

# Lecture 3 – A Tour of Machine Learning Classifiers Using scikit-learn

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# Introduction

- Introduction to robust and popular algorithms for classification, such as logistic regression, support vector machines, and decision trees.
- Examples and explanations using the scikit-learn machine learning library, which provides a wide variety of machine learning algorithms via a user friendly Python API.
- Discussions about the strengths and weaknesses of classifiers with linear and non-linear decision boundaries.

# Choosing a Classification Algorithm

- No single classifier works best across all possible scenarios
- Main steps:
  - Selecting features and collecting training samples.
  - Choosing a performance metric.
  - Choosing a classifier and optimization algorithm.
  - Evaluating the performance of the model.
  - Tuning the algorithm.

# First steps with scikit-learn

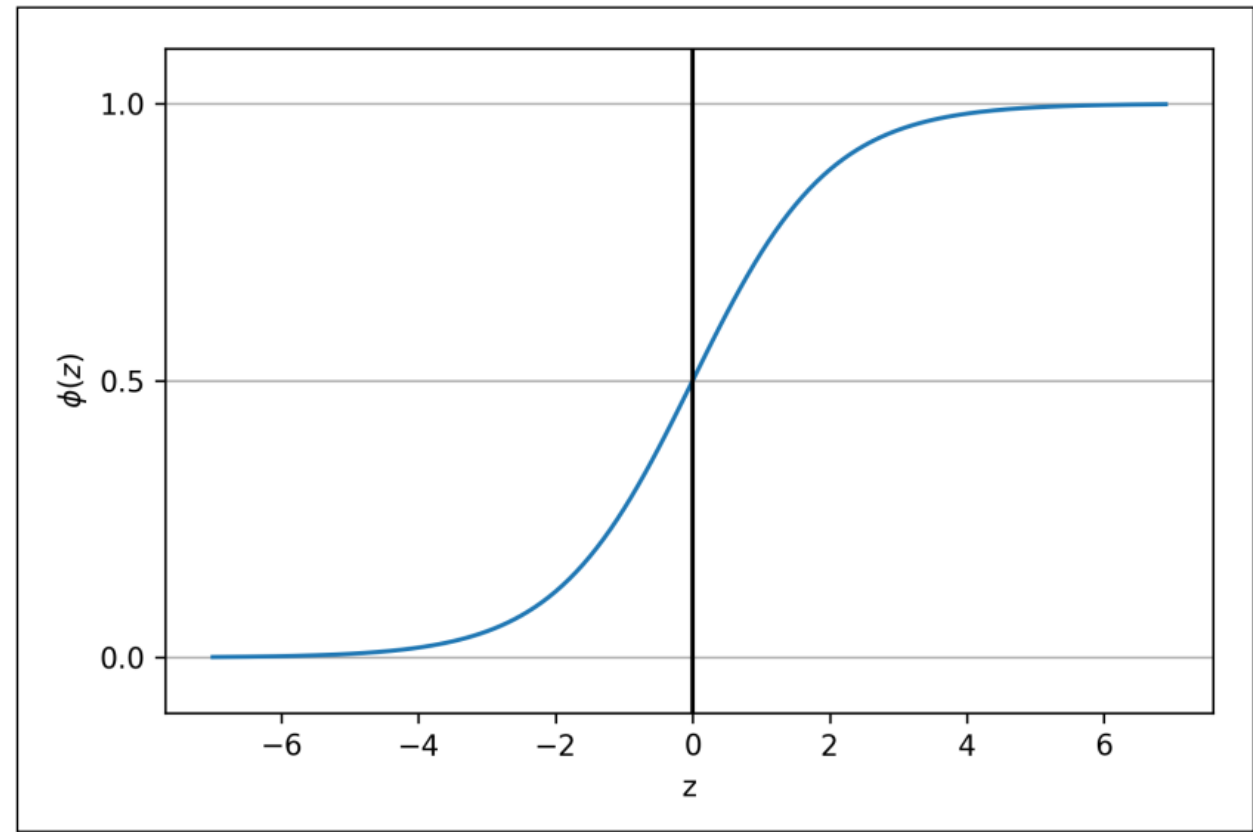
- Train and test perceptron model in Python with scikit-learn API

# Logistic Regression

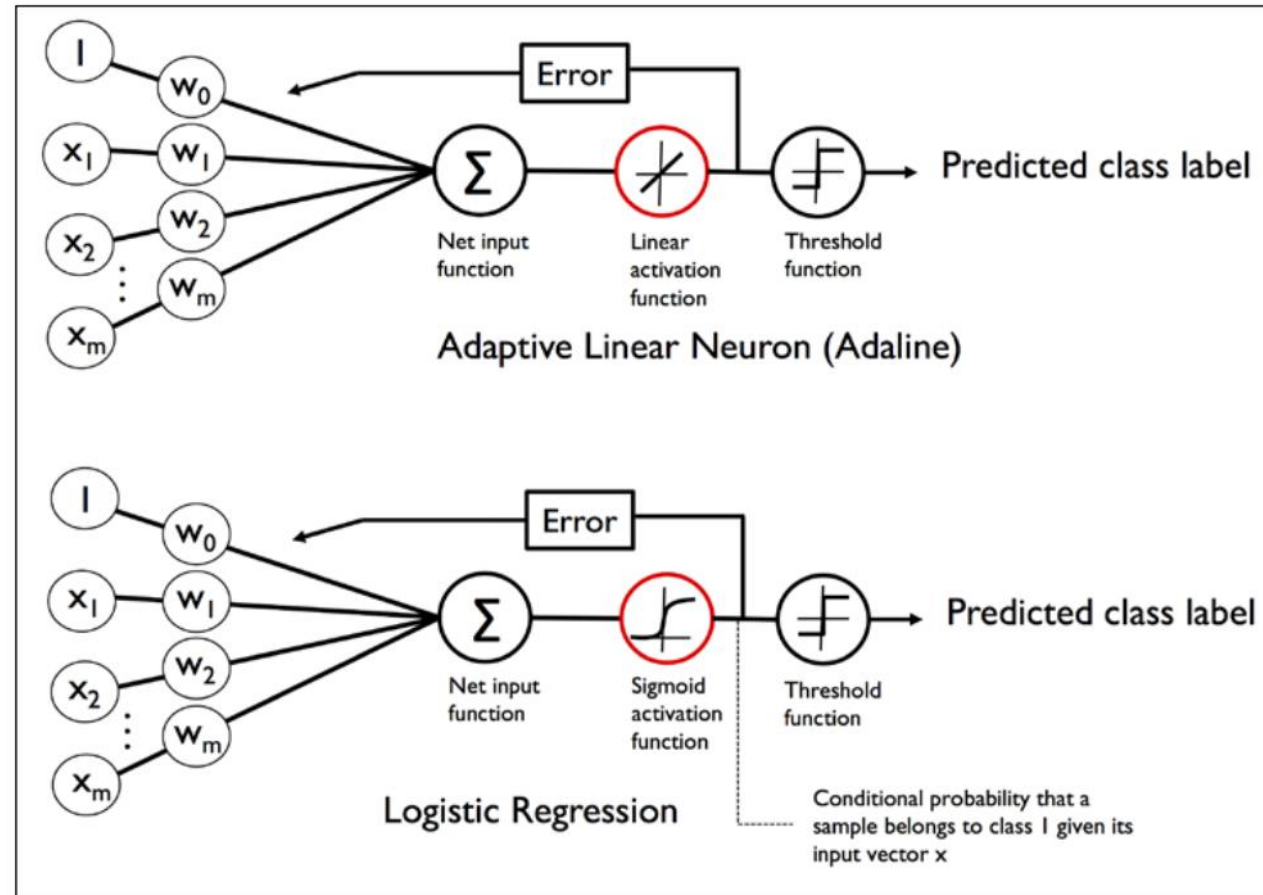
- We are interested in predicting the probability that a certain sample belongs to a particular class.
- To do that, we use the **logistic sigmoid function**, sometimes simply abbreviated to **sigmoid function** due to its characteristic S-shape:

$$\phi(z) = \frac{1}{1 + e^{-z}}$$

$$z = \mathbf{w}^T \mathbf{x} = w_0x_0 + w_1x_1 + \dots + w_mx_m$$



# Logistic Regression



# Logistic Regression

- The output of the sigmoid function is then interpreted as the probability of a particular sample belonging to class 1,  $\varphi(z)=P(y=1|\mathbf{x};\mathbf{w})$ , given its features  $\mathbf{x}$  parameterized by the weights  $\mathbf{w}$ .
- For example, if we compute  $\varphi(z)=0.8$  for a particular flower sample, it means that the chance that this sample is an *Irisversicolor* flower is 80%.
- The predicted probability can then simply be converted into a binary outcome via a threshold function:

$$\hat{y} = \begin{cases} 1 & \text{if } \phi(z) \geq 0.5 \\ 0 & \text{otherwise} \end{cases}$$

$$\hat{y} = \begin{cases} 1 & \text{if } z \geq 0.0 \\ 0 & \text{otherwise} \end{cases}$$

