Scaling up the LASSO with interaction features

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DNA sequences

P_1 ... A T C G C T G A A T A C G G C T C G A A A T C G G A ... ✓
P_2 ... T T C G G T G A G T A C G G C T C G A A A T C G G A ... ✗
P_3 ... A T C G C T G A A T A C G G C T C G A A A T C G G A ... ✗
P_4 ... T T C G C T G A G T A C G G C T C G A A A T C G G A ... ✓
P_5 ... T T C G C T G A G T A C G G C T C G A A A T C G G A ... ✓
P_6 ... A T C G G T G A G T A C G G T T C G A T A T C G G A ... ✗
P_7 ... A T C G G T G A A T A C G G T T C G A T A T C G G A ... ✗
P_8 ... T T C G G T G A G T A C G G C T C G A T A T C G G A ... ✓

Sequence

Query

Response to treatment?
Disease risk?
Drug assimilation rate?
Ancestry?

...

DNA sequences

DNA sequences

Single Nucleotide Polyphormisms (SNPs)

Response to treatment?
Disease risk?
Drug assimilation rate?
Ancestry?
. . .

DNA sequences

	s_1	— — —	s_2	— — —	s_3	— — — —	s_4	— — — —	s_5	— — — — — —	y
P_1 ...	1		0		1		0		0	...	✓
P_2 ...	0		1		0		0		0	...	✗
P_3 ...	1		0		1		0		0	...	✗
P_4 ...	0		0		0		0		0	...	✓
P_5 ...	0		0		0		0		0	...	✓
P_6 ...	1		1		0		1		1	...	✗
P_7 ...	1		1		1		1		1	...	✗
P_8 ...	0		1		0		0		1	...	✓
	↑		↑		↑		↑		↑		

Single Nucleotide Polyphormisms (SNPs)

Sequence → Query →

Response to treatment?
Disease risk?
Drug assimilation rate?
Ancestry?
. . .

The LASSO is commonly used to predict $\boldsymbol{y}$:

$$\underbrace{\begin{pmatrix} \boldsymbol{y}_1 \\ \vdots \\ \boldsymbol{y}_n \end{pmatrix}}_{\in \mathbb{R}^n} \approx \underbrace{\begin{pmatrix} | & | & & | \\ \boldsymbol{X}_1 & \boldsymbol{X}_2 & \dots & \boldsymbol{X}_n \\ | & | & & | \end{pmatrix}}_{\boldsymbol{X} \in [\![0,1]\!]^{n \times p}} \cdot \underbrace{\begin{pmatrix} \boldsymbol{w}_1^* \\ \vdots \\ \boldsymbol{w}_n^* \end{pmatrix}}_{\in \mathbb{R}^p} \qquad \text{Typically, } n << p.$$

$$\boldsymbol{w}^* \leftarrow \underset{\boldsymbol{w} \in \mathbb{R}^p}{\operatorname{argmin}} \; \frac{1}{n} \underbrace{\|\boldsymbol{y} - \boldsymbol{X}\boldsymbol{w}\|_2^2}_{\text{data fitting term}} + \underbrace{\lambda \|\boldsymbol{w}\|_1}_{\text{sparsity inducing penalty}} \qquad \text{(LASSO)}$$

The penalty forces only a few features to be selected in the model, for ex:

$$\boldsymbol{y} = \boldsymbol{w}_1^* \boldsymbol{X}_{s_1} + \boldsymbol{w}_4^* \boldsymbol{X}_{s4} + \boldsymbol{w}_5^* \boldsymbol{X}_{s_5}$$

Motivating example

We would like to also consider second order interaction effects of the form:

$$\boldsymbol{X}_j \odot \boldsymbol{X}_k, \quad (j, k) \in [\![1, p]\!]^2$$

where $\odot$ is the Hadamard product (=entrywise product).

Typically, we would like to be able to learn a model such as:

$$\boldsymbol{y} = \boldsymbol{w}_1^* \boldsymbol{X}_{s_1} + \boldsymbol{w}_4^* \boldsymbol{X}_{s_4} + \boldsymbol{w}_5^* \boldsymbol{X}_{s_5} + \boldsymbol{w}_{1,2}^* \boldsymbol{X}_{s_1} \odot \boldsymbol{X}_{s_2}$$

We would like to also consider second order interaction effects of the form:

$$\boldsymbol{X}_j \odot \boldsymbol{X}_k, \quad (j, k) \in [\![1, p]\!]^2$$

where $\odot$ is the Hadamard product (=entrywise product).

Typically, we would like to be able to learn a model such as:

$$\boldsymbol{y} = w_1^* \boldsymbol{X}_{s_1} + w_4^* \boldsymbol{X}_{s_4} + w_5^* \boldsymbol{X}_{s_5} + w_{1,2}^* \boldsymbol{X}_{s_1} \odot \boldsymbol{X}_{s_2}$$

Why is it interesting?

brown hair genes
AND
*MCR*1*-variant 1*
$\Longrightarrow$

brown hair genes
AND
*MCR*1*-variant 2*
$\Longrightarrow$

We would like to also consider second order interaction effects of the form:

$$\boldsymbol{X}_j \odot \boldsymbol{X}_k, \quad (j,k) \in [\![1,p]\!]^2$$

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Typically, we would like to be able to learn a model such as:

$$\boldsymbol{y} = \boldsymbol{w}_1^* \boldsymbol{X}_{s_1} + \boldsymbol{w}_4^* \boldsymbol{X}_{s_4} + \boldsymbol{w}_5^* \boldsymbol{X}_{s_5} + \boldsymbol{w}_{1,2}^* \boldsymbol{X}_{s_1} \odot \boldsymbol{X}_{s_2}$$

Why is it difficult?

The number of interactions terms is equal to:

$$D = \frac{p(p-1)}{2}$$

If $p = 100.000$, then $D = 5 \times 10^9$.
Classical LASSO solvers will be too slow.

⟹ This work aims at providing a framework to fit sparse linear models with second order interaction terms when the data is binary.

Problem formulation

$$\boldsymbol{y} = \underbrace{\begin{pmatrix} \boldsymbol{y}_1 \\ \vdots \\ \boldsymbol{y}_n \end{pmatrix}}_{\in \mathbb{R}^n}, \quad \boldsymbol{X} = \underbrace{\begin{pmatrix} | & | & & | \\ \boldsymbol{X}_1 & \boldsymbol{X}_2 & \dots & \boldsymbol{X}_n \\ | & | & & | \end{pmatrix}}_{\in [\![0,1]\!]^{n \times p}}, \quad \boldsymbol{Z} = \underbrace{\begin{pmatrix} | & | & & | & | & & | \\ \boldsymbol{X}_1 & \boldsymbol{X}_2 & \dots & \boldsymbol{X}_n & \boldsymbol{X}_1\boldsymbol{X}_n & \dots & \boldsymbol{X}_n\boldsymbol{X}_n \\ | & | & & | & | & & | \end{pmatrix}}_{\in [\![0,1]\!]^{n \times D}}$$

- We will indifferently use $\boldsymbol{X}_j \odot \boldsymbol{X}_k$ and $\boldsymbol{X}_j \boldsymbol{X}_k$.

- Primal problem

$$\min_{(\boldsymbol{w},b) \in \mathbb{R}^D \times \mathbb{R}} g_\lambda(\boldsymbol{w}, b) = \frac{1}{n} \|\boldsymbol{y} - \boldsymbol{Z}\boldsymbol{w} - b\|_2^2 + \lambda \|\boldsymbol{w}\|_1 \tag{1}$$

- Dual problem

$$\max_{\boldsymbol{\theta} \in \mathbb{R}^n} f_\lambda(\boldsymbol{\theta}) = \frac{1}{2}\|\boldsymbol{y}\|_2^2 - \frac{1}{2}\|\boldsymbol{\theta} - \boldsymbol{y}\|_2^2 \text{ s.t. } \begin{cases} \left|(\boldsymbol{X}_j\boldsymbol{X}_k)^T\boldsymbol{\theta}\right| \leq \lambda & (j,k) \in [\![1,p]\!]^2 \\ \mathbf{1}^T\boldsymbol{\theta} = 0 \end{cases} \tag{2}$$

- Safe Pattern Pruning (SPP) (Nakagawa et al., 2016)

- SPP relies on **safe screening rules**. Given primal and dual feasible solutions, safe screening rules identify features which are guaranteed not be active at the optimum.

- The idea of SPP is to leverage **the tree structure of interactions features**, and propose a screening rule applicable to entire branches.
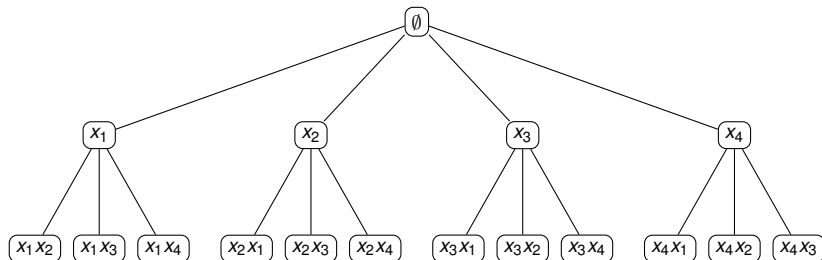
- Limitations:
  - ✓ SPP does not allow to prune enough branches, especially when *n* increases.
  - ✓ The size of the safe set can be big (for medium values of λ)
  - ✓ A dual feasible point is expensive to compute.

- We propose **WHInter**:
  - ✓ Working set strategy.
  - ✓ New branch pruning strategy for the identification of the active set.
  - ✓ Efficient computation of branch bounds using a Maximum Inner Product Search (MIPS) framework for binary data.

WHInter achieves a **speed ups of up to one order of magnitude** compared to SPP.

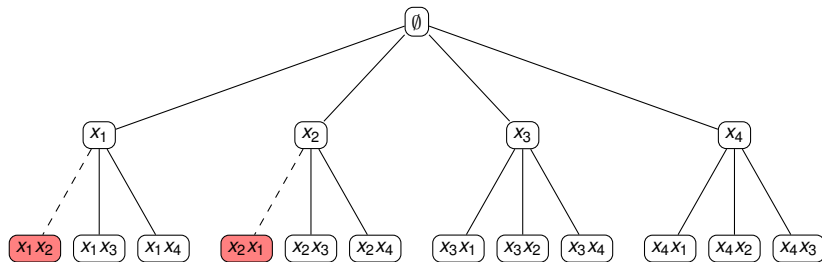**Input:** $X \in [\![0,1]\!]^{n \times p}, \quad y \in \mathbb{R}^n$

$\mathcal{M}_\lambda = \left\{ \quad \right\}$

WHInter pseudo algorithm

Input: $X \in [\![0,1]\!]^{n \times p}, \quad y \in \mathbb{R}^n$

$\mathcal{M}_\lambda = \left\{ \boxed{x_1 x_2} \right\}$

Initialize $\mathcal{M}_\lambda$.

Input: $\boldsymbol{X} \in [\![0, 1]\!]^{n \times p}, \quad \boldsymbol{y} \in \mathbb{R}^n$

$$\mathcal{M}_\lambda = \left\{ \boxed{x_1 x_2} \right\}$$

Initialize $\mathcal{M}_\lambda$.
Pre-solve and initialize ϕ.

$$\boldsymbol{w}, b \leftarrow \underset{(\boldsymbol{w}, b) \in \mathbb{R}^D \times \mathbb{R}}{\operatorname{argmin}} \frac{1}{n} \|\boldsymbol{y} - \boldsymbol{Z}_{\mathcal{M}_\lambda} \boldsymbol{w} - b\|_2^2 + \lambda \|\boldsymbol{w}\|_1$$

$$\phi \leftarrow \boldsymbol{y} - \boldsymbol{Z}_{\mathcal{M}_\lambda} \boldsymbol{w} - b$$

Problem formulation

$$y = \underbrace{\begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}}_{\in \mathbb{R}^n}, \quad X = \underbrace{\left(\begin{array}{c|c|c|c} | & | & & | \\ X_1 & X_2 & \ldots & X_n \\ | & | & & | \end{array} \right)}_{\in [\![0,1]\!]^{n \times p}}, \quad Z = \underbrace{\left(\begin{array}{c|c|c|c|c|c|c} | & | & & | & | & & | \\ X_1 & X_2 & \ldots & X_n & X_1 X_n & \ldots & X_n X_n \\ | & | & & | & | & & | \end{array} \right)}_{\in [\![0,1]\!]^{n \times D}}$$

- The KKT conditions state that:

$$\forall (j,k) \in [\![1,p]\!]^2, \quad \left| (X_j X_k)^T \theta^* \right| \in \begin{cases} \{\lambda\} \text{ if } w_{j,k}^* \neq 0 \\ [-\lambda, \lambda] \text{ if } w_{j,k}^* = 0 \end{cases} \tag{3}$$

  We will say that the constraint relative to $X_j X_k$ is violated whenever $\left| (X_j X_k)^T \theta \right| > \lambda$

- The primal and dual optimal variables ($w*$, $b*$) and θ^* are related as follows:

$$\theta^* = y - Zw^* - b^*$$

Input: $\boldsymbol{X} \in [\![0, 1]\!]^{n \times p}, \quad \boldsymbol{y} \in \mathbb{R}^n$

$$\mathcal{M}_\lambda = \left\{ \; \boxed{x_1 x_2} \; \right\}$$

Identify violated constraints and update working set.

Compute the bound $\eta(\phi, \boldsymbol{X}_j)$.

We define $\eta(\phi, \boldsymbol{X}_j)$ as an upper bound on $\displaystyle\max_{\boldsymbol{X}_k : \, \boldsymbol{X}_j \boldsymbol{X}_k \notin \mathcal{M}_\lambda} \left| \left(\boldsymbol{X}_j \boldsymbol{X}_k \right)^T \phi \right|$.

If $\eta(\phi, \boldsymbol{X}_j) \leq \lambda$, then we know that all features in the branch respect the optimality conditions.

Input: $\boldsymbol{X} \in [\![0,1]\!]^{n \times p}, \quad \boldsymbol{y} \in \mathbb{R}^n$

$$\mathcal{M}_\lambda = \left\{ \boxed{x_1 x_2} \right\}$$
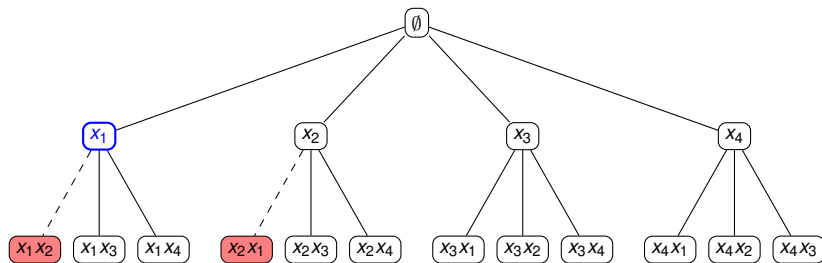
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$$\eta(\phi, \boldsymbol{X}_1) < \lambda$$

Input: $\boldsymbol{X} \in [\![0,1]\!]^{n \times p}$, $\quad \boldsymbol{y} \in \mathbb{R}^n$

$$\mathcal{M}_\lambda = \left\{ \boxed{x_1 x_2} \right\}$$
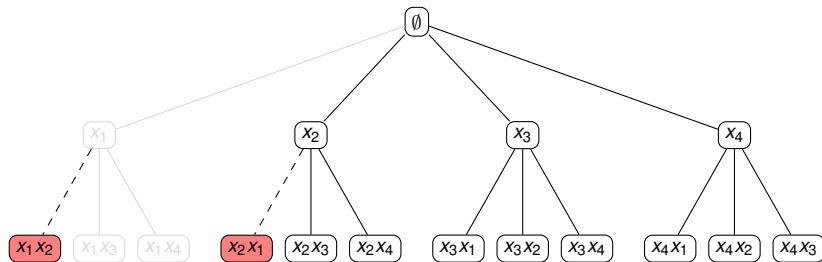
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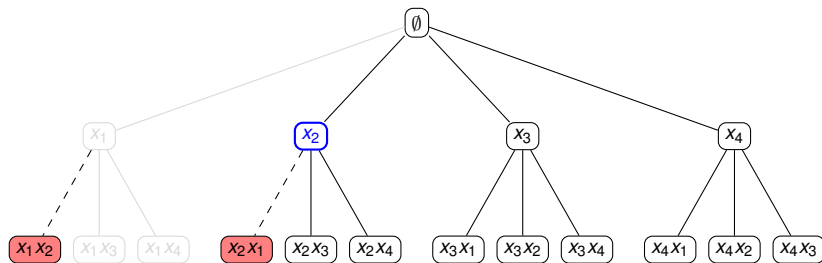
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$$\eta(\phi, \boldsymbol{X}_2) \geq \lambda$$

Input: $\boldsymbol{X} \in [\![0,1]\!]^{n \times p}, \quad \boldsymbol{y} \in \mathbb{R}^n$

$$\mathcal{M}_\lambda = \left\{ \; \boxed{x_1 x_2} \; \right\}$$
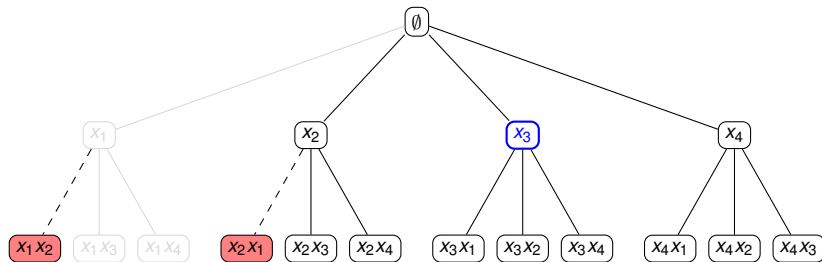
Identify violated constraints and update working set.
Compute the bound $\eta(\phi, \boldsymbol{X}_j)$.

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$$\eta(\phi, \boldsymbol{X}_3) \geq \lambda$$

Input: $\boldsymbol{X} \in [\![0,1]\!]^{n \times p}, \quad \boldsymbol{y} \in \mathbb{R}^n$

$$\mathcal{M}_\lambda = \left\{ \boxed{x_1 x_2} \right\}$$
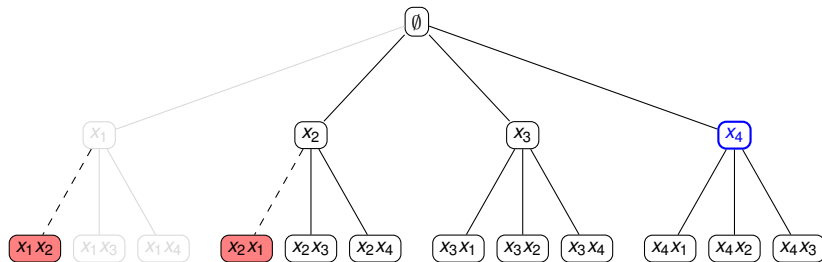
Identify violated constraints and update working set.
Compute the bound $\eta(\phi, \boldsymbol{X}_j)$.

We define $\eta(\phi, \boldsymbol{X}_j)$ as an upper bound on $\max\limits_{\boldsymbol{X}_k:\, \boldsymbol{X}_j \boldsymbol{X}_k \notin \mathcal{M}_\lambda} \left| \left(\boldsymbol{X}_j \boldsymbol{X}_k\right)^T \phi \right|$.

$$\eta(\phi, \boldsymbol{X}_4) < \lambda$$

WHInter pseudo algorithm

Input: $X \in [\![0,1]\!]^{n \times p}, \quad y \in \mathbb{R}^n$

$$\mathcal{M}_\lambda = \left\{ \boxed{x_1 x_2} \right\}$$
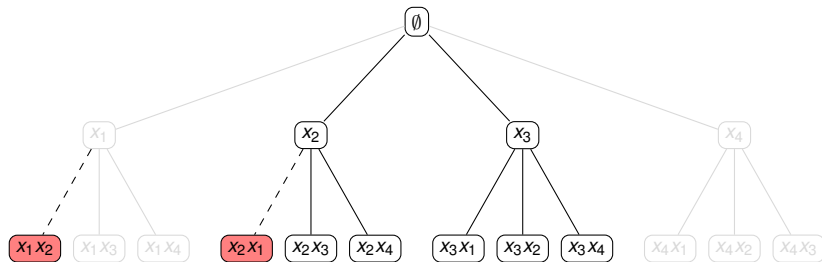
Identify violated constraints and update working set.
Compute the bound $\eta(\phi, X_j)$.

We define $\eta(\phi, X_j)$ as an upper bound on $\displaystyle\max_{X_k : X_j X_k \notin \mathcal{M}_\lambda} \left| \left(X_j X_k \right)^T \phi \right|$.

$$\eta(\phi, X_4) < \lambda$$

Input: $\boldsymbol{X} \in [\![0,1]\!]^{n \times p}, \quad \boldsymbol{y} \in \mathbb{R}^n$

$\mathcal{M}_\lambda = \left\{ \boxed{x_1 x_2} \right\}$

Identify violated constraints and update working set.
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We define $\eta(\phi, \boldsymbol{X}_j)$ as an upper bound on $\max\limits_{\boldsymbol{X}_k : \, \boldsymbol{X}_j \boldsymbol{X}_k \notin \mathcal{M}_\lambda} \left| \left(\boldsymbol{X}_j \boldsymbol{X}_k \right)^T \phi \right|$.

done

WHInter pseudo algorithm

Input: $\boldsymbol{X} \in [\![0,1]\!]^{n \times p}, \quad \boldsymbol{y} \in \mathbb{R}^n$

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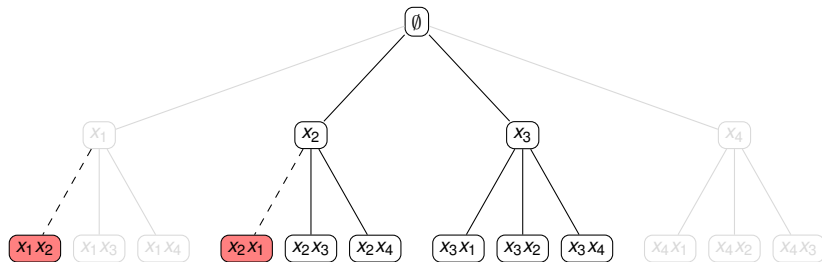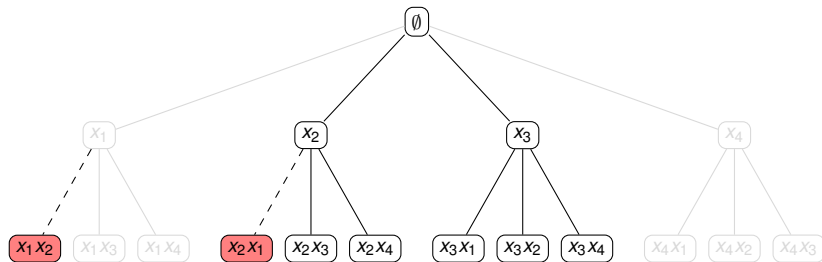
Identify violated constraints and update working set.
If $\eta(\phi, \boldsymbol{X}_j) \geq \lambda$, compute $\boldsymbol{m}_j(\phi)$ and update $\mathcal{M}_\lambda$.

