

Calibration results

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Camera-system parameters:

cam0 (/cam0/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.EquidistantDistortedPinholeCameraGeometry'>

distortion: [-0.03213376 -0.03359785 0.05214567 -0.02128835] +- [0.00386092 0.01209689 0.01624541 0.00758411]

projection: [1073.78581812 1073.0469094 936.33468526 541.04099939] +- [3.37566848 3.29742297 1.03937502 0.73314031]

reprojection error: [0.000001, -0.000000] +- [0.330918, 0.362639]

Target configuration

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Type: aprilgrid

Tags:

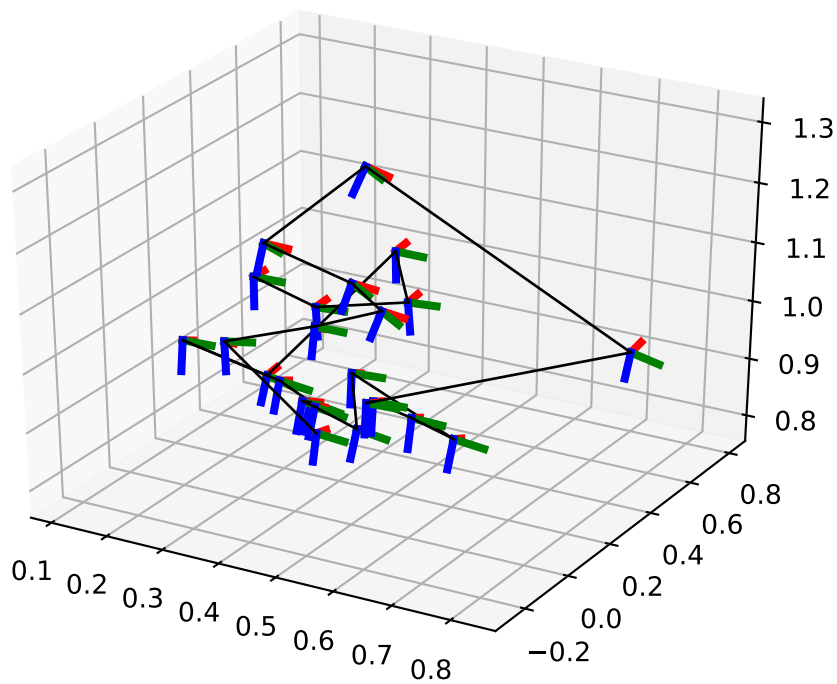
Rows: 6

Cols: 6

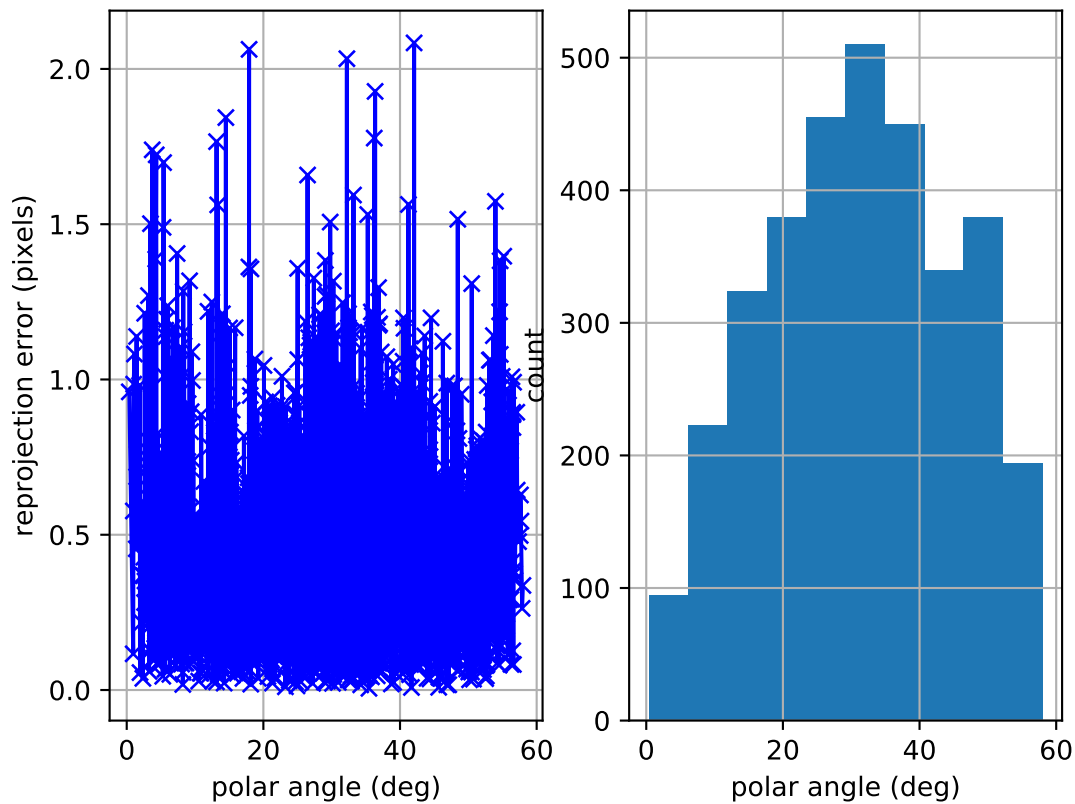
Size: 0.088 [m]

Spacing 0.026399999999999996 [m]

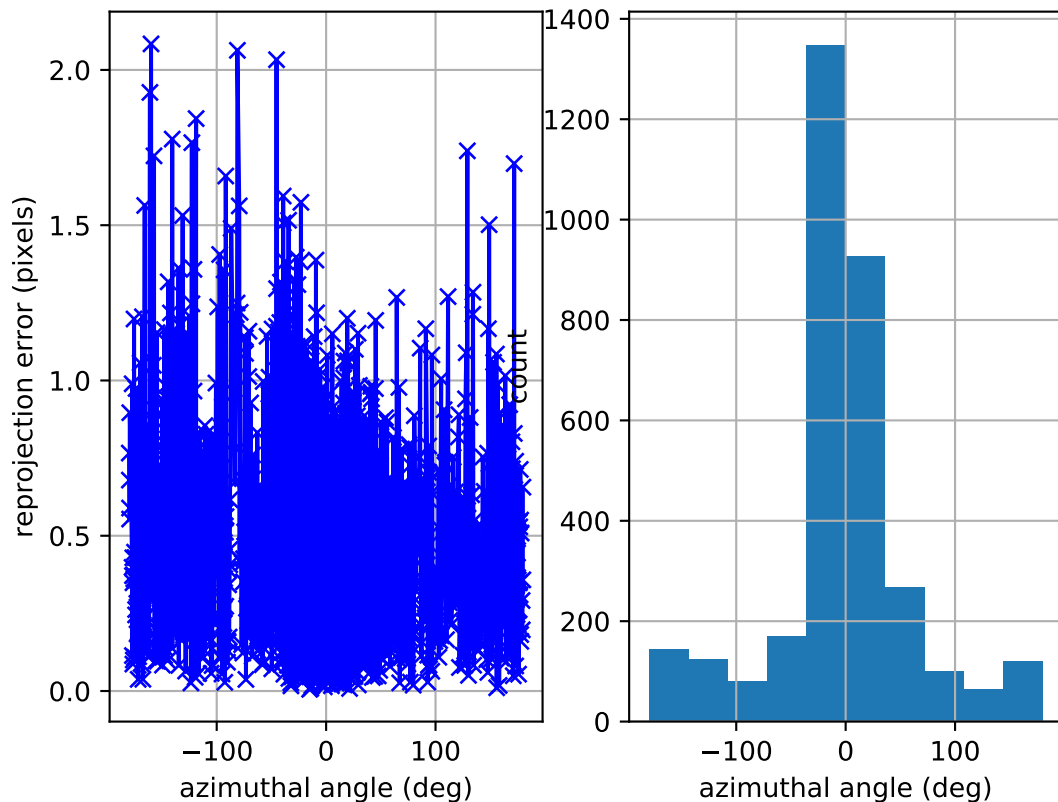
cam0: estimated poses



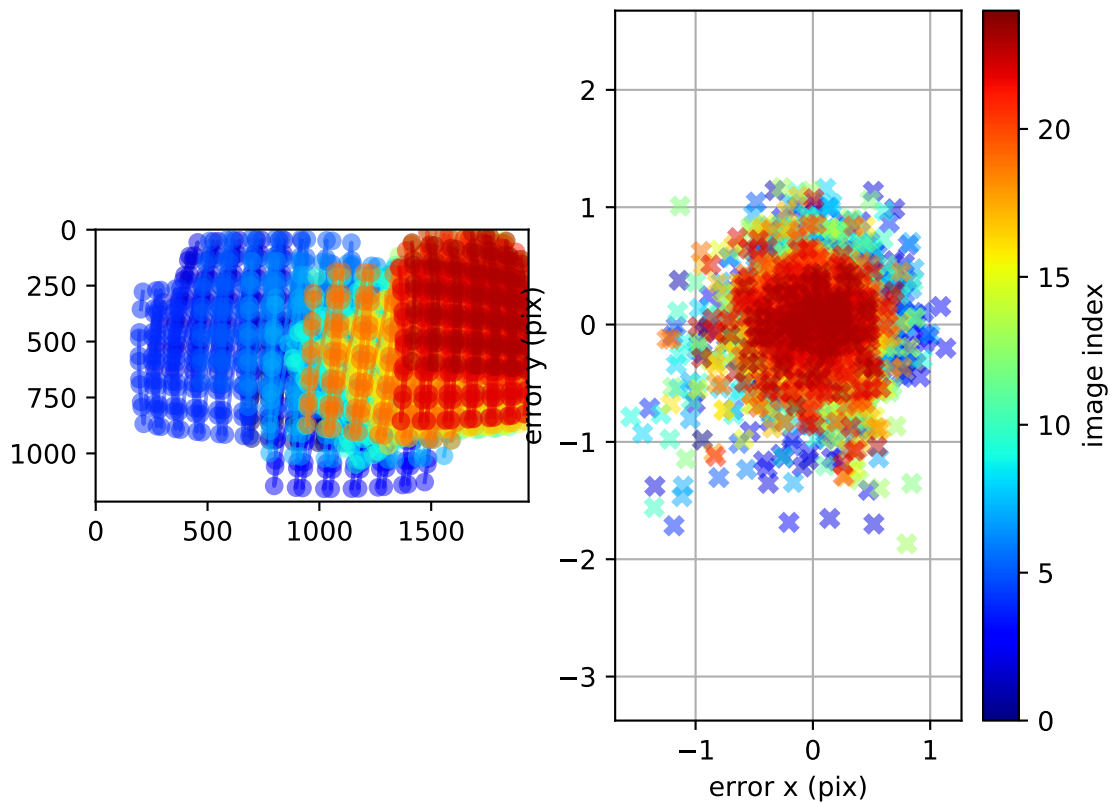
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

cam0

