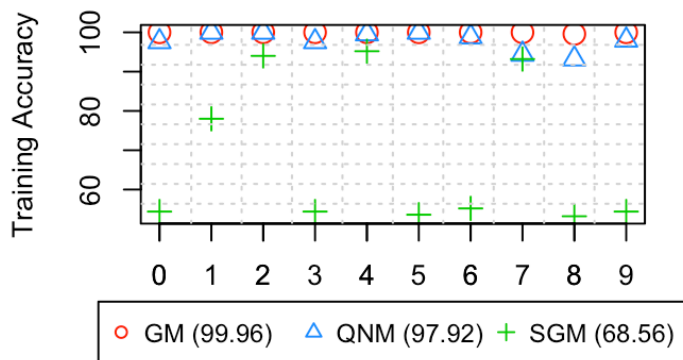
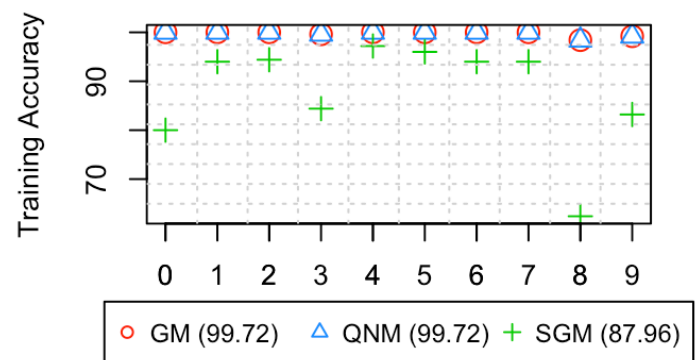
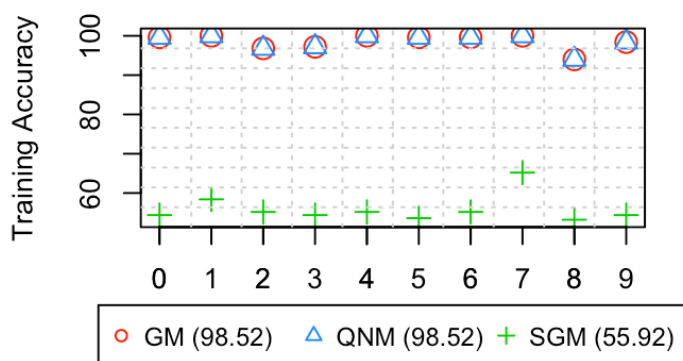
Training accuracy

```
leg_tr <- function(la)
{
  axis(side=1, labels=NULL, at=0:9)
  grid(10)
  leg_gm <- paste("GM (", mean(la[la$isd==1,$tr_acc),"),", sep="")
  leg_qnm <- paste("QNM (", mean(la[la0$isd==3,$tr_acc),"),", sep="")
  leg_sgm <- paste("SGM (", mean(la[la0$isd==7,$tr_acc),"),", sep="")
  legend("bottom", legend = c(leg_gm, leg_qnm, leg_sgm), col = c("red", "dodgerblue",
"green3"), cex=.9, pch=c(1,2,3), xpd=NA, inset=c(0,-0.7), horiz=TRUE)
}
```

```
par(mfrow=c(2,2))
plot(la0$num_target ,la0$tr_acc, col = col, cex=c(1.7,1.3,1.3), ylab="Training Accu
racy", xlab="", main="λ=0", pch=c(1,2,3))
leg_tr(la0)

plot(la1$num_target ,la1$tr_acc, col = col, cex=c(1.7,1.3,1.3), ylab="Training Accu
racy", xlab="", main="λ=1", pch=c(1,2,3))
leg_tr(la1)

plot(la10$num_target ,la10$tr_acc, col = col, cex=c(1.7,1.3,1.3), ylab="Training Ac
curacy", xlab="", main="λ=10", pch=c(1,2,3))
leg_tr(la10)
```

$\lambda=0$  $\lambda=1$  $\lambda=10$ 

Testing accuracy

```
leg_te <- function(la)
{
  axis(side=1, labels=NULL, at=0:9)
  grid(10)
  leg_gm <- paste("GM (", mean(la[la$isd==1,$te_acc]),")", sep="")
  leg_qnm <- paste("QNM (", mean(la[la0$isd==3,$te_acc]),")", sep="")
  leg_sgm <- paste("SGM (", mean(la[la0$isd==7,$te_acc]),")", sep="")
  legend("bottom", legend = c(leg_gm,leg_qnm,leg_sgm), col = c("red","dodgerblue",
"green3"), cex=.9, pch=c(1,2,3),xpd=NA, inset=c(0,-0.7), horiz=TRUE)
}
```

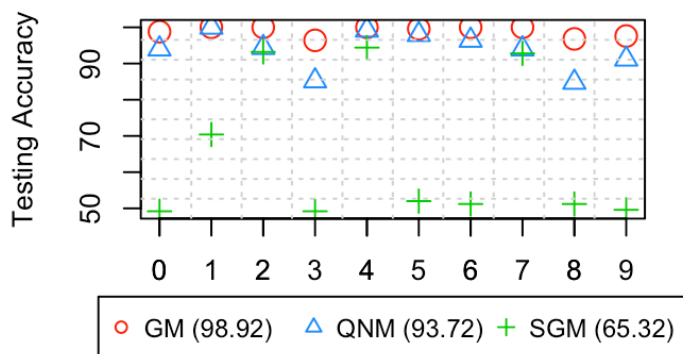
```
par(mfrow=c(2,2))
```

```
plot(la0$num_target ,la0$te_acc, col = col, cex=c(1.7,1.3,1.3), ylab="Testing Accuracy", xlab="", main="λ=0", pch=c(1,2,3))
leg_te(la0)
```

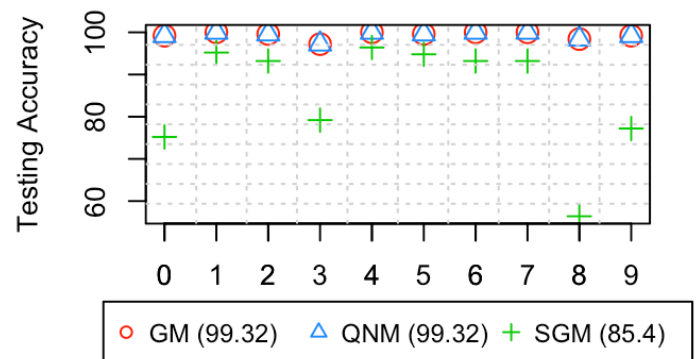
```
plot(la1$num_target ,la1$te_acc, col = col, cex=c(1.7,1.3,1.3), ylab="Testing Accuracy", xlab="", main="λ=1", pch=c(1,2,3))
leg_te(la1)
```

```
plot(la10$num_target ,la10$te_acc, col = col, cex=c(1.7,1.3,1.3), ylab="Testing Accuracy", xlab="", main="λ=10", pch=c(1,2,3))
leg_te(la10)
```

$\lambda=0$



$\lambda=1$



$\lambda=10$

