JHUML Final Project Submission

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Summary

The overall goal of this small project was to produce a prediction model to determine the quality of a performed exercise based on data from accelerometers. A final prediction model was produced by using a random forest based model. This final model was found to be reasonably accurate, with a final estimated (out-of-sample) accuracy of 93.9%.

Introduction

The goal of this project was to create a prediction model for determining the quality of exercise done by individuals based on accelerometers. A full description of this dataset and associated publications are available, as described in the course materials.

Results and Methods

In this section, a step-by-step description of the production and testing of the model is given.

Setup: load libraries and training data

Here, we also show a summary of all columns to indicate ones that we will end up eliminating.

```
library(caret)

## Loading required package: lattice

## Loading required package: ggplot2

library(e1071)
wltrain.full <- read.csv("C:\\Rstuff\\finalprojdata\\pml-training.csv")
#look at data
dim(wltrain.full)

## [1] 19622 160

table(wltrain.full$classe)

##
## A B C D E
## 5580 3797 3422 3216 3607</pre>
summary(wltrain.full)
```

```
## X user_name raw_timestamp_part_1 raw_timestamp_part_2 ## Min. : 1 adelmo :3892 Min. :1.322e+09 Min. : 294
## 1st Qu.: 4906 carlitos:3112 1st Qu.:1.323e+09 1st Qu.:252912
## Median : 9812 charles :3536 Median :1.323e+09 Median :496380
## Mean : 9812 eurico :3070 Mean :1.323e+09 Mean :500656
##
               cvtd_timestamp new_window num_window
                                                                          roll_belt
## 28/11/2011 14:14: 1498 no :19216 Min. : 1.0 Min. :-28.90
## 05/12/2011 11:24: 1497 yes: 406 1st Qu.:222.0 1st Qu.: 1.10
## 30/11/2011 17:11: 1440 Median :424.0 Median :113.00
## 05/12/2011 11:25: 1425 Mean :430.6 Mean : 64.41
## 02/12/2011 14:57: 1380
                                                   3rd Qu.:644.0 3rd Qu.:123.00
## 02/12/2011 13:34: 1375
                                                  Max. :864.0 Max. :162.00
## (Other) :11007
                          yaw_belt
##
      pitch_belt
                                                  total accel_belt kurtosis_roll_belt
## Min. :-55.8000 Min. :-180.00 Min. : 0.00 :19216
## 1st Qu.: 1.7600 1st Qu.: -88.30 1st Qu.: 3.00 #DIV/0! : 10
## Median : 5.2800 Median : -13.00 Median :17.00 -1.908453: 2
## Max. : 60.3000 Max. : 179.00 Max. :29.00 -0.025513:
                                                                          (Other) : 391
##
## kurtosis_picth_belt kurtosis_yaw_belt skewness_roll_belt
                              :19216
#DIV/0!: 406
              :19216
                                                        :19216
## #DIV/0! : 32
## 47.000000: 4
## -0.150950: 3
                                                  0.0000000 : 4
0.422463 : 2
                                                   -0.003095: 1
-0.010002: 1
## -0.684748: 3
## -1.750749:
                      3
## (Other) : 361
                                                   (Other) : 389
## skewness_roll_belt.1 skewness_yaw_belt max_roll_belt
                                                                            max picth belt
## #DIV/0! : 32
## 0.000000 : 4
## -2.156553: 3
                                                  Mean : -6.667 Mean :12.92
3rd Qu.: 18.500 3rd Qu.:19.00
Max. :180.000 Max. :30.00
## -3.072669:
## -6.324555: 3
## (Other) : 361
                                                     NA's :19216 NA's :19216
## max_yaw_belt min_roll_belt min_pitch_belt min_yaw_belt
## -1.1 : 30 Median : -7.85 Median :16.00 -1.4 : 29
## -1.2 : 26 Mean : -10.44 Mean :10.76 -1.2 : 26
## -0.9 : 24 3rd Qu.: 9.05 3rd Qu.:17.00 -0.9 : 24
## -1.3 : 22 Max. :173.00 Max. :23.00 -1.3 : 22
## (Other): 275 NA's :19216 NA's :19216 (Other): 275
## amplitude_roll_belt amplitude_pitch_belt amplitude_yaw_belt
## Min. : 0.000 Min. : 0.000 :19216
## lst Qu.: 0.300 lst Qu.: 1.000 #DIV/0!: 10
## Median : 1.000 Median : 1.000 0.00 : 12
## Mean : 3.769 Mean : 2.167 0.0000 : 384
## 3rd Qu.: 2.083 3rd Qu.: 2.000
## Max. :360.000 Max. :12.000
## NA's :19216 NA's :19216
## NA's :19216 NA's :19216
## var_total_accel_belt avg_roll_belt stddev_roll_belt var_roll_belt
## Min. : 0.000 Min. :-27.40 Min. : 0.000 Min. : 0.000
## lst Qu.: 0.100 lst Qu.: 1.10 lst Qu.: 0.200 lst Qu.: 0.000
## Median : 0.200 Median :116.35 Median : 0.400 Median : 0.100
## Mean : 0.926 Mean : 68.06 Mean : 1.337 Mean : 7.699
## 3rd Qu.: 0.300 3rd Qu.:123.38 3rd Qu.: 0.700 3rd Qu.: 0.500
## Max. :16.500 Max. :157.40 Max. :14.200 Max. :200.700
## NA's :19216 NA's :19216 NA's :19216 NA's :19216
## avg_pitch_belt stddev_pitch_belt var_pitch_belt avg_yaw_belt
## Min. :-51.400 Min. :0.000 Min. : 0.000 Min. :-138.300
## 1st Qu.: 2.025 1st Qu.:0.200 1st Qu.: 0.000 1st Qu.: -88.175
## Median : 5.200 Median :0.400 Median : 0.100 Median : -6.550
## Mean : 0.520 Mean :0.603 Mean : 0.766 Mean : -8.831
## 3rd Qu.: 15.775 3rd Qu.:0.700 3rd Qu.: 0.500 3rd Qu.: 14.125
## Max. : 59.700 Max. :4.000 Max. :16.200 Max. : 173.500
## NA's :19216 NA's :19216 NA's :19216 NA's :19216
## stddev_yaw_belt var_yaw_belt gyros_belt_x
## 1st Qu.: 0.100 1st Qu.: 0.010 1st Qu.:-0.030000
## Median: 0.300 Median: 0.090 Median: 0.030000
## Mean: 1.341 Mean: 107.487 Mean: -0.005592
\label{eq:continuous} \mbox{\#\# 3rd Qu.:} \quad \mbox{0.700} \quad \mbox{3rd Qu.:} \quad \mbox{0.475} \quad \mbox{3rd Qu.:} \quad \mbox{0.110000}
## Max. :176.600 Max. :31183.240 Max. :2.220000
## NA's :19216 NA's :19216
## gyros_belt_y gyros_belt_z accel_belt_x
## Min. :-0.64000 Min. :-1.4600 Min. :-120.000 Min. :-69.00
## 1st Qu.: 0.00000 1st Qu.:-0.2000 1st Qu.: -21.000 1st Qu.: 3.00
## Median : 0.02000 Median :-0.1000 Median : -15.000 Median : 35.00
## Mean : 0.03959 Mean :-0.1305 Mean : -5.595 Mean : 30.15
```

```
## 3rd Qu.: 0.11000 3rd Qu.:-0.0200 3rd Qu.: -5.000 3rd Qu.: 61.00
 ## Max. : 0.64000 Max. : 1.6200 Max. : 85.000 Max. :164.00
##
 ##
    accel helt z
                      magnet_belt_x magnet_belt_y magnet_belt_z
 ## Min. :-275.00 Min. :-52.0 Min. :354.0 Min. :-623.0
 ## 1st Qu.:-162.00 1st Qu.: 9.0 1st Qu.:581.0 1st Qu.:-375.0
 ## Median :-152.00
                      Median : 35.0 Median :601.0
                                                        Median :-320.0
 ## Mean : -72.59 Mean : 55.6 Mean :593.7 Mean :-345.5
 ## 3rd Qu.: 27.00 3rd Qu.: 59.0 3rd Qu.:610.0 3rd Qu.:-306.0
 ## Max. : 105.00 Max. :485.0 Max. :673.0 Max. : 293.0
 ##
       roll_arm
                        pitch_arm
                                                               total_accel_arm
                                            yaw_arm
 ## Min. :-180.00 Min. :-88.800 Min. :-180.0000 Min. : 1.00
 ## 1st Qu.: -31.77 1st Qu.:-25.900 1st Qu.: -43.1000 1st Qu.:17.00
## Median : 0.00 Median : 0.000 Median : 0.0000 Median :27.00
## Mean : 17.83 Mean : -4.612 Mean : -0.6188 Mean :25.51
## 3rd Qu.: 77.30 3rd Qu.: 11.200 3rd Qu.: 45.8750 3rd Qu.:33.00
 ## Max. : 180.00 Max. : 88.500 Max. : 180.0000 Max. :66.00
 ##
                      avg_roll_arm
                                         stddev_roll_arm
## var accel arm
                                                            var_roll_arm
## Min. : 0.00 Min. :-166.67 Min. : 0.000 Min. : 0.000 ## 1st Qu.: 9.03 1st Qu.: -38.37 1st Qu.: 1.376 1st Qu.: 1.898
 ## Median : 40.61
                     Median: 0.00 Median: 5.702 Median: 32.517
                      Mean : 12.68 Mean : 11.201 Mean : 417.264
 ## Mean : 53.23
 ## 3rd Qu.: 75.62 3rd Qu.: 76.33 3rd Qu.: 14.921 3rd Qu.: 222.647
## Max. :331.70 Max. : 163.33 Max. :161.964 Max. :26232.208
## NA's :19216 NA's :19216 NA's :19216 NA's :19216
## avg_pitch_arm stddev_pitch_arm var_pitch_arm avg_yaw_arm ## Min. :-81.773 Min. : 0.000 Min. : 0.000 Min. :-173.440
 ## 1st Qu.:-22.770 1st Qu.: 1.642 1st Qu.: 2.697 1st Qu.: -29.198
## Median: 0.000 Median: 8.133 Median: 66.146 Median: 0.000 ## Mean: -4.901 Mean: 10.383 Mean: 195.864 Mean: 2.359
## 3rd Qu.: 8.277 3rd Qu.:16.327 3rd Qu.: 266.576 3rd Qu.: 38.185
## Max. : 75.659 Max. :43.412 Max. :1884.565 Max. : 152.000
 ## NA's :19216 NA's :19216 NA's :19216 NA's :19216
 ## stddev_yaw_arm
                       var_yaw_arm
                                            gyros_arm_x
## Min.: 0.000 Min.: 0.000 Min.:-6.37000
## 1st Qu.: 2.577 1st Qu.: 6.642 1st Qu.:-1.33000
 ## Median : 16.682 Median : 278.309 Median : 0.08000
 ## Mean : 22.270 Mean : 1055.933 Mean : 0.04277
## 3rd Qu.: 35.984 3rd Qu.: 1294.850 3rd Qu.: 1.57000
 ## Max. :177.044 Max. :31344.568 Max. : 4.87000
                              :19216
 ## NA's
           :19216 NA's
 ## gyros arm v
                       gyros arm z
                                          accel arm x
                                                             accel arm v
