Model Checking

Lε

```
end procedure
                                                  end while;
                                         end for all;
                                        ; ii bns
                       \{i\} \cup T =: T
label(t) := label(t) \cup \{ \mathbf{EG} \ f_1 \};
                if EG f_1 \notin label(t) then
     for all t such that t \in S' and R(t, s) do
                                       \{s\} / T =: T
                                      choose s \in T;
                                           ob \emptyset \neq T slidw
 for all s \in T do label(s) := label(s) \cup \{EG \ f_1\};
                              T := \bigcup_{C \in SCC} \{s \mid s \in C\};
         SCC := \{ C \mid C \text{ is a nontrivial } SCC \text{ of } S' \};
                               \{(s)\mid pqpq \mid f \mid s\} =: S
                                       procedure CheckEG(f_1)
```

Figure 4.2
Procedure for labeling the states satisfying EG J.

is a path within C between any pair of states in C. Let  $s_1$  and  $s_2$  be states in C. Pick some instance of  $s_1$  on  $\pi_1$ . By the way in which  $\pi_1$  was selected, we know that there is an instance of  $s_2$  further along  $\pi_1$ . The segment from  $s_1$  to  $s_2$  lies entirely within C. This segment is a finite path from  $s_1$  to  $s_2$  in C. Thus, either C is a strongly connected component or it is contained within one. In either case, both conditions (1) and (2) are satisfied.

Next, assume that Conditions (1) and (2) are satisfied. Let  $\pi_0$  be the path from s to t. Let  $\pi_1$  be a finite path of length at least 1 that leads from t back to t. The existence of  $\pi_1$  is guaranteed because t is a state in a nontrivial strongly connected component. All the states on the infinite path  $\pi = \pi_0 \pi_1^{\omega}$  satisfy  $f_1$ . Since  $\pi$  is also a possible path starting at s in M, we see that M,  $s \models \mathbf{EG} f_1$ .

The algorithm for the case of  $g = \mathbf{EG} \ f_1$  follows directly from the lemma. We construct the restricted Kripke structure  $\mathbf{M}' = (S', R', L')$  as described above. We partition the graph (S', R') into strongly connected components using the algorithm of Tarjan [2]. This algorithm has time complexity O(|S'| + |R'|). Mext, we find those states that belong to nontrivial components. We then work backward using the converse of R' and find all of those states that can be reached by a path in which each state is labeled with  $f_1$ . The entire computation can be performed in time O(|S| + |R|). In Figure 4.2 we give a procedure