04_diff_prog

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1 Differentiable Programming 101

We study some initial examples of

- numerical differentiation
- symbolic differentiation
- automatic differentiation

2 Numerical Differentiation

Consider the sine function and its derivative,

$$f(x) = \sin(x), \quad f'(x) = \cos(x)$$

evaluated at the point x = 0.1.

```
[1]: import numpy as np
    f = lambda x: np.sin(x)
    x0 = 0.1
    exact = np.cos(x0)
    print("True derivative:", exact)
    print("Forward Difference\tError\t\t\tCentral Difference\tError\n")
    for i in range(10):
        h = 1/(10**i)
        f1 = (f(x0+h)-f(x0))/h
        f2 = (f(x0+h)-f(x0-h))/(2*h)
        e1 = np.abs(f1 - exact)
        e2 = np.abs(f2 - exact)
        print('%.5e\t\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\t\.5e\t\.5e\t\.5e\t\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5e\t\.5
```

True derivative: 0.9950041652780258 Forward Difference Error Central Difference Error 7.91374e-01 2.03630e-01 8.37267e-01 1.57737e-01 9.88359e-01 9.93347e-01 6.64502e-03 1.65751e-03 9.94488e-01 5.15746e-04 9.94988e-01

```
1.65833e-05
9.94954e-01
                         5.00825e-05
                                                  9.95004e-01
1.65834e-07
9.94999e-01
                         4.99333e-06
                                                  9.95004e-01
1.65828e-09
9.95004e-01
                         4.99183e-07
                                                  9.95004e-01
1.66720e-11
9.95004e-01
                         4.99136e-08
                                                  9.95004e-01
2.10021e-12
9.95004e-01
                         4.96341e-09
                                                  9.95004e-01
3.25943e-11
9.95004e-01
                         1.06184e-10
                                                  9.95004e-01
1.06184e-10
9.95004e-01
                         2.88174e-09
                                                  9.95004e-01
2.88174e-09
```

3 Symbolic Differentiation

Though very useful in simple cases, symbolic differentiation often leads to complex and redundant expressions. In addition, balkbox routines cannot be differentiated.

```
[2]: from sympy import *
x = symbols('x')
#
diff(cos(x), x)
```

[3]:
$$\frac{e^{-x}}{(1+e^{-x})^2}$$

Note that the derivative of

$$\sigma(x) = \frac{1}{1 + e^{-x}}$$

can be simply written as

$$\frac{d\sigma}{dx} = (1 - \sigma(x))\sigma(x)$$

```
[4]: # much more complicated
    x,w1,w2,w3,b1,b2,b3 = symbols('x w1 w2 w3 b1 b2 b3')
    y = w3*sigmoid(w2*sigmoid(w1*x + b1) + b2) + b3
    diff(y, w1)
```

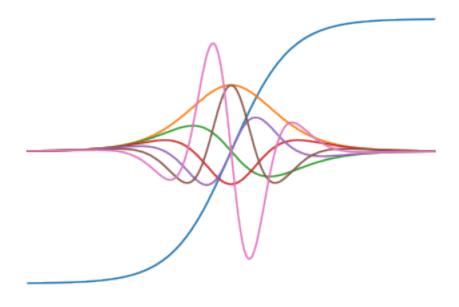
[4]:

```
\frac{w_2w_3xe^{-b_1-w_1x}e^{-b_2-\frac{w_2}{e^{-b_1-w_1x}+1}}}{\left(e^{-b_1-w_1x}+1\right)^2\left(e^{-b_2-\frac{w_2}{e^{-b_1-w_1x}+1}}+1\right)^2}
[5]: \frac{\mathrm{dydw1}=\mathrm{diff}(\mathtt{y},\ \mathtt{w1})}{\mathrm{print}(\mathrm{dydw1})}
w_2*w_3*x*\exp(-b_1-w_1*x)*\exp(-b_2-w_2/(\exp(-b_1-w_1*x)+1))/((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1))*((\exp(-b_1-w_1*x)+1)*((\exp(-b_1-
```

4 Automatic Differentiation

Here we show the simplicity and efficiency of autograd from numpy.

```
[6]: import autograd.numpy as np
     import matplotlib.pyplot as plt
     from autograd import elementwise_grad as egrad # for functions that vectorize_
     ⇔over inputs
     # We could use np.tanh, but let's write our own as an example.
     def tanh(x):
         return (1.0 - np.exp(-x)) / (1.0 + np.exp(-x))
     x = np.linspace(-7, 7, 200)
     plt.plot(x, tanh(x),
              x, egrad(tanh)(x),
                                                                # first derivative
             x, egrad(egrad(tanh))(x),
                                                                # second derivative
              x, egrad(egrad(egrad(tanh)))(x),
                                                                 # third derivative
              x, egrad(egrad(egrad(tanh))))(x),
                                                                  # fourth
      \rightarrow derivative
              x, egrad(egrad(egrad(egrad(tanh)))))(x), # fifth u
      \rightarrow derivative
              x, egrad(egrad(egrad(egrad(egrad(tanh))))))(x)) # sixth _
      \rightarrow derivative
     plt.axis('off')
     plt.savefig("tanh.png")
     plt.show()
```



```
[7]: from autograd import grad
grad_tanh = grad(tanh)  # Obtain its gradient function
gA = grad_tanh(1.0)  # Evaluate the gradient at x = 1.0
gN = (tanh(1.01) - tanh(0.99)) / 0.02 # Compare to finite differences
print(gA, gN)
```

 $0.39322386648296376\ 0.3932226889551027$

[]: