Introduction to classification and regression trees, random forests and model-based recursive partitioning in R

Marjolein Fokkema

Department of Methods & Statistics
Institute of Psychology
Leiden University

Course Overview

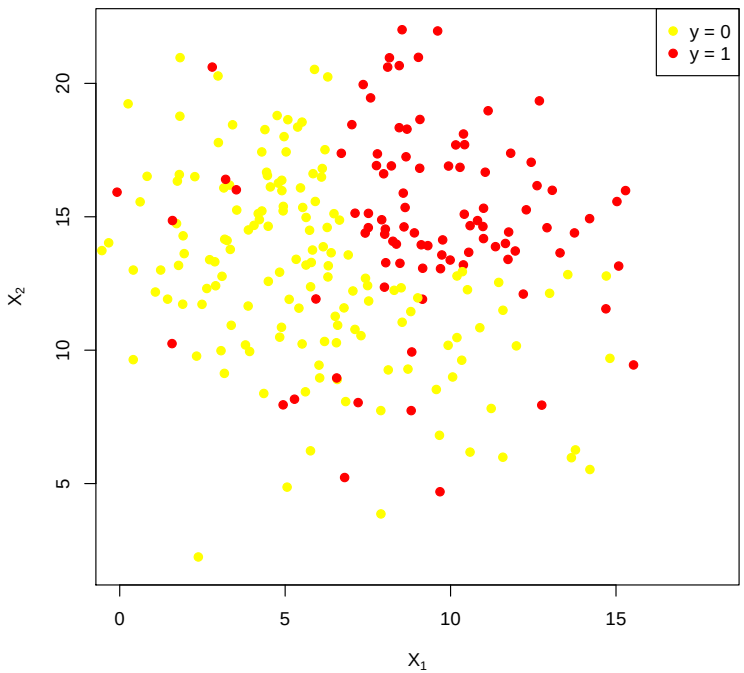
- Day 1: Single trees
  - Introduction to recursive partitioning methods (CART)
  - Unbiased recursive partitioning
  - Model-based recursive partitioning
  - Trees for clustered / multilevel data
- Day 2: Ensemble methods
  - Bagging, Boosting and Random Forests
  - Interpretation: Variable importance
  - Tuning parameters
  - Requests?

Recursive partitioning

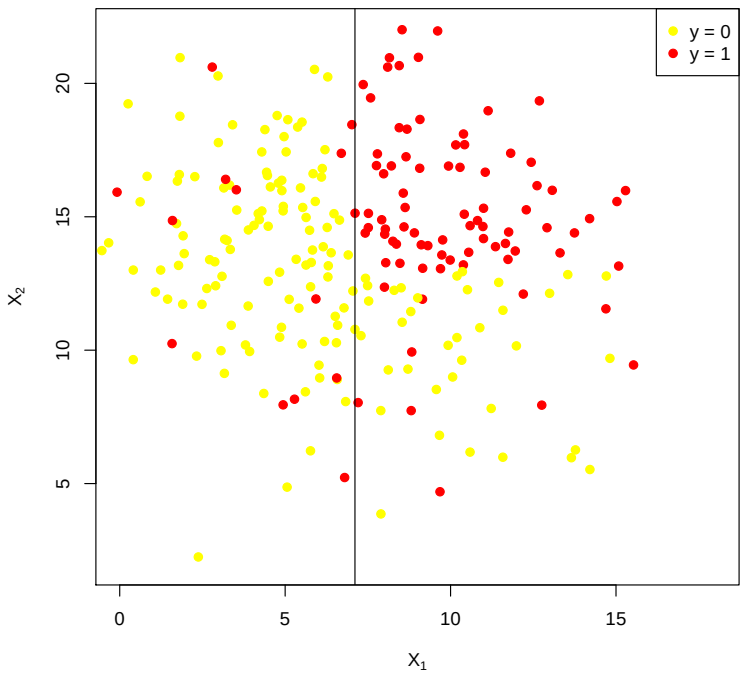
aim: predict Y from $X_1, \ldots, X_p$

how: find subgroups, characterized by values of $X_1, \ldots, X_p$, that are most similar in terms of outcome Y (within each subgroup)

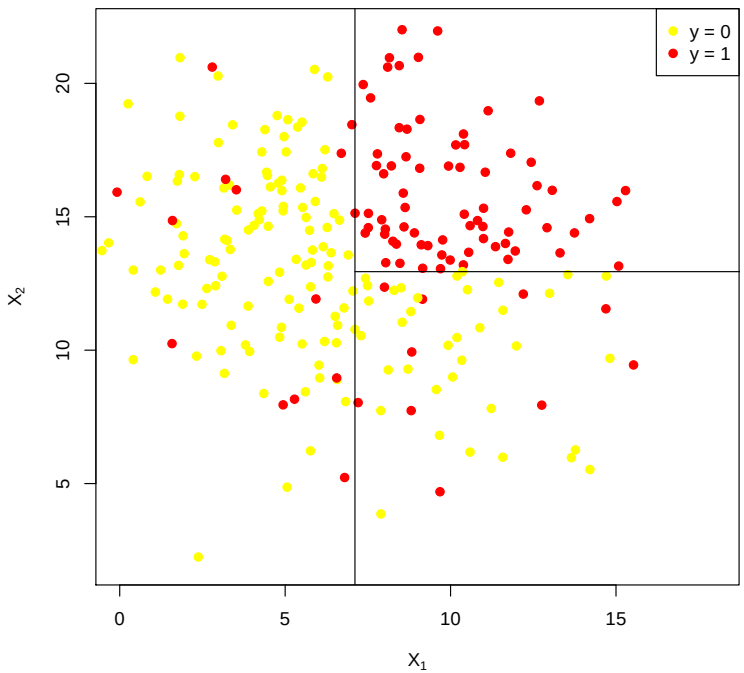
Categorical outcome Y



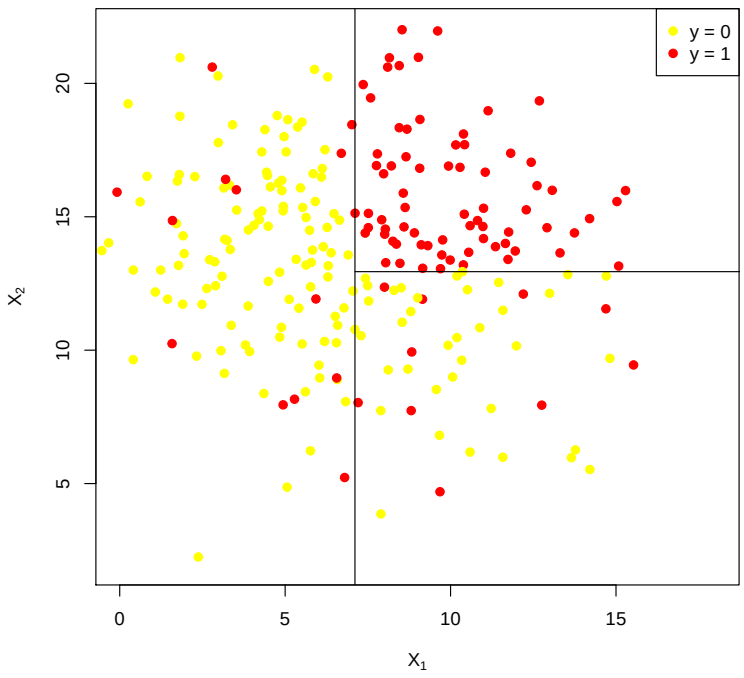
Categorical outcome Y

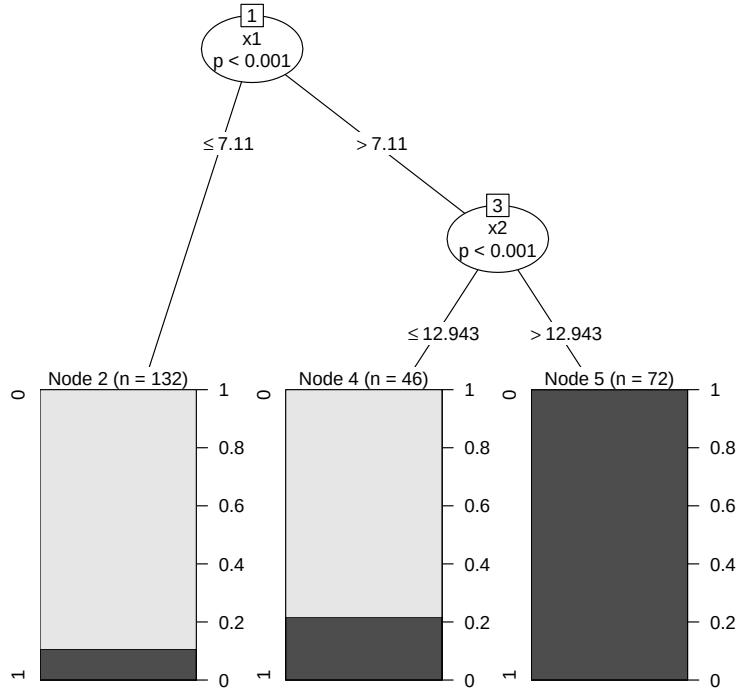


Categorical outcome Y



Categorical outcome Y





Classification and regression trees

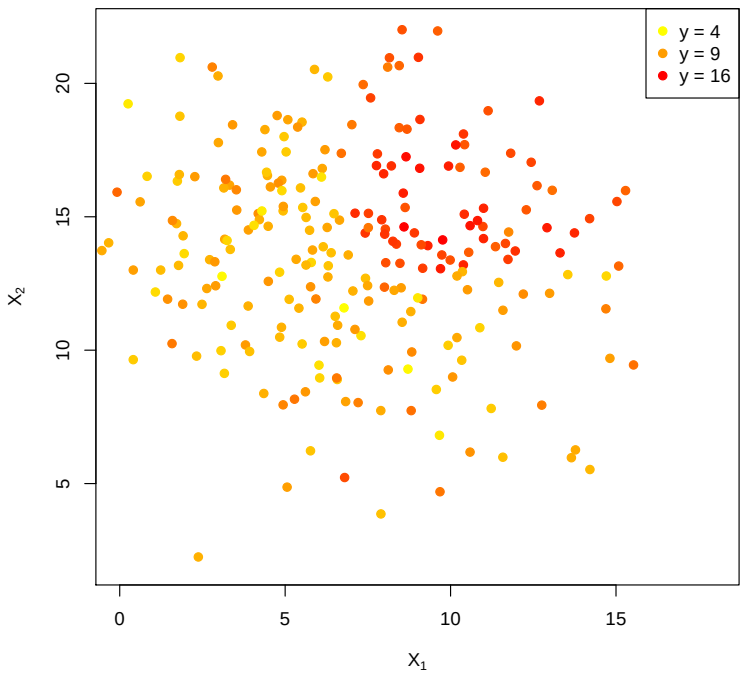
aim: predict Y from $X_1, \ldots, X_p$

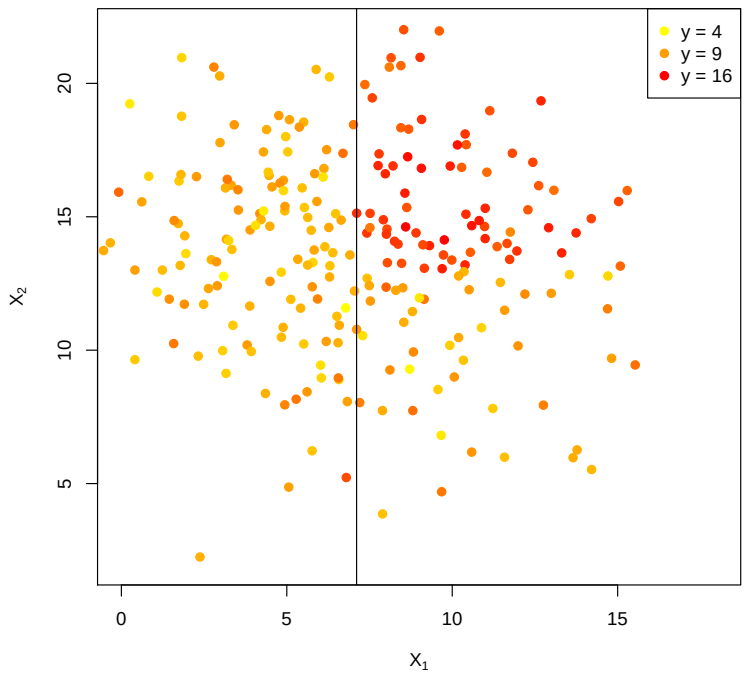
how: find subgroups, characterized by values of $X_1, \ldots, X_p$, that are most similar in terms of Y (within each subgroup)

note: a partition can theoretically take any shape. To turn the partitioning into a feasible task, (most) RPMs:

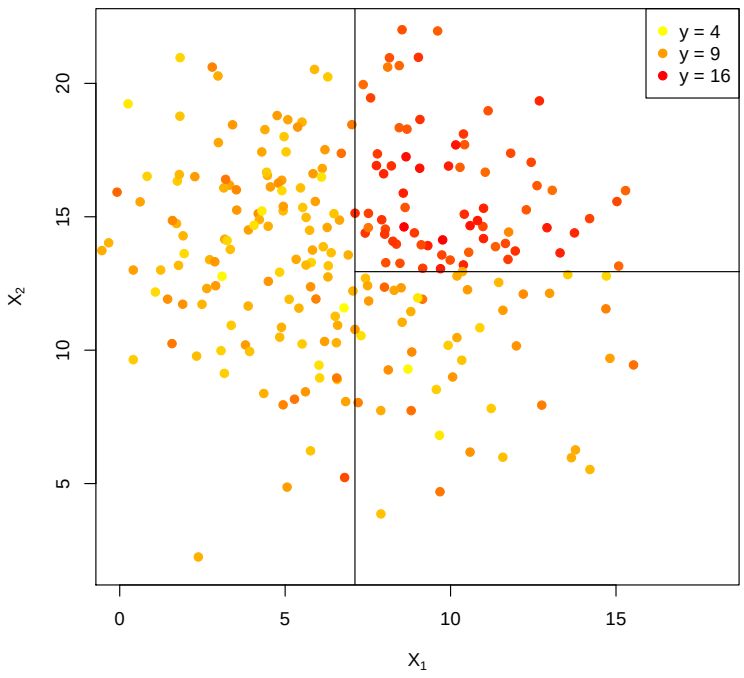
- split the data (variable space) recursively
- using one variable per split (rectangular areas)
- create binary splits only

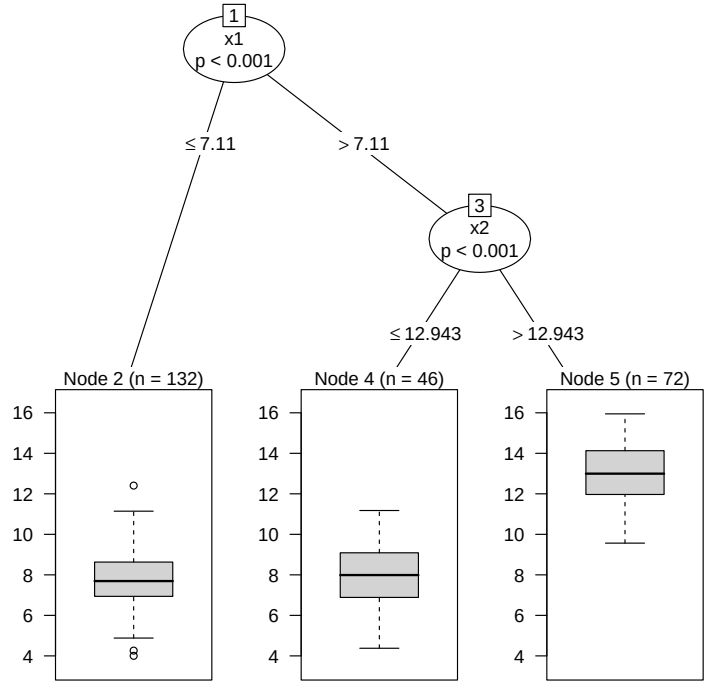
Continuous Y





Continuous Y





Questions

1. How is the tree built?

2. How can we make predictions from the tree?

Questions

1. How is the tree built?
   - recursive partitioning (binary or multiway)

2. How can we make predictions from the tree?

Questions

1. How is the tree built?
   - recursive partitioning (binary or multiway)
   - split selection based on impurity reduction (or association measure)
2. How can we make predictions from the tree?

Questions

1. How is the tree built?
   - recursive partitioning (binary or multiway)
   - split selection based on impurity reduction (or association measure)
2. How can we make predictions from the tree?
   - drop new observation down the tree
   - terminal node yields prediction:
     - majority class (classification)
     - mean (regression)

Tree building - multiway or binary

traditional recursive partitioning algorithms:

- multiway splitting (of categorical variables only): C4.5 (Quinlan, 1993)
  implemented in `Weka`, available through `RWeka`
- binary splitting: CART (Breiman et al., 1984)
  implemented in packages and functions `rpart` and `tree`

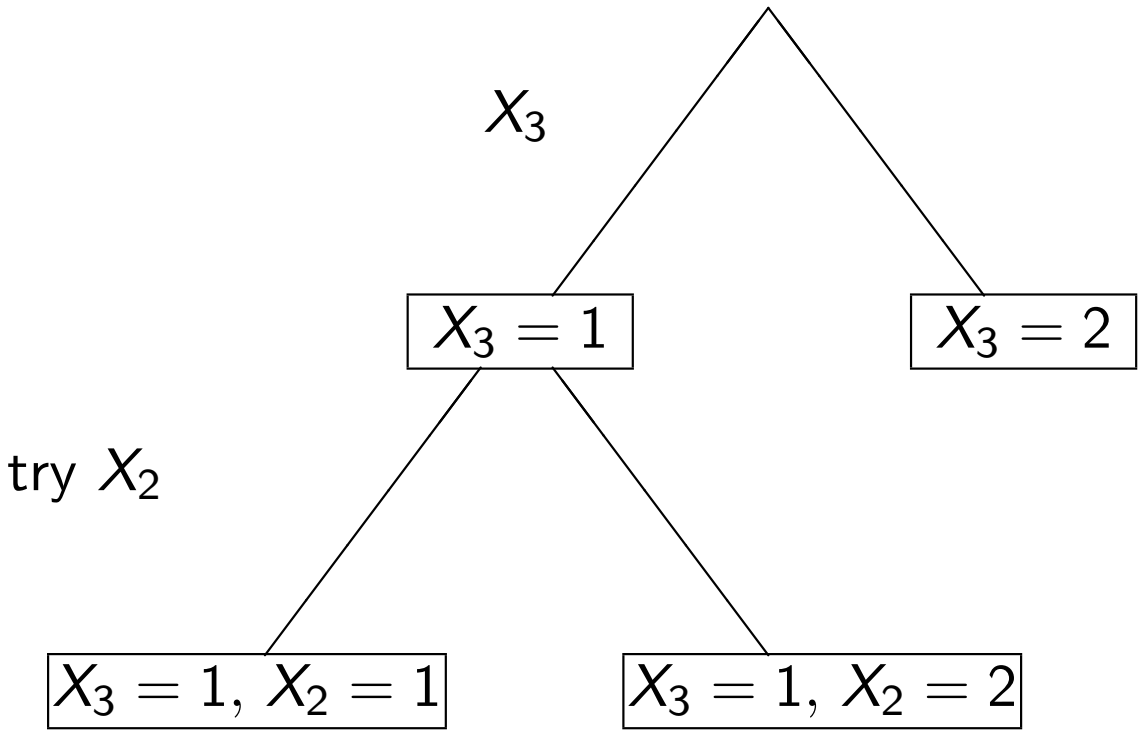
Multiway splitting (C4.5)

from the starting node

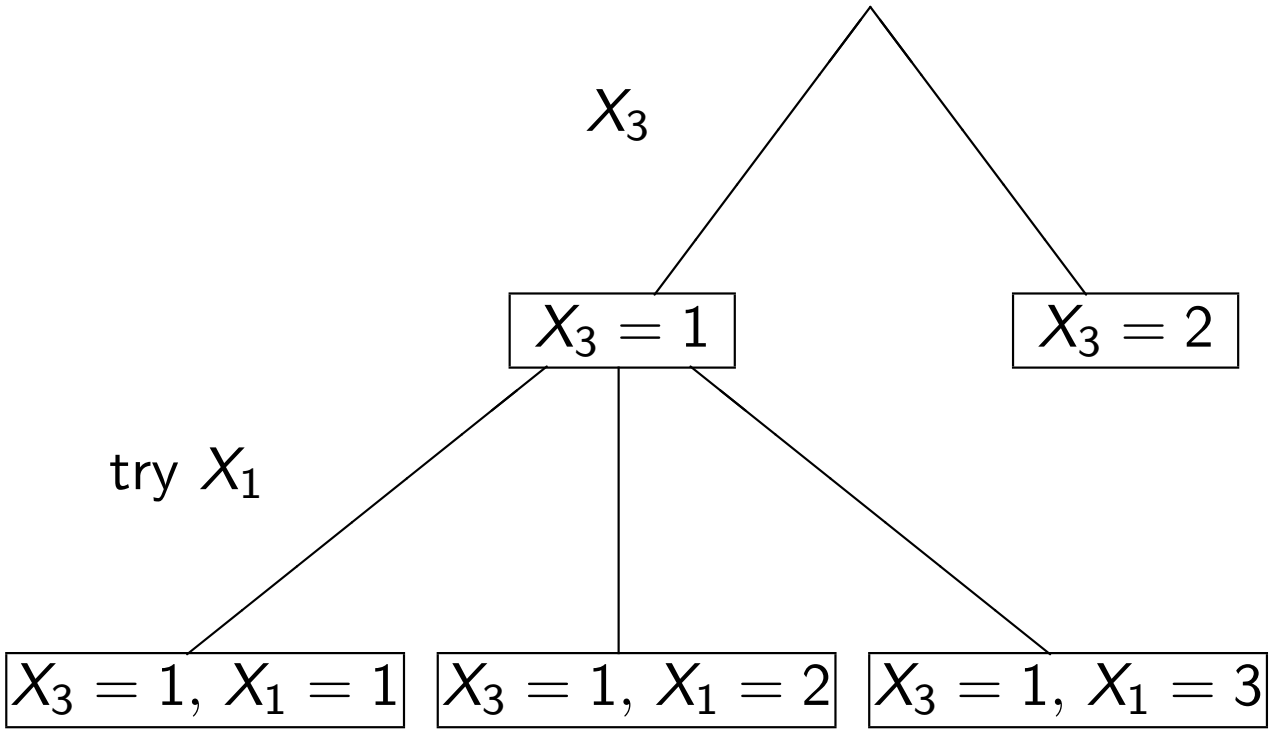
- produce as many nodes as categories
- select variable for splitting if most informative with respect to impurity reduction

...

