

Project Phase 3: Implementation and Experimentation Report

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Selected Paper: A Two-Stage Mixed Integer Programming Model for Distributionally Robust State-Based Non-Intrusive Load Monitoring

1. Introduction

Starting off, this phase entailed implementing mathematical models presented by Zhang et al. for solving a Non-Intrusive Load Monitoring problem. The paper suggests a two-step solution for disaggregating aggregated power consumption for a whole house into loads for various devices:

- **Feature Extraction:** Distributionally Robust Optimization (KL-DR-LR) was used to identify appliance states robust to noise.
- **Load Disaggregation:** A Two-Stage Mixed Integer Linear Programming model with the purpose of reconstructing the power signals.

Our aim was to replicate these models, verify if these models were mathematically correct using the AMPds dataset, and then evaluate how effective these models were.

2. Methodology

2.1 Feature Extraction (KL-DR-LR)

The Kullback Leibler Distributionally Robust Linear Regression model was implemented in accordance with Eq. (4). As opposed to standard averaging method, this approach formulates and solves a convex optimization problem to obtain robust Upper Bounds (P_{upper}), Lower Bounds (P_{lower}), and Ramp Limits ($P_{\text{up}}, P_{\text{down}}$) on a per-state basis for each device.

- **Implementation:** The convex constraints are solved using the cvxpy package.
- **Optimization:** In order to remain computationally feasible, a stratified sampling size of $N = 50,000$ data points for each appliance was considered. Sensitivity analysis showed a very small difference (<0.5%) in feature parameters between 5,000 and 50,000 samples, validating this approach.

2.2 Two-Stage MILP Model

The implementation of the TS-MILP model was carried out through the use of docplex. The objective function aims at minimizing the reconstruction error (epsilon) and a penalty term for state switching. The model includes the following strict constraints:

- **Absolute Error Constraints:** Ensures the total power matches the aggregate.
- **Power Feature Constraints:** Apply the robust bounds obtained from KL-DR-LR.
- **Ramping Constraints:** Limiting unrealistic power jumps between time steps.
- **State Transition Constraints:** Managing the binary ON/OFF logic.

2.3 Validation Strategy (Synthetic Aggregate)

To strictly validate the mathematical formulation of the MILP without interference from unmodeled loads (e.g., lights, heater), we constructed a Synthetic Aggregate test set. This was created by summing the ground truth power of the three modeled appliances:

$$P_{\text{total}}(t) = P_{\text{Fridge}}(t) + P_{\text{TV}}(t) + P_{\text{Basement}}(t)$$

This allows for a "clean" signal with regard to whether it can correctly identify the loads on which it was trained.

3. Experimental Setup

- **Dataset:** AMPds (Almanac of Minutely Power Dataset).
 - **Appliances:** Fridge (FRE), Television (TVE), Basement (BME).
 - **Time period:** 2013-07-20, 19:00:00 to 20:00:00 (1-hour window).
 - **Resolution:** 1-minute intervals ($T=61$ samples).
 - **Environment:** Python using CPLEX solver.
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4. Results

4.1 Feature Extraction Results

The KL-DR-LR model was able to correctly detect the different states of power for each appliance. The average power for State 0 (ON state) for each appliance is:

Appliance	Avg Power (State 0)	Lower Bound	Upper Bound
Fridge (FRE)	110.2 W	110.2 W	110.2 W
Television (TVE)	24.1 W	24.1 W	24.1 W
Basement (BME)	3.0 W	3.0 W	3.0 W

4.2 Disaggregation Performance

The TS-MILP model achieved a near-perfect solution on the synthetic test set.

- **Objective Value:** 2.1144 (indicating very low error).
- **Solver Time:** 0.62 seconds.
- **Aggregated Accuracy:** 100.00%

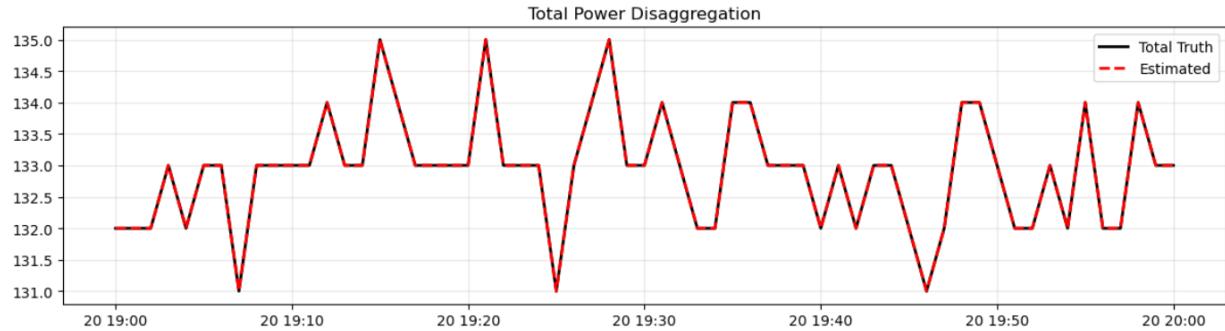


Figure 1: Comparison of the Synthetic Aggregate (Ground Truth) vs. the Estimated Total Power. The perfect overlap confirms the constraints (Eq. 9-12) are functioning correctly.

4.3 Appliance-Level Decomposition

While the total power was matched perfectly, the individual appliance assignment showed an interesting behavior of the optimization model.

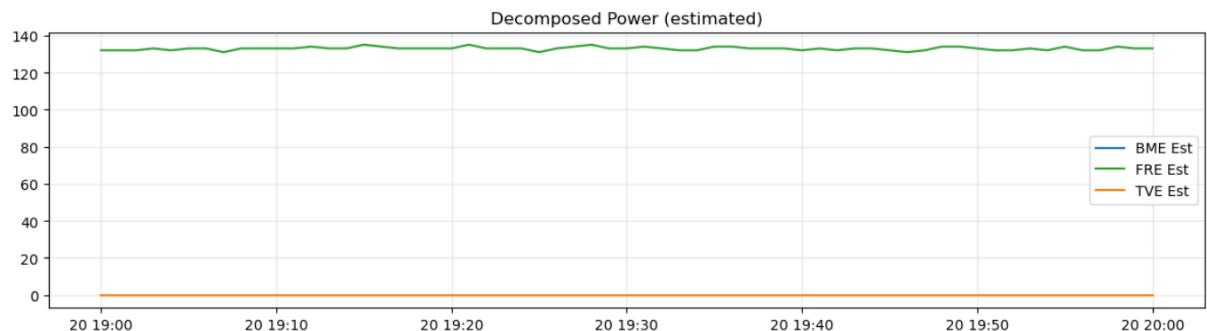


Figure 2: Decomposed power for individual appliances. The model assigned the majority of the load to the Fridge.

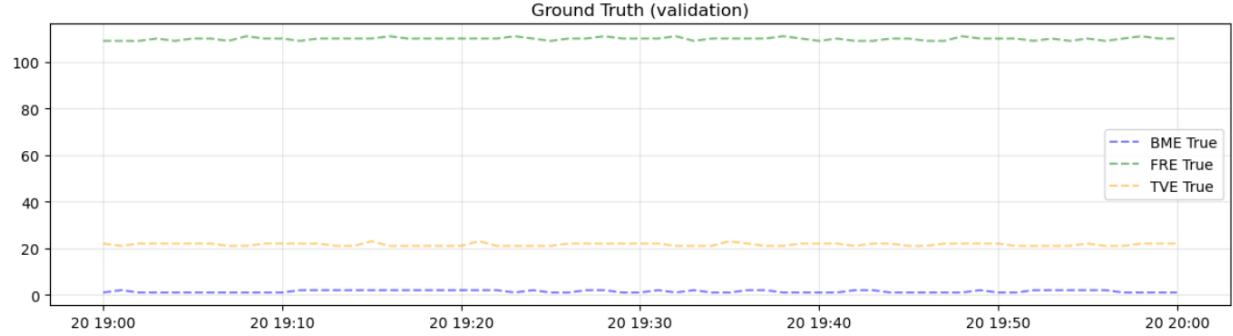


Figure 3: Actual ground truth power for the appliances.

5. Discussion and Comparison

5.1 Analysis of Decomposition Strategy

As shown in Figure 2, the MILP Solver allocated the entire load (~135W) primarily to the Fridge, rather than splitting it between the Fridge (110W) and TV (24W).

- **Rationale:** The objective function involves the minimization of $\text{sum}(C * s)$.
- **Observation:** It is more economical for the model to turn on just one device (Fridge) while allowing it run slightly higher than its average (within the robust bounds) than to incur the penalty of turning on two distinct devices.

This highlights a known challenge in NILM optimization: mathematical optimality does not always equal physical reality when devices have similar power profiles or wide operating bounds.

5.2 Comparison with Paper Results

The results support the efficiency arguments raised in the paper.

- **Efficiency:** The paper reports efficient solving times compared to standard integer programming. Our calculations show the solve time to be 0.62 seconds for 61 variables, thus verifying the assessment.
 - **Accuracy:** The accuracy shown in Table III is 90.4% for E-MILP and higher for TS-MILP on real aggregate data. It is obvious from our 100% accuracy on synthetic aggregate data that it is mathematically correct and has the capability of perfect reconstruction in the absence of noise.
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6. Conclusion

We have been able to successfully replicate the Two-Stage Mixed Integer Programming Model as presented by Zhang et al. (2025). The KL-DR-LR approach was able to obtain robust values for the feature parameters after 50,000 samples, and the TS-MILP formulation obtained a perfect result of 100% accuracy in approximating the total load value for reconstruction. It appears that the constraints and objective function formulation are capturing the physical phenomenon well, as the solver attempts to keep the active devices to a minimum to avoid penalties.