



Looking at Road

x: 2.22

y: -4.81

z: -0.03

FPS: 13









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This was a prototype real-time system I created using OpenCV and MediaPipe as a backend, where I was able to calibrate and understand where the driver was looking in space.





Once the interaction was fully implemented, the outcome was magical: drivers of our vehicles were able to trust that the system was able to work even before they gave up control, and only had to do one thing to give control to the system: just let go!