# Logistic Regression – Cost Function

- Likelihood function and log-likelihood:

$$L(\mathbf{w}) = P(\mathbf{y} | \mathbf{x}; \mathbf{w}) = \prod_{i=1}^n P(y^{(i)} | \mathbf{x}^{(i)}; \mathbf{w}) = \prod_{i=1}^n \left( \phi(z^{(i)}) \right)^{y^{(i)}} \left( 1 - \phi(z^{(i)}) \right)^{1-y^{(i)}}$$

$$J(\mathbf{w}) = \sum_{i=1}^n \left[ -y^{(i)} \log \left( \phi(z^{(i)}) \right) - (1 - y^{(i)}) \log \left( 1 - \phi(z^{(i)}) \right) \right]$$

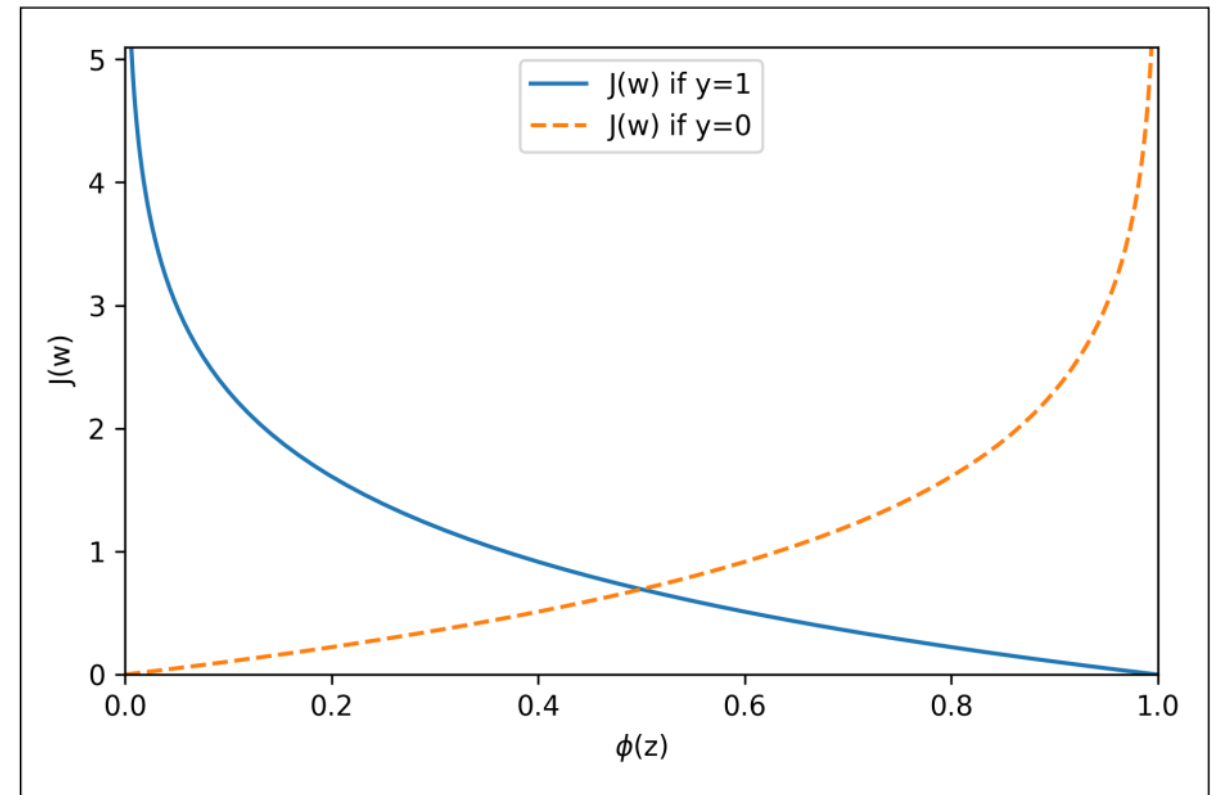


# Cost Function – Single Example

$$J(\phi(z), y; \mathbf{w}) = -y \log(\phi(z)) - (1-y) \log(1-\phi(z))$$

- Looking at the equation, we can see that the first term becomes zero if  $y = 0$ , and the second term becomes zero if  $y=1$ :

$$J(\phi(z), y; \mathbf{w}) = \begin{cases} -\log(\phi(z)) & \text{if } y = 1 \\ -\log(1-\phi(z)) & \text{if } y = 0 \end{cases}$$



# Gradient for Logistic Regression

$$J(\phi(z), y; \mathbf{w}) = -y \log(\phi(z)) - (1-y) \log(1-\phi(z))$$

$$\frac{\partial}{\partial w_j} l(\mathbf{w}) = \left( y \frac{1}{\phi(z)} - (1-y) \frac{1}{1-\phi(z)} \right) \frac{\partial}{\partial w_j} \phi(z)$$

$$\begin{aligned} \frac{\partial}{\partial z} \phi(z) &= \frac{\partial}{\partial z} \frac{1}{1+e^{-z}} = \frac{1}{(1+e^{-z})^2} e^{-z} = \frac{1}{1+e^{-z}} \left( 1 - \frac{1}{1+e^{-z}} \right) \\ &= \phi(z)(1-\phi(z)) \end{aligned}$$

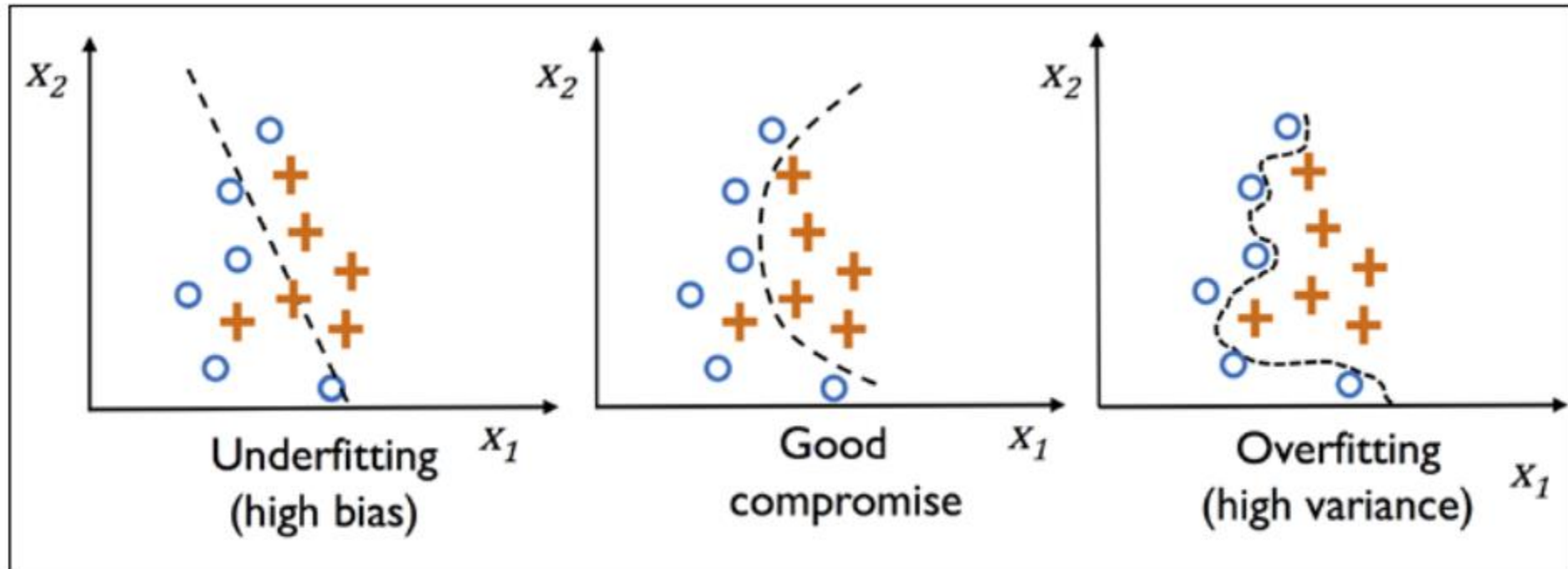
$$\begin{aligned} &\left( y \frac{1}{\phi(z)} - (1-y) \frac{1}{1-\phi(z)} \right) \frac{\partial}{\partial w_j} \phi(z) \\ &= \left( y \frac{1}{\phi(z)} - (1-y) \frac{1}{1-\phi(z)} \right) \phi(z)(1-\phi(z)) \frac{\partial}{\partial w_j} z \\ &= (y(1-\phi(z)) - (1-y)\phi(z)) x_j \\ &= (y - \phi(z)) x_j \end{aligned}$$

$$w_j := w_j + \eta \sum_{i=1}^n \left( y^{(i)} - \phi(z^{(i)}) \right) x_j^{(i)}$$

