#### Bayesian Inference in Normal Models

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#### Inference in normal distributions

The univariate normal, or Gaussian, probability distribution with mean  $\mu$  and variance  $\sigma^2$  has the density

$$P(x|\mu,\sigma) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}.$$

A random variable x that is normally distributed with mean  $\mu$  and variance  $\sigma^2$  can be written

$$x \sim N(\mu, \sigma^2).$$

#### Inference in normal distributions

- A common elementary data analysis problem is when we observe n iid samples from  $N(\mu, \sigma^2)$ , where μ and  $\sigma^2$  are unknown, and we aim to infer μ.
- ▶ In other words, we observe

$$D=x_1,x_2\cdots x_n,$$

where we assume

$$x_i \sim N(\mu, \sigma^2)$$
, for  $i \in 1, 2 \cdots n$ ,

where both  $\mu$  and  $\sigma^2$  are unknown, and we aim to infer the value of  $\mu.$ 

▶ In other words, we aim to determine the posterior distribution

$$P(\mu|D)$$
.

# Likelihood of $\mu$ and $\sigma^2$

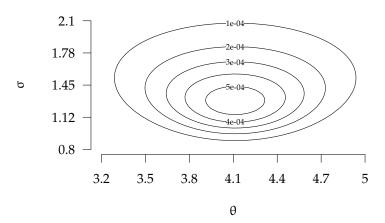
► The likelihood of  $\mu$  and  $\sigma^2$  given D is

$$\begin{split} P(x_1, x_2 \cdots x_n | \mu, \sigma^2) &= \prod_{i=1}^n P(x_i | \mu, \sigma^2), \\ &= \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x_i - \mu)^2}{2\sigma^2}}, \\ &= \left(\frac{1}{\sqrt{2\pi\sigma^2}}\right)^n e^{\left(-\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2\right)}, \\ &\propto \sigma^{-n} e^{\left(-\frac{1}{2\sigma^2} [ns^2 + n(\bar{x} - \mu)^2]\right)}, \end{split}$$

with

$$\bar{\mathbf{x}} \doteq \frac{1}{n} \sum_{i=1}^{n} \mathbf{x}_{i}, \quad \mathbf{s}^2 \doteq \frac{1}{n} \sum_{i=1}^{n} (\mathbf{x}_i - \bar{\mathbf{x}})^2.$$

### *Likelihood of* $\mu$ *and* $\sigma^2$



The likelihood of  $\boldsymbol{\mu}$  and  $\boldsymbol{\sigma}$  when

$$D = 2.41, 5.37, 5.28, 4.89, 4.40, 4.63, 4.67, 4.52, 1.10, 3.86$$

with  $\bar{x} = 4.11$  and s = 1.28.



#### Conjugate prior for $\mu$ and $\sigma$

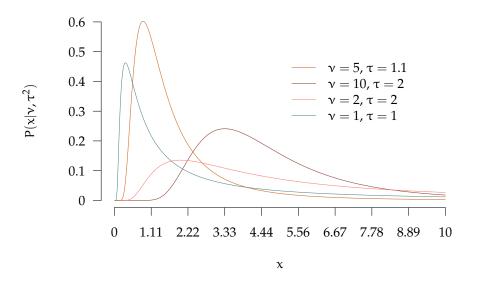
- A common choice of conjugate prior is the normal/inverse-gamma distribution, also known as the *normal*  $\times$  *scaled inverse-* $\chi^2$  distribution.
- ► Thus, our full model is

$$\begin{split} &x_i \sim N(\mu,\sigma^2), \quad \text{for } i \in 1,2 \cdots n, \\ &\mu \sim N(\mu_0,\sigma^2/\kappa_0), \\ &\sigma^2 \sim \text{Inv-}\chi^2(\nu_0,\sigma_0^2). \end{split}$$

This corresponds to the joint prior density

$$\begin{split} P(\mu,\sigma^2) &= N\text{-Inv-}\chi^2(\mu,\sigma^2|\mu_0,\kappa_0,\nu_0,\sigma_0^2), \\ &= N(\mu|\mu_0,\sigma^2/\kappa_0) \times \text{Inv-}\chi^2(\sigma^2|\nu_0,\sigma_0^2), \\ &\propto \sigma^{-1}(\sigma^2)^{-(\nu_0/2+1)}e^{\left(-\frac{1}{2\sigma^2}[\nu_0\sigma_0^2 + \kappa_0(\mu_0-\mu)^2]\right)} \end{split}$$

# *The scaled inverse-* $\chi^2$ *distribution*



The mean is  $\frac{v}{v-2}\sigma_0^2$ , mode is  $\frac{v}{v+2}\sigma_0^2$ .

#### *Joint posterior on* $\mu$ *and* $\sigma$

With the normal likelihood and normal/scaled inverse- $\chi^2$  distribution, the joint posterior is:

$$\begin{split} P(\mu,\sigma^2|D) &\propto P(D|\mu,\sigma^2)P(\mu,\sigma^2),\\ &\propto \sigma^{-n}e^{\left(-\frac{1}{2\sigma^2}\left[ns^2+n(\bar{x}-\mu)^2\right]\right)}\\ &\times \sigma^{-1}(\sigma^2)^{-(\nu_0/2+1)}e^{\left(-\frac{1}{2\sigma^2}\left[\nu_0\sigma_0^2+\kappa_0(\mu_0-\mu)^2\right]\right)}\\ &= N\text{-Inv-}\chi^2(\mu,\sigma^2|\mu_n,\kappa_n,\nu_n,\sigma_n^2) \end{split}$$

where

$$\begin{split} &\mu_n = \frac{\kappa_0 \mu_0 + nx}{\kappa_n}, \\ &\kappa_n = \kappa_0 + n, \\ &\nu_n = \nu_0 + n, \\ &\sigma_n^2 = \frac{1}{\nu_n} \left( \nu_0 \sigma_0^2 + ns^2 + \frac{n\kappa_0}{\kappa_0 + n} (\mu_0 - \bar{x})^2 \right). \end{split}$$

# Marginal posterior of $\sigma^2$

► The marginal posterior of  $\sigma^2$  is obtained by integrating over μ:

$$\begin{split} P(\sigma^2|D) &= \int P(\sigma^2,\mu|D) \; d\mu, \\ &= \int N\text{-Inv-}\chi^2(\mu,\sigma^2|\mu_n,\kappa_n,\nu_n,\sigma_n^2) d\mu, \\ &\propto (\sigma^2)^{-(\nu_n/2+1)} e^{\left(-\frac{1}{2\sigma^2}[\nu_n\sigma_n^2]\right)}, \\ &= \text{Inv-}\chi^2(\sigma^2|\nu_n,\sigma_n^2) \end{split}$$

# Marginal posterior of $\mu$

► The marginal posterior of  $\mu$  is obtained by integrating over  $\sigma^2$ :

$$\begin{split} P(\mu|D) &= \int P(\sigma^2,\mu|D) \; d\sigma^2, \\ &= \int N\text{-Inv-}\chi^2(\mu,\sigma^2|\mu_n,\kappa_n,\nu_n,\sigma_n^2) d\sigma^2, \\ &\propto \left[1 + \frac{\kappa_n}{\nu_n\sigma_n^2} \left(\mu - \mu_n\right)^2\right]^{-(\nu_n+1)/2}, \\ &= t_{\nu_n} \left(\mu|\mu_n,\sigma_n^2/\kappa_n\right). \end{split}$$

which is a (non-standard) t-distribution with  $v_n$  degrees of freedom, location  $v_n$  and scale  $\sigma_n^2/\kappa_n$ .

## Marginal posterior density of $\mu$

To infer the marginal probability of  $\mu$ , we must integrate over the *nuisance* variable  $\sigma^2$ :

$$P(\mu|D) = \int P(\mu, \sigma^2|D) d\sigma^2,$$

which can be done by

$$= \int \overbrace{P(\mu|\sigma^2,D)}^{\text{conditional}} \underbrace{P(\sigma^2|D)}_{\substack{\text{marginal} \\ \text{posterior}}} d\sigma^2.$$

This demonstrates that the posterior distribution  $P(\mu|D)$  is an infinite mixture of normal distributions.

## Marginal posterior density of $\mu$

► If we fix  $\sigma^2$  at any value and, using the previous prior on  $\mu$ , i.e.  $\mu \sim N(\mu_0, \sigma^2/\kappa_0)$ , then

$$\begin{split} P(\mu|D,\sigma^2) &\propto P(D|\mu,\sigma)P(\mu|\mu_0,\sigma^2/\kappa_0),\\ &= N(\mu_n,\sigma^2/\kappa_n), \end{split}$$

where

$$\mu_n = \frac{\frac{\kappa_0}{\sigma^2}\mu_0 + \frac{n}{\sigma^2}\bar{x}}{\frac{\kappa_0}{\sigma^2} + \frac{n}{\sigma^2}}, \quad \sigma^2/\kappa_n = \frac{1}{\frac{\kappa_0}{\sigma^2} + \frac{n}{\sigma^2}}.$$

Integrating over  $\sigma^2$ , when  $\sigma^2$  has a scaled inverse  $\chi^2$  distribution with parameters  $\nu_n$ ,  $\sigma_n^2$  leads to a non-standard t-distribution leads to  $t_{\nu_n}$  ( $\mu | \mu_n$ ,  $\sigma_n^2 / \kappa_n$ ) as before.

### Posterior predictive distribution

► Given our n observed values

$$D = 2.41, 5.37, 5.28, 4.89, 4.40, 4.63, 4.67, 4.52, 1.10, 3.86,$$

and our assumed probabilistic generative model, what is *next* value that we predict?

▶ In other words, what is

$$P(x_{n+1}|D) = \iint P(x_{n+1}|\mu, \sigma^2)P(\mu, \sigma^2|D)d\mu d\sigma^2$$

► This is again a t-distribution:

$$t_{\nu_n}\left(\mu|\mu_n,\left(1+\frac{1}{\kappa_n}\right)\sigma_n^2\right)$$



### Inferences concerning differences of normal means

Let us assume that we have observed two sets of data as follows:

$$x_1, x_2 \cdots x_n \overset{\text{\tiny iid}}{\sim} N(\mu_x, \sigma^2), \quad y_1, y_2 \cdots y_n \overset{\text{\tiny iid}}{\sim} N(\mu_y, \sigma^2).$$

- In other words, both  $x_1, x_2 \cdots x_n$  and  $y_1, y_2 \cdots$  are independently and identically normally distributed, with different means  $\mu_x$ ,  $\mu_y$  but with a common variance  $\sigma^2$ .
- ► In general, we know neither  $\mu_x$ ,  $\mu_y$  nor  $\sigma^2$ .
- ► In such a situation, a common problem we are faced with is to infer the difference

$$\mu_{x} - \mu_{y}$$
,

given  $D = \{x_1, x_2 \cdots x_n, y_1, y_2 \cdots y_n\}$ , while integrating over the nuisance variable  $\sigma^2$ , i.e.,

$$P(\mu_x - \mu_y|D)$$
.



Inference of the differences of means is a special kind of posterior predictive inference:

$$\int P(\mu_x - \mu_y | \mu_x, \mu_y, \sigma^2) P(\mu_x, \mu_y, \sigma^2 | D) d\mu_x d\mu_y d\sigma^2.$$

- ▶ We can approach this problem using the methods we have used to deal with inference in the univariate normal distribution.
- ▶ We begin by assuming, as before,

$$\begin{split} &\mu_x \sim N(\mu_0, \sigma^2/\kappa_0), \\ &\mu_y \sim N(\mu_0, \sigma^2/\kappa_0), \\ &\sigma^2 \sim \text{Inv-}\chi^2(\nu_0, \sigma_0^2). \end{split}$$

Given that

$$P(\mu_x,\mu_y,\sigma^2|D) = P(\mu_x,\mu_y,|\sigma^2,D)P(\sigma^2|D)$$

From previous results, we see that

$$\begin{split} P(\mu_x, \mu_y, | \sigma^2, D) &= P(\mu_x | \sigma^2, D) P(\mu_y | \sigma^2, D), \\ &= N(\mu_n^x, \sigma^2 / \kappa_n^x) N(\mu_n^y, \sigma^2 / \kappa_n^y) \end{split}$$

where  $\mu_n^x$ ,  $\mu_n^y$ ,  $\kappa_n^x$  and  $\kappa_n^y$  are defined analogously with previous results.

As such,

$$\begin{split} &\int P(\mu_x - \mu_y | \mu_x, \mu_y, \sigma^2) P(\mu_x, \mu_y | \sigma^2, D) d\mu_x d\mu_y \\ &= N(\mu_n^x - \mu_n^y, \sigma^2 / \kappa_n^x + \sigma^2 / \kappa_n^y). \end{split}$$

For simplicity, let's assume  $\kappa_0 \doteq 0$ . In that case,

$$=N(\bar{x}-\bar{y},\frac{\sigma^2}{n}+\frac{\sigma^2}{m}).$$

► Integrating over  $\sigma^2$  as before leads to

$$\begin{split} &\int N(\bar{x}-\bar{y},\frac{\sigma^2}{n}+\frac{\sigma^2}{m})P(\sigma^2|D) \\ &=t_{\nu_n}\left(\bar{x}-\bar{y},\sigma_n^2\left(\frac{1}{n}+\frac{1}{m}\right)\right) \end{split}$$

► In the case of the non-informative prior case, i.e.,

$$P(\mu_x,\mu_y,\sigma^2) \propto \frac{1}{\sigma^2}$$

the marginal posterior over  $\mu_x - \mu_y$  is

$$P(\mu_{x} - \mu_{y}|D) = t_{\nu} \left(\bar{x} - \bar{y}, s^{2} \left(\frac{1}{n} + \frac{1}{m}\right)\right)$$

where

$$v = n + m - 2$$
,  $s^2 = \frac{(n_x - 1)s_x^2 + (n_y - 1)s_y^2}{n_x + n_y - 2}$ .

▶ This is an identical distribution to the sampling distribution of the difference of the means.