$$\boldsymbol{m}_j(\phi) = \max_{\boldsymbol{X}_k : \boldsymbol{X}_j \boldsymbol{X}_k \notin \mathcal{M}_\lambda} \left| \left(\boldsymbol{X}_j \boldsymbol{X}_k \right)^T \phi \right|, \quad \mathcal{M}_\lambda \leftarrow \mathcal{M}_\lambda \cup \left\{ \boldsymbol{X}_j \boldsymbol{X}_k : \left| \left(\boldsymbol{X}_j \boldsymbol{X}_k \right)^t \phi \right| \geq \lambda \right\}$$

Input: $\mathbf{X} \in [\![0, 1]\!]^{n \times p}$, $\quad \mathbf{y} \in \mathbb{R}^n$

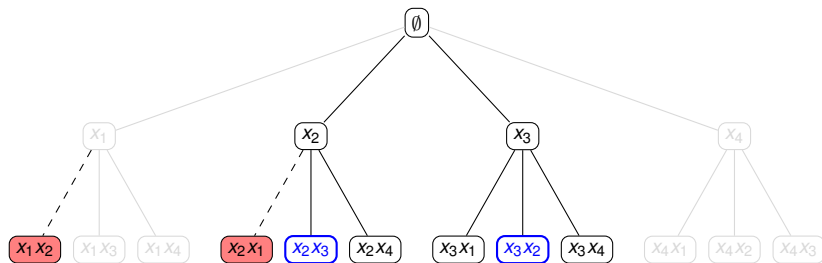$$\mathcal{M}_\lambda = \left\{ \boxed{x_1 x_2} \right\}$$

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$$\left| (\mathbf{X}_2 \mathbf{X}_3)^T \phi \right| \geq \lambda$$

Input: $\boldsymbol{X} \in [\![0,1]\!]^{n \times p}, \quad \boldsymbol{y} \in \mathbb{R}^n$

$$\mathcal{M}_\lambda = \left\{ \boxed{x_1 x_2} \quad \boxed{x_2 x_3} \right\}$$

Identify violated constraints and update working set.
If $\eta(\phi, \boldsymbol{X}_j) \geq \lambda$, compute $\boldsymbol{m}_j(\phi)$ and update $\mathcal{M}_\lambda$.

$$\boldsymbol{m}_j(\phi) = \max_{\boldsymbol{X}_k \,:\, \boldsymbol{X}_j \boldsymbol{X}_k \notin \mathcal{M}_\lambda} \left| (\boldsymbol{X}_j \boldsymbol{X}_k)^T \phi \right|, \quad \mathcal{M}_\lambda \leftarrow \mathcal{M}_\lambda \cup \left\{ \boldsymbol{X}_j \boldsymbol{X}_k : \left| (\boldsymbol{X}_j \boldsymbol{X}_k)^t \phi \right| \geq \lambda \right\}$$

$$\left| (\boldsymbol{X}_2 \boldsymbol{X}_3)^T \phi \right| \geq \lambda$$

WHInter pseudo algorithm

Input: $X \in [\![0, 1]\!]^{n \times p}, \quad y \in \mathbb{R}^n$

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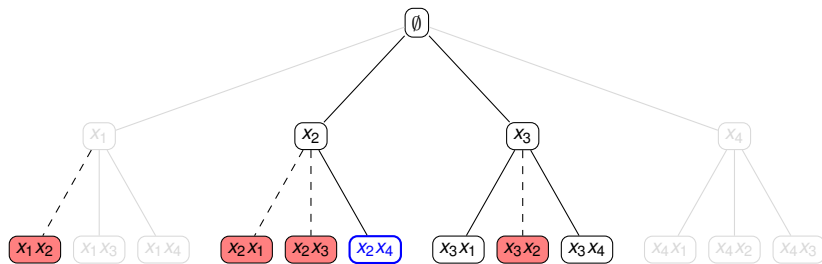
Identify violated constraints and update working set.
If $\eta(\phi, X_j) \geq \lambda$, compute $m_j(\phi)$ and update $\mathcal{M}_\lambda$.

$$m_j(\phi) = \max_{X_k : X_j X_k \notin \mathcal{M}_\lambda} \left| (X_j X_k)^T \phi \right|, \quad \mathcal{M}_\lambda \leftarrow \mathcal{M}_\lambda \cup \left\{ X_j X_k : \left| (X_j X_k)^t \phi \right| \geq \lambda \right\}$$

$$\left| (X_2 X_4)^T \phi \right| < \lambda$$

Input: $\boldsymbol{X} \in [\![0, 1]\!]^{n \times p}, \quad \boldsymbol{y} \in \mathbb{R}^n$

$$\mathcal{M}_\lambda = \left\{ \boxed{x_1 x_2} \quad \boxed{x_2 x_3} \right\}$$

Identify violated constraints and update working set.
If $\eta(\phi, \boldsymbol{X}_j) \geq \lambda$, compute $\boldsymbol{m}_j(\phi)$ and update $\mathcal{M}_\lambda$.

$$\boldsymbol{m}_j(\phi) = \max_{\boldsymbol{X}_k : \, \boldsymbol{X}_j \boldsymbol{X}_k \notin \mathcal{M}_\lambda} \left| (\boldsymbol{X}_j \boldsymbol{X}_k)^T \phi \right|, \quad \mathcal{M}_\lambda \leftarrow \mathcal{M}_\lambda \cup \left\{ \boldsymbol{X}_j \boldsymbol{X}_k : \left| (\boldsymbol{X}_j \boldsymbol{X}_k)^t \phi \right| \geq \lambda \right\}$$

$$\left| (\boldsymbol{X}_3 \boldsymbol{X}_1)^T \phi \right| < \lambda$$

Input: $\boldsymbol{X} \in [\![0, 1]\!]^{n \times p}, \quad \boldsymbol{y} \in \mathbb{R}^n$

$$\mathcal{M}_\lambda = \left\{ \boxed{x_1 x_2} \quad \boxed{x_2 x_3} \right\}$$

Identify violated constraints and update working set.
If $\eta(\phi, \boldsymbol{X}_j) \geq \lambda$, compute $\boldsymbol{m}_j(\phi)$ and update $\mathcal{M}_\lambda$.

$$\boldsymbol{m}_j(\phi) = \max_{\boldsymbol{X}_k: \, \boldsymbol{X}_j \boldsymbol{X}_k \notin \mathcal{M}_\lambda} \left| (\boldsymbol{X}_j \boldsymbol{X}_k)^T \phi \right|, \quad \mathcal{M}_\lambda \leftarrow \mathcal{M}_\lambda \cup \left\{ \boldsymbol{X}_j \boldsymbol{X}_k : \left| (\boldsymbol{X}_j \boldsymbol{X}_k)^t \phi \right| \geq \lambda \right\}$$

$$\left| (\boldsymbol{X}_3 \boldsymbol{X}_4)^T \phi \right| < \lambda$$

Input: $\boldsymbol{X} \in [\![0, 1]\!]^{n \times p}, \quad \boldsymbol{y} \in \mathbb{R}^n$

$$\mathcal{M}_\lambda = \left\{ \boxed{x_1 x_2} \quad \boxed{x_2 x_3} \right\}$$

Identify violated constraints and update working set.
If $\eta(\phi, \boldsymbol{X}_j) \geq \lambda$, compute $\boldsymbol{m}_j(\phi)$ and update $\mathcal{M}_\lambda$.