Multiway splitting (C4.5)



Multiway splitting (C4.5)



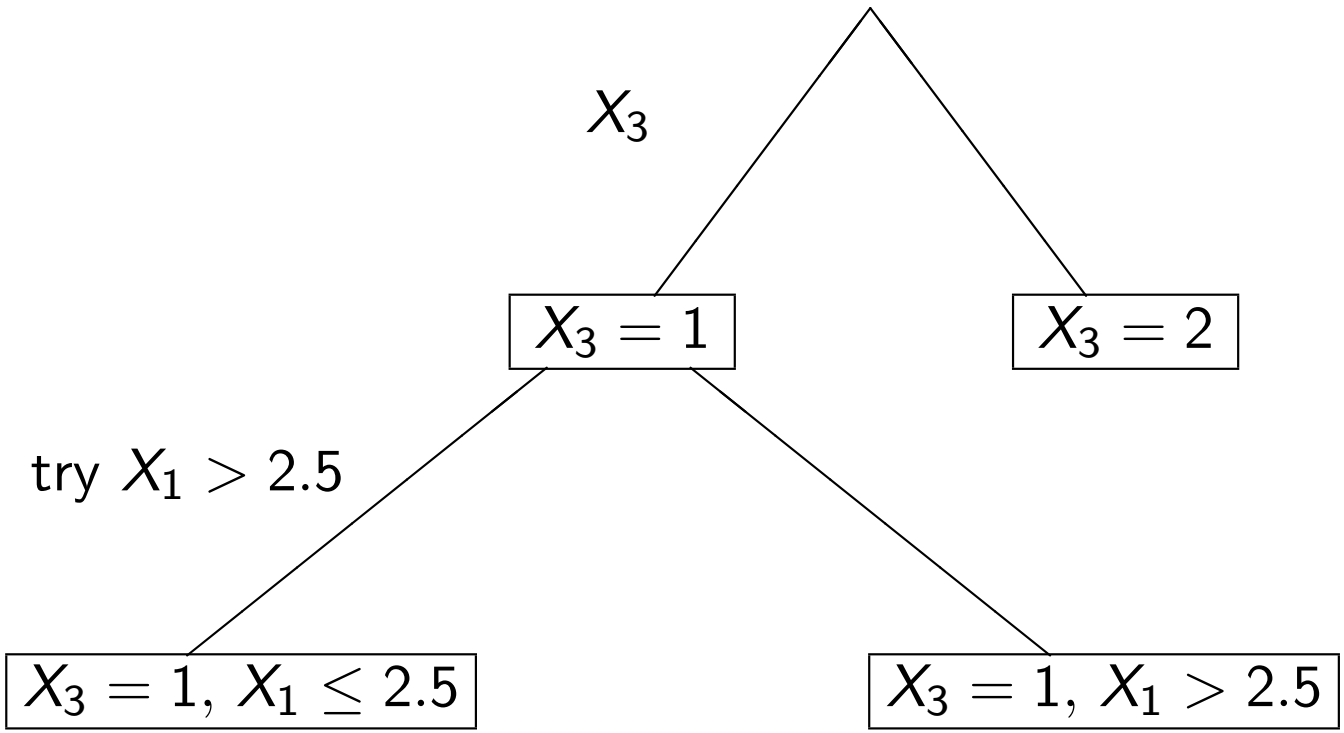
Binary splitting

from the current node

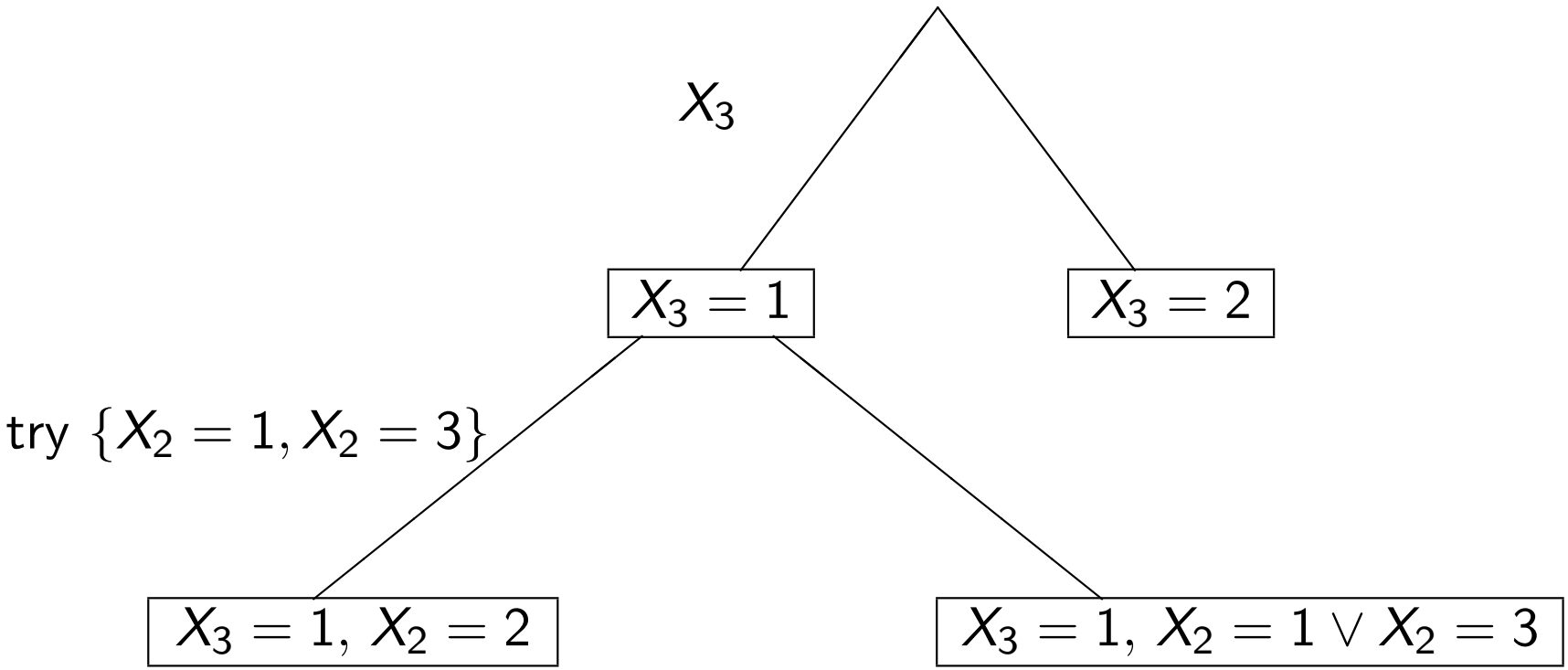
- try all possible cutpoints for all variables
- split using the best cutpoint = produce two nodes

...

Binary splitting - continuous predictor variables



Binary splitting - categorical predictor variables

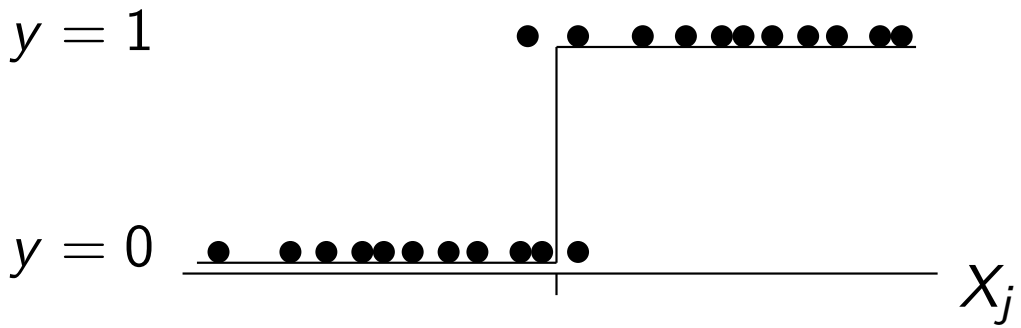


Tree building - multiway or binary?

Any multi-way split can be represented as a series of binary splits.

Binary splitting

continuous, ordinal



categorical

$$AB|CD \text{ or } A|BCD \text{ or } AD|BC \text{ or } C|ABD \ldots$$

note: to reduce number of possible splits, CART 'orders' the levels of categorical variables by the mean of the outcome (regression) or the proportion of class 1 observations (classification)

Cutpoint selection in CART

for current node C and daughter nodes C_{L,c_j} and C_{R,c_j}

- select the best cutpoint c_j^* within the range of each predictor variable X_j with respect to impurity reduction

$$c_j^* = \arg\max_{c_j} \Delta\mathfrak{I}\left(C, C_{L,c_j}, C_{R,c_j}\right)$$

(in regression: improvement in SSE instead of impurity reduction)

Impurity reduction

impurity reduction = impurity before splitting -
impurity after splitting (weighted mean over nodes)

Impurity reduction

impurity reduction = impurity before splitting -
impurity after splitting (weighted mean over nodes)

$$\Delta\mathfrak{I}\left(C, C_{L,c_j}, C_{R,c_j}\right) = \mathfrak{I}(C) - \left(\frac{n_{L,c_j}}{n}\mathfrak{I}(C_{L,c_j}) + \frac{n_{R,c_j}}{n}\mathfrak{I}(C_{R,c_j})\right)$$

where n_{L,c_j} is the number of observations in C that are assigned to the left node

(e.g., for a continuous predictor, $n_{L,c_j} = \sum_i \mathrm{I}(x_{ij} \leq c_j)$)

Impurity measures

- Gini index (used in CART)

$$\mathfrak{I}(C) = \sum_{k=0}^{K} \hat{p}_k (1 - \hat{p}_k)$$

- Shannon entropy (used in C4.5)

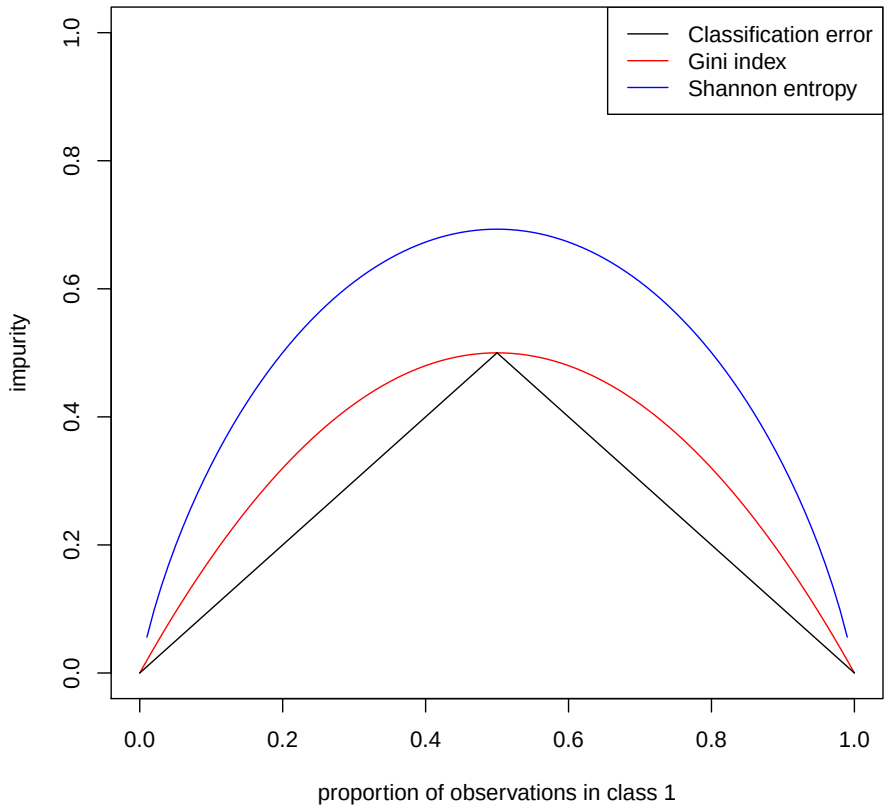
$$\mathfrak{I}(C) = -\sum_{k=0}^{K} \hat{p}_k \log \hat{p}_k$$

- Classification error (never or rarely used)

$$\mathfrak{I}(C) = 1 - \max_k \hat{p}_k$$

Impurity measures

Impurity measures for $K = 2$ response classes:



Impurity in a node is:

0, if all observations are of the same class.

max, if each class is held by the same number of observations.

Classification and regression trees

- tree building:

Classification and regression trees

- tree building:
  - recursively select splitting variable and cutpoint

Classification and regression trees

- tree building:
  - recursively select splitting variable and cutpoint
  - stop splitting if

Classification and regression trees

- tree building:
  - recursively select splitting variable and cutpoint
  - stop splitting if
    - the impurity reduction does not exceed a (user) pre-specified threshold

Classification and regression trees

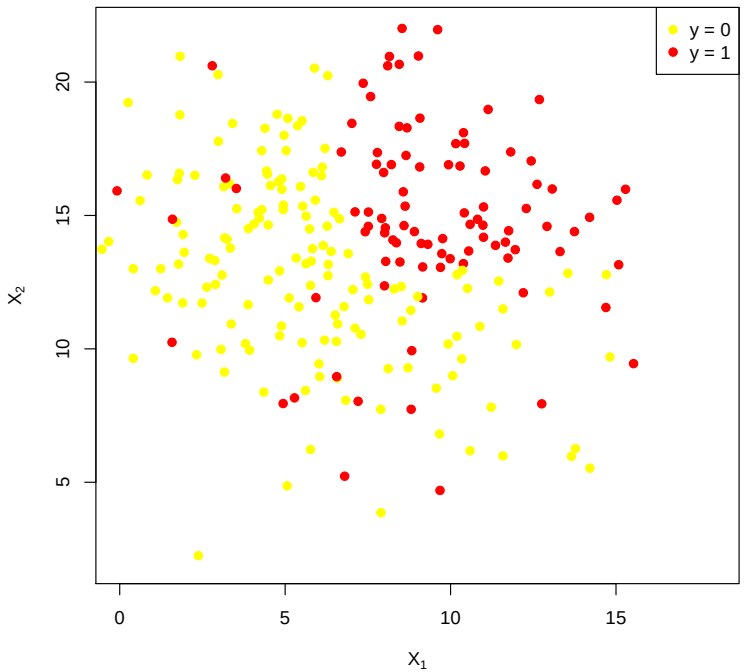
- tree building:
  - recursively select splitting variable and cutpoint
  - stop splitting if
    - the impurity reduction does not exceed a (user) pre-specified threshold
    - the number of observations in any node would be smaller than a (user) pre-specified number minimum number

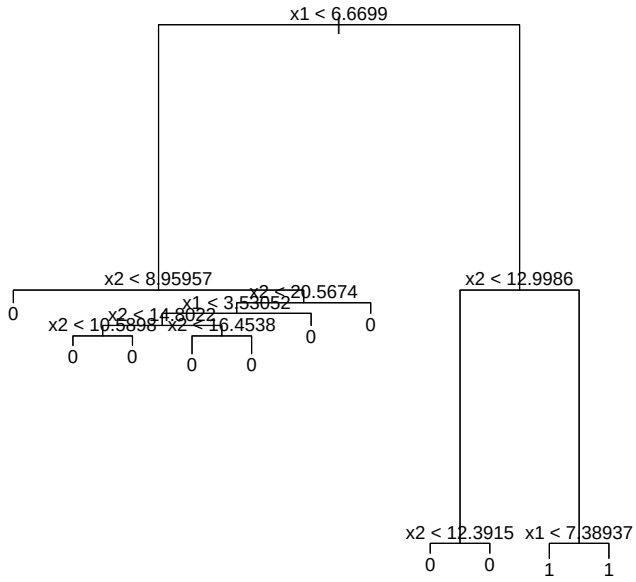
Classification and regression trees

- tree building:
  - recursively select splitting variable and cutpoint
  - stop splitting if
    - the impurity reduction does not exceed a (user) pre-specified threshold
    - the number of observations in any node would be smaller than a (user) pre-specified number minimum number
  - prune (Hastie et al., 2001) if necessary

Pruning

Full tree likely to overfit:





Pruning

- Find the optimal number of nodes |T| for tree T
- Create a range of subtrees T_M through T_1,
  - T_M is the full tree, T_1 is a tree with 1 node
  - In every subtree T_m, the node that least improved impurity is removed from tree T_{m+1}
- Full tree T was build by minimizing $\sum_{m=1}^{M} \sum_{x_i \in C_m} L(y_i - \hat{y}_i)$ in the training data
- Find optimal number of nodes |T| by minimizing $\sum_{m=1}^{|T|} \sum_{x_i \in C_m} L(y_i - \hat{y}_i) + \alpha|T|$ in the training data
- Optimal value of α is determined through k-fold CV

Short detour: Model validation

aim: evaluate model performance and compare models

usually based on prediction error estimates

$$\frac{1}{n}\sum_{i=1}^{n} \mathrm{I}(\hat{y}_i \neq y_i)$$

in classification

$$\frac{1}{n}\sum_{i=1}^{n} (\hat{y}_i - y_i)^2$$

in regression

Naive approach

- fit model on training sample
- estimate error on same training sample

Naive approach

- fit model on training sample
- estimate error on same training sample

bad idea!

Naive approach

- error estimation would be overoptimistic
- especially for models that overfit, i.e. that
  - fit too closely to random variation in the training sample
  - are not generalizable to other samples from the same data generating process

  $\Rightarrow$ rewards overfitting

Test sample

test sample should not be identical to the training sample!

cross validation:

Test sample

test sample should not be identical to the training sample!

cross validation:

- set aside part of the original sample as a test sample

Test sample

test sample should not be identical to the training sample!

cross validation:

- set aside part of the original sample as a test sample
  - tradeoff between size of training and test sample

Test sample

test sample should not be identical to the training sample!

cross validation:

- set aside part of the original sample as a test sample
  - tradeoff between size of training and test sample
  - better: more than one test sample

Test sample

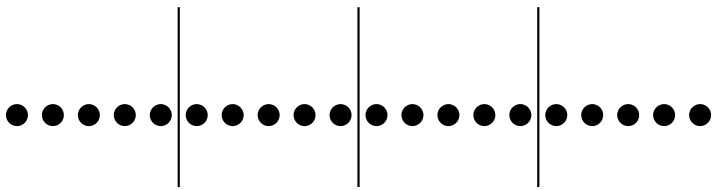
test sample should not be identical to the training sample!

cross validation:

- set aside part of the original sample as a test sample
  - tradeoff between size of training and test sample
  - better: more than one test sample
- k-fold cross validation

Cross validation (CV)

k-fold CV: randomly separate original training sample into k subsets



- in k steps:
- fit model on training sample minus kth subset
- assess prediction error on kth subset (test sample)
  $\Rightarrow$ gives k error estimates
- average over k error estimates

Cross validation (CV)

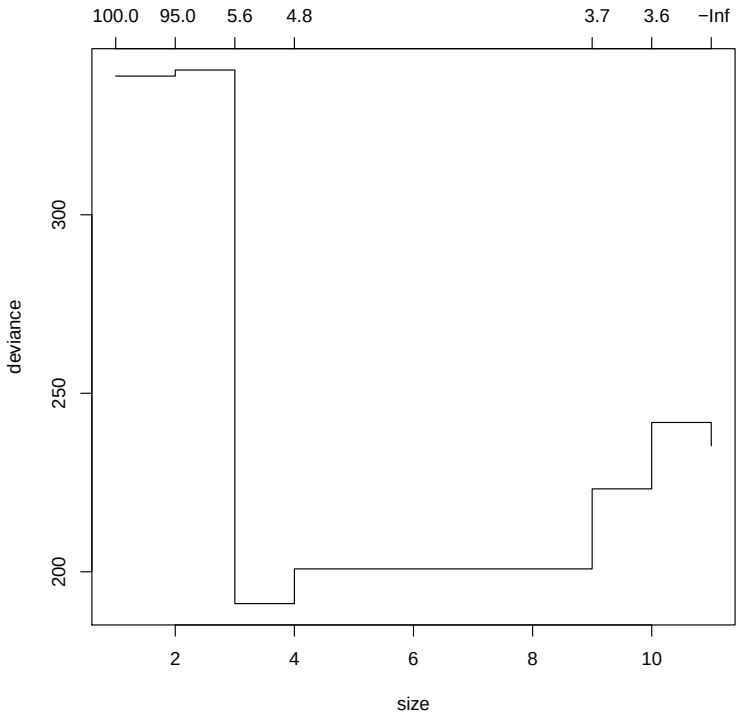
How many folds to use?

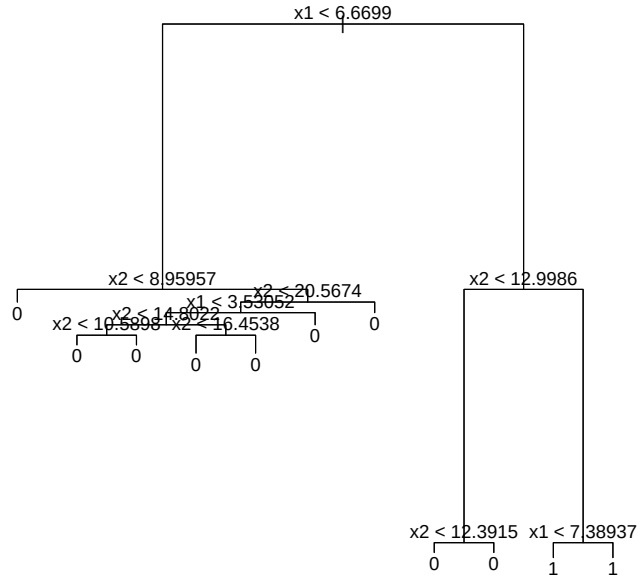
Extreme case: N-fold-CV (leave-one-out-CV, can be overly optimistic)

Rule of thumb: $k = 10$ gives realistic estimates of prediction error Kohavi (1995)

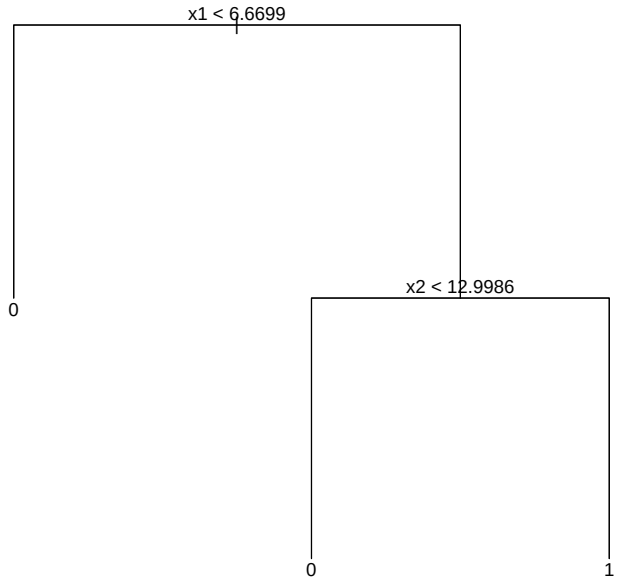
Note: Whenever you perform cross-validation, or random sampling, make sure you can exactly reproduce your results by setting the random seed (e.g, `set.seed(42)`).

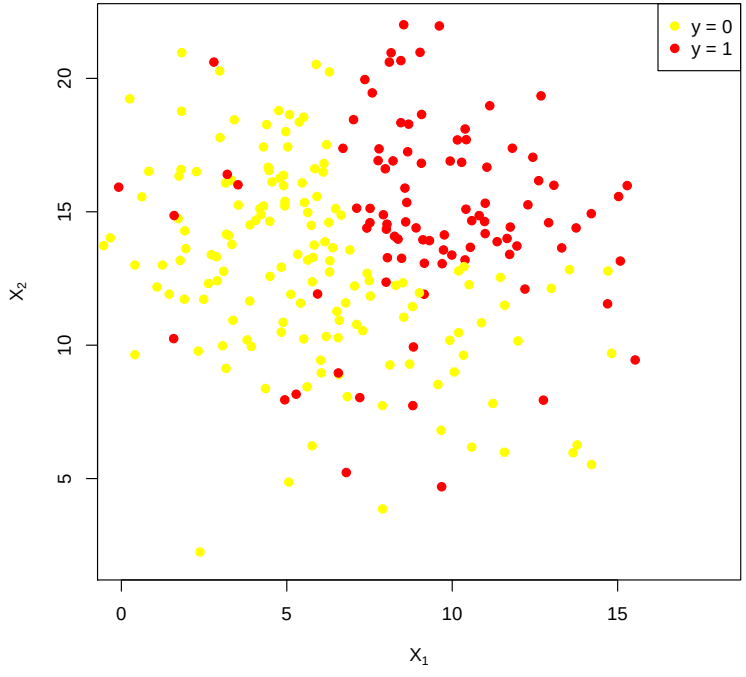
Back to pruning





Prune tree





Classification and regression trees

- missing values
  by means of surrogate variables (Hastie et al., 2001)
- observation weights
  useful if classes are unbalanced, or if different costs are associated with different types of misclassifications

Growing CARTs with package `tree`

`tree` options and other functions controlling tree growing and size:

`na.action =`	function to filter missing data. The default is `na.pass` as tree handles missing values by dropping them down the tree as far as possible.
`mincut =`	minimum number of observations to include in either child node. The default is 5.
`minsize =`	smallest allowed node size. The default is 10.
`mindev =`	The within-node deviance must be at least this times that of the root node for the node to be split. Default is .01.
`cv.tree()`	Performs k-fold CV cost-complexity (pruning) parameter.
`prune.tree()`	Prunes tree to size found with `cv.tree`.

Interpretation

- variables that appear in the tree are (supposed to be) more relevant than those that do not appear in the tree

Interpretation

- variables that appear in the tree are (supposed to be) more relevant than those that do not appear in the tree
- variables that appear high up in the tree affect more observations than those that appear lower in the tree

Interpretation

- variables that appear in the tree are (supposed to be) more relevant than those that do not appear in the tree
- variables that appear high up in the tree affect more observations than those that appear lower in the tree

Note: only descriptive (beware of causal attributions)!

Comparison to linear models

	regression tree	linear model
model	$f(\mathbf{x}) = \sum_m \hat{y}_m \mathsf{I}(\mathbf{x} \in C_m)$	$f(\mathbf{x}) = \hat{\beta}_0 + \hat{\beta}_1 \cdot x_1 + \ldots$

Comparison to linear models

	regression tree	linear model
model	$f(\mathbf{x}) = \sum_m \hat{y}_m \mathsf{I}(\mathbf{x} \in C_m)$	$f(\mathbf{x}) = \hat{\beta}_0 + \hat{\beta}_1 \cdot x_1 + \ldots$
fitting	recursive partitioning	least squares, closed form

Comparison to linear models

	regression tree	linear model
model	$f(\mathbf{x}) = \sum_m \hat{y}_m \mathsf{I}(\mathbf{x} \in C_m)$	$f(\mathbf{x}) = \hat{\beta}_0 + \hat{\beta}_1 \cdot x_1 + \ldots$
fitting	recursive partitioning	least squares, closed form
$N < p$	can deal	cannot, need penalized regression

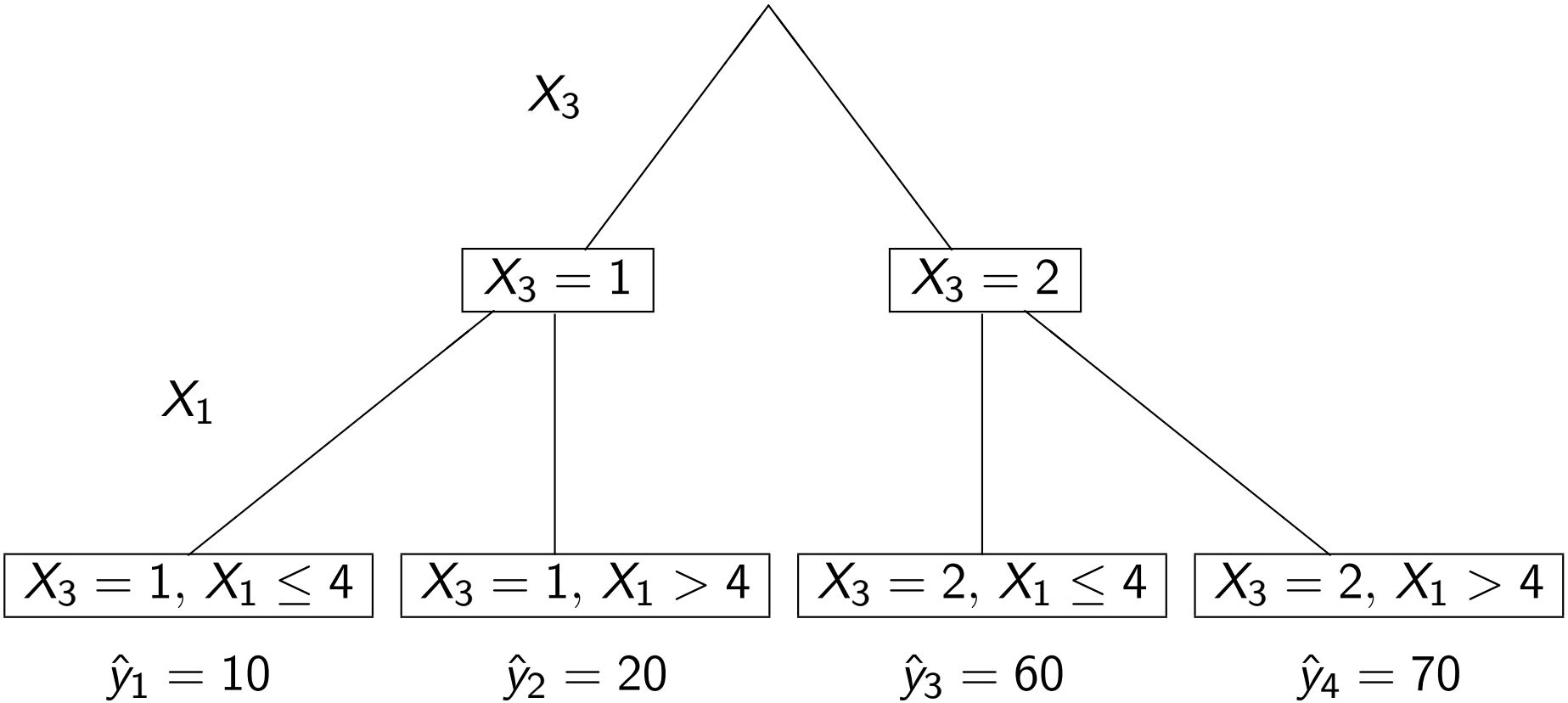
Comparison to linear models

	regression tree	linear model
model	$f(\mathbf{x}) = \sum_m \hat{y}_m \mathsf{I}(\mathbf{x} \in C_m)$	$f(\mathbf{x}) = \hat{\beta}_0 + \hat{\beta}_1 \cdot x_1 + \ldots$
fitting	recursive partitioning	least squares, closed form
$N < p$	can deal	cannot, need penalized regression
interpret.	easy, tree structure	$\hat{\beta}_j$ with sd

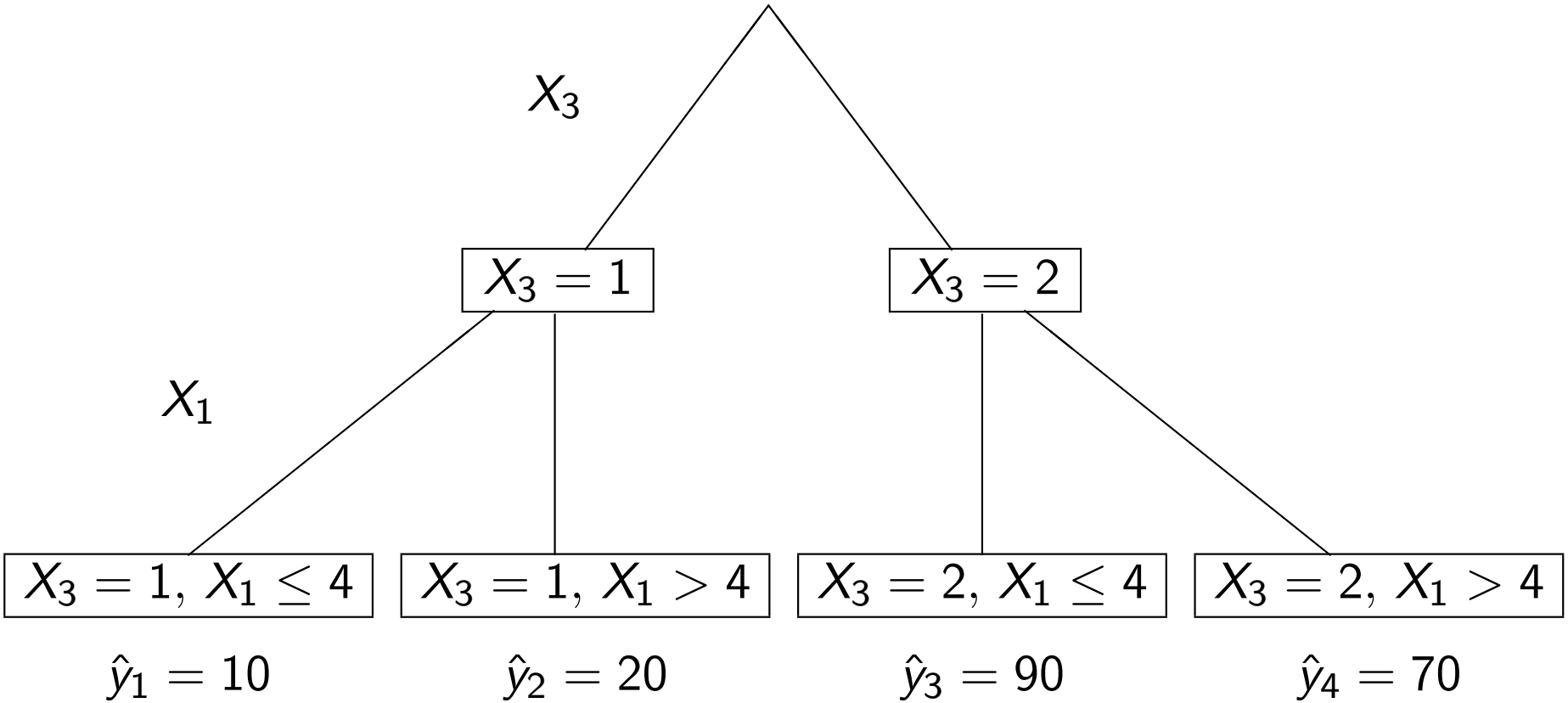
Comparison to linear models

	regression tree	linear model
model	$f(\mathbf{x}) = \sum_m \hat{y}_m \mathsf{I}(\mathbf{x} \in C_m)$	$f(\mathbf{x}) = \hat{\beta}_0 + \hat{\beta}_1 \cdot x_1 + \ldots$
fitting	recursive partitioning	least squares, closed form
$N < p$	can deal	cannot, need penalized regression
interpret.	easy, tree structure	$\hat{\beta}_j$ with sd
main effect	?	$\hat{\beta}_1 \cdot x_1$
interaction	?	$\hat{\beta}_{1,2} \cdot x_1 \cdot x_2$

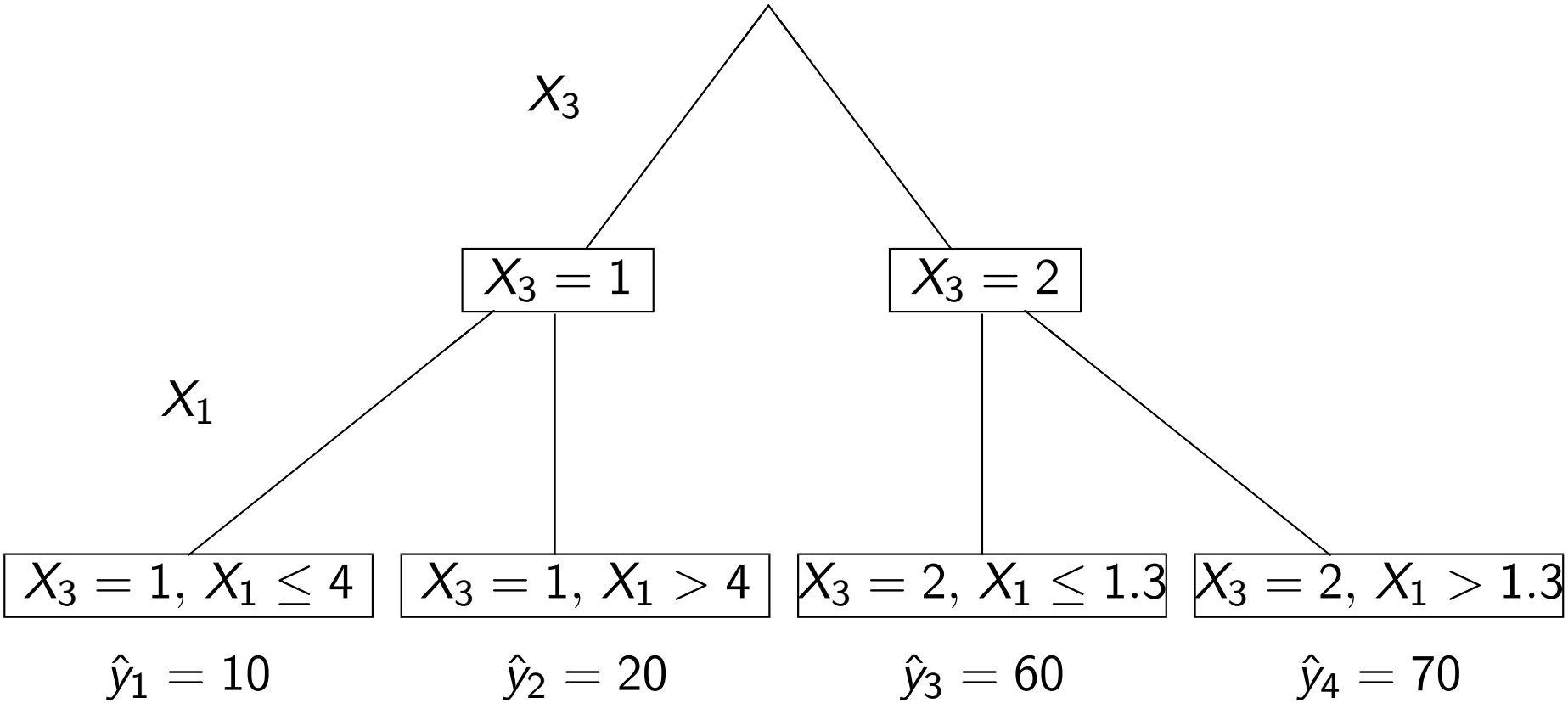
Interpretation: Two main effects



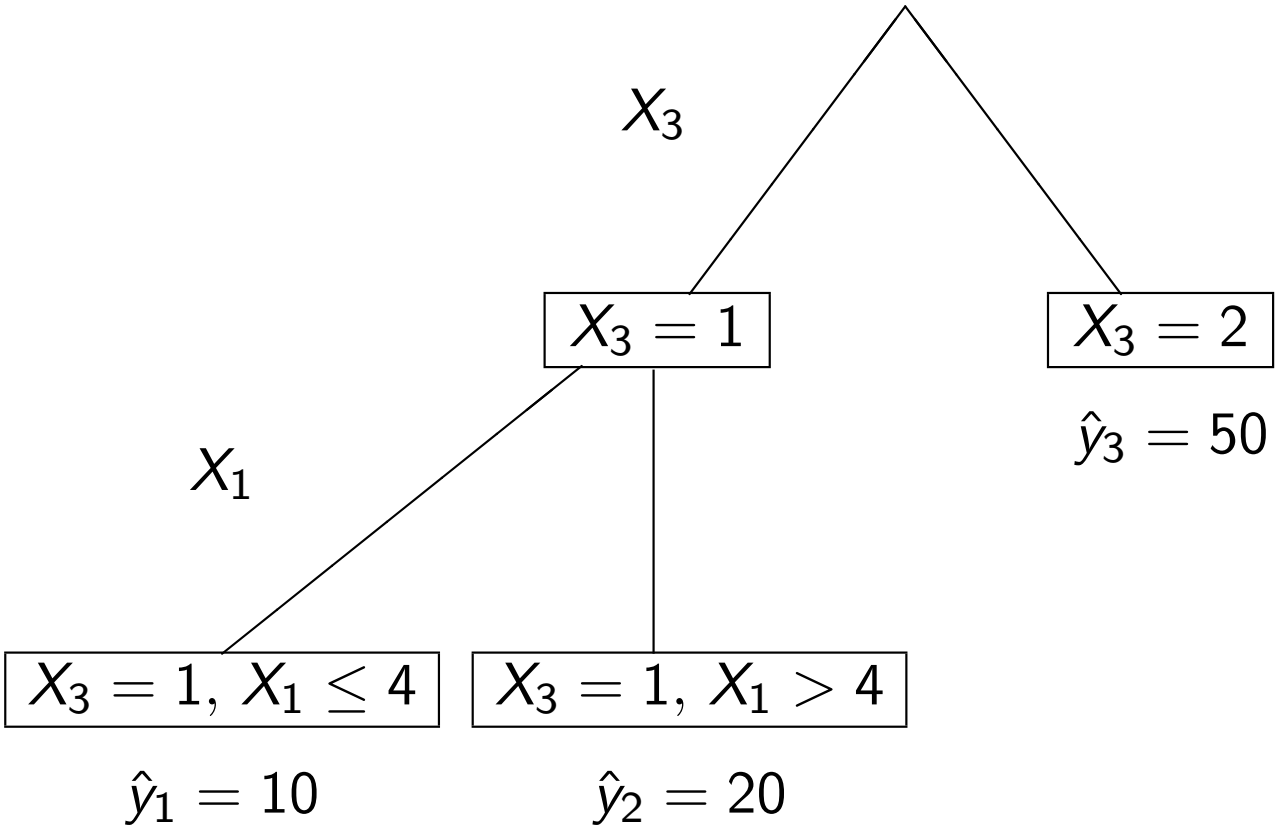
Interpretation: Interaction



Interpretation: Interaction



Interpretation: Interaction



Problems of CART

I. variable selection bias

Problems of CART

I. variable selection bias

- continuous variables and variables with many categories, as well es variables with missing values, are preferred in original CART and C4.5 (cf., e.g., White and Liu, 1994, Loh and Shih, 1997, Jensen and Cohen, 2000, Kim and Loh, 2001, Dobra and Gehrke, 2001)

Problems of CART

I. variable selection bias

- continuous variables and variables with many categories, as well es variables with missing values, are preferred in original CART and C4.5 (cf., e.g., White and Liu, 1994, Loh and Shih, 1997, Jensen and Cohen, 2000, Kim and Loh, 2001, Dobra and Gehrke, 2001)
- due to multiple testing and biased entropy estimation (Strobl et al., 2007)

Problems of CART

I. variable selection bias

Problems of CART

I. variable selection bias

- continuous variables and variables with many categories, as well es variables with missing values, are preferred in original CART and C4.5 (cf., e.g., White and Liu, 1994, Loh and Shih, 1997, Jensen and Cohen, 2000, Kim and Loh, 2001, Dobra and Gehrke, 2001)

Problems of CART

I. variable selection bias

- continuous variables and variables with many categories, as well es variables with missing values, are preferred in original CART and C4.5 (cf., e.g., White and Liu, 1994, Loh and Shih, 1997, Jensen and Cohen, 2000, Kim and Loh, 2001, Dobra and Gehrke, 2001)
- due to multiple testing and biased entropy estimation (Strobl et al., 2007)

Solution

I. variable selection bias

Solution

I. variable selection bias

- unbiased variable selection approaches (Loh and Shih, 1997, Kim and Loh, 2001, Dobra and Gehrke, 2001, Shih, 2004, Lausen et al., 2004, Hothorn et al., 2006, Strobl et al., 2007)

Solution

I. variable selection bias

- unbiased variable selection approaches (Loh and Shih, 1997, Kim and Loh, 2001, Dobra and Gehrke, 2001, Shih, 2004, Lausen et al., 2004, Hothorn et al., 2006, Strobl et al., 2007)

  $\Rightarrow$ p-value of optimally selected (χ^2, rank or Gini) statistic (Shih, 2004, Lausen et al., 2004, Strobl et al., 2007)
  correct for optimal choice of cutpoint

Solution

I. variable selection bias

- unbiased variable selection approaches (Loh and Shih, 1997, Kim and Loh, 2001, Dobra and Gehrke, 2001, Shih, 2004, Lausen et al., 2004, Hothorn et al., 2006, Strobl et al., 2007)

  $\Rightarrow$ p-value of optimally selected (χ^2, rank or Gini) statistic (Shih, 2004, Lausen et al., 2004, Strobl et al., 2007)
  correct for optimal choice of cutpoint

  $\Rightarrow$ separate variable and cutpoint selection (Loh and Shih, 1997, Kim and Loh, 2001, Hothorn et al., 2006)

Solution

I. variable selection bias

- package `party` or `partykit` for unbiased recursive partitioning (Hothorn et al., 2006, 2017, Hothorn and Zeileis, 2015)
  - function `ctree` for classification, regression and survival trees

Solution

I. variable selection bias

- package `party` or `partykit` for unbiased recursive partitioning (Hothorn et al., 2006, 2017, Hothorn and Zeileis, 2015)
  - function `ctree` for classification, regression and survival trees
- splitting based on p-values of conditional inference tests, that also serve as a stopping criterion
  $\Rightarrow$ separates variable and split selection
  $\Rightarrow$ no overfitting
  $\Rightarrow$ pruning not necessary

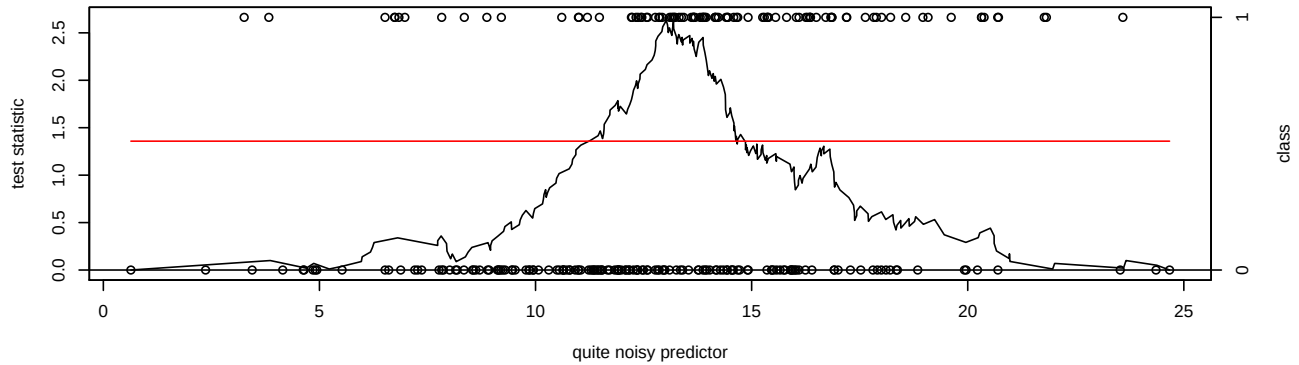
Conditional inference trees (Hothorn et al., 2006)

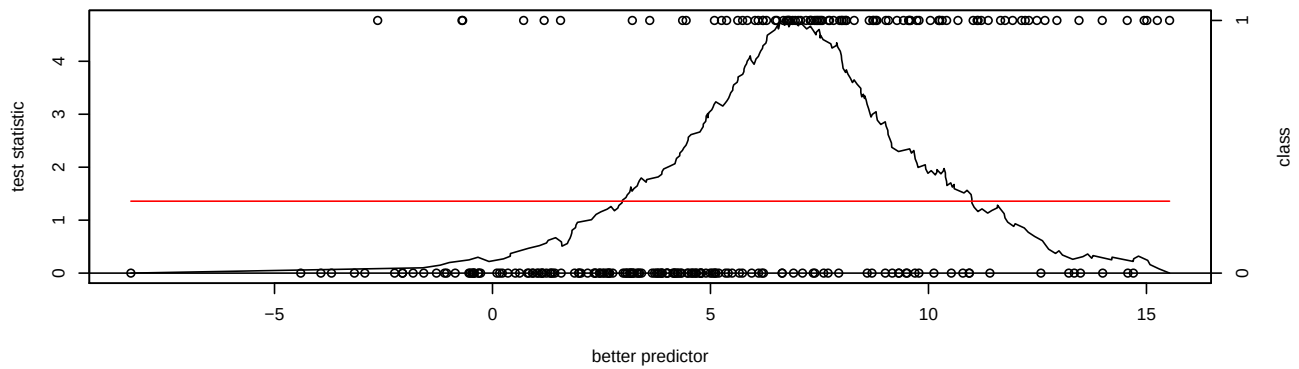
1. Test the global null hypothesis of independence between any of the m covariates and the response. If null hypothesis can be rejected, select the covariate X_j^* with strongest association to Y. Otherwise, stop.