# Logistic Regression using scikit-learn

- Train and test LR model in Python with scikit-learn API (IRIS dataset)

# Overfitting Regularization



# Regularization

- Penalize extreme parameter (weight) values. The most common form of regularization is so-called L2 regularization (sometimes also called L2 shrinkage or weight decay), which can be written as follows:

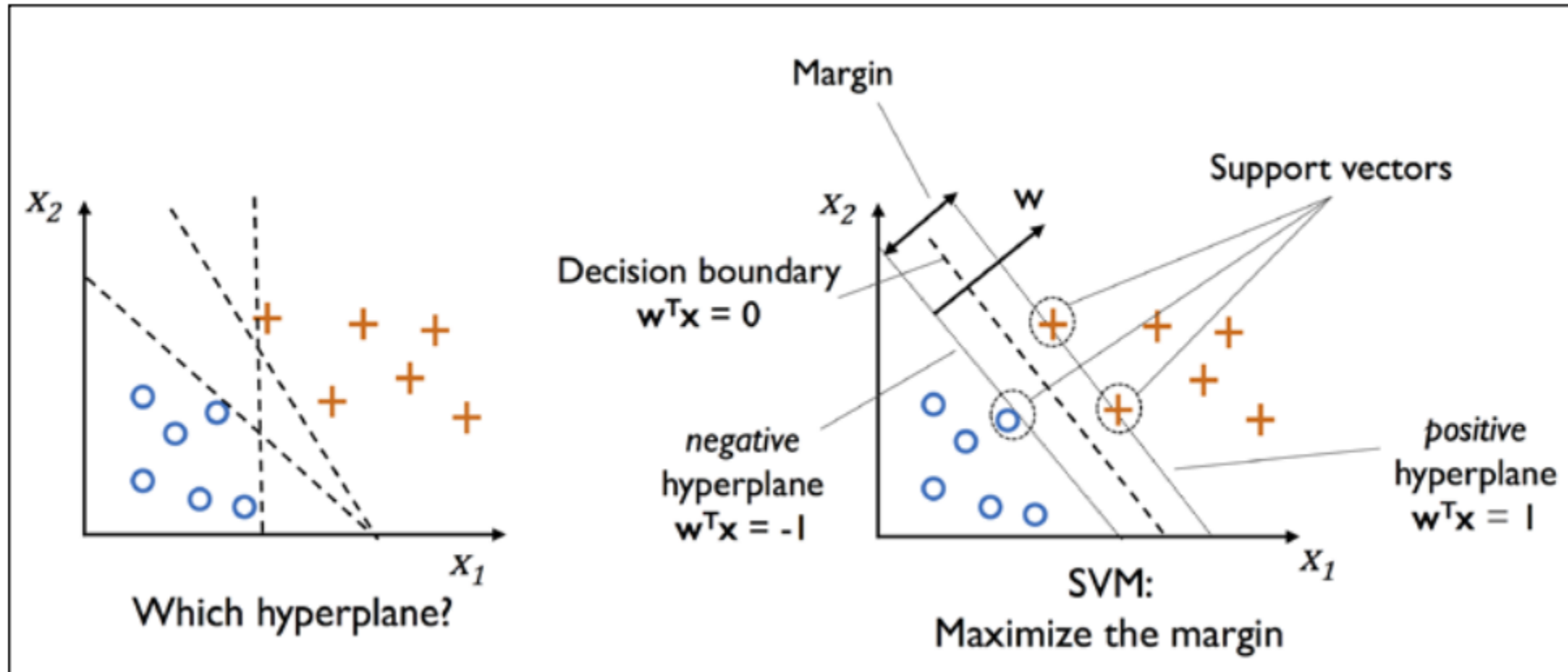
$$\frac{\lambda}{2} \|\mathbf{w}\|^2 = \frac{\lambda}{2} \sum_{j=1}^m w_j^2$$

$$J(\mathbf{w}) = \sum_{i=1}^n \left[ -y^{(i)} \log(\phi(z^{(i)})) - (1 - y^{(i)}) \log(1 - \phi(z^{(i)})) \right] + \frac{\lambda}{2} \|\mathbf{w}\|^2$$

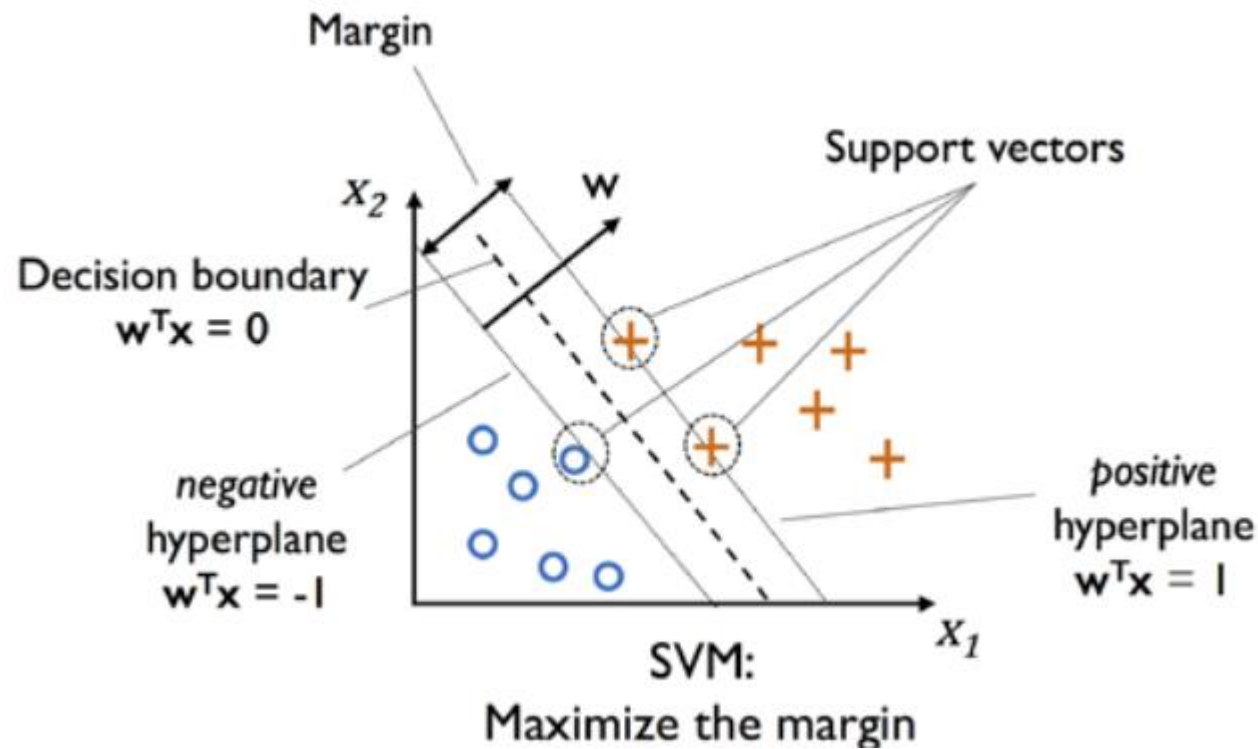
# Logistic Regression using scikit-learn

- Including regularization...

