Calibration results
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Camera-system parameters:
cam0 (/cam0/image_raw):
type: <class 'aslam_cv.libaslam_cv_python.DoubleSphereCameraGeometry'>
distortion: [] +- []
projection: [-0.18794831   0.64641843 878.33246454 877.84138478 940.70909594
545.85407126] +- [0.00248158 0.00104256 0.08480272 0.08752288 1.05569206 0.83164943]
reprojection error: [0.000008, 0.000004] +- [0.351019, 0.325709]

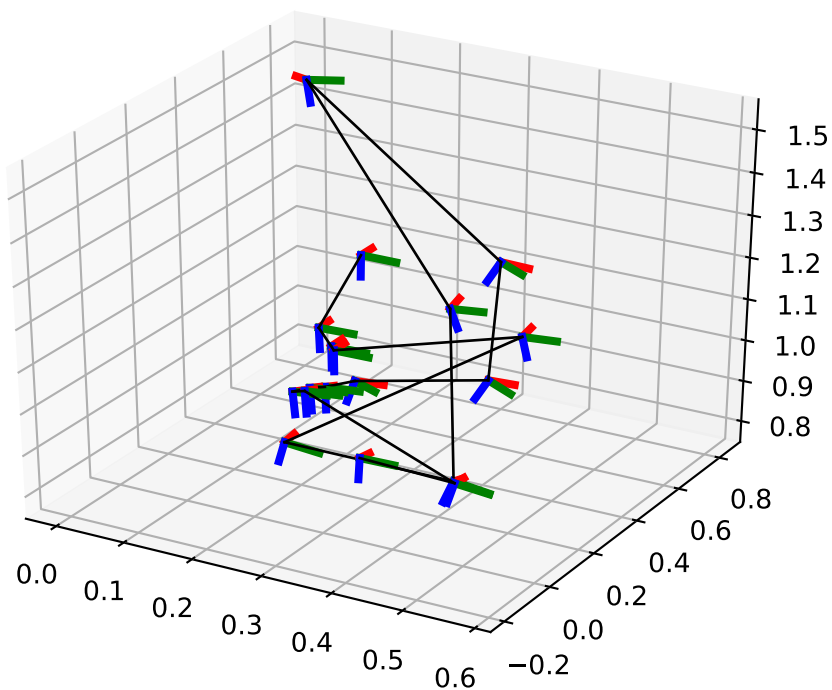Target configuration
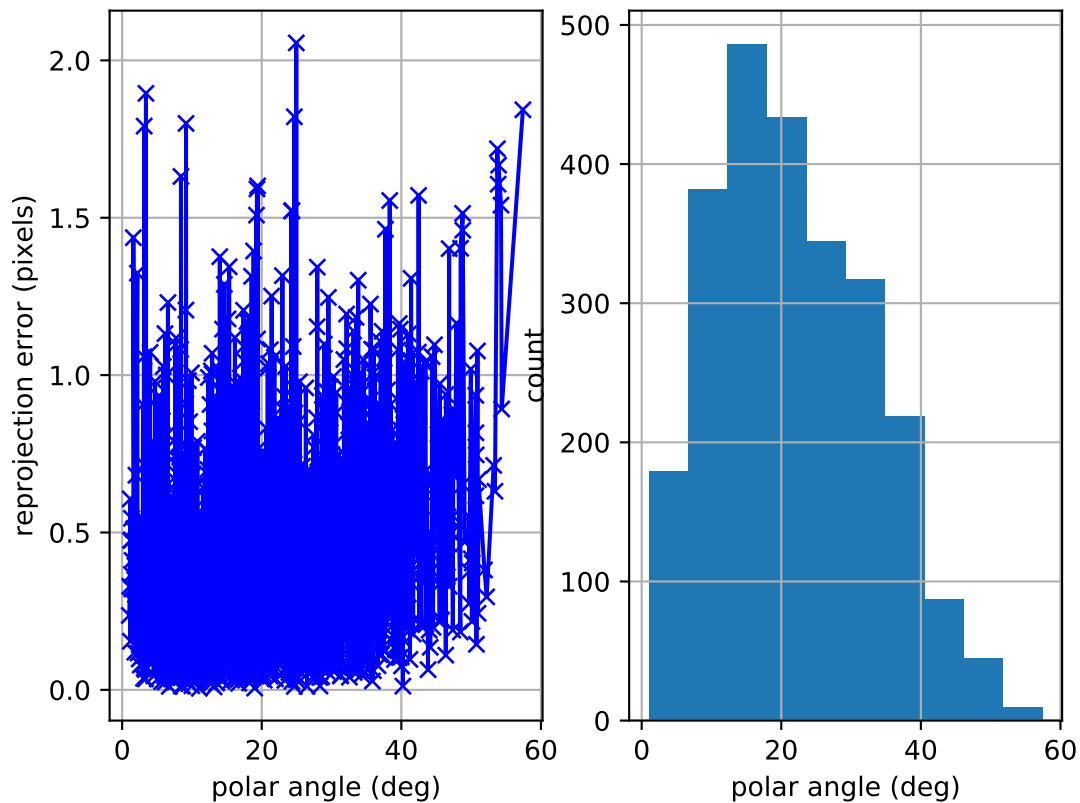====================

Type: aprilgrid
Tags:
Rows: 6
Cols: 6
Size: 0.088 [m]
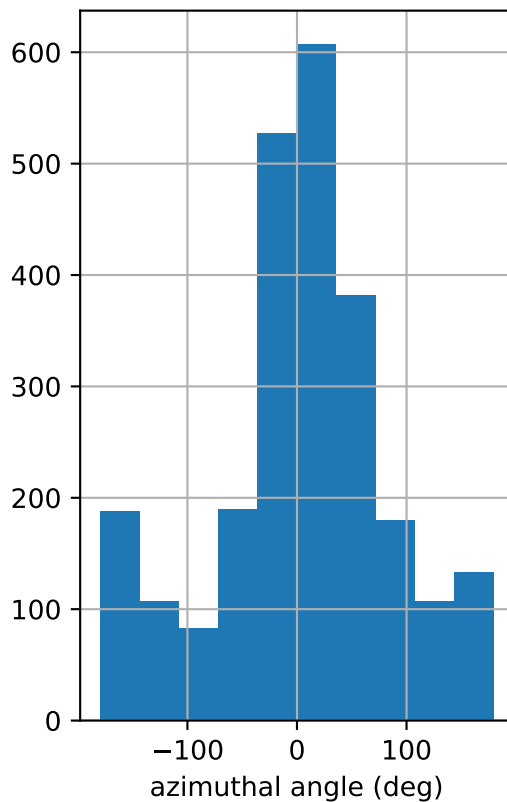Spacing 0.026399999999999996 [m]
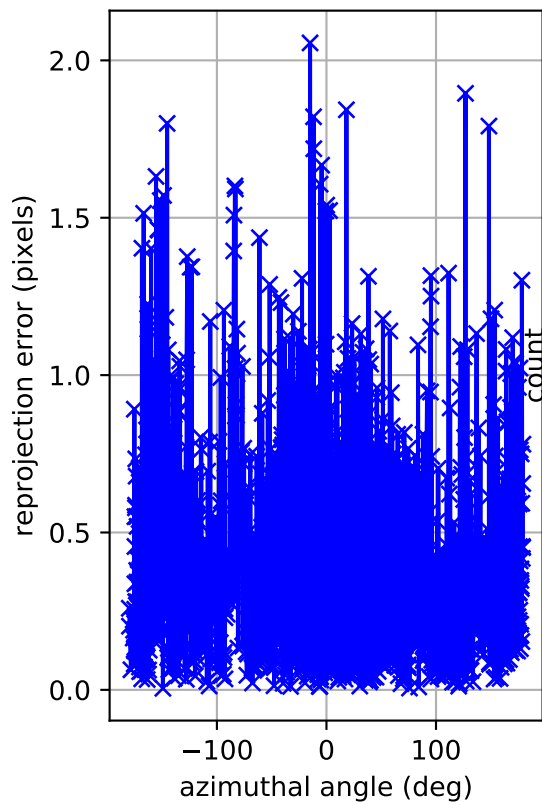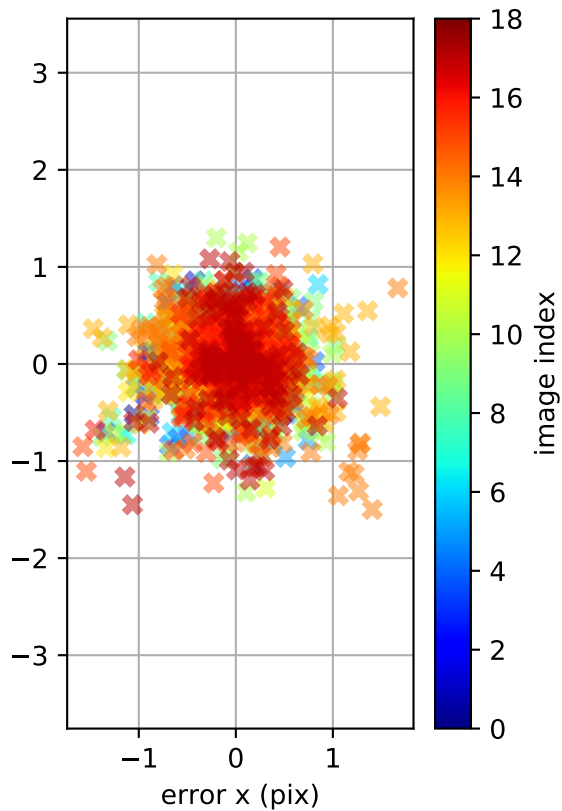
cam0: estimated poses
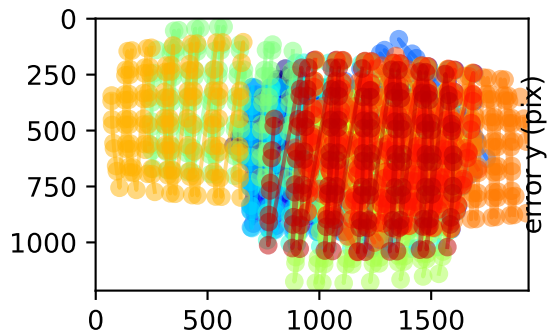
cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners