Calibration results
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Camera-system parameters:
cam0 (/cam0/image_raw):
type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
distortion: [-0.31487994 0.07920199 -0.00036394 -0.00299327] +- [0.00152111 0.00080965 0.00012904 0.00009981]
projection: [1124.27811239 1126.64161766 967.95755015 547.65007274] +- [2.93723879 2.93521684 0.61215554
1.04444247]
reprojection error: [0.000003, 0.000001] +- [1.006523, 0.627354]

Target configuration
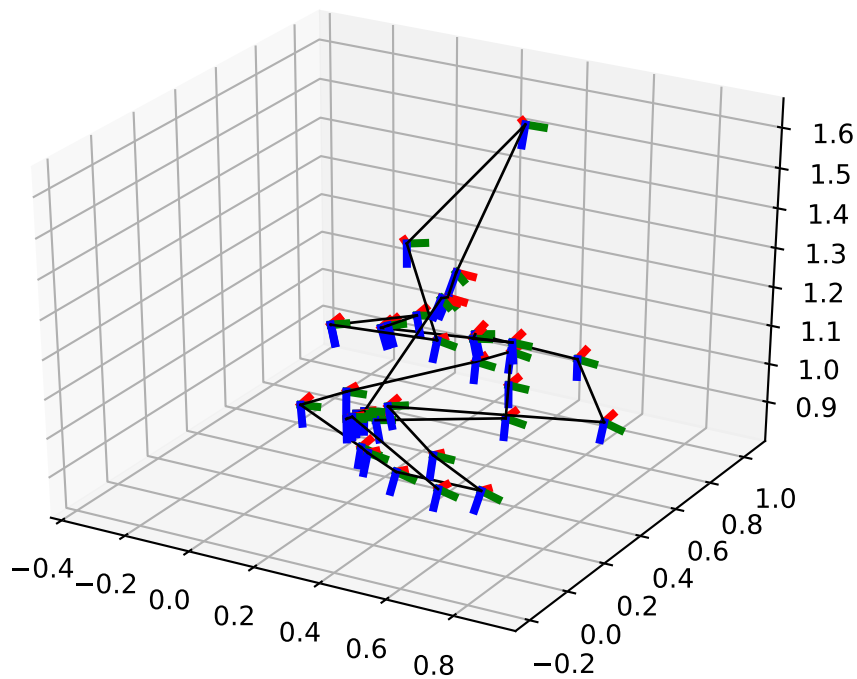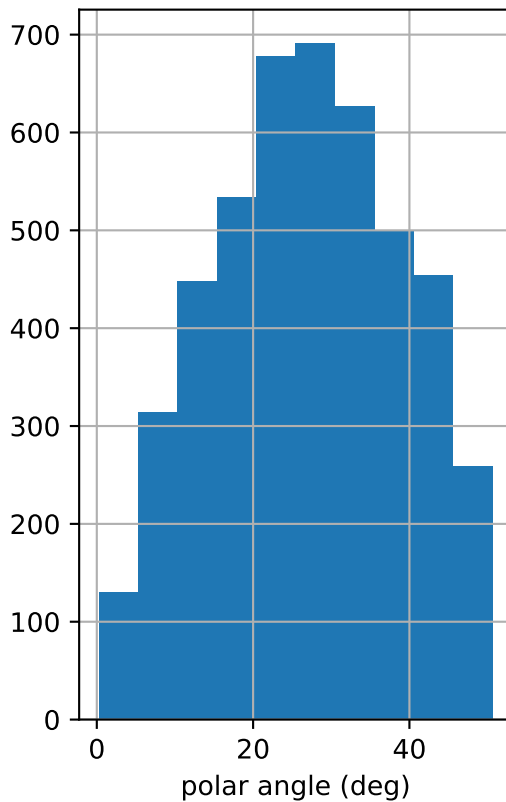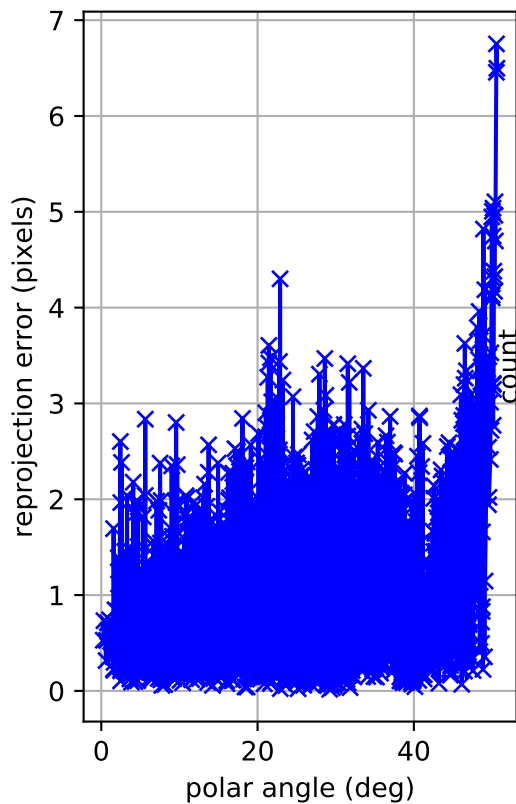====================