# Maximum Margin with Support Vector Machines (SVMs)



# Maximum Margin Intuition



$$w_0 + \mathbf{w}^T \mathbf{x}_{pos} = 1$$

$$w_0 + \mathbf{w}^T \mathbf{x}_{neg} = -1$$

$$\Rightarrow \mathbf{w}^T (\mathbf{x}_{pos} - \mathbf{x}_{neg}) = 2$$

$$\|\mathbf{w}\| = \sqrt{\sum_{j=1}^m w_j^2}$$

$$\frac{\mathbf{w}^T (\mathbf{x}_{pos} - \mathbf{x}_{neg})}{\|\mathbf{w}\|} = \frac{2}{\|\mathbf{w}\|}$$



# SVM optimization

- The left side of the preceding equation can then be interpreted as the distance between the positive and negative hyperplane, which is the so-called **margin** that we want to maximize. Now, the objective function of the SVM becomes the maximization of this margin by:

$$\text{maximizing } \frac{2}{\|\mathbf{w}\|}$$

$$w_0 + \mathbf{w}^T \mathbf{x}^{(i)} \geq 1 \text{ if } y^{(i)} = 1$$

$$w_0 + \mathbf{w}^T \mathbf{x}^{(i)} \leq -1 \text{ if } y^{(i)} = -1$$

$$\text{for } i = 1 \dots N$$

# Dealing with a nonlinearly separable case using slack variables

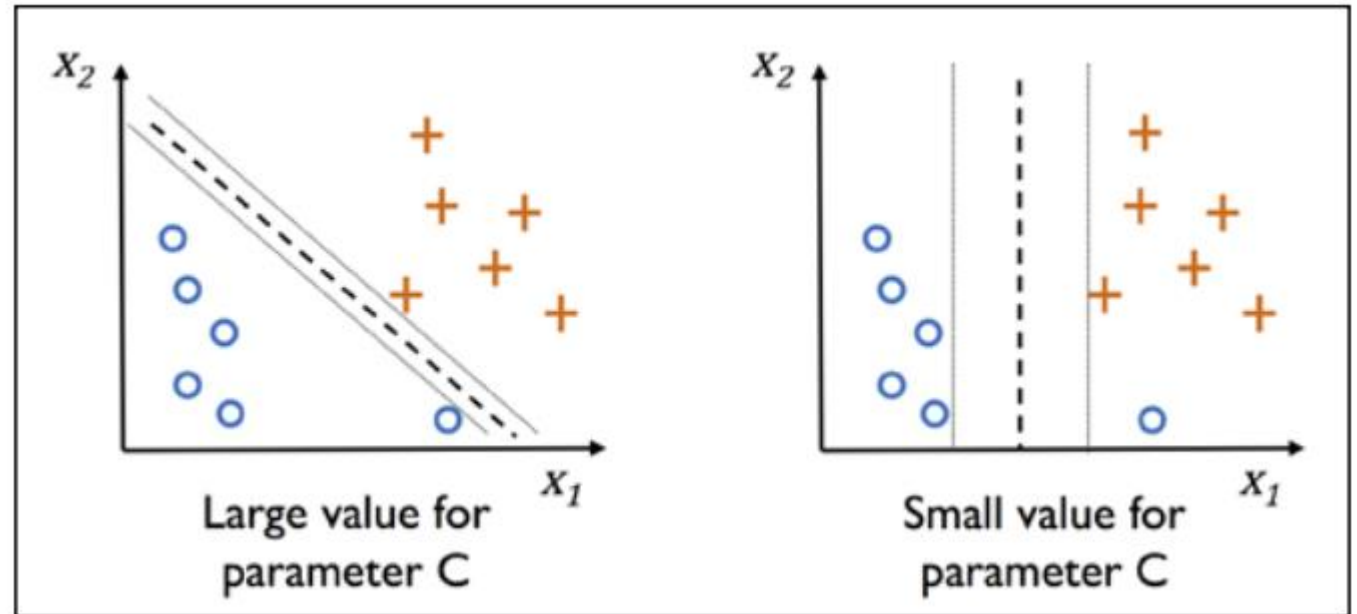
- **Soft-margin classification:**

$$w_0 + \mathbf{w}^T \mathbf{x}^{(i)} \geq 1 - \xi^{(i)} \text{ if } y^{(i)} = 1$$

$$w_0 + \mathbf{w}^T \mathbf{x}^{(i)} \leq -1 + \xi^{(i)} \text{ if } y^{(i)} = -1$$

for  $i = 1 \dots N$

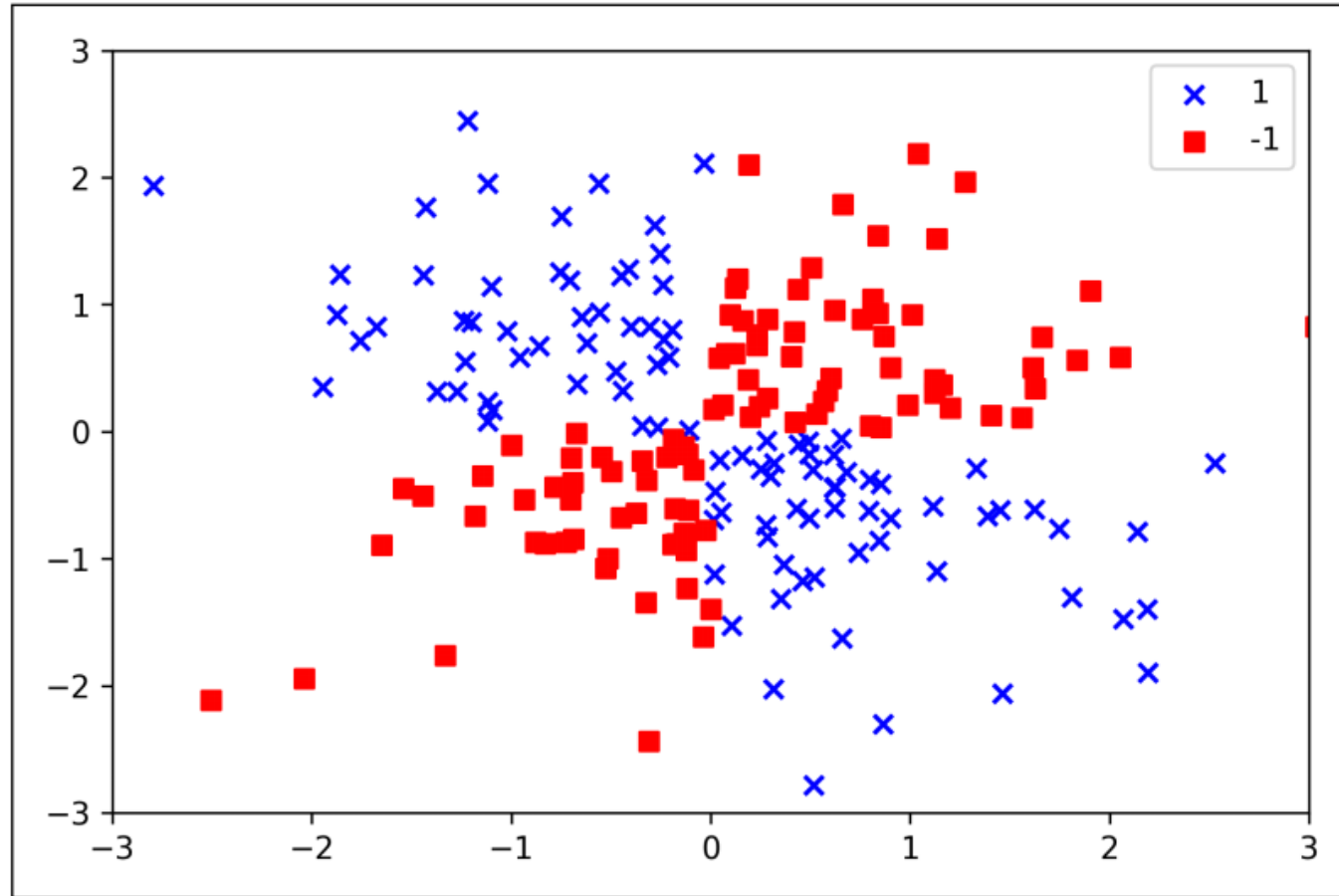
$$\frac{1}{2} \|\mathbf{w}\|^2 + C \left( \sum_i \xi^{(i)} \right)$$



# SVM using scikit-learn

- IRIS dataset...

# Solving nonlinear problems using a kernel SVM

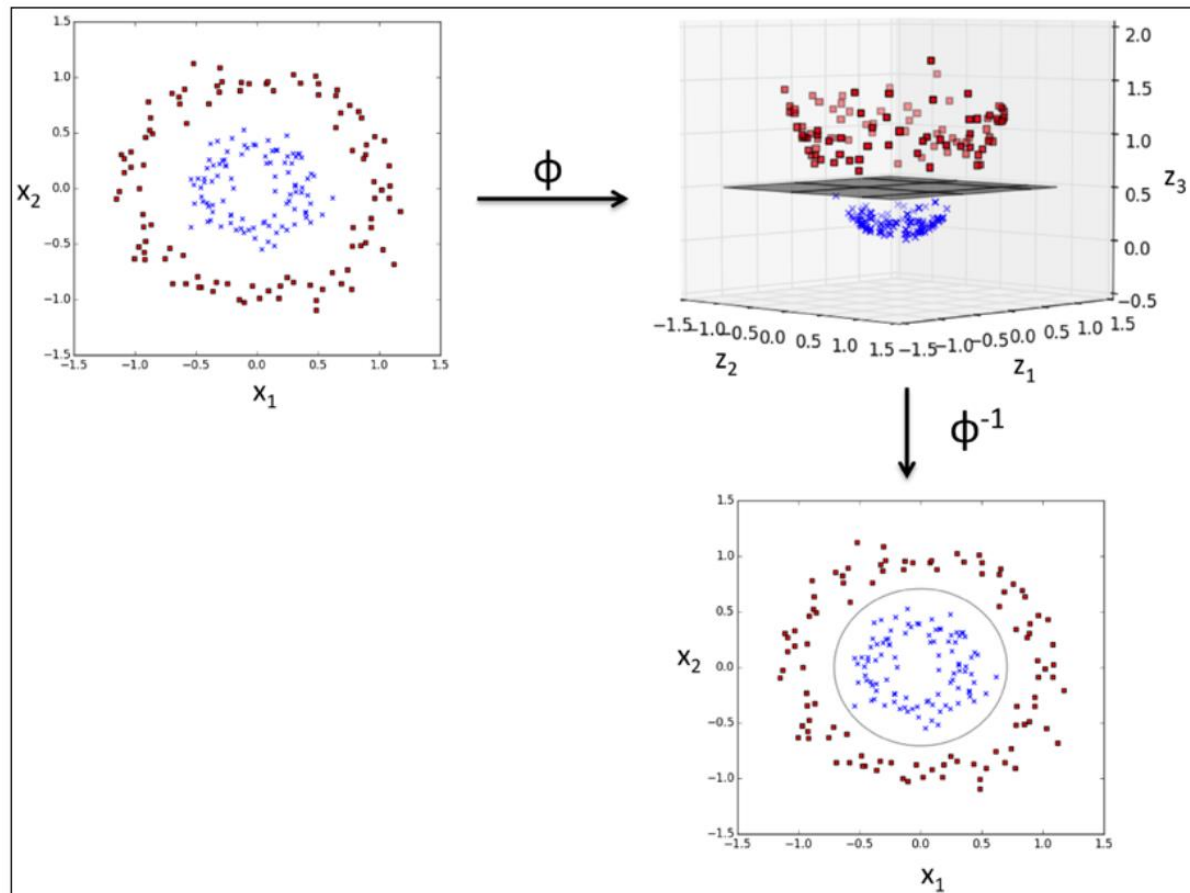


# Kernel Methods

- The basic idea behind **kernel methods** to deal with such linearly inseparable data is to create nonlinear combinations of the original features to project them onto a higher-dimensional space via a mapping function  $\phi$  where it becomes linearly separable.

$$\phi(x_1, x_2) = (z_1, z_2, z_3) = (x_1, x_2, x_1^2 + x_2^2)$$

# Kernel Methods



# Kernel Trick

- A problem with this mapping approach is that the construction of the new features is computationally very expensive, especially if we are dealing with high-dimensional data.
- This is where the so-called kernel trick comes into play:

$$\mathbf{x}^{(i)T} \mathbf{x}^{(j)} \text{ by } \phi(\mathbf{x}^{(i)})^T \phi(\mathbf{x}^{(j)})$$

$$\mathcal{K}(\mathbf{x}^{(i)}, \mathbf{x}^{(j)}) = \phi(\mathbf{x}^{(i)})^T \phi(\mathbf{x}^{(j)})$$

# Kernel

- Gaussian Kernel:

$$\mathcal{K}(\mathbf{x}^{(i)}, \mathbf{x}^{(j)}) = \exp\left(-\frac{\|\mathbf{x}^{(i)} - \mathbf{x}^{(j)}\|^2}{2\sigma^2}\right)$$

$$\mathcal{K}(\mathbf{x}^{(i)}, \mathbf{x}^{(j)}) = \exp\left(-\gamma \|\mathbf{x}^{(i)} - \mathbf{x}^{(j)}\|^2\right)$$

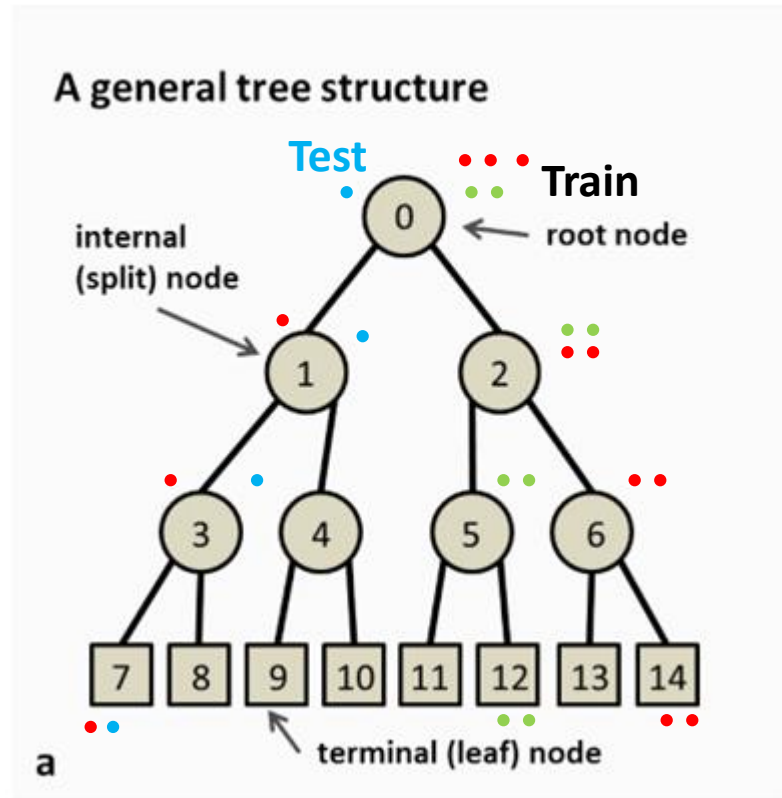


# SVM using scikit-learn

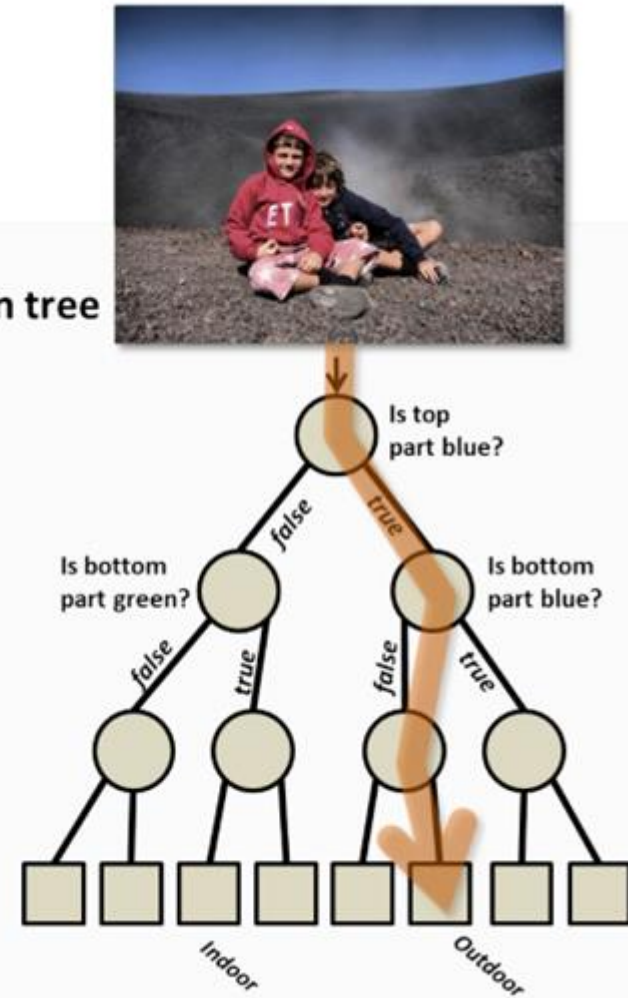
- Nonlinear case...

# Decision Tree

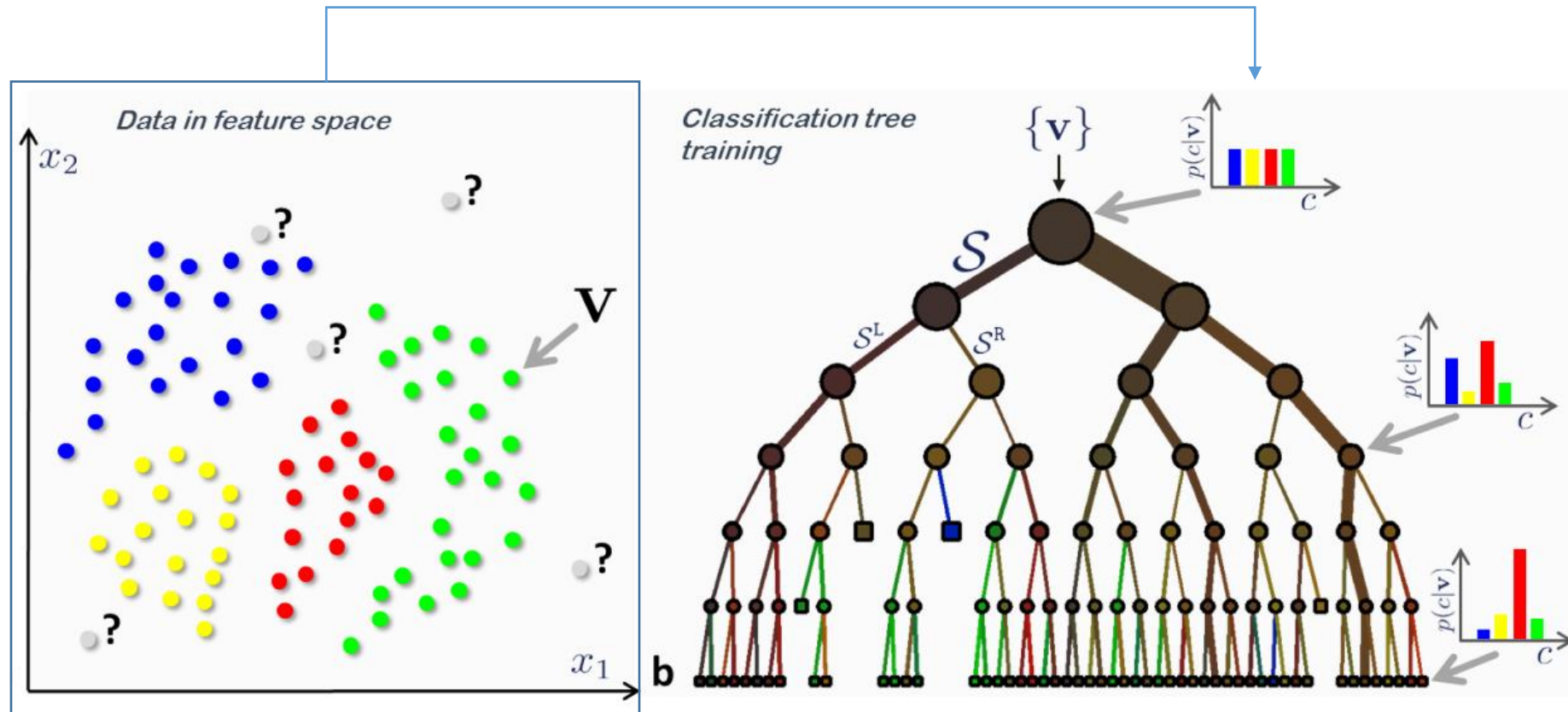
- General overview:



**A decision tree**



# Decision Trees

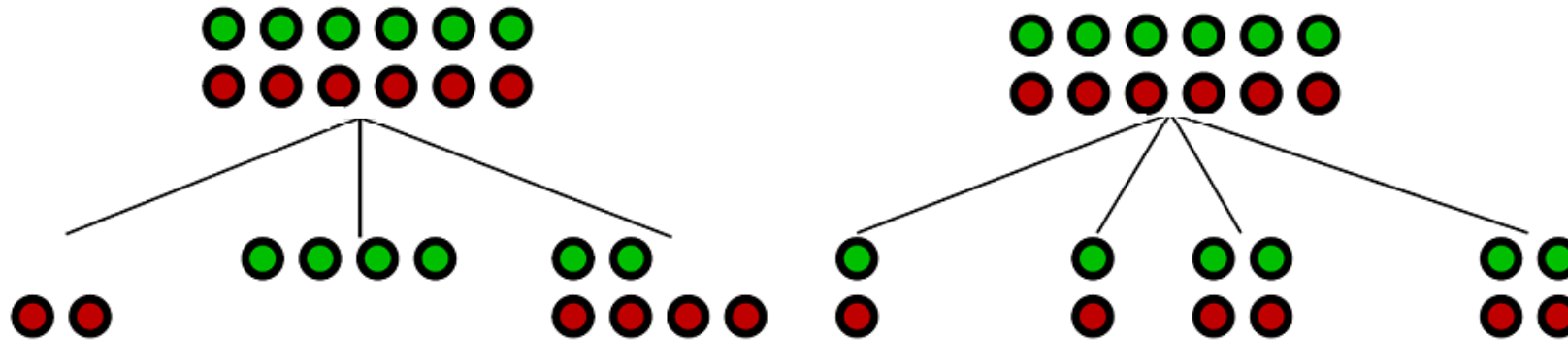


$$\mathbf{v} = (x_1, \dots, x_d) \in \mathbb{R}^d$$

$$\mathcal{S}_j = \mathcal{S}_j^L \cup \mathcal{S}_j^R$$

# Decision trees

- How to build a tree and the splits?
  - A good attribute separates the examples into subsets that, ideally, are all positive and all negative, for example:

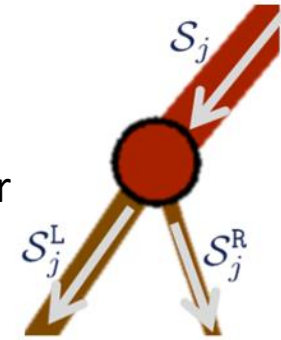


- For this, the concept of Information Gain or entropy reduction can be used;

# Decision Trees

- Training:

$|S|$  - total number  
of examples



$$I_j = H(\mathcal{S}_j) - \sum_{i \in \{L, R\}} \frac{|\mathcal{S}_j^i|}{|\mathcal{S}_j|} H(\mathcal{S}_j^i) \longrightarrow \text{Information Gain}$$

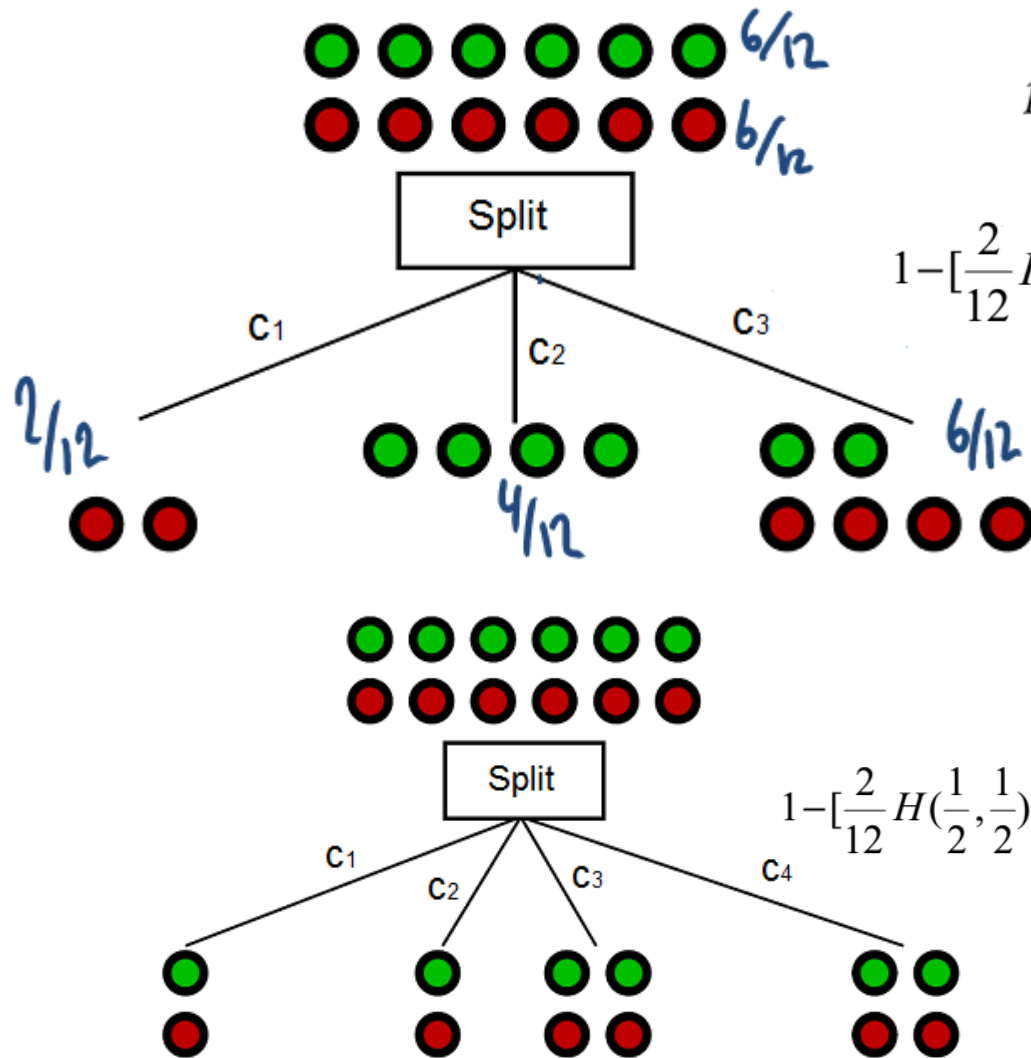
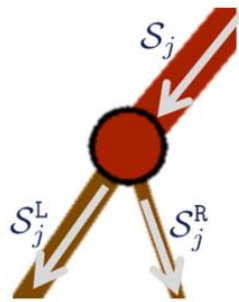
$$H(\mathcal{S}) = - \sum_{c \in \mathcal{C}} p(c) \log p(c) \longrightarrow \text{Entropy}$$

