- Reliability \rightarrow R(t) = P[T>t] =1 F_T(t)
- R(0) = 1
- $\lim_{t\to\infty} R(t)=0$
- $N_s(t) + N_f(t) = N_0$ $R(t) = \frac{N_s(t)}{N_0} = 1 - \frac{N_f(t)}{N_0}$
- N'f(t) \rightarrow failure rate of components.
- $R'(t) = -f_X(t)$
- Correctness, precision, timeliness
- HAZARD RATE → system is not expected to survive any additional time x after t

$$P[T \le t + x \mid T > t] = \frac{P[t < T \le t + x]}{P[T > t]} = \frac{F_X(t + x) - F_X(t)}{R(t)}$$

- failure rate or hazard rate h(t) \rightarrow $h(t) = \lim_{x \to 0} \frac{F_X(t+x) F_X(t)}{xR(t)} = h(t) = \frac{f_X(t)}{R(t)}$
- Hazard rate \rightarrow failures/10000 hr \rightarrow failures in time == failures/10⁹ hr. If X ¬ EXP (λ)

$$h(t) = \frac{f_x(t)}{R(t)}$$

$$h(t) = \frac{\lambda e^{-\lambda t}}{e^{-\lambda t}}$$

• $h(t) = \lambda$ \rightarrow constant failure rate / hazard rate for an exponentially distributed lifetime is constant

The cumulative hazard H(t)

$$H(t) = \int_{0}^{t} h(x)dx$$
$$= -\int_{0}^{t} \frac{R'(x)}{R(x)} dx$$
$$= -[lnR(x)]_{0}^{t}$$
$$= -lnR(t)$$

This gives

$$R(t) = e^{-H(t)}$$

- 2 PP → hazard rate or reliability
- MORTALITY CURVE

• Reliability block diagrams (RBD) \rightarrow E_k = block k is operational.

 \rightarrow reliability of block k is $R_k = P(E_k)$

• Series Systems
$$\rightarrow R_s = P[E_1] P[E_2] \cdots P[E_n] = R_1 R_2 \cdots R_n = R_s = \prod_{i=1}^n R_i$$

- \rightarrow For homogeneous = identical reliability \rightarrow Rs= Rⁿ
- $\rightarrow R_s < \min(R_1, R_2, \dots, R_n)$
- → number of components increases; the system's reliability decreases
- \rightarrow PP
- →n-out-of-n system

$$1 - R_P = (1 - R_1) (1 - R_2) \dots (1 - R_n)$$

 $R_P = 1 - \prod_{i=1}^n (1 - R_i)$

Parallel System → 'redundant units' →

- → homogeneous modules = identical reliability → $R_P=1-(1-R)^n$
- →Effects & PP
- →1-out-of-n system
- SERIES-PARALLEL SYSTEM →PP

• K-OUT-OF-N SYSTEM
$$\Rightarrow$$

$$PP$$

$$PP$$

$$R_{n|k} = \sum_{i=k}^{n} {n \choose i} R^{i} (1-R)^{n-i}$$

• Triple modular redundancy (TMR) \rightarrow triplex system \rightarrow 2-out-of-3 system \rightarrow Derivation \rightarrow R_{TMR} = $3R^2 - 2R^3$ \rightarrow 2 PP

- Task
- System availability → availability & reliability

$$A = \frac{Up \ Time}{Up \ Time + Down \ Time}$$

$$A = \frac{MTTF}{MTTF + MTTR} = \frac{MTTF}{MTBF}$$

$$U = 1 - A$$

$$U = \frac{MTTR}{MTTF + MTTP} = \frac{MTTR}{MTBF}$$

- Unavailability →
- PP

- Fault, Error, Failure
- Software Reliability vs Hardware Reliability
- Probability of Failure on Demand (POFOD):
- Rate of Occurrence of Failures (ROCOF) → Failure Intensity
- Mean time to failure (MTTF)
- Availability (AVAIL)
- Reliability validation → The reliability measurement process
- statistical testing.
- PP of MTTF & etc.

- Queuing Theory → inter-arrival times & service time
- Input Source → Population size → mostly infinity
- Queuing Behavior → jockey, balk, renege
- Service time / holding time
- Cost optimization model \rightarrow total cost = waiting cost + cost of providing service
- Graph
- PP

Lecture 19

- Kendall Notation \rightarrow A/B/C/X/Y/Z \rightarrow default; ∞ , ∞ and FIFO
- PP
- Job flow balance
- One-step behavior
- Homogeneity
- Exclusivity
- Non-blocking
- Independence
- Terminology and Notation $\rightarrow \lambda$, μ , state of the sys., queue length
- Little's Law \rightarrow L = λ W \rightarrow Derivation
- Utilization Law $\rightarrow \rho = \lambda/(s\mu)$; server ; CPU ;etc.
- system's service capacity → sµ
- Operational Analysis & Stochastic Analysis

- Transient State & Steady State
- Steady State Notations $\rightarrow P_n$, $L = \sum_{n=0}^{\infty} nP_n$, $L_q = \sum_{n=s}^{\infty} (n-s)P_n$, W
- M/m/1 queue analysis \rightarrow the birth-and-death process
- mean entering rate = mean leaving rate \rightarrow balance equation \rightarrow conversation of flow
- $\bullet \quad P_n = \rho^n P_0 \&$
- $\therefore P_0 = 1 \rho$ & reason

- M/M/1 Analysis \rightarrow at least k customers in the system; $P[N \ge k] = \rho^k$
 - → expected number of customers in the system,

$$L = E[N] = \frac{\rho}{1-\rho}$$

→ expected time spent in the system,

$$W = \frac{1}{\mu - \lambda}$$
 $W = \frac{1}{\mu (1 - \rho)} = \frac{W_s}{(1 - \rho)}$

→ mean waiting time,

$$W_q = W - W_S$$
 $W_q = \frac{L}{\mu}$

→ number of customers in the queue,

$$L_q = \frac{\rho^2}{1-\rho}$$

→ number of customers in the service facility

$$L_s = L - L_q$$
 $L_s = \rho$

distribution of total time, service time & waiting time

$$W_s(t) = P \{s \le t\} = 1 - e^{-\mu t} = 1 - e^{-t/W_s}$$

 $W(t) = P \{W \le t\} = 1 - e^{-t/W}$

 $W_q(t) = P \{q \le t\} = 1 - \rho e^{-t/W}$ (When queue discipline is FCFS)

- PASTA (Poisson Arrivals See Time Averages) Theorem
- 2 PP

Lecture 22

• M/M/1/K System (Finite Buffer Capacity)

$$\Rightarrow \quad P_n = \rho^n \frac{1-\rho}{1-\rho^{k+1}}$$

$$P_0 = \frac{1}{1+k} \Rightarrow P_n = \frac{1}{1+k}$$

$$L = \frac{\rho}{1-\rho} - (k+1) \frac{\rho^{k+1}}{1-\rho^{k+1}} & \& L = k/2 \text{ iff } \rho = 1$$

→ Average Number of customers in the Service & in the Queue,

Ls= 1 -
$$P_0$$
 & $L_q = L - L_s \rightarrow L_q = L - (1 - P_0)$

• Effective Arrival Rate $\rightarrow \lambda_a = \lambda (1 - \mathbf{P_k})$

$$W = \frac{L}{\lambda_a} = \frac{L}{\lambda (1 - Pk)} \quad \& \quad W_q = \frac{L_q}{\lambda (1 - Pk)}$$

• Server Utilization (U),

$$\rightarrow$$
 U = $\rho(1 - P_k)$

• 2 PP

- Queuing models involving nonexponential dist. \rightarrow mean = $1/\mu$ & variance = σ^2
- The M/G/1 Model,

$$P_0 = 1 - \rho$$
,

$$L_q = \frac{\lambda^2 \sigma^2 + \rho^2}{2(1 - \rho)},$$

$$L = \rho + L_q,$$

$$W_q = \frac{L_q}{\lambda}$$
,

$$W = W_q + \frac{1}{\mu}.$$

- Pollaczek-Khintchine formula \rightarrow above formula of L_q
- service-time distribution is exponential $\rightarrow \sigma^2 = 1/\mu^2$
- UNIFORM DISTRIBUTION,
 - → The expected value of X is $E[X] = (b+a)/2 = 1/\mu$
 - The variance of X is $Var[X] = (\mathbf{b} \mathbf{a})^2/12 = \sigma^2$
 - → PP
- M/D/s Model \rightarrow fixed constant / degenerate service- time distribution \rightarrow special case of the M/G/1 model where $\sigma^2 = 0$,

$$\downarrow L_q = \frac{\rho^2}{2(1-\rho)},$$

- Erlang-n Distribution \rightarrow exponential distribution in series
 - \rightarrow service time = n/ μ for n stages
 - \rightarrow population mean = $E[X] = n\alpha$
 - →variance V [X] = $n\alpha^2$ & α is given by $1/\mu$
- hypo-exponential/generalized Erlang dist. → diff. service rate for every server
- Hyper-Exponential Distribution → exponential distribution in parallel In k cumulative k formulae lecture main h

- QUEUING NETWORKS
- Open queuing networks
- Closed queuing networks
- Jackson's Network → service rate → node-dependent & state-dependent
 - $\rightarrow \rho$ < 1 & service jobs by FCFS
 - \rightarrow n_i = state of node i & total no. of customers in node i
 - \rightarrow p(n) = p(n₁) p(n₂) p(n_M)

- Burke's Theorem →
- Two Stages Tandem Network → rate diagram

⇒
$$P(n_0,n_1) = P(n_0) P(n_1)$$

= $\rho_0^{n_0} (1 - \rho_0) \rho_1^{n_1} (1 - \rho_1)$; Jackson theorem on TN

$$\rightarrow$$
 For stability, $\rho_0 = \frac{\lambda}{\mu_0} < 1 \& \rho_1 = \frac{\lambda}{\mu_1} < 1$

- PP remaining formulas of M/M/1 lec: 21
- Open Central Server Networks →

$$\lambda_{j} = \begin{cases} \frac{\lambda}{p_{0}}, & j = 0\\ \frac{p_{j}}{p_{0}}\lambda, & j = 1, 2, 3, \dots, \underline{m} \end{cases}$$

• PP \rightarrow see W formula

Lecture 27

- Petri nets (PNs) → contention for resources &
 → synchronization b/w concurrent various activities.
- Representation using set notation \rightarrow M = (P,T,I,O,MP/ μ) 7& example
- Dynamic Behavior of Petri-Nets → t ki sb i/p P k pass token hoga tuh hi t will fire
- Dual of a petri-net → Places & Transitions replaced & Example

Lecture 28

- Inverse of Petri Net → switches input functions with output functions.
- Petri Nets as Multi-graph → bold input output lines
- State of a Petri Net \rightarrow cardinality, $\mu \rightarrow$ marking function

→ Condition/Events nets, Parallelism/Concurrency, Synchronization

• The Bounded Buffer Producer/Consumer Problem

Lecture 29

- Mutual Exclusion (Conflict)
- Inhibitor Arcs, conflict \rightarrow if t_x fires, Crucial \rightarrow t absorbs one t
- Reachability, Reversibility \rightarrow comes back to μ_0 ,
- K-bounded Petri-Net → 3-bounded Petri-Net if max no. of tokens is 3
- PP, Deadlock PN
- Properties of PN → liveness, safeness, boundedness, conservation

- 2 PP
- Matrix analysis → D = D⁺ D⁻ → incidence matrix, pre-incidence → input matrix → $\mathbf{M}' = \mathbf{M} - \mathbf{e_i} \ \mathbf{D}^- + \mathbf{e_i} \ \mathbf{D}^+ = \mathbf{M} + \mathbf{e_i} \ \mathbf{D}$

- PP
- Timed Petri Nets & The Semantics of the Firing

- Simulation → Advantages, state variables, event
 - → Continuous-Time and Discrete-Time Models
 - → Continuous-State and Discrete-State Models or continuous event model & discrete event model
 - →Open and Closed Models
- Simulation Efficiency Considerations → level of details important
- Types of Simulations \rightarrow 1) Emulation \rightarrow enables host PC to behave like guest PC
 - \rightarrow 2) Static (Monte Carlo) Simulation \rightarrow PP in z lc 25 pdf

Lecture 26

- → 3) Discrete-Event Simulations →
 - a) An event scheduler
 - b) Simulation Clock and a Time-advancing Mechanism fixed-increment approach & event-increment approach
 - c) Event processing routines

Cache-hit & Cache-miss

- d) Initialization Routines
- e) Event-generation

Execution Driven

Trace Driven

Distribution Driven

- f) Recording and summarization of data
- →4) Continuous-Event Simulations Simulation Algorithm
- Generation of random numbers →
 - 1. Inverse Transformation method.
 - 2. Convolution method.
 - 3. Acceptance-rejection method.

PP → see HW numerical