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done

Input: $\boldsymbol{X} \in [\![0,1]\!]^{n \times p}, \quad \boldsymbol{y} \in \mathbb{R}^n$

$$\mathcal{M}_\lambda = \left\{ \boxed{x_1 x_2} \quad \boxed{x_2 x_3} \right\}$$

Solve subproblem restricted to $\mathcal{M}_\lambda$
Update residuals

$$\boldsymbol{w}, b \leftarrow \underset{(\boldsymbol{w},b) \in \mathbb{R}^D \times \mathbb{R}}{\mathrm{argmin}} \frac{1}{n} \|\boldsymbol{y} - \boldsymbol{Z}_{\mathcal{M}_\lambda} \boldsymbol{w} - b\|_2^2 + \lambda \|\boldsymbol{w}\|_1$$

$$\phi \leftarrow \boldsymbol{y} - \boldsymbol{Z}_{\mathcal{M}_\lambda} \boldsymbol{w} - b$$

Input: $\boldsymbol{X} \in [\![0,1]\!]^{n \times p}, \quad \boldsymbol{y} \in \mathbb{R}^n$

$$\mathcal{M}_\lambda = \left\{ \begin{array}{c} x_1 x_2 \end{array} \begin{array}{c} x_2 x_3 \end{array} \right\}$$

1: Initialize $\mathcal{M}_\lambda$. Pre-solve and initialize ϕ.
2: **repeat**:
3:     **for** each branch *j* **do**:
        # Identify violated constraints and update working set.
4:         Compute the bound $\eta(\phi, \boldsymbol{X}_j)$.
5:         If $\eta(\phi, \boldsymbol{X}_j) \geq \lambda$, compute $\boldsymbol{m}_j(\phi)$ and update $\mathcal{M}_\lambda$.
6:     Solve subproblem
7: **until** no violated constraint remains.

Input: $\boldsymbol{X} \in [\![0,1]\!]^{n \times p}$, $\quad \boldsymbol{y} \in \mathbb{R}^n$

$$\mathcal{M}_\lambda = \left\{ \boxed{x_1 x_2} \quad \boxed{x_2 x_3} \right\}$$

1: Initialize $\mathcal{M}_\lambda$. Pre-solve and initialize ϕ.
2: **repeat**:
3:    **for** each branch j **do**:
     # Identify violated constraints and update working set.
4:      Compute the bound $\eta(\phi, \boldsymbol{X}_j)$.
5:      If $\eta(\phi, \boldsymbol{X}_j) \geq \lambda$, compute $\boldsymbol{m}_j(\phi)$ and update $\mathcal{M}_\lambda$.
6:    Solve subproblem
7: **until** no violated constraint remains.

Input: $X \in [\![0, 1]\!]^{n \times p}, \quad y \in \mathbb{R}^n$

$$\mathcal{M}_\lambda = \left\{ \boxed{x_1 x_2} \quad \boxed{x_2 x_3} \right\}$$

1: Initialize $\mathcal{M}_\lambda$. Pre-solve and initialize ϕ.
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5:        If $\eta(\phi, X_j) \geq \lambda$, compute $m_j(\phi)$ and update $\mathcal{M}_\lambda$.
6:     Solve subproblem
7: **until** no violated constraint remains.

- Suppose the current residual is ϕ. For each branch $j \in [\![1, p]\!]$, we want a bound $\eta(\phi, \boldsymbol{X}_j)$ such that:

$$\boldsymbol{m}_j(\phi) = \max_{\boldsymbol{X}_k \,:\, \boldsymbol{X}_j \boldsymbol{X}_k \notin \mathcal{M}_\lambda} \left| (\boldsymbol{X}_j \boldsymbol{X}_k)^T \phi \right| \leq \eta(\phi, \boldsymbol{X}_j)$$

- One possibility is to use the following bound (as in Nakagawa et al.):

$$\boldsymbol{m}_j(\phi) \leq \max_{\boldsymbol{x} \in [\![0,1]\!]^n} \left| (\boldsymbol{X}_j \odot \boldsymbol{x})^T \phi \right|$$

$$= \max \left(\sum_{i:\phi_i > 0} \boldsymbol{X}_{ij} \phi_i, \, - \sum_{i:\phi_i < 0} \boldsymbol{X}_{ij} \phi_i \right)$$

$$= \zeta(\phi, \boldsymbol{X}_j)$$

✓ can be computed very efficiently.
✓ but becomes too loose when n increases, leading to only few branches pruned.

- Suppose the current residual is ϕ.

  Suppose we have already computed $\boldsymbol{m}_j(\phi^{prev}) = \max\limits_{\boldsymbol{X}_k \,:\, \boldsymbol{X}_j\boldsymbol{X}_k \notin \mathcal{M}_\lambda} \left| (\boldsymbol{X}_j\boldsymbol{X}_k)^T \phi^{prev} \right|$

  We propose the following bound:

$$
\begin{aligned}
\boldsymbol{m}_j(\phi) &= \max_{\boldsymbol{x} \in \mathcal{D}e(\boldsymbol{X}_j)} \left| \boldsymbol{x}^T \phi \right| \\
&= \max_{\boldsymbol{x} \in \mathcal{D}e(\boldsymbol{X}_j)} \left| \boldsymbol{x}^T \phi^{prev} + \boldsymbol{x}^T \left(\phi - \phi^{prev} \right) \right| \\
&\leq \max_{\boldsymbol{x} \in \mathcal{D}e(\boldsymbol{X}_j)} \left| \boldsymbol{x}^T \phi^{prev} \right| + \max_{\boldsymbol{x} \in \mathcal{D}e(\boldsymbol{X}_j)} \left| \boldsymbol{x}^T \left(\phi - \phi^{prev} \right) \right| \\
&\leq \boldsymbol{m}_j(\phi_{prev}) + \max_{\boldsymbol{x} \in [\![0,1]\!]^n} \left| \left(\boldsymbol{X}_j \odot \boldsymbol{x} \right)^T \left(\phi - \phi^{prev} \right) \right| \\
&= \boldsymbol{m}_j(\phi_{prev}) + max \left(\sum_{i:\phi_i > \phi_i^{prev}} \boldsymbol{X}_{ij} \left(\phi_i - \phi_i^{prev} \right), - \sum_{i:\phi_i < \phi_i^{prev}} \boldsymbol{X}_{ij} \left(\phi_i - \phi_i^{prev} \right) \right) \\
&= \eta(\phi, \boldsymbol{X}_j)
\end{aligned}
$$

- We leverage previously computed maximum inner products and the fact that residuals along the regularization path are correlated.
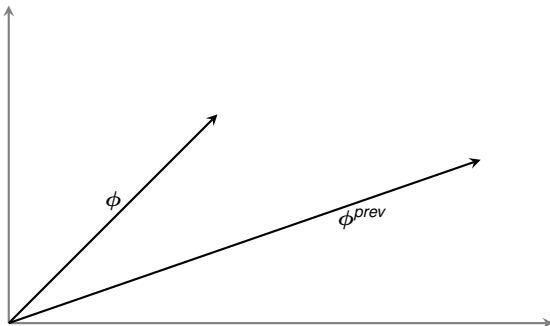
- Suppose the current residual is ϕ.
  Suppose we have already computed $\boldsymbol{m}_j(\phi^{prev}) = \max\limits_{\boldsymbol{X}_k : \boldsymbol{X}_j \boldsymbol{X}_k \notin \mathcal{M}_\lambda} \left| (\boldsymbol{X}_j \boldsymbol{X}_k)^T \phi^{prev} \right|$
  We propose the following bound:

$$
\begin{aligned}
\boldsymbol{m}_j(\phi) &= \max_{\boldsymbol{x} \in \mathcal{D}e(\boldsymbol{X}_j)} \left| \boldsymbol{x}^T \phi \right| \\
&= \max_{\boldsymbol{x} \in \mathcal{D}e(\boldsymbol{X}_j)} \left| \alpha \boldsymbol{x}^T \phi^{prev} + \boldsymbol{x}^T \left(\phi - \alpha \phi^{prev} \right) \right| \\
&\leq \max_{\boldsymbol{x} \in \mathcal{D}e(\boldsymbol{X}_j)} |\alpha| \left| \boldsymbol{x}^T \phi^{prev} \right| + \max_{\boldsymbol{x} \in \mathcal{D}e(\boldsymbol{X}_j)} \left| \boldsymbol{x}^T \left(\phi - \alpha \phi^{prev} \right) \right| \\
&\leq |\alpha| \, \boldsymbol{m}_j(\phi_{prev}) + \max_{\boldsymbol{x} \in \llbracket 0,1 \rrbracket^n} \left| (\boldsymbol{X}_j \odot \boldsymbol{x})^T \left(\phi - \alpha \phi^{prev} \right) \right| \\
&= |\alpha| \, \boldsymbol{m}_j(\phi_{prev}) + max \left(\sum_{i : \phi_i > \alpha \phi_i^{prev}} \boldsymbol{X}_{ij} \left(\phi_i - \alpha \phi_i^{prev} \right), - \sum_{i : \phi_i < \alpha \phi_i^{prev}} \boldsymbol{X}_{ij} \left(\phi_i - \alpha \phi_i^{prev} \right) \right) \\
&= \eta(\phi, \boldsymbol{X}_j, \alpha)
\end{aligned}
$$