Type: aprilgrid
Tags:
Rows: 6
Cols: 6
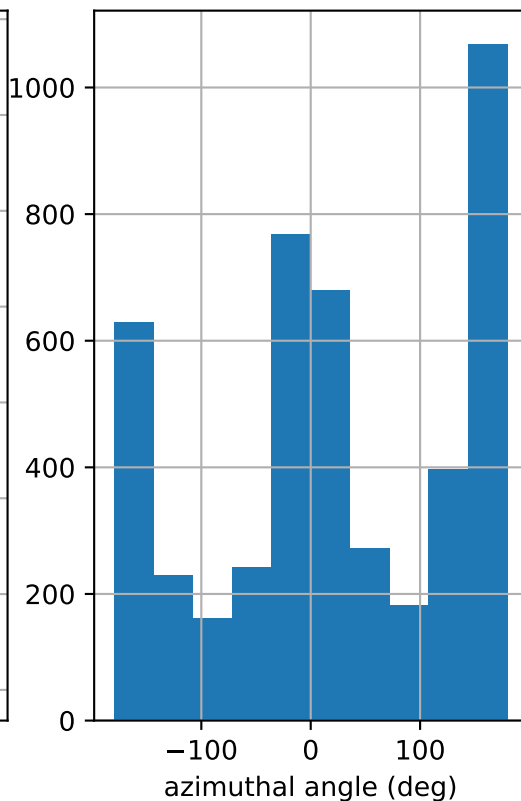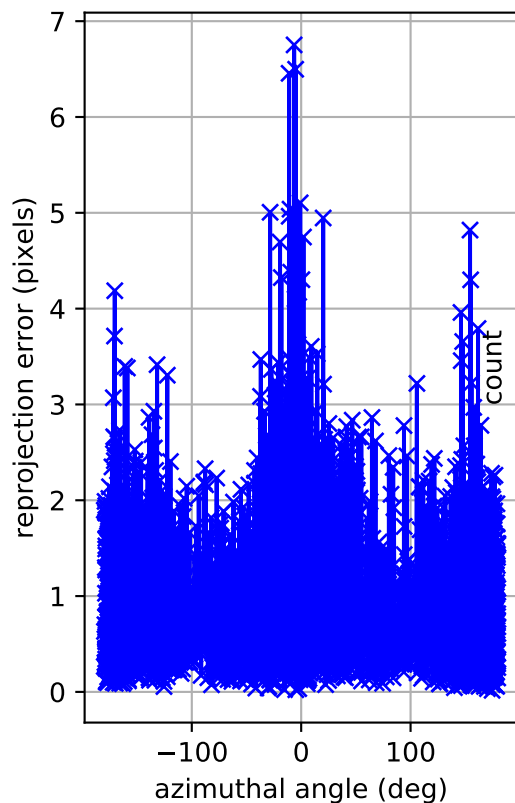Size: 0.088 [m]
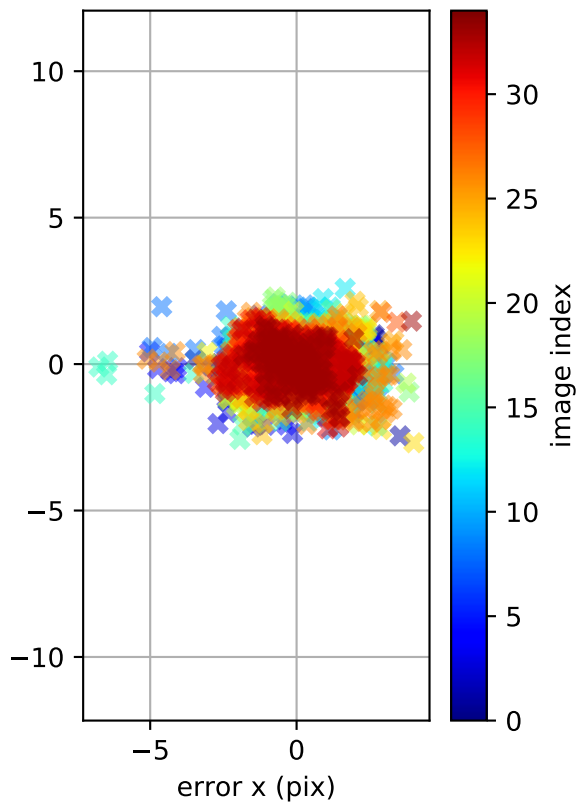Spacing 0.026399999999999996 [m]

cam0: estimated poses
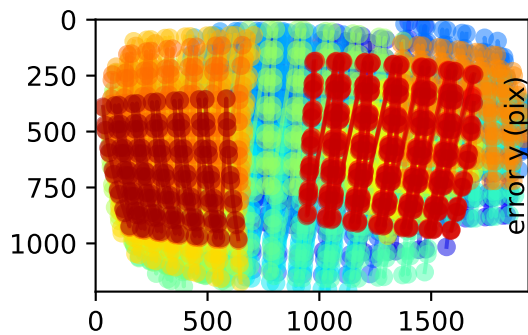
cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners