CS450: Numerical Analysis Solutions to HW 5

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Problem 1:

 \mathbf{a}

$$p(t) = x_1 + x_2t + x_3t^2$$

$$Ax = \begin{bmatrix} 1 & t_1 & t_1^2 \\ 1 & t_2 & t_2^2 \\ 1 & t_3 & t_3^2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = y$$

$$\begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$x = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \rightarrow p(t) = t^2$$

b

$$p(t) = y_1 \frac{(t - t_2)(t - t_3)}{(t_1 - t_2)(t_1 - t_3)} + y_2 \frac{(t - t_1)(t - t_3)}{(t_2 - t_1)(t_2 - t_3)} + y_3 \frac{(t - t_1)(t - t_2)}{(t_3 - t_1)(t_3 - t_2)} = \frac{(t - 1)t}{2} + 0 + \frac{t(t + 1)}{2} = t^2$$

 \mathbf{c}

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & t_2 - t_1 & 0 \\ 1t_3 - t_1 & (t_3 - t_1)(t_3 - t_2) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$$
$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$
$$x = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \rightarrow p(t) = 1 + (-1)(t+1) + 1(t+1)(t) = t^2$$

Problem 2:

a

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 4 & 8 \\ 1 & 3 & 9 & 27 \\ 1 & 4 & 16 & 64 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 11 \\ 29 \\ 65 \\ 125 \end{bmatrix} \rightarrow x = \begin{pmatrix} 5 \\ 2 \\ 3 \\ 1 \end{pmatrix}$$
$$p(t) = 5 + 2t + 3t^2 + t^3$$

b

$$p(t) = y_1 \frac{(t - t_2)(t - t_3)(t - t_4)}{(t_1 - t_2)(t_1 - t_3)(t_1 - t_4)} + y_2 \frac{(t - t_1)(t - t_3)(t - t_4)}{(t_2 - t_1)(t_2 - t_3)(t_1 - t_4)}$$
$$+ y_3 \frac{(t - t_1)(t - t_2)(t - t_4)}{(t_3 - t_1)(t_3 - t_2)(t_3 - t_4)} + y_4 \frac{(t - t_1)(t - t_2)(t - t_3)}{(t_4 - t_1)(t_4 - t_2)(t_4 - t_3)} = 5 + 2t + 3t^2 + t^3$$

Problem 3:

Since derivatives of sin(t) are trigonometric functions, which vary from -1 to 1: M = |cos(t)| = 1

$$h = \frac{\left(\frac{\pi}{2}\right)}{4} = \frac{\pi}{8}$$
$$error = \frac{Mh^n}{4n}$$

For $n = 5 \to error = \frac{1(\frac{\pi}{8})^5}{4*5} \approx 4.7*10^{-4}$ Output:

```
Ax=y
A =
[[ 0.
[ 0.02378152  0.06055913  0.15421257
                                                         ]
                                    0.39269908
                                                         1
[ 0.38050426  0.48447307  0.61685028  0.78539816
 [ 6.08806819 3.87578459
                        2.4674011
                                    1.57079633
                                                         ]]
                                               1.
y=
[ 0.
             0.38268343 0.70710678 0.92387953 1.
                                                        ]
                                                        ]
[ 0.02871423 -0.20358546  0.01995143
                                   0.99631698 0.
error points
[ 0.08156991
            0.41617974 0.16104572
                                   0.40593701 0.96036883 0.45437729
            0.90819928
                        0.28901118
                                   0.43435661]
 0.24161395
errors
[ 1.86469987e-04
                  1.94357425e-05
                                  2.11471087e-04
                                                  1.12468444e-05
                  4.56490243e-05
                                  1.54886499e-04
  7.11447481e-05
                                                  5.82384784e-05
  1.05610800e-04
                  3.27894494e-05]
max error
```

0.000211471086827

A is a vandermonde matrix. x represents the polynomial coefficients in decreasing order starting with t^4 . The max error on the points sampled is $2.1 * 10^{-4}$ which is below the calculated value. To find the number of points required for an error of 10^{-10} :

$$10^{-10} = \frac{1(\frac{\pi}{8})^n}{4n}$$

Solving for n yields: $n \approx 19.94 \rightarrow n = 20$

Problem 4:

$$Q_n(f) = \sum_{i=1}^n w_i f(x_i)$$
$$= \sum_{i=1}^n \left(\int_a^b l_i(x) dx \right) f(x_i)$$
$$= \int_a^b \left(\sum_{i=1}^n l_i(x) f(x_i) \right) dx$$

But $p(x) = \sum_{i=1}^{n} l_i(x) f(x_i) \approx f(x)$

$$= \int_{a}^{b} (p(x))dx \approx \int_{a}^{b} (f(x))dx = I(f)$$

Problem 5:

$$avg = \frac{f(x+h) - f(x)}{2h} + \frac{f(x) - f(x-h)}{2h} = \frac{f(x+h) - f(x-h)}{2h}$$

$$f(x+h) \approx f(x) + f'(x)h + f''(x)h^2 + \frac{f'''(x)h^3}{6} + \dots$$

$$f(x-h) \approx f(x) - f'(x)h + f''(x)h^2 - \frac{f'''(x)h^3}{6} + \dots$$

$$\frac{f(x+h) - f(x-h)}{2h} = \frac{f(x+h) - f(x-h)}{2h} - \frac{f'''(x)h^2}{6} + \dots$$

$$= \frac{f(x+h) - f(x-h)}{2h} + O(h^2)$$

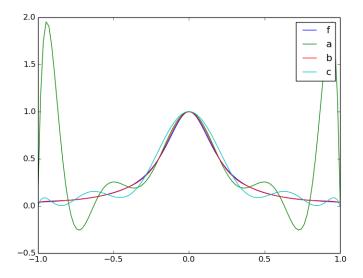
Problem 6:

For forward difference: $F(h) = a_0 + a_1 h + O(h^2)$, so p = 1. $q = \frac{.2}{1} = 2$

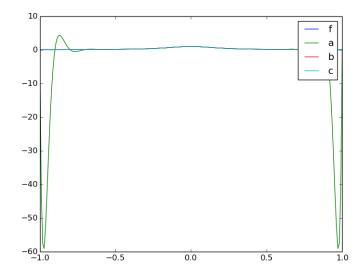
$$F(0) = a_0 = F(h) + \frac{F(h) - F(\frac{h}{2})}{q^{-p} - 1} = F(h) + \frac{F(h) - F(\frac{h}{2})}{2^{-1} - 1} = 2F(\frac{h}{2}) - F(h) = 2(-.9091) - (-.8333) = -.9849$$

Problem 7:

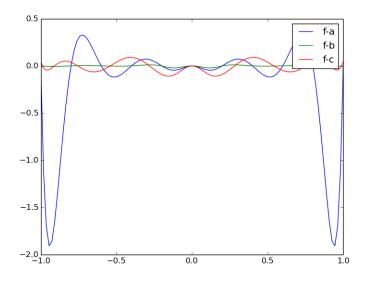
Interpolants and function (n = 11)



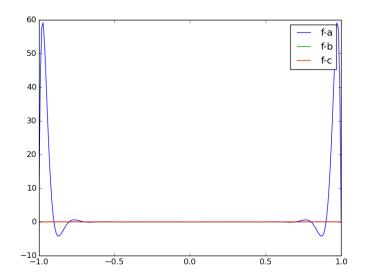
Interpolants and function (n = 21)



Error (n = 11)



Error (n = 21)



Max errors

1.9079060982 #a n = 11

0.0215283590725 #b n = 11

 $0.109147304176 \ \#c \ n = 11$

59.1223686715 #a n = 21

0.00312636097646 #b n = 21

0.0152923024513 #c n = 21

Method b with n=21 is the most accurate. Method a with n=21 is the least accurate.