- We leverage previously computed maximum inner products and the fact that residuals along the regularization path are correlated.

$$\eta(\phi, \boldsymbol{X}_j, \alpha) = |\alpha| \, \boldsymbol{m}_j + max \left(\sum_{i:\phi_i > \alpha \phi_i^{prev}} \boldsymbol{X}_{ij} \left(\phi_i - \alpha \phi_i^{prev} \right), - \sum_{i:\phi_i < \alpha \phi_i^{prev}} \boldsymbol{X}_{ij} \left(\phi_i - \alpha \phi_i^{prev} \right) \right)$$

$$\eta(\phi, \boldsymbol{X}_j, \alpha) = |\alpha| \, \boldsymbol{m}_j + max \left(\sum_{i:\phi_i > \alpha \phi_i^{prev}} \boldsymbol{X}_{ij} \left(\phi_i - \alpha \phi_i^{prev} \right), - \sum_{i:\phi_i < \alpha \phi_i^{prev}} \boldsymbol{X}_{ij} \left(\phi_i - \alpha \phi_i^{prev} \right) \right)$$

$$\eta(\phi, \mathbf{X}_j, \alpha) = |\alpha| \, \mathbf{m}_j + max \left(\sum_{i:\phi_i > \alpha \phi_i^{prev}} \mathbf{X}_{ij} \left(\phi_i - \alpha \phi_i^{prev} \right), - \sum_{i:\phi_i < \alpha \phi_i^{prev}} \mathbf{X}_{ij} \left(\phi_i - \alpha \phi_i^{prev} \right) \right)$$
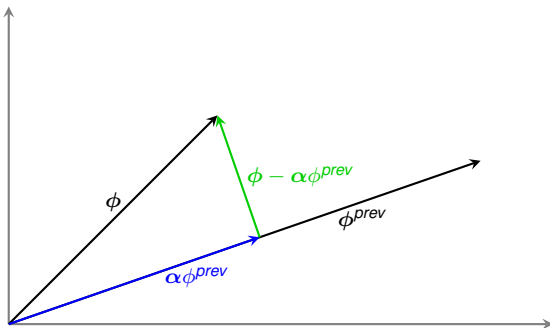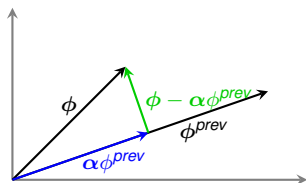
$$\eta(\phi, \mathbf{X}_j, \alpha) = |\alpha|\, \mathbf{m}_j + max \left(\sum_{i:\phi_i > \alpha\phi_i^{prev}} \mathbf{X}_{ij}\left(\phi_i - \alpha\phi_i^{prev}\right), - \sum_{i:\phi_i < \alpha\phi_i^{prev}} \mathbf{X}_{ij}\left(\phi_i - \alpha\phi_i^{prev}\right) \right)$$

How to choose α?

- Option 1: $\alpha^* = \underset{\alpha \in \mathbb{R}}{\operatorname{argmin}}\, \eta(\phi, \mathbf{X}_j, \alpha)$
  - ✓ η is a piecewise continuous function which is convex in α.
  - ✓ η can be minimized in $\mathcal{O}(n_j \log n_j)$ operations.

- Option 2: $\alpha_{\ell 2} = \dfrac{\phi^T \phi^{prev}}{\|\phi^{prev}\|_2^2}$
  - ✓ $\alpha_{\ell 2}$ minimizes $\|\phi - \alpha\phi^{prev}\|_2^2$.
  - ✓ $\alpha_{\ell 2}$ can be obtained in $\mathcal{O}(n_j)$ operations.

Input: $X \in [\![0, 1]\!]^{n \times p}, \quad y \in \mathbb{R}^n$

$\mathcal{M}_\lambda = \left\{ \boxed{x_1 x_2} \quad \boxed{x_2 x_3} \right\}$

1: Initialize $\mathcal{M}_\lambda$
2: **repeat**:
3:   **for** each branch j **do**:
      # Identify violated constraints and update working set.
4:     Compute the bound $\eta(\phi, X_j)$.
5:     If $\eta(\phi, X_j) \geq \lambda$, compute $m_j(\phi)$ and update $\mathcal{M}_\lambda$.
6:   Solve subproblem
7: **until** no violated constraint remains.

Input: $\boldsymbol{X} \in [\![0,1]\!]^{n \times p}, \quad \boldsymbol{y} \in \mathbb{R}^n$

$$\mathcal{M}_\lambda = \left\{ \boxed{x_1 x_2} \quad \boxed{x_2 x_3} \right\}$$

1: Initialize $\mathcal{M}_\lambda$
2: **repeat**:
3:     **for** each branch *j* **do**:
      # Identify violated constraints and update working set.
4:       Compute the bound $\eta(\phi, \boldsymbol{X}_j)$.
5:       If $\eta(\phi, \boldsymbol{X}_j) \geq \lambda$, compute $\boldsymbol{m}_j(\phi)$ and update $\mathcal{M}_\lambda$. ⬅
6:     Solve subproblem
7: **until** no violated constraint remains.

- Whenever $\eta(\phi, \boldsymbol{X}_j, \alpha^*) \geq \lambda$, then there is a chance that branch j contains a feature which is violated for the current residual ϕ. In this case we need to:
  - ✓ identify all violated features.
  - ✓ compute:

$$\boldsymbol{m}_j = \max_{\boldsymbol{X}_k : \boldsymbol{X}_j \boldsymbol{X}_k \notin \mathcal{M}_\lambda} \left| \left(\boldsymbol{X}_j \odot \boldsymbol{X}_k \right)^T \phi \right|$$

  which naively requires computing all inner products.

- We note that $\boldsymbol{m}_j$ can be rewritten as:

$$\boldsymbol{m}_j = \max_{\boldsymbol{X}_k : \boldsymbol{X}_j \boldsymbol{X}_k \notin \mathcal{M}_\lambda} \left| \boldsymbol{X}_k^T \left(\boldsymbol{X}_j \odot \phi \right) \right|$$

This is (almost) a Maximum Inner product Search (MIPS) problem with query vector $\boldsymbol{X}_j \odot \phi$ and database or probe vectors $\{ \boldsymbol{X}_k, k \in [\![1, p]\!] : \boldsymbol{X}_j \boldsymbol{X}_k \notin \mathcal{M}_\lambda \}$.

- Relevant work in the data mining literature (far from exhaustive):

    ✓ State-of-the-art exact MIPS algorithm:

    Christina Teflioudi and Rainer Gemulla. "Exact and Approximate Maximum Inner Product Search with LEMP". . In: *TODS* (2016)

    ✓ All pairs similarity search algorithm:

    Roberto J. Bayardo, Yiming Ma, and Ramakrishnan Srikant. "Scaling up all pairs similarity search". In: *Proc. 16th Int. Conf. World Wide Web - WWW '07* (2007), p. 131

- We borrow the idea of computing inner products on restricted sets of dimensions, and bounding the part of the inner product on the remaining dimensions.

- We implement this idea in the case of our particular setting where:
    ✓ queries are sparse vectors of the form: $\boldsymbol{X}_j \odot \phi$, and ϕ can have both positive and negative entries.
    ✓ probes are binary vectors.