$c \in \{c_k\}$  indexing the class

Ex.:  $S$  contains 10 examples of class  $c_1$   
and 10 examples of class  $c_2$ :

$$H(S) = -(H(10/20) + H(10/20)) = -H(10/20, 10/20)$$

Log2 is normally used!



$$p = n = 6, H(6/12, 6/12) = 1 \text{ bit}$$

$$1 - \left[ \frac{2}{12} H(0,1) + \frac{4}{12} H(1,0) + \frac{6}{12} H\left(\frac{2}{6}, \frac{4}{6}\right) \right] = .541 \text{ bits}$$

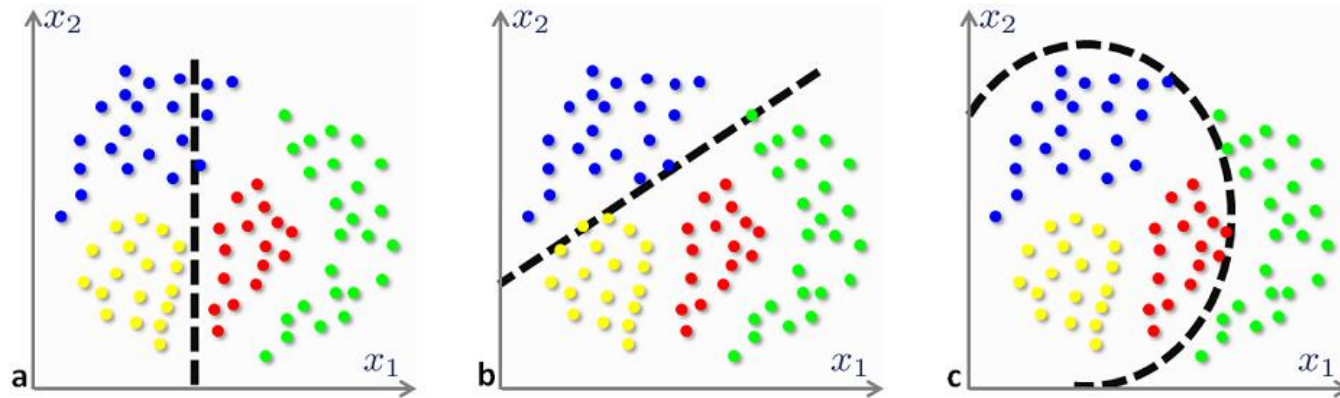
$$I_j = H(S_j) - \sum_{i \in \{L,R\}} \frac{|S_j^i|}{|S_j|} H(S_j^i)$$

$$H(S) = - \sum_{c \in \mathcal{C}} p(c) \log p(c)$$

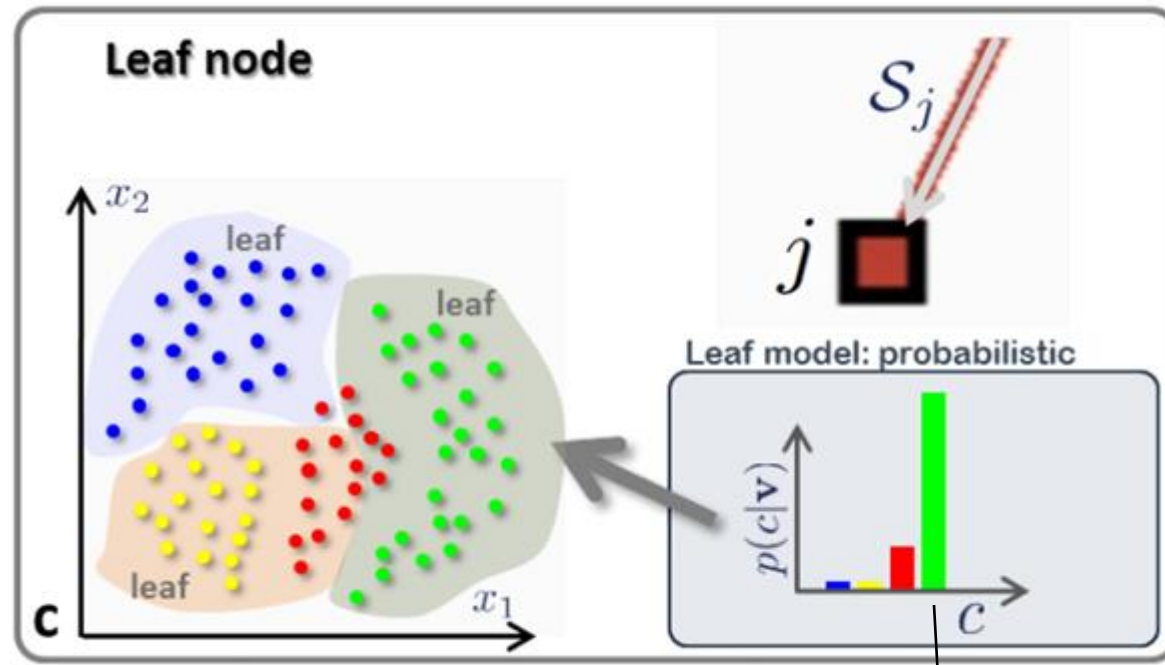
$$1 - \left[ \frac{2}{12} H\left(\frac{1}{2}, \frac{1}{2}\right) + \frac{2}{12} H\left(\frac{1}{2}, \frac{1}{2}\right) + \frac{4}{12} H\left(\frac{2}{4}, \frac{2}{4}\right) + \frac{4}{12} H\left(\frac{2}{4}, \frac{2}{4}\right) \right] = 0 \text{ bits}$$

# Decision Trees

- In practical cases (simple version):
  - Calculate the entropy of the full *dataset*
  - For each *feature*:
    - Split into intervals (linear *grid* or histogram grid)
    - Calculate the average information gain considering the intervals
  - Select the *feature* with the highest average information gain
  - Repeat the process (grow the tree) until the stop criterion is reached (maximum size, maximum probability, etc).
- Several other approaches, each with a different algorithm. For instance:



In the test phase



Majoritary class!



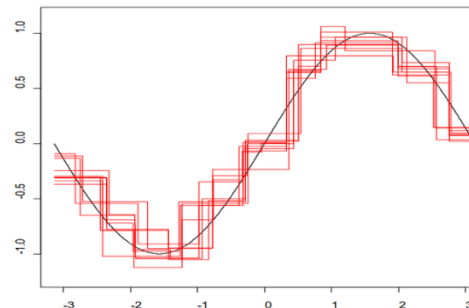
# Decision Tree no scikit-learn

- IRIS example...

# Random Forests

- Algorithm:
  - For  $b=1$  to  $B$  (each tree):
    1. Remove a  $Z^*$  subset of the training data at random.
    2. For each subset, generate a tree of predetermined size, repeating the following steps recursively (*random tree*):
      - I. Randomly select a subset of  $m$  attributes, of the available  $p$  (only a part of the attributes are used).
      - II. Determine the best split of the data based on the information gain.
      - III. Divide the node into two child nodes.
- The result will be given by the combination of the various trees:

