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Dissolved Oxygen (DO) Meter Hydrological Modelling Using Predictive Algorithms

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Abstract— Dissolved oxygen is one of the critical indicators of a body of water's health and water quality. It refers to the presence of free, non-compound oxygen found in water. It also influences the growth and survival of the aquatic organisms living in it. This study aims to develop a low-cost, multi-function device that could determine the value of the dissolved oxygen (DO) level through hydrological modelling of water parameters such as temperature, pH, and conductivity using Decision Tree, Decision forest, and Multi-layer Perceptron machine learning algorithms. Using various metrics, the most efficient model was built using Random Forest algorithm, for it yielded the most reliable metrics when compared to the other two algorithms. The evaluated model has the following metrics: The Coefficient of Determination, or how well a model explains and predicts future outcomes, is 0.99. The Mean Absolute Error, or the average magnitude of the errors in a set of predictions, is 0.32. The Mean Squared Error, utilized in order to measure the performance of an estimator, is 0.36. The Root Mean Squared Error, or how concentrated the data is around the line of best fit, is 0.60. Relative to Atlas Scientific's DO Sensor, the device can predict the dissolved oxygen level of a given water pond with 2.61% error. The final device is a handheld device consisting of the sensors for the highest- ranking parameters with respect to their relationship to DO: temperature, conductivity, and pH.

Keywords — water parameters, dissolved oxygen, Python, machine learning, hydrological modelling, water meter

I. INTRODUCTION

Water, easily the most ubiquitous resource, has numerous parameters with different implications regarding its state. One of the most important ones is the dissolved oxygen level. Knowing the dissolved oxygen level of a fish-filled body of water is crucial; especially in the case of fish farmers, this would dictate their livelihood.

Dissolved oxygen (DO) is the most critical indicator of a body of water's health and water quality [1]. The amount of DO present in a body of water influences the growth and survival of the aquatic organisms living in it. It is highly relevant to measure the DO level of aquaculture farms to

ensure its capacity to support aquatic life. The DO level, however, depends on many factors such as temperature, salinity, oxygen depletion, oxygen source, and others [2]. Moreover, DO measurement can be done through the use of one of the following: dissolved oxygen, multi-parameter measuring device, or laboratory testing or the Wrinkler method. However, prices for DO meters prove to be very costly, especially to the small farmers, price is between Php 20,000 up to half a million pesos or \$ 384 to \$ 9,600.00 [3] [15].

If one, however, wishes to measure the DO level cost-effectively, the trade-off would be the process being labor-intensive. DO levels are typically and traditionally measured by means of the Wrinkler method [4], where titration is used to account for DO in a given water sample. The process uses a total of five reagents such as Sodium thiosulfate, Manganese sulfate, alkali-iodide-azide, concentrated sulfuric acid, and starch solution. Aside from being labor-intensive, the method evidently requires reagents that the common aquaculture farmer cannot simply obtain.

These lead to the evaluation of the dissolved oxygen level of a certain body of water by developing hydrological models using certain parameters, namely: temperature, pH Level and conductivity, through a comparative study between various machine learning [11],[12], algorithms specifically (a) Decision Tree Regression (DTR); (b) Random Forest (RFR); and (c) Multilayer Perceptron (MLP).

II. METHODOLOGY

The study mostly relied on the physical construction of a buoy for the data acquisition. From the construction of the buoy, the data was analyzed and resulted to a practical and cost-effective solution for the development of the DO meter. After the development of the final device, as shown in Fig.1, it was tested for accuracy. Using Arduino Mega (ATMega2560) as microcontroller, the buoy recorded measurements from the sensors and saved it in a 4GB micro SD card.

The block diagram of this study is presented in Fig. 2. of Preparation of the gathered data was first done followed by the modelling process where three methods of predictive algorithms were tested. Finally the evaluation of the result was performed.



Fig. 1 The prototype of the floating sensor design

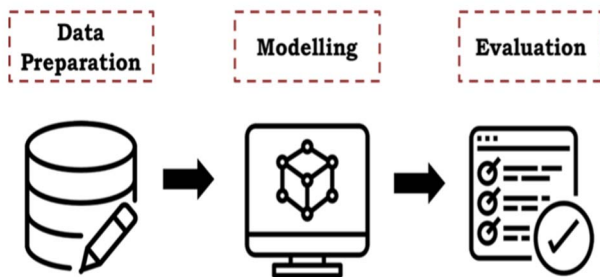


Fig. 2 Block diagram

A. Data Acquisition

This study focuses on the determination of the inherent relationships that exist between the different physical parameters of water. Fig. 2 illustrates the flowchart of the developed sensor node. In coordination with the Bureau of Fisheries and Aquatic Resources (BFAR) – Batangas, a three weeks' worth of dataset from a fish-breeding facility situated at Brgy. Ambulong, Batangas was gathered. The floating device (buoy) equipped with multiple sensors to record various pondwater parameters is developed for data gathering. The time when these parameters were measured was also taken into consideration.

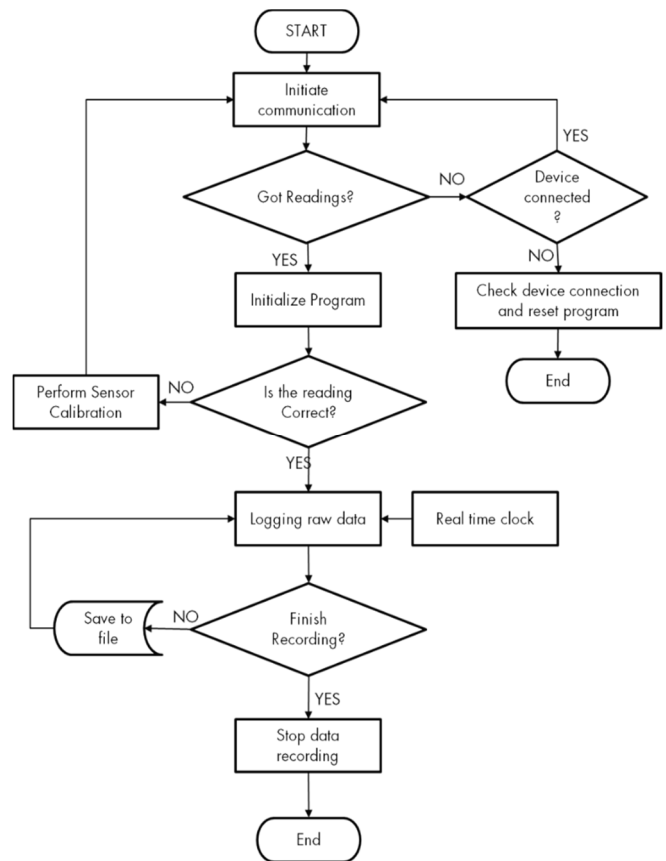


Fig. 3. Sensor node operation flowchart

Fig. 3 illustrates the flowchart of the developed sensor node. Fig. 4 presents a photo of the buoy being deployed in a concreted pond at BFAR – ITSO.



Fig. 4 Buoy gathering parameters reading of a pond

B. Application of Various Machine Learning Algorithms to Data

Tested by other relevant literatures, the researchers utilized key algorithms to create a predictive model that can quantify levels of DO using other known physical pondwater parameters. These algorithms are: (1) Random Forest Regression, (2) Decision Tree Regression and (3) Multi-layer Perceptron.

C. Data Resampling and Parameter Selection

The dataset gathered is then filtered using various methods to rid it of errors, fragmented data, garbled sensor inputs, etc. The filtering accepts only complete data, which is only achieved when all sensors record their measured parameters, and non-erroneous values.

The filtered dataset is resampled into a minute, 5-minute, 10-minute, 30-minute and 60-minute intervals. This is done to identify which interpolation would produce the best model, as evaluated.

The sampled datasets were also utilized to quantify how relevant each considered parameter is, to the predictive model built. By using Feature Importance, the relative importance of each parameters to DO level is known.

D. Model Evaluation

Several predictive models were built based on various combination of pondwater parameters. These models were evaluated using the following criterion: Coefficient of Determination (R Square), Mean Absolute Error (MAE), Mean Squared Error (MSE), and Root Mean Squared Error (RMSE).

Higher level of R Square suggests that there is less error or unexplained variance and therefore, better prediction and more precise DO level [17].

MAE evaluates how huge errors affects the accuracy of the model built. MSE is kept at minimum to ensure that the predicted DO level is close to the actual DO level. Lower level of RMSE is desired to avoid large errors between the predicted and actual levels of DO.

E. Design of a Cost-Effective DO Meter

The whole process of the meter's development resulted to a handheld device shown in Fig.5. The parts as seen on the image are labeled. The receptacle is where the sensors are contained for protection and for easy handling of the meter. The chassis hold inside the circuits and the supply of the device. The LCD display shows the value of the predicted dissolved oxygen level.