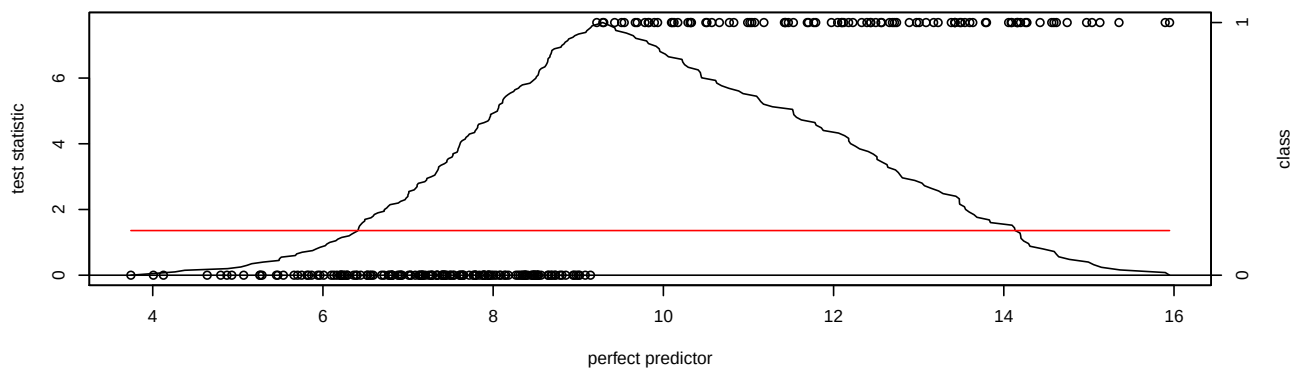
2. Select the splitting value for X_j^* that optimally separates the observations in terms of outcome Y.

3. Split the observations and repeat the procedure in each of the resulting daughternodes.

Test statistics for selecting splitting value







ctree function

ctree options controlling tree growing process:

mincriterion =	value of the test statistic or (1-p)-value that must be exceeded in order to implement a split.
maxdepth =	maximum depth of the tree. The default maxdepth = Inf means that no restrictions are applied to tree sizes.
minsplit =	the minimum sum of weights in a node in order to be considered for splitting.
minbucket =	the minimum sum of weights in a terminal node
minprob =	proportion of observations needed to establish a terminal node
splittry =	number of variables that are inspected for admissible splits if the best split doesn't meet the sample size constraint

ctree function

ctree options controlling tree growing process:

multiway =	a logical indicating if multiway splits for all factor levels are implemented for unordered factors.
maxsurrogate =	number of surrogate splits to evaluate. Note that currently only surrogate splits in ordered covariables are implemented.
majority =	if TRUE, observations which can't be classified to a daughter node because of missing information are randomly assigned (following the node distribution). If FALSE, they go with the majority (the default in ctree).

Model-based recursive partitioning

Rationale:

Global parametric model (e.g., $Y = X\beta + \epsilon$) may not fit the data well. When additional covariates are available, it may be possible to partition the data with respect to these covariates and find better-fitting models in each cell of the partition.

Zeileis et al. (2008)

Model-based recursive partitioning

1. Fit a parametric model (e.g., estimate $\hat{\beta}$ for a (G)LM) to all observations in the current node.

2. Test whether the parameter estimates are stable with respect to every ordering of $U_1, \ldots, U_q$. If null hypothesis of parameter stability can be rejected, select covariate U_j^* associated with the highest instability. Otherwise, stop.

3. Select the splitting value for U_j^* that locally optimizes the loss function in each of the resulting daughter nodes.

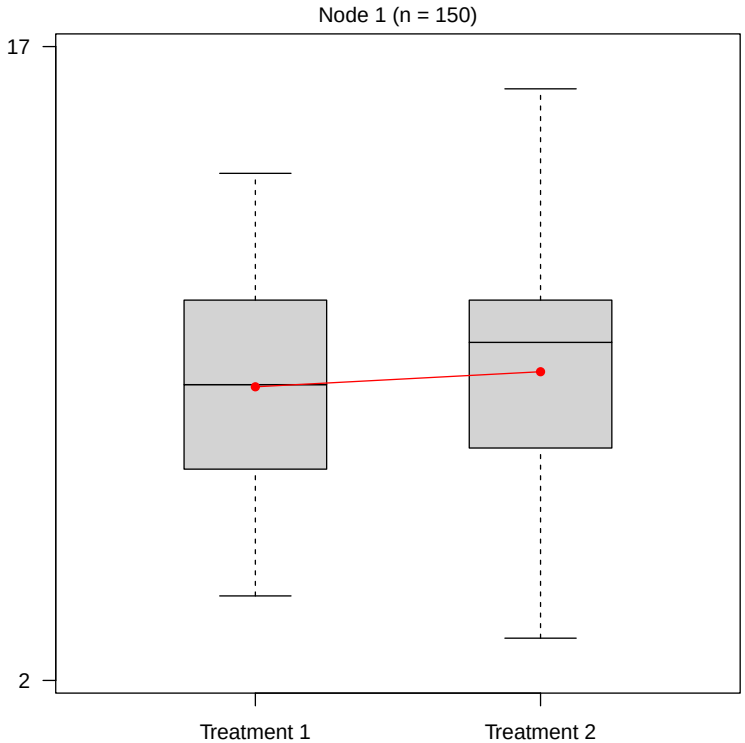
4. Split the observations and repeat the procedure in each of the resulting daughternodes.

Example: Linear-model based recursive partitioning

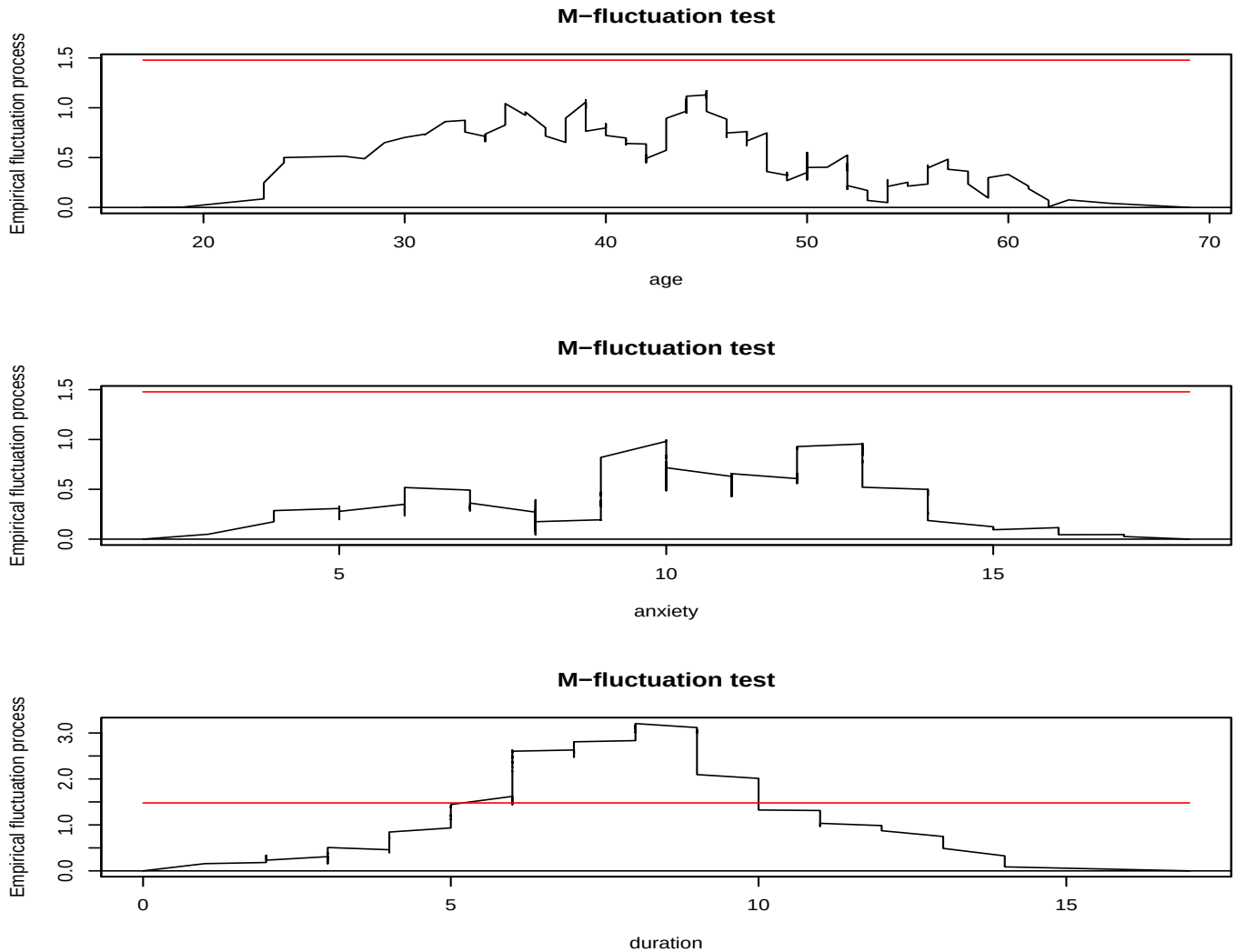
Dataset of $N = 150$ patients receiving one of two treatments for depression.

- X: treatment indicator
- Y: post-treatment depressive symptom score
- $Z_1, \ldots, Z_p$: age, anxiety, duration

