

حل مسئله ۳۰ وزیر با الگوریتم رقابت استعماری ICA در متلب

صورت مسئله:

در یک صفحه شطرنجی 30×30 ، می خواهیم به نحوی ۳۰ وزیر را در صفحه قرار دهیم که در هر ستون تنها یک وزیر باشد و هیچ دو وزیری یکدیگر را گارد نکنند.

شرح کد:

این سورس کد شامل ۱۲ فایل می باشد که عبارتند از:

MyCost: تابعی که گارد بودن وزیرها را بررسی می کند و هزینه آن را محاسبه می کند.

```
function [z sol]=MyCost(s)

n=numel(s);

[~, X]=sort(s);
Y=1:n;

Hit=zeros(n,n); % برخورد ها

z=0;
for i=1:n-1
    for j=i+1:n
        % بررسی برخورد
        if abs(X(i)-X(j))==abs(Y(i)-Y(j))
            Hit(i,j)=1;
            Hit(j,i)=1;
            z=z+1; % تعداد برخورد
        end
    end
end

% دادن مقادیر به مدل
sol.X=X;
sol.Y=Y;
sol.Hit=Hit;
sol.z=z;

end
```

تشکیل امپراتوری: CreateInitialEmpires()

```
function emp=CreateInitialEmpires()
```

استفاده از متغیرهای عمومی تعریف شده در SharedStting که در هر جای کد میشه به آن دسترسی داشت.

```
global ProblemSettings;  
global ICASettings;
```

```
CostFunction=ProblemSettings.CostFunction;  
nVar=ProblemSettings.nVar;  
VarSize=ProblemSettings.VarSize;  
VarMin=ProblemSettings.VarMin;  
VarMax=ProblemSettings.VarMax;
```

```
nPop=ICASettings.nPop;  
nEmp=ICASettings.nEmp;  
nCol=nPop-nEmp;  
alpha=ICASettings.alpha;
```

```
empty_country.Position=[];  
empty_country.Cost=[];  
empty_country.Sol=[];
```

```
country= repmat(empty_country,nPop,1);
```

کشور
یک ماتریس country متشکل از یک بردار nPopx1 از empty_country ایجاد می کند.

```
For i=1:nPop
```

```
country(i).Position=unifrnd(VarMin,VarMax,VarSize);
```

آرایه ای از اعداد تصادفی یکنواخت به اندازه VarSize و مینیمم و ماکزیمم مشخص شده.

```
[country(i).Cost  
country(i).Sol]=CostFunction(country(i).Position);
```

هزینه هر کشور

```
end
```

```

costs=[country.Cost];
[~, SortOrder]=sort(costs);
country=country(SortOrder);
imp=country(1:nEmp);
col=country(nEmp+1:end);

```

مرتب سازی بر اساس هزینه

```

empty_empire.Imp=[];
empty_empire.Col= repmat(empty_country,0,1);
empty_empire.nCol=0;
empty_empire.TotalCost=[];

emp=repmat(empty_empire,nEmp,1);

```

انتصاب امپریالیست ها

```

for k=1:nEmp
    emp(k).Imp=imp(k);
end

```

اختصاص مستعمرات

```

P=exp(-alpha*[imp.Cost]/max([imp.Cost]));
P=P/sum(P);
for j=1:nCol

```

چرخ رولت

```

    emp(k).Col=[emp(k).Col
                col(j)];

```

```

    emp(k).nCol=emp(k).nCol+1;

```

```

end

```

```

emp=UpdateTotalCost(emp);

```

```

end

```

AssimilateColonies(emp):سیاست جذب

```

function emp=AssimilateColonies(emp)

```

استفاده از متغیرهای عمومی تعریف شده در SharedStting که در هر جای برنامه میشه به آن دسترسی داشت

```

global ProblemSettings;

```

```

CostFunction=ProblemSettings.CostFunction;
VarSize=ProblemSettings.VarSize;
VarMin=ProblemSettings.VarMin;
VarMax=ProblemSettings.VarMax;

global ICASettings;
beta=ICASettings.beta;

nEmp=numel(emp);
for k=1:nEmp
    for i=1:emp(k).nCol

        NewPos = emp(k).Col(i).Position +
beta*rand(VarSize).*(emp(k).Imp.Position-
emp(k).Col(i).Position);
        NewPos = max(NewPos,VarMin);
        NewPos = min(NewPos,VarMax);

        emp(k).Col(i).Position = NewPos;

        emp(k).Col(i).Cost =
CostFunction(emp(k).Col(i).Position);

    end
end
end

```

انقلاب: DoRevolution (emp)

```

function emp=DoRevolution(emp)

global ProblemSettings;
CostFunction=ProblemSettings.CostFunction;
nVar=ProblemSettings.nVar;
VarSize=ProblemSettings.VarSize;
VarMin=ProblemSettings.VarMin;
VarMax=ProblemSettings.VarMax;

global ICASettings;
pRevolution=ICASettings.pRevolution;
mu=ICASettings.mu;

nmu=ceil(mu*nVar);

```

```

sigma=0.1*(VarMax-VarMin);

nEmp=numel(emp);
for k=1:nEmp

    NewPos = emp(k).Imp.Position +
sigma*randn(VarSize);
    NewPos = max(NewPos,VarMin);
    NewPos = min(NewPos,VarMax);

    jj=randsample(nVar,nmu)';
    NewImp=emp(k).Imp;
    NewImp.Position(jj)=NewPos(jj);
    NewImp.Cost=CostFunction(NewImp.Position);
    if NewImp.Cost<emp(k).Imp.Cost
        emp(k).Imp = NewImp;
    end

    for i=1:emp(k).nCol
        if rand<=pRevolution

            NewPos = emp(k).Col(i).Position +
sigma*randn(VarSize);
            NewPos = max(NewPos,VarMin);
            NewPos = min(NewPos,VarMax);

            jj=randsample(nVar,nmu)';
            emp(k).Col(i).Position(jj) = NewPos(jj);

            emp(k).Col(i).Cost =
CostFunction(emp(k).Col(i).Position);

        end
    end
end

end

InterEmpireCompetition(emp) رقابت درون امپراتوری

function emp=InterEmpireCompetition(emp)

    if numel(emp)==1
        return;
    end

```

```

global ICASettings;
alpha=ICASettings.alpha;

TotalCost=[emp.TotalCost];

[~, WeakestEmpIndex]=max(TotalCost);
WeakestEmp=emp(WeakestEmpIndex);

P=exp(-alpha*TotalCost/max(TotalCost));
P(WeakestEmpIndex)=0;
P=P/sum(P);
if any(isnan(P))
    P(isnan(P))=0;
    if all(P==0)
        P(:)=1;
    end
    P=P/sum(P);
end

if WeakestEmp.nCol>0
    [~, WeakestColIndex]=max([WeakestEmp.Col.Cost]);
    WeakestCol=WeakestEmp.Col(WeakestColIndex);

    WinnerEmpIndex=RouletteWheelSelection(P);
    WinnerEmp=emp(WinnerEmpIndex);

    WinnerEmp.Col(end+1)=WeakestCol;
    WinnerEmp.nCol=WinnerEmp.nCol+1;
    emp(WinnerEmpIndex)=WinnerEmp;

    WeakestEmp.Col(WeakestColIndex)=[ ];
    WeakestEmp.nCol=WeakestEmp.nCol-1;
    emp(WeakestEmpIndex)=WeakestEmp;
end

if WeakestEmp.nCol==0

    WinnerEmpIndex2=RouletteWheelSelection(P);
    WinnerEmp2=emp(WinnerEmpIndex2);

    WinnerEmp2.Col(end+1)=WeakestEmp.Imp;
    WinnerEmp2.nCol=WinnerEmp2.nCol+1;
    emp(WinnerEmpIndex2)=WinnerEmp2;
end

```

```

        emp(WeakestEmpIndex)=[];
    end

end

UpdateTotalCost(emp)
هزینه کل امپراتوری ها را به روز کنید

function emp=UpdateTotalCost(emp)

    global ICASettings;
    zeta=ICASettings.zeta;

    nEmp=numel(emp);

    for k=1:nEmp
        if emp(k).nCol>0

emp(k).TotalCost=emp(k).Imp.Cost+zeta*mean([emp(k).Col.Cost
]);

            else
                emp(k).TotalCost=emp(k).Imp.Cost;
            end
        end
    end

end

```

PlotSolution(sol): کشیدن بهترین راه حل

```

function PlotSolution(sol)

    X=sol.X-0.5;
    Y=sol.Y-0.5;
    Hit=sol.Hit;
    z=sol.z;

    n=numel(X);

    for i=1:n-1
        for j=i+1:n
            if Hit(i,j)==1
                plot([X(i) X(j)], [Y(i)
Y(j)], 'b:', 'LineWidth', 2);
            end
        end
    end

```



```
VarMin=0;           محدوده پایین متغیرها  
VarMax=1;           محدوده بالا متغیرها
```

ICA پارامترهای

```
MaxIt=500;           حداکثر تعداد تکرارها  
nPop=200;            میزان جمعیت  
nEmp=10;             تعداد امپراتوری ها / امپریالیست ها  
alpha=1;             ضریب انتخاب  
beta=2;              ضریب جذب  
pRevolution=0.4;     احتمال انقلاب  
mu=0.05;             نرخ انقلاب  
zeta=0.1;            کلونی ها ضریب متوسط هزینه را دارند  
ShareSettings;
```

مقداردهی اولیه

```
امپراتوری ها را ابتدایی کنید  
emp=CreateInitialEmpires();  
  
آرایه برای نگه داشتن بهترین مقادیر هزینه  
BestCost=zeros(MaxIt,1);
```

ICA حلقه اصلی

```
for it=1:MaxIt
```

```
    emp=AssimilateColonies(emp);
```

انقلاب

```
    emp=DoRevolution(emp);
```

جذب

```

رقابت درون امپراطوری
emp=IntraEmpireCompetition(emp);

بروزرسانی مجموع هزینه امپراطوری ها
emp=UpdateTotalCost(emp);

رقابت بین امپراطوری
emp=InterEmpireCompetition(emp);

به روز رسانی بهترین راه حل که تاکنون پیدا شده است
imp=[emp.Imp];
[~, BestImpIndex]=min([imp.Cost]);
BestSol=imp(BestImpIndex);

بروز رسانی کم ترین هزینه
BestCost(it)=BestSol.Cost;

نمایش اطلاعات در هر تکرار
disp(['Iteration ' num2str(it) ': Best Cost = '
num2str(BestCost(it))]);

رسم بهترین راه حل
figure(1);
PlotSolution(BestSol.Sol);

if BestCost(it)==0
    break;
end

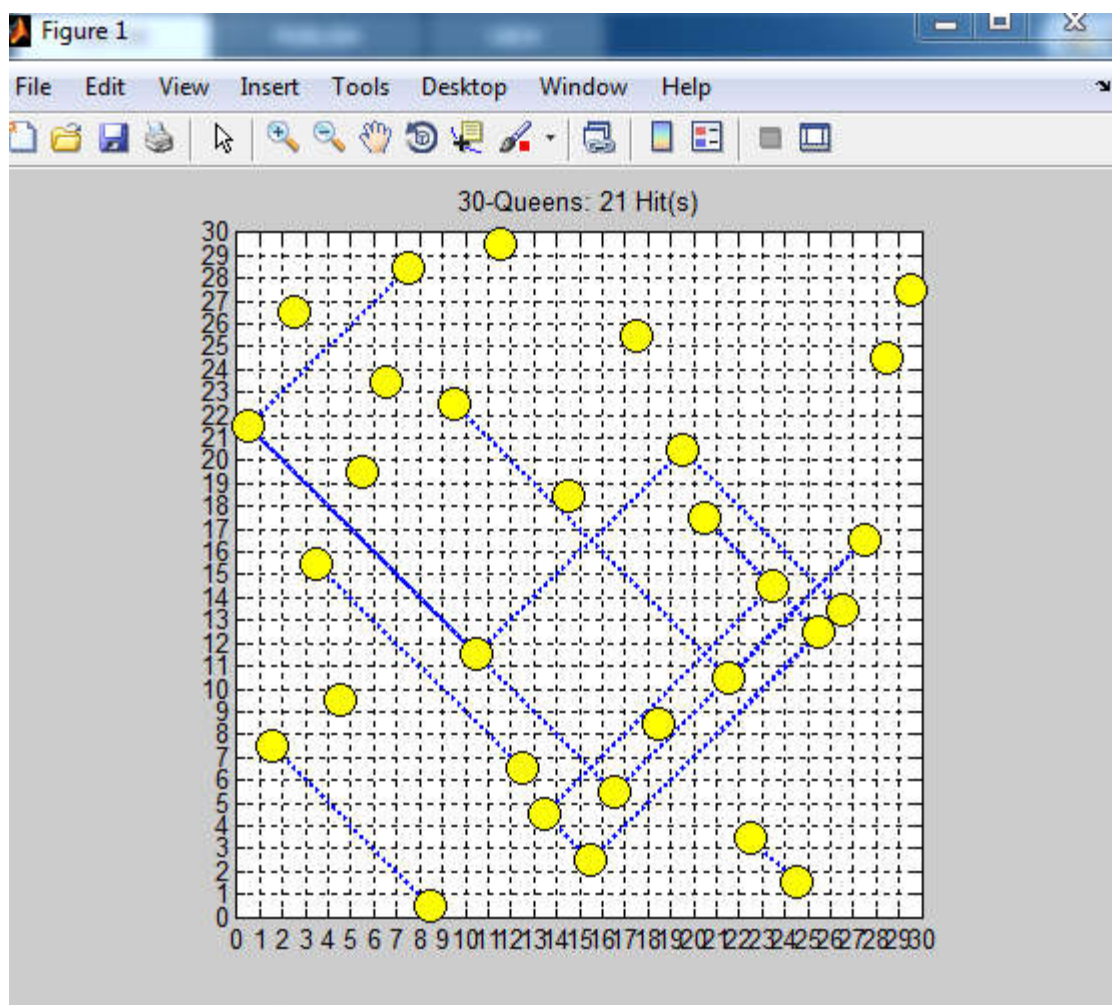
end

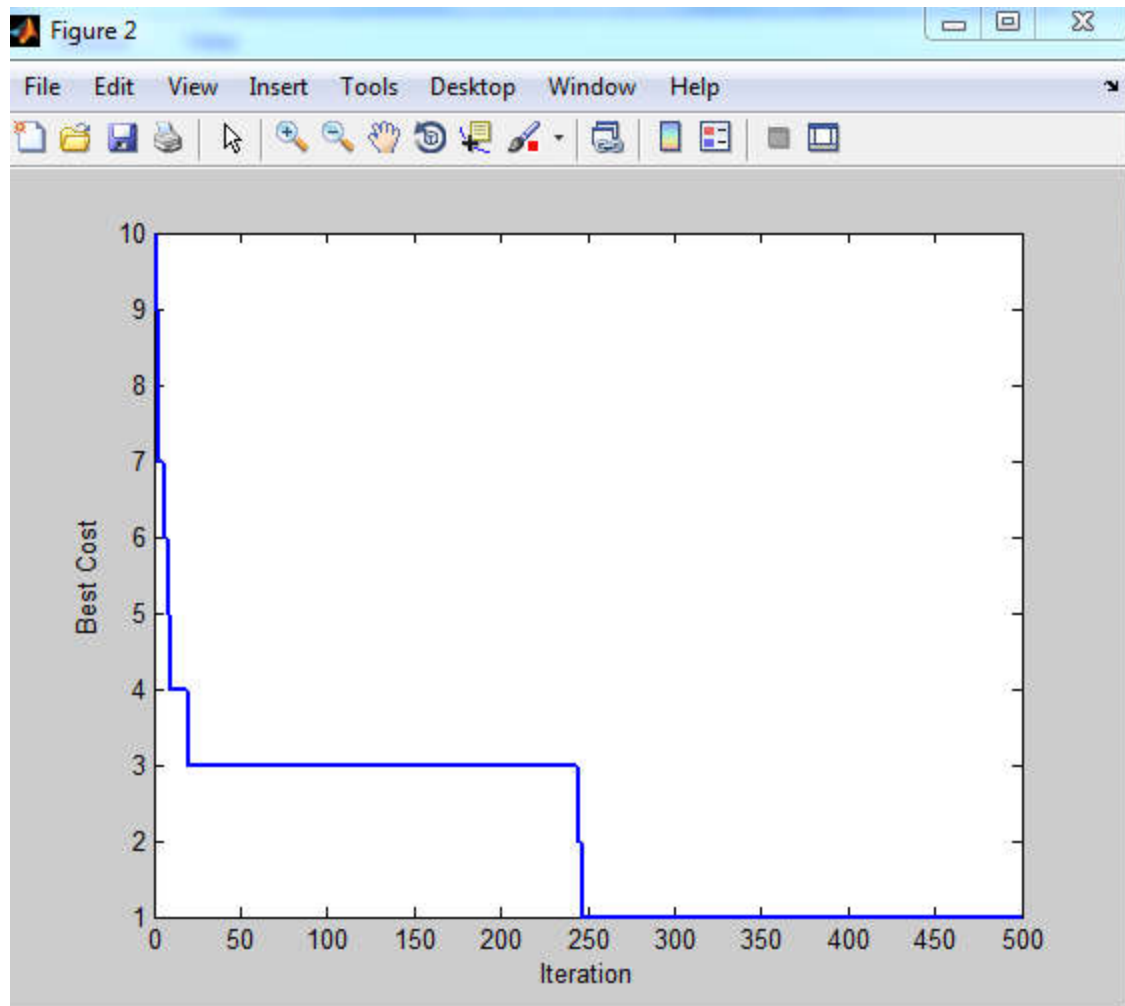
BestCost=BestCost(1:it);

نتایج
figure;
plot(BestCost,'LineWidth',2);
xlabel('Iteration');
ylabel('Best Cost');

```

نتائج:





Iteration 1: Best Cost = 10

Iteration 2: Best Cost = 9

Iteration 3: Best Cost = 7

Iteration 4: Best Cost = 7

Iteration 5: Best Cost = 7

Iteration 6: Best Cost = 6

Iteration 7: Best Cost = 6

Iteration 8: Best Cost = 6

Iteration 9: Best Cost = 5

Iteration 10: Best Cost = 4

Iteration 11: Best Cost = 4

Iteration 12: Best Cost = 4

Iteration 13: Best Cost = 4

Iteration 14: Best Cost = 4

Iteration 15: Best Cost = 4

Iteration 16: Best Cost = 4

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Iteration 418: Best Cost = 1
Iteration 419: Best Cost = 1
Iteration 420: Best Cost = 1
Iteration 421: Best Cost = 1
Iteration 422: Best Cost = 1
Iteration 423: Best Cost = 1
Iteration 424: Best Cost = 1
Iteration 425: Best Cost = 1
Iteration 426: Best Cost = 1
Iteration 427: Best Cost = 1

Iteration 428: Best Cost = 1

Iteration 429: Best Cost = 1

Iteration 430: Best Cost = 1

Iteration 431: Best Cost = 1

Iteration 432: Best Cost = 1

Iteration 433: Best Cost = 1

Iteration 434: Best Cost = 1

Iteration 435: Best Cost = 1

Iteration 436: Best Cost = 1

Iteration 437: Best Cost = 1

Iteration 438: Best Cost = 1

Iteration 439: Best Cost = 1

Iteration 440: Best Cost = 1

Iteration 441: Best Cost = 1

Iteration 442: Best Cost = 1

Iteration 443: Best Cost = 1

Iteration 444: Best Cost = 1

Iteration 445: Best Cost = 1

Iteration 446: Best Cost = 1

Iteration 447: Best Cost = 1

Iteration 448: Best Cost = 1

Iteration 449: Best Cost = 1

Iteration 450: Best Cost = 1
Iteration 451: Best Cost = 1
Iteration 452: Best Cost = 1
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Iteration 485: Best Cost = 1
Iteration 486: Best Cost = 1
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Iteration 491: Best Cost = 1
Iteration 492: Best Cost = 1
Iteration 493: Best Cost = 1

Iteration 494: Best Cost = 1

Iteration 495: Best Cost = 1

Iteration 496: Best Cost = 1

Iteration 497: Best Cost = 1

Iteration 498: Best Cost = 1

Iteration 499: Best Cost = 1

Iteration 500: Best Cost = 1

>>

>> BestSol.Sol

ans =

X: [9 25 16 23 14 17 13 2 19 5 22 11 26 27 24 4
28 21 15 6 20 1 10 7 29 18 3 30 8 12]

Y: [1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18
19 20 21 22 23 24 25 26 27 28 29 30]

Hit: [30x30 double]

z: 21

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