Fig. 5 Buoy, floating sensor design

III. EXPERIMENTS AND RESULTS

A. Nature of Filtered Dataset

Table I and Table II illustrate the statistical description of the filtered data set with the following parameters: Dissolved Oxygen (DO) level in mg/L; Electrical Conductivity (EC) in $\mu\text{S/m}$; Total Dissolved Solids (TDS) in ppm; Salinity (SAL) in psu; Specific Gravity (SG); Turbidity (TURB) in NTU; Temperature (Temp) in $^{\circ}\text{C}$; pH (PH) Level.

The gathered dataset has a sample size of 1,019,189. The DO level ranges from 3.00 mg/L to 37.4 mg/L. Electrical conductivity has the highest deviation with $\sim 133 \mu\text{S/m}$. Total dissolved solids has a mean of ~ 134 ppm, and ranges from 17ppm to 450ppm. Salinity of the pondwater ranges from 0 psu to 0.4 psu. The specific gravity is constant at 1. The turbidity ranges from -2289.0 NTU to 37.4 NTU. Temperature ranges from 25.6 to 32.2. The pH of pondwater is about 6.59 to 10.8.

B. Evaluation of Parameter Relevance to DO

Using key algorithms, features were selected based on Feature Importance, a method that uses algorithms of Decision Tree Regression (DTR) and Random Forest (RFR).

For most of the evaluation made using various samples from different time intervals, the key parameters which yielded notable levels of coefficients are as follows: time, pH, temp, EC, TDS and SAL.

C. Model Evaluation

Knowing the degree of how each parameter affect DO level, various predictive models are created utilizing RFR, DTR, and MLP, with different combinations of parameters as input. These models are evaluated based on R Square, MAE, MSE, RMSE.

For the ease of discussion, evaluations using dataset from every minute, every 10 minutes and every hour time intervals are shown.

TABLE I. MODEL EVALUATION

Metrics		R Square	MAE	MSE	RMSE
Every Minute	RFR	0.992	0.322	0.360	0.600
	DTR	0.984	0.386	0.715	0.846
	MLP	0.452	3.869	23.864	4.885
Every 10 Minute	RFR	0.984	0.570	0.696	0.834
	DTR	0.967	0.695	1.456	1.207
	MLP	0.196	4.826	34.976	5.914
Every Hour	RFR	0.889	1.629	4.686	2.165
	DTR	0.656	2.424	14.487	3.806
	MLP	-129.419	69.738	5495.280	74.130

It can be inferred from Table I that the predictive model built using every minute dataset with top 6 parameters as input, is superior with highest R Square of 0.992, and least MAE, MSE and RMSE of values 0.322, 0.360, and 0.600 respectively. Moreover, in all evaluations, MLP performed inferior having least R square and high levels of error. Based from the table, utilizing RFR created desirable predictive models with high levels of R Square and low levels of MAE, MSE, and RMSE. The highest R Square (0.98401) is obtained by a model built using top 6 parameters as input. Similar observations were seen in every hour, RFR built a desirable predictive model with great levels of R Square and small levels of MAE, MSE, and RMSE. Likewise, this evaluation is obtained by a model built using top 6 parameters as input.

From these simulations, it can be inferred that the top performing models are built from Per Minute Sampling, using Random Forest and Decision Tree algorithms based on the following Top 6 Key Parameters: (1) Time when data was taken, (2) pH, (3) Temperature, (4) Electric Conductivity, (5) Total Dissolved Solids, and (6) Salinity.

With this, the researchers tested how well these models perform in actual setting. These models were uploaded to an R-pi microcontroller for the handheld device developed by the researchers. These models were tested its prediction schemes on the same pond where data was gathered.

Tables II and III show the parameter measurements during the testing, the predicted DO and the actual DO.

TABLE II. DEVICE EVALUATION – DECISION TREE

DECISION TREE REGRESSION ALGORITHM				
Trial No.	Time	Predicted DO	Actual DO (Atlas Scientific)	Percent Error
1	11:01	17.84	15.95	11.850
2	12:09	18.21	14.84	22.709
3	12:11	18.21	16.67	9.238
4	12:15:50	18.21	16.37	11.240

5	12:18:50	18.21	20.01	8.996
6	12:26:50	18.21	20.34	10.472
7	13:21	18.24	17.85	2.185
8	13:50:31	18.24	17.98	1.446
9	14:42:48	19.5	20.03	2.646
10	14:55:12	15.1	14.89	1.410
AVERAGE:				8.219

TABLE III. DEVICE EVALUATION – RANDOM FOREST

RANDOM FOREST REGRESSION ALGORITHM				
Trial No	Time	Predicted DO	Actual DO (Atlas Scientific)	Percent Error
1	11:10:31	15.83	16.55	4.350
2	13:36:03	19.29	19.26	0.156
3	14:51:38	19.68	20.98	6.196
4	14:56:42	19.68	19.22	2.393
5	15:12:20	21.24	21.19	0.236
6	15:21:21	21.21	22.36	5.143
7	15:23:20	21.24	21.39	0.701
8	15:25:21	18.5	18.27	1.259
9	15:28:21	21.17	21.97	3.641
10	15:29:47	18.5	18.13	2.041
AVERAGE:				2.612

As can be seen in the Table II and III, the average percent errors between the predicted DO level and measured level are 8.22% and 2.61%, using DTR and RFR algorithms respectively. From this, it can be inferred that the most effective model uploaded into the device is built using Random Forest Regression algorithm, based on top 6 parameters. In summary, the metrics of the testing done is shown in the Table IV.

TABLE IV. DEVICE EVALUATION SUMMARY

Metric	RFR	DTR
Coefficient of Determination	0.831	0.263
Mean Absolute Error	0.526	1.396
Mean Squared Error	0.460	2.901
Root Mean Squared Error	0.678	1.703

D. Statistical Analysis

To test whether the difference between these percent errors is significant or not, statistical analysis should be performed. The researchers used equal variance t-test since the sample size between observed values are equal.

The following hypotheses were established:

Ho: There is no significant difference between the percentage errors of predicted and measured DO level, using

predictive model built through Random Forest Regression (RFR) algorithm and Decision Tree Regression (DTR)

H_A: There is a significant difference between the percentage errors of predicted and measured DO level, using predictive model built through Random Forest Regression (RFR) algorithm and Decision Tree Regression (DTR). Table V shows the static obtained using t-test

TABLE V. TABLE 5 T-TEST STATISTICS COEFFICIENT

Statistic	Coefficient
Mean diff.	5.607
SE	2.210
t value	2.537
df	18
two-tailed p	0.021

By performing Equal Variance t-test, with degrees of freedom (df) = 18, the computed two tailed p-value is 0.020638. Since $p < 0.05$, the researchers reject the null hypothesis and accepts the alternative hypothesis.

Hence, there is a significant difference between the means of percentage errors of predicted and measured DO level, using predictive model built through Random Forest Regression (RFR) algorithm and Decision Tree Regression (DTR). This suggests that the predictive model built using Random Forest should be adapted.

E. Device Comparison with Atlas Scientific DO Sensor

Table VI summarizes the comparison between DO Sense, the handheld device developed, and Atlas Scientific DO Sensor.

TABLE VI. DO-SENSE VS ATLAS SCIENTIFIC DO SENSOR

Device	DO sense	Atlas Scientific DO Sensor with peripherals
Nature	Multiparameter	Dissolved Oxygen
Measuring Range	DO: 3.067 – 37.43 g/mL	DO: 0 -100 g/mL
	pH: 0 – 14	
	Temperature: -50°C – 125°C	
	Electrical Conductivity: 5 – 200k uS/cm	
	Total Dissolved Oxygen – ppm	
	Salinity – psu	
Reading Stabilization	1 to 2 minutes	1 minute
Cost	Php 23,867.00	Php 19,000.00

IV. CONCLUSIONS

Considering the study's findings, the researchers were successful in developing a sensor node equipped with various

sensing device which gathers measurements of the defined water parameters (temperature, pH, and conductivity). DO Sense, the device developed, is a handheld device consisting of sensors for each of the highest-ranking parameters with respect to their relationship to DO: temperature, pH, and turbidity. In comparison [13] with Atlas Scientific's DO Sensor, the device was able to determine the value of DO with only 2.61% error. Also, several formulated predictive models were processed and analyzed according to pertinent parameters and out these models, the Random Forest Regression algorithm was found to be the most efficient [18] and applicable method based on the results.

For the future works of this study, it is recommended to add more sensors for the analysis of the correlation of the variations in the chemical properties of water to the dissolved oxygen levels.

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