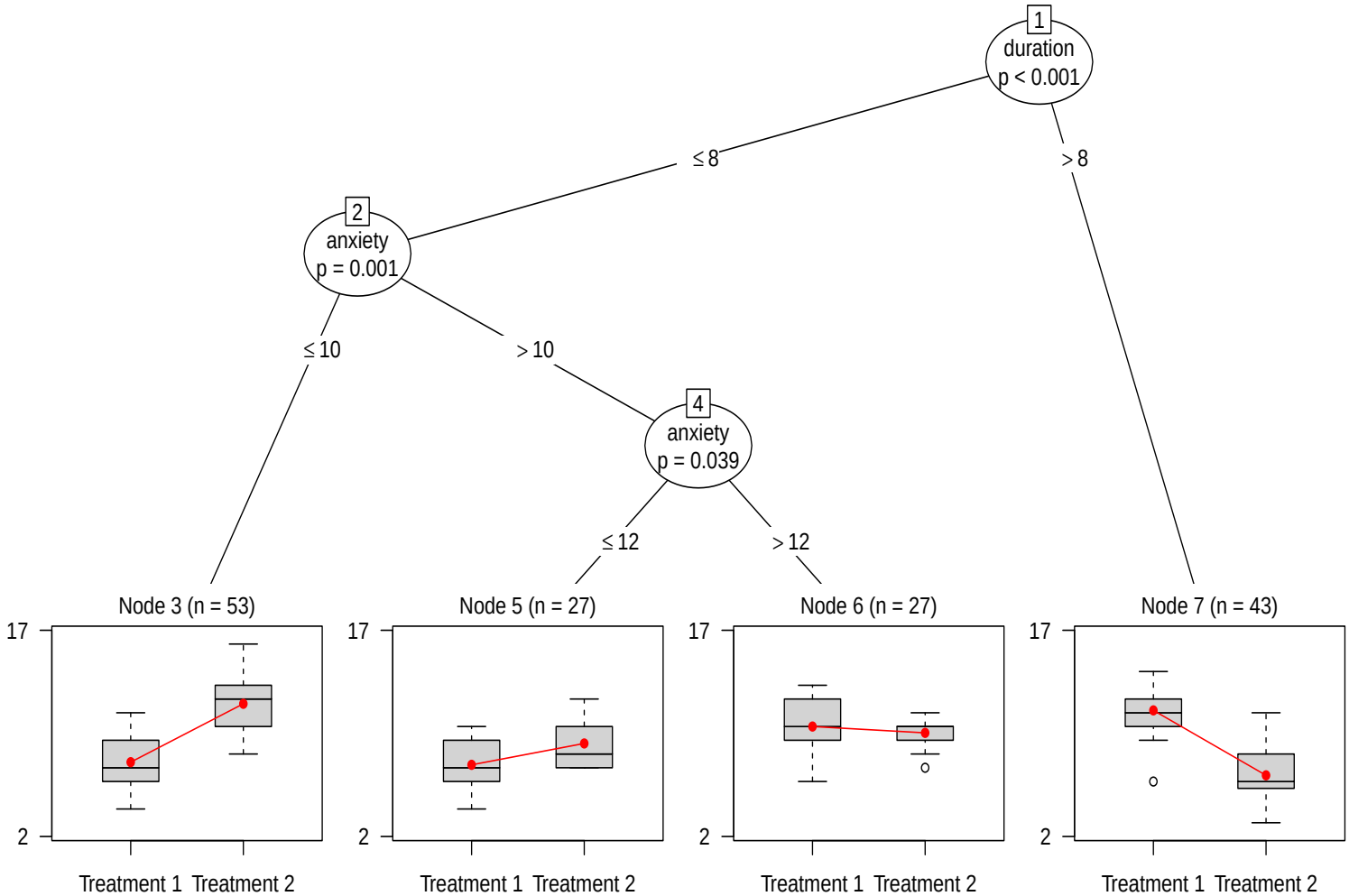
Global linear model



Parameter stability tests for linear model



Linear model tree



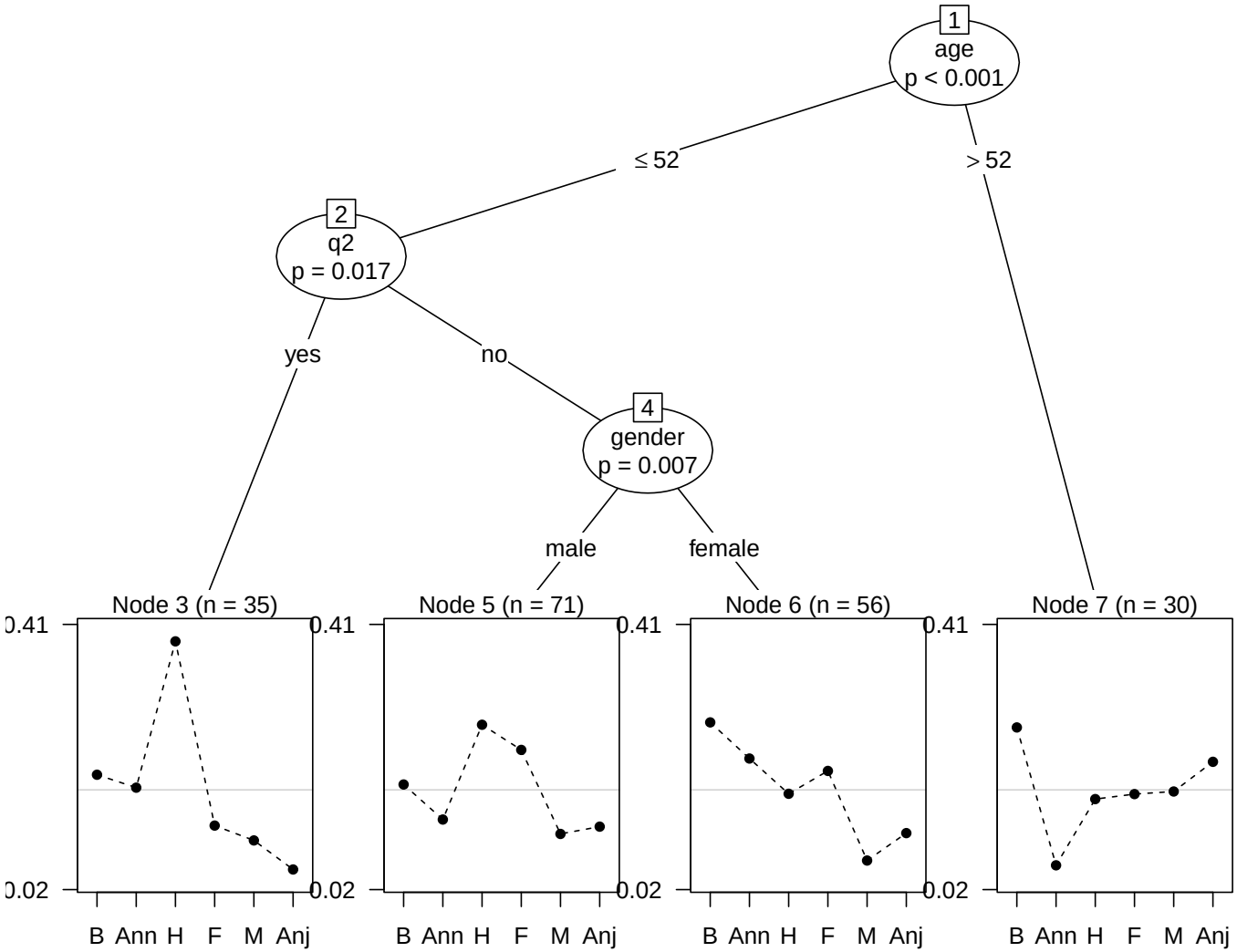
Example: Bradley-Terry model based recursive partitioning

Dataset of $N = 192$ respondents, who judged the attractiveness of the top six contestants on Germany's Next Topmodel 2007.

- preference: Preferences for all 15 paired comparisons from 6 contestants: Barbara, Anni, Hana, Fiona, Mandy, and Anja.
- $Z_1, \ldots, Z_p$: gender, age, q1, q2, q3
  q1: Do you recognize the women on the pictures?
  q2: Did you watch Germany's Next Topmodel regularly?
  q3: Do you know who won Germany's Next Topmodel?

Further reference: Strobl et al. (2011) and R-package `psychotree`.

Bradley-Terry tree



Clustered / multilevel / longitudinal data

Lower-level observations nested within higher-level units $\Rightarrow$

Linear mixed-effects model: $y = X\beta + Ub + \epsilon$

Recursive partitioning of mixed-effects models:

- replace fixed-effects part $X\beta$ by $f(X)$, found through recursive partitioning
- estimate random-effects parameters as usual

Example: mixed-effects model based recursive partitioning

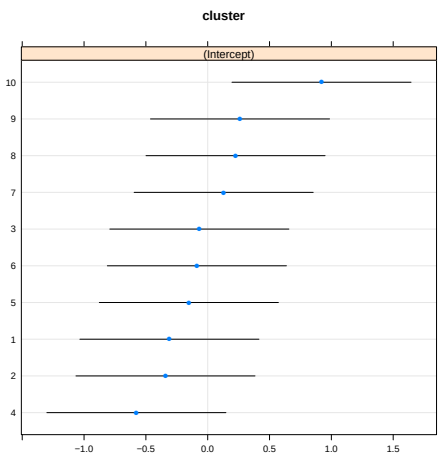
Dataset of $N = 150$ patients receiving one of two treatments for depression.

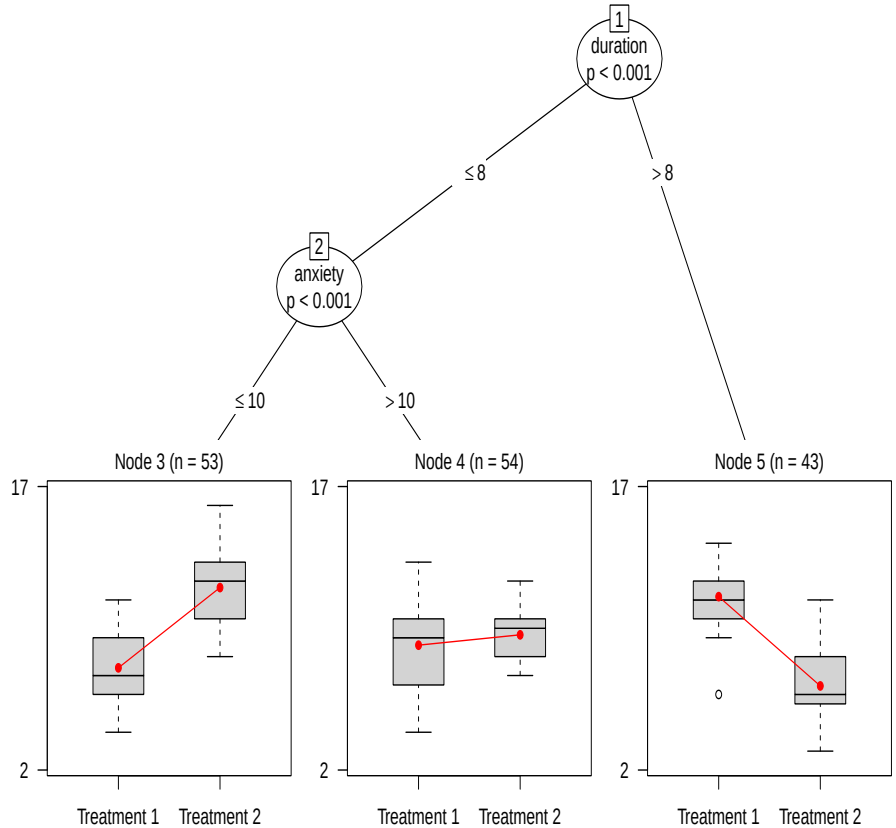
- X: treatment indicator
- Y: post-treatment depressive symptom score
- $Z_1, \ldots, Z_p$: age, anxiety, duration
- U: dummy indicators for treatment center ($n = 10$)

Further reference: Fokkema et al. (2015) and R-package `glmertree`.

Linear mixed-effects model tree

$$Y = X\beta_j + Ub + \epsilon$$





References I

L. Breiman, J. H. Friedman, R. A. Olshen, and C. J. Stone. *Classification and Regression Trees*. Chapman and Hall, New York, 1984.

A. Dobra and J. Gehrke. Bias correction in classification tree construction. In C. E. Brodley and A. Pohoreckyj Danyluk, editors, *Proceedings of the Seventeenth International Conference on Machine Learning (ICML 2001), Williams College, Williamstown, MA, USA*, pages 90–97. Morgan Kaufmann, 2001.

M. Fokkema, N. Smits, A. Zeileis, T. Hothorn, and H. Kelderman. Detecting treatment-subgroup interactions in clustered data with generalized linear mixed-effects model trees. *Working Papers in Economics and Statistics*, 2015.

T. Hastie, R. Tibshirani, and J. H. Friedman. *The Elements of Statistical Learning*. Springer, New York, 2001.

T. Hothorn and A. Zeileis. partykit: A modular toolkit for recursive partytioning in r. *Journal of Machine Learning Research*, 16:3905–3909, 2015.

T. Hothorn, K. Hornik, and A. Zeileis. Unbiased recursive partitioning: A conditional inference framework. *Journal of Computational and Graphical Statistics*, 15(3):651–674, 2006.

T. Hothorn, K. Hornik, C. Strobl, and A. Zeileis. `party`: A laboratory for recursive part(y)itioning. 2017. URL `http://CRAN.R-project.org/package=party`. R package version 1.2-3.

D. D. Jensen and P. R. Cohen. Multiple comparisons in induction algorithms. *Machine Learning*, 38(3):309–338, 2000.

H. Kim and W. Loh. Classification trees with unbiased multiway splits. *Journal of the American Statistical Association*, 96:589–604, 2001.

R. Kohavi. A study of cross-validation and bootstrap for accuracy estimation and model selection. In *International Joint Conference on Artificial Intelligence (IJCAI*, volume 14, pages 1137–1145. Stanford, CA, 1995.

B. Lausen, T. Hothorn, F. Bretz, and M. Schumacher. Assessment of optimal selected prognostic factors. *Biometrical Journal*, 46(3):364–374, 2004.

W. Loh and Y. Shih. Split selection methods for classification trees. *Statistica Sinica*, 7:815–840, 1997.

J. R. Quinlan. *C4.5: Programms for Machine Learning*. Morgan Kaufmann Publishers Inc., San Francisco, 1993.

Y.-S. Shih. A note on split selection bias in classification trees. *Computational Statistics and Data Analysis*, 45(3): 457–466, 2004.

References II

C. Strobl, A.-L. Boulesteix, and T. Augustin. Unbiased split selection for classification trees based on the Gini Index. *Computational Statistics & Data Analysis*, 52(1):483–501, 2007.

C. Strobl, F. Wickelmaier, and A. Zeileis. Accounting for individual differences in bradley-terry models by means of recursive partitioning. *Journal of Educational and Behavioral Statistics*, 36(2):135–153, 2011.

A. White and W. Liu. Bias in information based measures in decision tree induction. *Machine Learning*, 15(3): 321–329, 1994.

A. Zeileis, T. Hothorn, and K. Hornik. Model-based recursive partitioning. *Journal of Computational and Graphical Statistics*, 17(2):492–514, 2008.