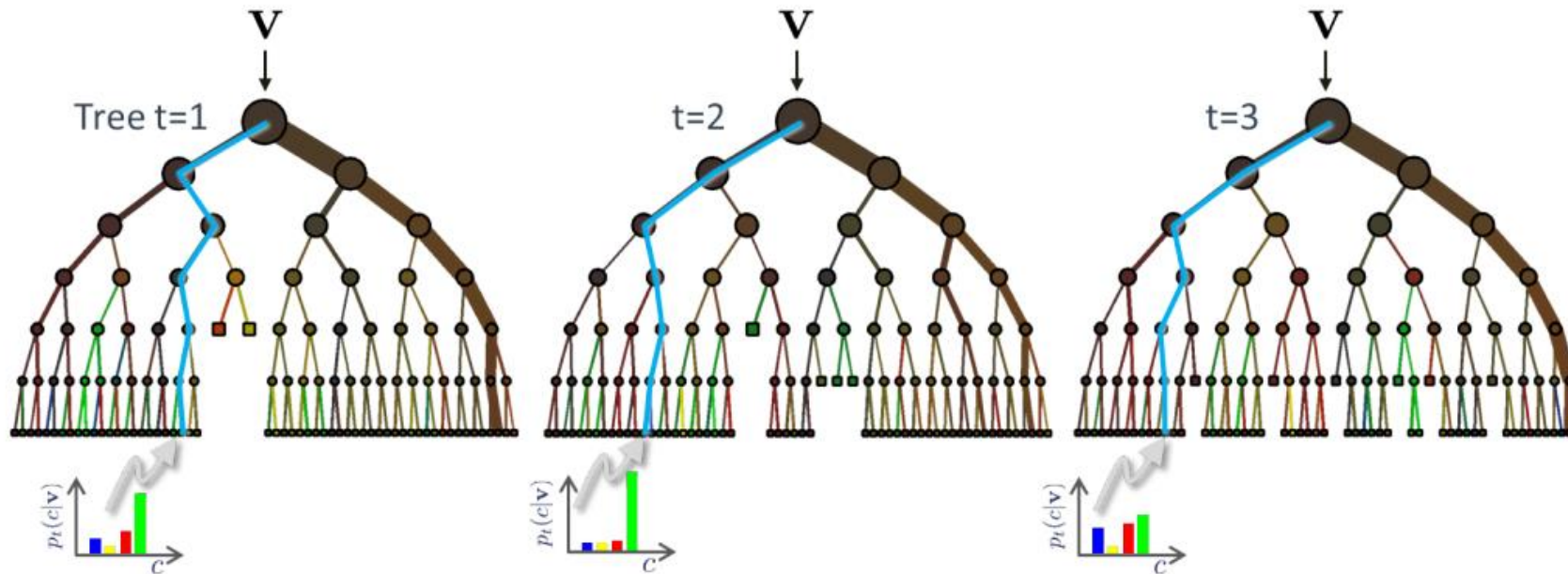
Why does it work?



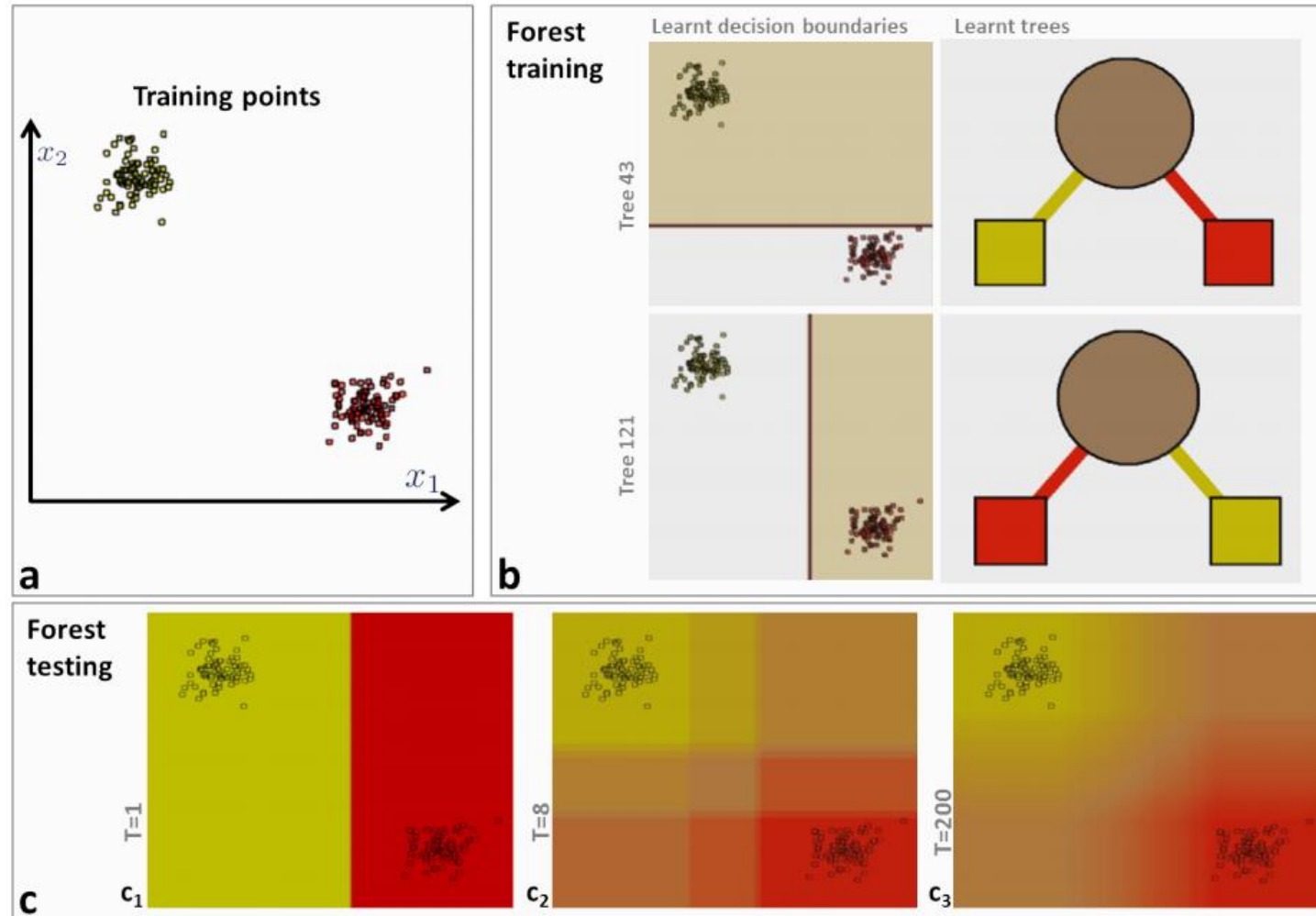
# Random Forests

- **Training:** the trees are trained separately and individually (usually in a distributed way).

- **Test:** 
$$p(c|\mathbf{v}) = \frac{1}{T} \sum_t p_t(c|\mathbf{v})$$



# Number of Trees (Impact)



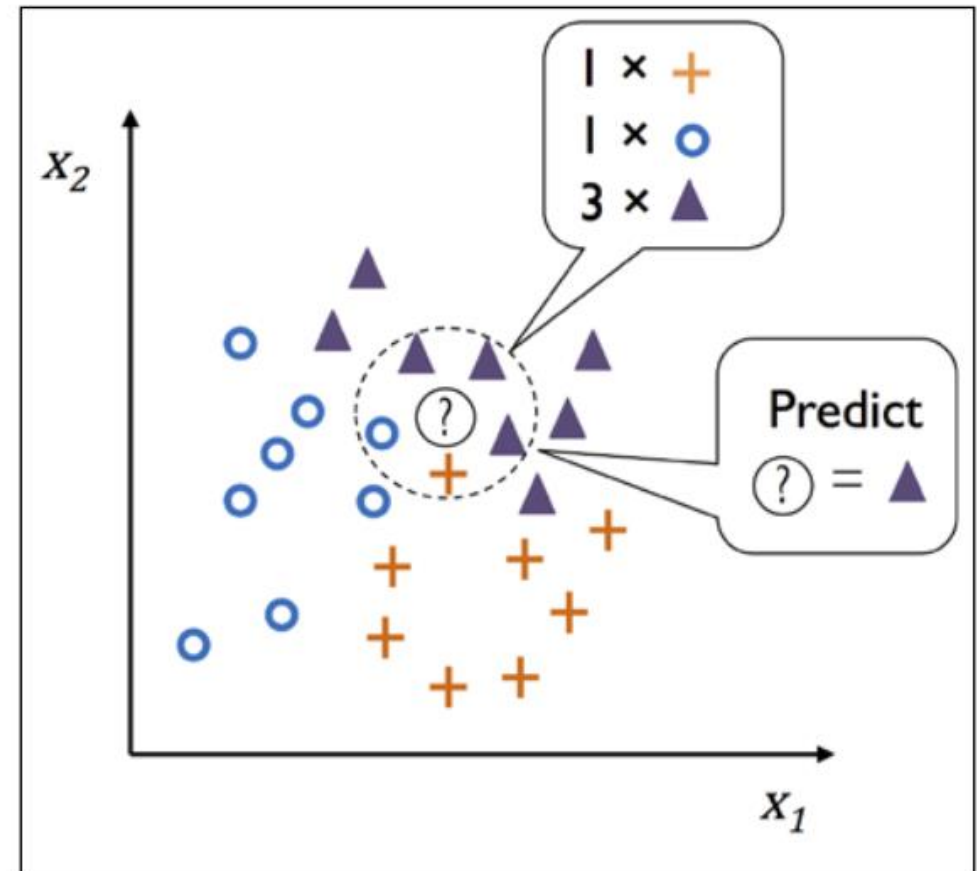
Smoother separation →

# Random Forest with scikit-learn

- IRIS example...

# K-Nearest Neighbors

1. Choose the number of  $k$  and a distance metric.
2. Find the  $k$ -nearest neighbors of the sample that we want to classify.
3. Assign the class label by majority vote.



# kNN with scikit-learn

- IRIS example...