Input: $\boldsymbol{Q} = \left\{ \boldsymbol{X}_j : \eta(\phi, \boldsymbol{X}_j) \geq \lambda \right\} \in [0,1]^{n \times q}, \quad \boldsymbol{P} \in [0,1]^{n \times p}, \quad \phi \in \mathbb{R}^n$

Param: $n_c \in \mathbb{N}$

Output: $\boldsymbol{m} \in \mathbb{R}^q$ and $\boldsymbol{k} \in \mathbb{R}^q$.

1: Reorder the dimensions $1 \ldots n$ such that $|\phi|$ is sorted in descending order.

2: Reorder the vectors $\boldsymbol{P}_j$ in $\boldsymbol{P}$ in increasing order of $\mathrm{nnz}(\boldsymbol{P}_j)$.

3: Initialize the best inner products $\boldsymbol{m} \in \mathbb{R}^q$ for each query.

    We note $\mathcal{N}_j \subset [\![1, n]\!]$ the set of non zero entries of $\boldsymbol{X}_j$.

4: **for** $j \in [\![1, q]\!]$ **do**

      # Compute $\boldsymbol{r}^+ \in \mathbb{R}^n$ and $\boldsymbol{r}^- \in \mathbb{R}^n$ the partial inner product upperbounds.

5:   **for** $i \in \mathcal{N}_j$ **do**

6:     $r_i^+ = \sum\limits_{m > i; \; m : \phi_m > 0} \boldsymbol{X}_{mj} \phi_m \quad$ and $\quad r_i^- = \sum\limits_{m > i; \; m : \phi_m < 0} \boldsymbol{X}_{mj} \phi_m$

7:   **for** $k \in [\![1, p]\!]$ **do**

8:     d = 0 (inner product initialization); c = 0 (counter initialization);

9:     **for** $i \in \mathcal{N}_j$ **do**

10:       $d = d + \boldsymbol{Q}_{ij} \boldsymbol{P}_{ik} \phi_i; \quad c = c + 1.$

11:       **if** $c \bmod n_c == 0$ **then**

12:         **if** $(d + r_i^+) < \min(\boldsymbol{m}_j, \lambda)$ and $\left| (d + r_i^-) \right| < \min(\boldsymbol{m}_j, \lambda)$ **then** go to next probe.

13:     **if** $\boldsymbol{m}_j < d < \lambda$ **then** set $\boldsymbol{m}_j = d$ and $\boldsymbol{k}_j = k$

14:     **if** $d \geq \lambda$ **then** add $\boldsymbol{X}_j \boldsymbol{X}_k$ to $\mathcal{M}_\lambda$

Maximum Inner Product Search

Input: $Q = \{X_j : \eta(\phi, X_j) \geq \lambda\} \in [0,1]^{n \times q}, \quad P \in [0,1]^{n \times p}, \quad \phi \in \mathbb{R}^n$

Param: $n_c \in \mathbb{N}$

Output: $m \in \mathbb{R}^q$ and $k \in \mathbb{R}^q$.

1: Reorder the dimensions $1 \ldots n$ such that $|\phi|$ is sorted in descending order.

2: Reorder the vectors P_j in P in increasing order of $\texttt{nnz}(P_j)$.

3: Initialize the best inner products $m \in \mathbb{R}^q$ for each query.

   We note $\mathcal{N}_j \subset [\![1, n]\!]$ the set of non zero entries of X_j.

4: **for** $j \in [\![1, q]\!]$ **do**

   # Compute $r^+ \in \mathbb{R}^n$ and $r^- \in \mathbb{R}^n$ the partial inner product upperbounds.

5:     **for** $i \in \mathcal{N}_j$ **do**

6:       $r_i^+ = \sum_{m > i;\ m:\phi_m > 0} X_{mj}\phi_m \quad and \quad r_i^- = \sum_{m > i;\ m:\phi_m < 0} X_{mj}\phi_m$

7:     **for** $k \in [\![1, p]\!]$ **do**

8:       d = 0 (inner product initialization); c = 0 (counter initialization);

9:       **for** $i \in \mathcal{N}_j$ **do**

10:        $d = d + Q_{ij}P_{ik}\phi_i; \quad c = c + 1$.

11:        **if** $c \bmod n_c == 0$ **then**

12:          **if** $(d + r_i^+) < \min(m_j, \lambda)$ and $\left|(d + r_i^-)\right| < \min(m_j, \lambda)$ **then** go to next probe.

13:       **if** $m_j < d < \lambda$ **then** set $m_j = d$ and $k_j = k$

14:       **if** $d \geq \lambda$ **then** add $X_j X_k$ to $\mathcal{M}_\lambda$

Maximum Inner Product Search

Input: $Q = \{ X_j : \eta(\phi, X_j) \geq \lambda \} \in [0,1]^{n \times q}, \quad P \in [0,1]^{n \times p}, \quad \phi \in \mathbb{R}^n$

Param: $n_c \in \mathbb{N}$

Output: $m \in \mathbb{R}^q$ and $k \in \mathbb{R}^q$.

1: Reorder the dimensions $1 \ldots n$ such that $|\phi|$ is sorted in descending order.
2: Reorder the vectors P_j in P in increasing order of $\texttt{nnz}(P_j)$.
3: Initialize the best inner products $m \in \mathbb{R}^q$ for each query.
   We note $\mathcal{N}_j \subset [\![1, n]\!]$ the set of non zero entries of X_j.
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6:     $r_i^+ = \sum\limits_{m>i; \; m:\phi_m>0} X_{mj}\phi_m \quad$ *and* $\quad r_i^- = \sum\limits_{m>i; \; m:\phi_m<0} X_{mj}\phi_m$
7:   **for** $k \in [\![1, p]\!]$ **do**
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9:     **for** $i \in \mathcal{N}_j$ **do**
10:       $d = d + Q_{ij}P_{ik}\phi_i; \quad c = c + 1.$
11:       **if** $c \bmod n_c == 0$ **then**
12:         **if** $(d + r_i^+) < \min(m_j, \lambda)$ and $\left| (d + r_i^-) \right| < \min(m_j, \lambda)$ **then** go to next probe.
13:     **if** $m_j < d < \lambda$ **then** set $m_j = d$ and $k_j = k$
14:     **if** $d \geq \lambda$ **then** add $X_j X_k$ to $\mathcal{M}_\lambda$

Maximum Inner Product Search

Input: $\mathbf{Q} = \left\{ \mathbf{X}_j : \eta(\phi, \mathbf{X}_j) \geq \lambda \right\} \in [0, 1]^{n \times q}, \quad \mathbf{P} \in [0, 1]^{n \times p}, \quad \phi \in \mathbb{R}^n$

Param: $n_c \in \mathbb{N}$

Output: $\mathbf{m} \in \mathbb{R}^q$ and $\mathbf{k} \in \mathbb{R}^q$.

