

1.

1- (1) $P(\text{Type 1 error})$

$= P(\text{Reject } H_0 / H_0 \text{ is true})$

$$= P\left(\sum_{i=1}^5 X_i = 5 / H_0: p = \frac{1}{2}\right)$$

$$= \binom{5}{5} \left(\frac{1}{2}\right)^5 \left(\frac{1}{2}\right)^0 = \frac{1}{32} \#$$

(2) $P(\text{Type 2 error})$

$= P(\text{Accept } H_0 / H_a \text{ is true})$

$$= P\left(\sum_{i=1}^5 X_i < 5 / H_a: p = \frac{3}{4}\right)$$

$$= \sum_{k=0}^4 \binom{5}{k} \left(\frac{3}{4}\right)^k \left(\frac{1}{4}\right)^{5-k}$$

$$= 0.7629 \#$$

2.

2. $\begin{cases} H_0: \sigma^2 = 0.8 \\ H_a: \sigma^2 > 0.8 \end{cases}$

$$\chi^2 = \frac{9 \cdot (1.2)^2}{(0.9)^2} = 16$$

H_0 is rejected when $\chi^2 > 16.919$

A: accept $\sigma = 0.9$

3(1)

Given an undirected graph $G=(V,E)$, a set of random variables $X = (X_v)_{v \in V}$ indexed by V form a **Markov random field with respect to G** if they satisfy the **local Markov properties**:

- **Pairwise Markov property**: Any **two non-adjacent variables are conditionally independent** given all other variables: $X_u \perp\!\!\!\perp X_v \mid X_{V \setminus \{u,v\}}$
- **Local Markov property**: A variable is conditionally independent of all other variables given its neighbors: $X_v \perp\!\!\!\perp X_{V \setminus N'[v]} \mid X_{N(v)}$
where $N(v)$ is the set of neighbors of v , $N'[v] = v \cup N(v)$ is the closed neighbourhood of v .
- **Global Markov property**: Any two subsets of variables are conditionally independent given a separating subset: $X_A \perp\!\!\!\perp X_B \mid X_S$
where every path from a node in A to a node in B passes through S

3(2)

Local Markov property (for DAG)

- Each variable is conditionally independent of its non-descendants given its parent variables:
$$X_v \perp\!\!\!\perp X_{V \setminus \text{de}(v)} \mid X_{\text{pa}(v)} \quad \text{for all } v \in V$$

where $\text{de}(v)$ denotes the set of descendants of v (thus $V \setminus \text{de}(v)$ is the set of non-descendants of v)

3(3)

Definition: Markov blanket

- The Markov blanket of a node is the set of nodes consisting of its **parents**, its **children**, and any **other parents of its children**.



4.

optimal projection vector:
(0.99130435 -0.13158907)

corresponding eigenvalue:
8.6783

```
1  import numpy as np
2
3  a = np.array([[5, 3], [3, 5], [3, 4], [4, 5], [4, 7], [5, 6]])
4  b = np.array([[9, 10], [7, 7], [8, 5], [8, 8], [7, 2], [10, 8]])
5
6  a_centered = a - np.mean(a, axis=0)
7  b_centered = b - np.mean(b, axis=0)
8
9  s_1 = np.zeros((2, 2))
10 for i in range(a.shape[0]):
11     tmp_a = a_centered[i].reshape(2, 1)
12     s_1 += np.matmul(tmp_a, tmp_a.T)
13
14 s_1 /= (a.shape[0] - 1)
15 # print(s_1)
16
17 s_2 = np.zeros((2, 2))
18 for i in range(b.shape[0]):
19     tmp_b = b_centered[i].reshape(2, 1)
20     s_2 += np.matmul(tmp_b, tmp_b.T)
21
22 s_2 /= (b.shape[0] - 1)
23 # print(s_2)
24
25 s_w = s_1 + s_2
26
27 tmp = (mean_a - mean_b).reshape(2, 1)
28 s_b = np.matmul(tmp, tmp.T)
29
30 fld = np.matmul(np.linalg.inv(s_w), s_b)
31 e_val, e_vec = np.linalg.eig(fld)
32
33 print(e_val[0])
34 print(e_vec.T[0])
```