

# Module Interface Specification for FBP CT Image Reconstruction

Qianlin Chen

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# 1 Revision History

Date	Version	Notes
March 11	1.0	Initial document

## 2 Symbols, Abbreviations and Acronyms

See SRS Documentation at [\[give url —SS\]](#)

[\[Also add any additional symbols, abbreviations or acronyms —SS\]](#)

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### 3 Introduction

The following document details the Module Interface Specifications for FBP CT Image Reconstruction. Complementary documents include the System Requirement Specifications and Module Guide. The full documentation and implementation can be found at [MIS](#).

### 4 Notation

[You should describe your notation. You can use what is below as a starting point. —SS]

The structure of the MIS for modules comes from [Hoffman and Strooper \(1995\)](#), with the addition that template modules have been adapted from [Ghezzi et al. \(2003\)](#). The mathematical notation comes from Chapter 3 of [Hoffman and Strooper \(1995\)](#). For instance, the symbol  $:=$  is used for a multiple assignment statement and conditional rules follow the form  $(c_1 \Rightarrow r_1 | c_2 \Rightarrow r_2 | \dots | c_n \Rightarrow r_n)$ .

The following table summarizes the primitive data types used by FBP CT Image Reconstruction.

Data Type	Notation	Description
character	char	a single symbol or digit
integer	$\mathbb{Z}$	a number without a fractional component in $(-\infty, \infty)$
natural number	$\mathbb{N}$	a number without a fractional component in $[1, \infty)$
real	$\mathbb{R}$	any number in $(-\infty, \infty)$

The specification of FBP CT Image Reconstruction uses some derived data types: sequences, strings, and tuples. Sequences are lists filled with elements of the same data type. Strings are sequences of characters. Tuples contain a list of values, potentially of different types. In addition, FBP CT Image Reconstruction uses functions, which are defined by the data types of their inputs and outputs. Local functions are described by giving their type signature followed by their specification.

### 5 Module Decomposition

The following table is taken directly from the Module Guide document for this project.

Level 1	Level 2
Hardware-Hiding	Hardware-Hiding Module
	Filter Module
	FBP Module
	IO Handler Module
Behaviour-Hiding	Services Module
Software Decision	Sinogram Simulation Module

Table 1: Module Hierarchy

## 6 MIS of Filter Module

### 6.1 Module

Filter

### 6.2 Uses

### 6.3 Syntax

#### 6.3.1 Exported Constants

None

#### 6.3.2 Exported Access Programs

Name	In	Out	Exceptions
get_fourier_filter	s: int, filter_name: str	filter: $\mathbb{R}^s$	OutOfRangeException, NULL

### 6.4 Semantics

#### 6.4.1 State Variables

None

#### 6.4.2 Environment Variables

None

#### 6.4.3 Assumptions

Input size s is a positive number.

#### 6.4.4 Access Routine Semantics

get\_filter(s, filter\_name):

- output: out :=  $2\Re(\mathcal{F}(f(s)))$  with  
 $f(s) := (filter\_name = 'shepp' \Rightarrow f(s) \parallel filter\_name = 'ramp' \Rightarrow g(s) \parallel filter\_name = None \Rightarrow None)$  where:

—

$$f(s) = \begin{cases} 0.25, & s = 0 \\ \frac{-1}{\pi s^2}, & s \text{ is odd} \\ 0, & s \text{ is even} \end{cases} \quad (1)$$



—

$$g(s) = \frac{\sin \pi \cdot freq(n)}{\pi \cdot freq(n)} \cdot freq(n) \quad (2)$$

$freq(n)$  corresponds to the frequency bins in the discrete Fourier domain:

$$freq(n) = \begin{cases} \frac{n}{s}, & 0 \leq n < \frac{s}{2} \\ \frac{n-s}{s}, & \frac{s}{2} \leq n < s \end{cases} \quad (3)$$

- exception:  $exc := (s < 0 \Rightarrow OutOfRange|filter\_name \notin \{ramp, None, shepp\} \Rightarrow NULL)$

#### 6.4.5 Local Functions

None

## 7 MIS of FBP Module

### 7.1 Module

FBP

### 7.2 Uses

Filter Module

### 7.3 Syntax

#### 7.3.1 Exported Constants

None

#### 7.3.2 Exported Access Programs

Name	In	Out	Exceptions
reconstruct	sinogram: $\mathbb{R}^{m \times n}$ , $\theta : \mathbb{R}^n$ , filter_name: string, os: int	image: $\mathbb{R}^{os \times os}$	ValueError, EmptyArrayError

### 7.4 Semantics

#### 7.4.1 State Variables

$filter \in \mathbb{R}^s$ : The fourier filter.

#### 7.4.2 Environment Variables

None

#### 7.4.3 Assumptions

Input sinogram are valid 2D frequency spectra.

#### 7.4.4 Access Routine Semantics

reconstruct(sinogram, theta, filter\_name, os):

- transition:  $filter := sinogram \Rightarrow Filter.get\_filter(sinogram.size, filter\_name)$   
(get\_filter from Filter Module<sup>10</sup>)
- output:  $out :=$ 
  - $\mathcal{F}^{-1}(\mathcal{F}(sinogram) \cdot filter)$

- perform interpolation over angle  $\theta$  with the preset image size  $os$ .
- exception:  $exc :=$

Exceptions	Description
$os < 0 \parallel \theta < 0 \Rightarrow ValueError$	Valid output size and interpolation angle should not be negative.
$sinogram.size < 0 \Rightarrow EmptyArrayError$	The input sinogram is invalid if the input array size is smaller than 0.

#### 7.4.5 Local Functions

None

## 8 MIS of Sinogram Simulation Module

### 8.1 Module

Sinogram Simulation

### 8.2 Uses

None

### 8.3 Syntax

#### 8.3.1 Exported Constants

None

#### 8.3.2 Exported Access Programs

Name	In	Out	Exceptions
radon	image: $\mathbb{R}^{m \times m}$ , preserve_angle: Boolean, theta: $\mathbb{R}^n$	sinogram: $\mathbb{R}^{m \times m}$	None

### 8.4 Semantics

#### 8.4.1 State Variables

None

#### 8.4.2 Environment Variables

None

#### 8.4.3 Assumptions

Input Image are valid 2D frequency spectra.

#### 8.4.4 Access Routine Semantics

radon(image, preserve\_angle, theta):

- output: out := sinogram where
  - Use padded\_radon to find out the padded\_image and center of the input image
  - $\text{sinogram} := \text{padded\_image} \Rightarrow \int_{-\infty}^{\infty} \text{padded\_imgae}(x \cos(\text{theta}) + y \sin(\text{theta}), x \sin(\text{theta}) - y \cos(\text{theta})) dy$
- exception: None

#### 8.4.5 Local Functions

`padding_radon(image, preserve_angle):`

- transition: None
- output: `out :=`

**padded\_image** :=

- The diagonal length of the padded square image is calculated as:  $d = \sqrt{2} \cdot \max(image.size)$
- The required padding size for each dimension is:  $|d - s|, \forall s \in image.size$

**center** :=  $\frac{padded\_image[0]}{2}$

- exception: If image is not an 2D array, raise `ValueError`

## 9 MIS of IO Handler Module

### 9.1 Module

IO Handler

### 9.2 Uses

FBP Module

Sinogram Simulation Module

Services Module

Hardware Handling Module

### 9.3 Syntax

#### 9.3.1 Exported Constants

None

#### 9.3.2 Exported Access Programs

Name	In	Out	Exceptions
select_service	op: String	None	None
process_service	File, theta: $\mathbb{R}^n$ , filter_name: String, os: int, preserve_angle: Boolean	None	?
get_reconstruction	None	reconstruction: $\mathbb{R}^{os \times os}$	?

### 9.4 Semantics

#### 9.4.1 State Variables

service: Service sinogram reconstructed\_image

#### 9.4.2 Environment Variables

None

#### 9.4.3 Assumptions

Input Image are valid 2D frequency spectra.

#### 9.4.4 Access Routine Semantics

select\_services(op):

- transition:  $service := op = 'reconstruction' \Rightarrow 0 \parallel op = 'verification' \Rightarrow 1$
- exception:  $exc := op \notin ['reconstruction', 'verification'] \Rightarrow ValueError$

process\_service(file, theta, filter\_name, os, preserve\_angle):

- transition: use load\_image to load the image data as a 2D array.  
 $\mathbf{sinogram} := service = 0 \Rightarrow load\_image(file, preserve\_angle) \parallel service = 1 \Rightarrow simulation.radon()$   
 $\mathbf{reconstructed\_image} := fbp.reconstruct() \text{ from module...}$
- exception:  $exc := ?$

get\_reconstruction(None):

- output:  $out := reconstructed\_image$
- exception:  $exc := None$

#### 9.4.5 Local Functions

load\_image(file, preserve\_angle):

- output: read image file and return a 2D numpy array.
- exception:  $exc := \text{file does not exist then FileNotFoundError.}$

## **10 MIS of Configuration Module**

### **10.1 Module**

Configuration

### **10.2 Uses**

None

### **10.3 Syntax**

#### **10.3.1 Exported Constants**

VERIFICATION = 0

RECONSTRUCTION = 1

#### **10.3.2 Exported Access Programs**

None

### **10.4 Semantics**

#### **10.4.1 State Variables**

None

#### **10.4.2 Environment Variables**

None

#### **10.4.3 Assumptions**

None

#### **10.4.4 Access Routine Semantics**

None

#### **10.4.5 Local Functions**

None



## References

- Carlo Ghezzi, Mehdi Jazayeri, and Dino Mandrioli. *Fundamentals of Software Engineering*. Prentice Hall, Upper Saddle River, NJ, USA, 2nd edition, 2003.
- Daniel M. Hoffman and Paul A. Strooper. *Software Design, Automated Testing, and Maintenance: A Practical Approach*. International Thomson Computer Press, New York, NY, USA, 1995. URL <http://citeseer.ist.psu.edu/428727.html>.

## 11 Appendix

[Extra information if required —SS]