1: Reorder the dimensions $1 \ldots n$ such that $|\phi|$ is sorted in descending order.
2: Reorder the vectors $\mathbf{P}_j$ in $\mathbf{P}$ in increasing order of $\texttt{nnz}(\mathbf{P}_j)$.
3: Initialize the best inner products $\mathbf{m} \in \mathbb{R}^q$ for each query.
   We note $\mathcal{N}_j \subset [\![1, n]\!]$ the set of non zero entries of $\mathbf{X}_j$.
4: **for** $j \in [\![1, q]\!]$ **do**
    # Compute $\mathbf{r}^+ \in \mathbb{R}^n$ and $\mathbf{r}^- \in \mathbb{R}^n$ the partial inner product upperbounds.
5: **for** $i \in \mathcal{N}_j$ **do**
6:   $r_i^+ = \displaystyle\sum_{m > i; \ m : \phi_m > 0} \mathbf{X}_{mj} \phi_m \quad and \quad r_i^- = \displaystyle\sum_{m > i; \ m : \phi_m < 0} \mathbf{X}_{mj} \phi_m$
7: **for** $k \in [\![1, p]\!]$ **do**
8:   d = 0 (inner product initialization); c = 0 (counter initialization);
9:   **for** $i \in \mathcal{N}_j$ **do**
10:    $d = d + \mathbf{Q}_{ij} \mathbf{P}_{ik} \phi_i; \quad c = c + 1$.
11:    **if** $c \bmod n_c == 0$ **then**
12:     **if** $(d + r_i^+) < \min(\mathbf{m}_j, \lambda)$ and $\left| (d + r_i^-) \right| < \min(\mathbf{m}_j, \lambda)$ **then** go to next probe.
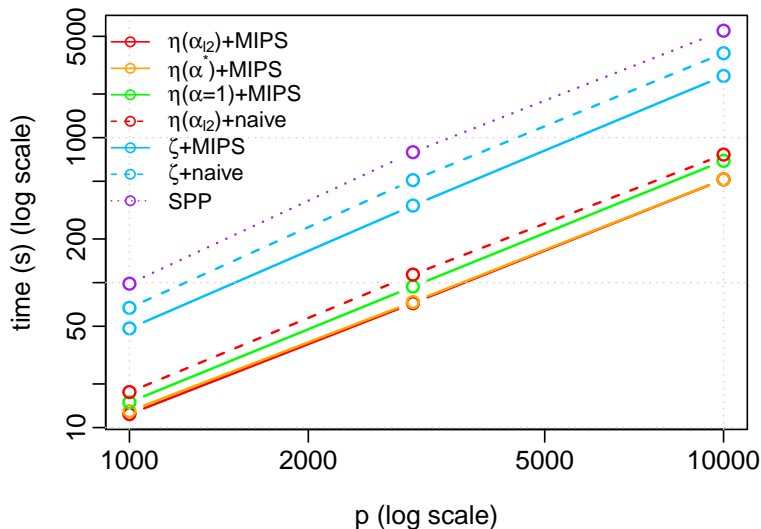13:   **if** $\mathbf{m}_j < d < \lambda$ **then** set $\mathbf{m}_j = d$ and $\mathbf{k}_j = k$
14:   **if** $d \geq \lambda$ **then** add $\mathbf{X}_j \mathbf{X}_k$ to $\mathcal{M}_\lambda$

- We propose **WHInter**:
  - ✓ Working set strategy.
  - ✓ New branch pruning strategy for the identification of the active set.
  - ✓ Efficient computation of branch bounds using a Maximum Inner Product Search (MIPS) framework for binary data.

- Evaluation of WHInter on:
  - ✓ Simulated datasets.
  - ✓ Real toxicogenetics dataset.

- We simulate $\boldsymbol{X} \in [\![0, 1]\!]^{n \times p}$ where $\boldsymbol{X}_{ik} \sim \text{Bernoulli}(q_k)$, and $q_k \sim \text{Unif}(0.1, 0.5)$ for different combinations of n and p.
- We randomly pick a set $\mathcal{S}$ of 100 features (among original and interaction ones).
- The associated weights are drawn from a standard gaussian distribution.
- We set $\phi = \boldsymbol{Z}_{\mathcal{S}} \boldsymbol{w}$
- We choose 100 values of λ logarithmically spaced in $[\lambda_{max}, 0.01\lambda_{max}]$. We stop the algirithm as soon as more than 150 features are selected in the model.
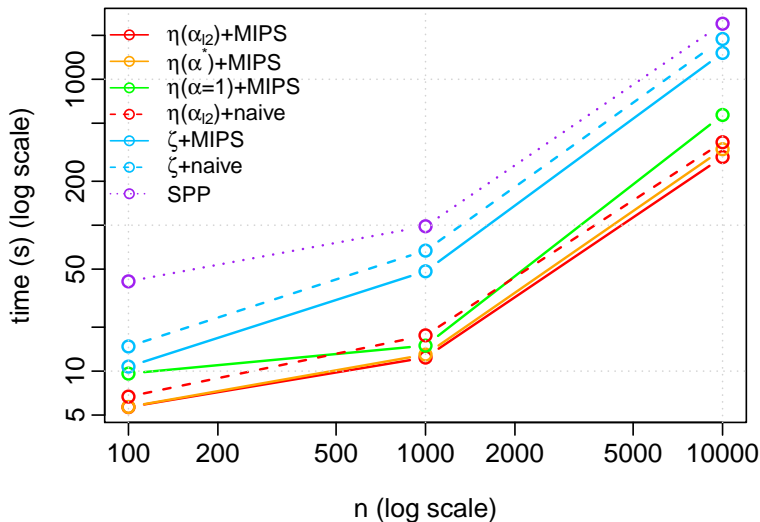
$n = 1000$ fixed, p varied.

$p = 1000$ fixed, n varied.
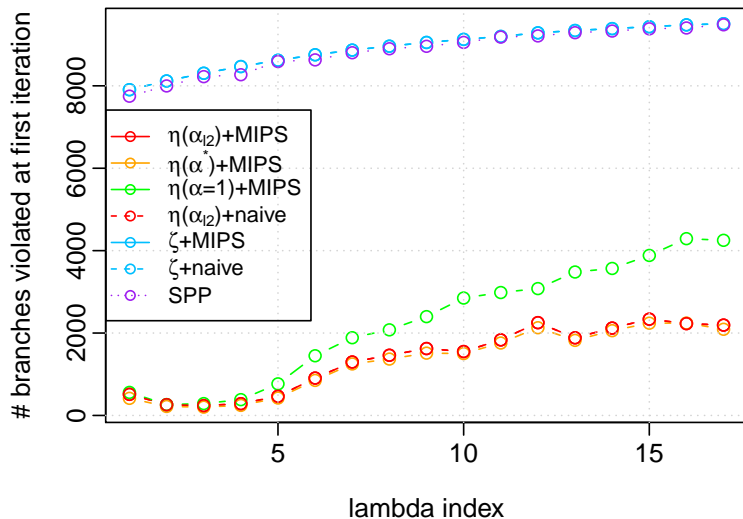
$n = 1000, p = 10000$.

- We consider the SNPs from chromosomes 1 and 19 of 620 lymphoblastoid cell lines, represented by $X^1 \in [\![0,1]\!]^{620 \times 102196}$ and $X^{19} \in [\![0,1]\!]^{620 \times 28418}$.
- The response $y \in \mathbb{R}^{620}$ is the cytotoxicity (EC10) of a chemical compound.
- Correction for population structure was applied as in Price et al (2006).

Method	Chromosome 19			Chromosome 1		
	Preproc (min)	Path (min)	Tot. time (min)	Preproc (h)	Path (h)	Tot. time (h)
$\eta(\alpha_{l2}) + MIPS$	13	13	26	2.5	1.4	3.9
$\eta(\alpha^*) + MIPS$	13	13	26	2.5	1.2	3.7
$\eta(\alpha = 1) + MIPS$	13	22	35	2.5	2.9	5.4
$\eta(\alpha_{l2}) + naive$	13	23	36	2.5	2.5	5
$\zeta + MIPS$	7	84	91	1.2	13.5	14.7
$\zeta + naive$	7	109	116	1.2	17.2	18.4
SPP	7	173	180	1.2	25.2	26.4

Thank you for your attention.

Roberto J. Bayardo, Yiming Ma, and Ramakrishnan Srikant. "Scaling up all pairs similarity search". In: *Proc. 16th Int. Conf. World Wide Web - WWW '07* (2007), p. 131.

0livier Fercoq, Alexandre Gramfort, and Joseph Salmon. "Mind the duality gap: safer rules for the Lasso". In: *ICML*. 2015, pp. 333–342.

Kazuya Nakagawa et al. "Safe Pattern Pruning: An Efficient Approach for Predictive Pattern Mining". In: *KDD* (2016). arXiv: 1602.04548.

Christina Teflioudi and Rainer Gemulla. "Exact and Approximate Maximum Inner Product Search with LEMP". In: *TODS* (2016).