## 1st Qu.:-0.8000 1st Qu.:-0.0700 1st Qu.:-242.00 1st Qu.:-54.0
 ## Median :-0.2400 Median : 0.2300 Median : -44.00 Median : 14.0
 ## Mean :-0.2571 Mean : 0.2695 Mean : -60.24
 ## 3rd Qu.: 0.1400 3rd Qu.: 0.7200 3rd Qu.: 84.00 3rd Qu.: 139.0
 ## Max. : 2.8400 Max. : 3.0200 Max. : 437.00 Max. : 308.0
##
 ##
    accel arm z
                        magnet_arm_x
                                         magnet arm v
                                                           magnet arm z
 ## Min. :-636.00 Min. :-584.0 Min. :-392.0 Min. :-597.0
 ## 1st Qu.:-143.00 1st Qu.:-300.0 1st Qu.: -9.0 1st Qu.: 131.2
 ## Median : -47.00 Median : 289.0 Median : 202.0
                                                          Median : 444.0
## Mean : -71.25 Mean : 191.7 Mean : 156.6 Mean : 306.5
 ## 3rd Qu.: 23.00 3rd Qu.: 637.0 3rd Qu.: 323.0 3rd Qu.: 545.0
## Max. : 292.00 Max. : 782.0 Max. : 583.0 Max. : 694.0
 ## kurtosis_roll_arm kurtosis_picth_arm kurtosis_yaw_arm skewness_roll_arm
## -0.05695: 1 -0.07394: 1 -0.01749: 1 -0.03359: 1
## (Other): 324 (Other): 322 (Other): 389 (Other): 5
## :19216 :19216 Min. :-73.100 Min. :-173.000
## #DIV/0! : 80 #DIV/0! : 11 Ist Qu.: -0.175 Ist Qu.: -1.975
## -0.00184: 1 -1.62032: 2 Median: 4.950 Median: 23.250

## -0.01185: 1 0.55053: 2 Mean : 11.236 Mean : 35.751

## -0.01247: 1 -0.00311: 1 3rd Qu.: 26.775 3rd Qu.: 95.975

## -0.02063: 1 -0.00562: 1 Max. : 85.500 Max. : 180.000

## (Other): 322 (Other): 389 NA's :19216 NA's :19216
## max_yaw_arm min_roll_arm min_pitch_arm min_yaw_arm ## Min. : 4.00 Min. :-89.10 Min. :-180.00 Min. : 1.00
 ## 1st Qu.:29.00 1st Qu.:-41.98 1st Qu.: -72.62 1st Qu.: 8.00
 ## Median :34.00 Median :-22.45 Median : -33.85 Median :13.00
 ## Mean :35.46 Mean :-21.22 Mean :-33.92 Mean :14.66
 ## 3rd Qu.:41.00 3rd Qu.: 0.00 3rd Qu.: 0.00 3rd Qu.:19.00
 ## Max. :65.00 Max. : 66.40 Max. : 152.00 Max. :38.00
 ## NA's :19216 NA's :19216 NA's :19216 NA's :19216
 ## amplitude_roll_arm amplitude_pitch_arm amplitude_yaw_arm
 ## Min. : 0.000 Min. : 0.000 Min. : 0.00
```

```
## 1st Qu.: 5.425 1st Qu.: 9.925 1st Qu.:13.00
## Median: 28.450 Median: 54.900 Median: 22.00
## Mean: 32.452 Mean: 69.677 Mean: 20.79
## 3rd Qu.: 50.960 3rd Qu.:115.175 3rd Qu.:28.75
## Max. :119.500 Max. :360.000 Max. :52.00
## NA's :19216 NA's :19216 NA's :19216
## roll_dumbbell pitch_dumbbell yaw_dumbbell
## Min. :-153.71 Min. :-149.59 Min. :-150.871
## 1st Qu.: -18.49 1st Qu.: -40.89 1st Qu.: -77.644 ## Median: 48.17 Median: -20.96 Median: -3.324
 ## Mean : 23.84 Mean : -10.78 Mean : 1.674
     3rd Qu.: 67.61 3rd Qu.: 17.50 3rd Qu.: 79.643
 ## Max. : 153.55 Max. : 149.40 Max. : 154.952
 ##
 ## kurtosis_roll_dumbbell kurtosis_picth_dumbbell kurtosis_yaw_dumbbell
               :19216 · -0.5464: 2
                                                    :19216
 ##
                                                                                           :19216
                                                                       #DIV/0!: 406
 ## #DIV/0!: 5
## -0.2583: 2 -0.9334: 2

## -0.3705: 2 -2.0833: 2

## -0.5855: 2 -2.0851: 2

## -2.0851: 2 -2.0889: 2

## (Other): 393 (Other): 396
 ## skewness_roll_dumbbell skewness_pitch_dumbbell skewness_yaw_dumbbell
               :19216
 ## #DIV/0!: 4
## # -0.9324: 2 -0.3521: 2
## 0.1110: 2 -0.7036: 2
## 1.0312: 2 0.1090: 2
## -0.0082: 1 1.0326: 2
## (Other): 395 (Other): 396
 ## max_roll_dumbbell max_picth_dumbbell max_yaw_dumbbell min_roll_dumbbell
## max_roll_dumbbell max_picth_dumbbell max_yaw_dumbbell min_roll_dumbbel
## Min. :-70.10 Min. :-112.90 : 19216 Min. :-149.60
## lst Qu.:-27.15 lst Qu.: -66.70 -0.6 : 20 lst Qu.: -59.67
## Median : 14.85 Median : 40.05 0.2 : 19 Median : -43.55
## Mean : 13.76 Mean : 32.75 -0.8 : 18 Mean : -41.24
## 3rd Qu.: 50.58 3rd Qu.: 133.22 -0.3 : 16 3rd Qu.: -25.20
## Max. :137.00 Max. : 155.00 -0.2 : 15 Max. : 73.20
MA's :19216 NA's :19216 (Other): 318 NA's :19216
 ## min_pitch_dumbbell min_yaw_dumbbell amplitude_roll_dumbbell
## amplitude_pitch_dumbbell amplitude_yaw_dumbbell total_accel_dumbbell
 ## Min.: 0.00 :19216 Min.: 0.00
## 1st Qu.: 17.06 #DIV/0!: 5 1st Qu.: 4.00
## Median: 41.73 0.00: 401 Median: 10.00
## Mean : 65.93
                                                                                 Mean :13.72
 ## 3rd Ou : 99 55
                                                                                  3rd Ou.:19.00
 ## Max. :273.59
                                                                                  Max. :58.00
 ## NA's :19216
 ## var_accel_dumbbell avg_roll_dumbbell stddev_roll_dumbbell
## Min. : 0.000 Min. :-128.96 Min. : 0.000
## 1st Qu.: 0.378 1st Qu.: -12.33 1st Qu.: 4.639
## Median : 1.000 Median : 48.23 Median : 12.204
## Mean : 4.388 Mean : 23.86 Mean : 20.761
## 3rd Qu.: 3.434 3rd Qu.: 64.37 3rd Qu.: 26.356
## Max. :230.428 Max. : 125.99 Max. :123.778
 ## NA's :19216
                                   NA's :19216
                                                               NA's :19216
## var_roll_dumbbell avg_pitch_dumbbell stddev_pitch_dumbbell
## Min. : 0.00 Min. :-70.73 Min. : 0.000 ## 1st Qu.: 21.52 1st Qu.:-42.00 1st Qu.: 3.482
## Max. :15321.01 Max. :94.28 Max. :82.680
## NA's :19216 NA's :19216 NA's :19216
 ## var_pitch_dumbbell avg_yaw_dumbbell stddev_yaw_dumbbell
## Min. : 0.00 Min. :-117.950 Min. : 0.000 ## 1st Qu.: 12.12 1st Qu.: -76.696 1st Qu.: 3.885
## Median: 65.44 Median: -4.505 Median: 10.264
## Mean: 350.31 Mean: 0.202 Mean: 16.647
## Mean . 350.31 Mean . 0.202 Mean . 16.647

## 3rd Qu.: 370.11 3rd Qu.: 71.234 3rd Qu.: 24.674

## Max. :6836.02 Max. : 134.905 Max. :107.088

## NA's :19216 NA's :19216 NA's :19216

## var_yaw_dumbbell gyros_dumbbell_x gyros_dumbbell_
                                                                  gyros_dumbbell_y
## Min. : 0.00 Min. :-204.0000 Min. :-2.10000
## 1st Qu.: 15.09 1st Qu.: -0.0300 1st Qu.:-0.14000
## Median : 105.35 Median : 0.1300 Median : 0.03000
 ## Mean : 589.84 Mean : 0.1611 Mean : 0.04606
## 3rd Qu.: 608.79 3rd Qu.: 0.3500 3rd Qu.: 0.21000
## Max. :11467.91 Max. : 2.2200 Max. :52.00000
```

```
## NA's :19216
 ## gyros dumbbell z accel dumbbell x accel dumbbell z
## Min. : -2.380 Min. :-419.00 Min. :-189.00 Min. :-334.00
 ## 1st Qu.: -0.310 1st Qu.: -50.00 1st Qu.: -8.00 1st Qu.:-142.00
 ## Median : -0.130 Median : -8.00 Median : 41.50 Median : -1.00
 ## Mean : -0.129 Mean : -28.62 Mean : 52.63 Mean : -38.32
 ## 3rd Qu.: 0.030 3rd Qu.: 11.00 3rd Qu.: 111.00 3rd Qu.: 38.00
## Max. :317.000 Max. : 235.00 Max. : 315.00 Max. : 318.00
 ##
## magnet_dumbbell_x magnet_dumbbell_y magnet_dumbbell_z roll_forearm
 ## Min. :-643.0 Min. :-3600 Min. :-262.00 Min. :-180.0000
     1st Qu.:-535.0
                                                              1st Qu.: -45.00
                                 1st Ou.: 231
                                                                                          1st Ou.: -0.7375
## Median :-479.0
                                Median : 311
                                                              Median: 13.00 Median: 21.7000
## Mean :-328.5 Mean : 221 Mean : 46.05 Mean : 33.8265
## 3rd Qu::-304.0 3rd Qu:: 390 3rd Qu:: 95.00 3rd Qu:: 140.0000
 ## Max. : 592.0 Max. : 633 Max. : 452.00 Max. : 180.0000
 ##
                                yaw_forearm
 ## pitch_forearm
                                                          kurtosis_roll_forearm
 ## Min. :-72.50 Min. :-180.00
                                                                 :19216
## 1st Qu.: 0.00 1st Qu.: -68.60 #DIV/0!: 84
## Median : 9.24 Median : 0.00 -0.8079:
## Mean : 10.71 Mean : 19.21 -0.9169:
 ## 3rd Qu.: 28.40 3rd Qu.: 110.00 -0.0227:
 ## Max. : 89.80 Max. : 180.00 -0.0359:
                                                            (Other): 316
 ## kurtosis_picth_forearm kurtosis_yaw_forearm skewness_roll_forearm
## :19216 :19216 :19216 :19216 #DIV/0!: 85 #DIV/0!: 406 #DIV/0!: 83
## #DIV/0!: 85
## -0.0073: 1
                                                                         #DIV/0!: 83
                                                                          -0.1912:
                                                                          -0.4126:
 ## -0.0442: 1
 ## -0.0489:
                                                                           -0.0004:
## -0.0523:
                                                                          -0.0013:
 ## (Other): 317
                                                                          (Other): 317
## skewness_pitch_forearm skewness_yaw_forearm max_roll_forearm
        :19216 :19216 Min. :-66.60

PDIV/0!: 85 #DIV/0!: 406 1st Qu.: 0.00
## #DIV/0!: 85
 ## 0.0000 : 4
                                                                         Median : 26.80
 ## -0.6992:
                                                                          Mean : 24.49
## -0.0113: 1
                                                                          3rd Ou.: 45.95
 ## -0.0131:
                       1
                                                                           Max. : 89.80
NA's :19216
## (Other): 313
 ## max_picth_forearm max_yaw_forearm min_roll_forearm min_pitch_forearm
 ## Min. :-151.00
                                           :19216 Min. :-72.500 Min. :-180.00
## 1st Qu.: 0.00 #DIV/0!: 84 1st Qu.: -6.075 1st Qu.:-175.00
## NA's :19216 (Other): 211 NA's :19216 NA's :19216
 ## min_yaw_forearm amplitude_roll_forearm amplitude_pitch_forearm
## #DIV/0!: 84 lst Qu.: 1.125 lst Qu.: 2.0
## -1.2 : 32 Median : 17.770 Median : 83.7
## -1.3 : 31 Mean : 24.653 Mean :139.1
## -1.4 : 24 3rd Qu.: 39.875 3rd Qu.: 350.0
## -1.5 : 24 Max. :126.000 Max. :360.0
## (Other): 211 NA's :19216 NA's :19216
## amplitude_yaw_forearm total_accel_forearm var_accel_forearm
## :19216 Min. : 0.00 Min. : 0.00
## #DIV/0!: 84 1st Qu.: 29.00 1st Qu.: 6.759
## 0.00 : 322 Median : 36.00 Median : 21.165
                                       Median : 36.00 Median : 21.165
                                       Mean : 34.72 Mean : 33.502
3rd Qu.: 41.00 3rd Qu.: 51.240
##
##
                                     Max. :108.00 Max. :172.606
NA's :19216
##
##
 ## avg_roll_forearm stddev_roll_forearm var_roll_forearm
## Min. :-177.234 Min. : 0.000 Min. : 0.00
## 1st Qu.: -0.909 1st Qu.: 0.428 1st Qu.: 0.18
## Median: 11.172 Median: 8.030 Median: 64.48
## Mean: 33.165 Mean: 41.986 Mean: 5274.10
## avg_pitch_forearm stddev_pitch_forearm var_pitch_forearm
## Min. :-68.17 Min. : 0.000 Min. : 0.000
## 1st Qu.: 0.00 1st Qu.: 0.336 1st Qu.: 0.113 ## Median: 12.02 Median: 5.516 Median: 30.425 ## Mean : 11.79 Mean : 7.977 Mean : 139.593 ## 3rd Qu.: 28.48 3rd Qu.: 12.866 3rd Qu.: 165.532 ## Max. : 72.09 Max. : 47.745 Max. : 2279.617 ## NA's : 19216 NA
 ## NA's :19216
                                NA's :19216
                                                                 NA's :19216
 ## avg_yaw_forearm stddev_yaw_forearm var_yaw_forearm
                                                                                            qyros_forearm_x
## Min. :-155.06 Min. : 0.000 Min. : 0.00 Min. :-22.000
## 1st Qu.: -26.26 1st Qu.: 0.524 1st Qu.: 0.27 1st Qu.: -0.220
 ## Median : 0.00 Median : 24.743 Median : 612.21 Median : 0.050
```

```
## Mean : 18.00 Mean : 44.854 Mean : 4639.85 Mean : 0.158
## 3rd Qu.: 85.79 3rd Qu.: 85.817 3rd Qu.: 7368.41 3rd Qu.: 0.560 ## Max. : 169.24 Max. :197.508 Max. :39009.33 Max. : 3.970
## NA's :19216 NA's :19216 NA's :19216
## gyros_forearm_y
                      gyros_forearm_z accel_forearm_x accel_forearm_y
## Min. : -7.02000 Min. : -8.0900 Min. :-498.00 Min. :-632.0
## 1st Qu.: -1.46000 1st Qu.: -0.1800 1st Qu.:-178.00 1st Qu.: 57.0
## Median: 0.03000 Median: 0.0800 Median: -57.00 Median: 201.0
## Mean : 0.07517 Mean : 0.1512 Mean : -61.65 Mean : 163.7
## 3rd Qu.: 1.62000 3rd Qu.: 0.4900 3rd Qu.: 76.00 3rd Qu.: 312.0
## Max. :311.00000 Max. :231.0000 Max. : 477.00 Max. : 923.0
## accel_forearm_z magnet_forearm_x magnet_forearm_y magnet_forearm_z
## Min. :-446.00 Min. :-1280.0 Min. :-896.0 Min. :-973.0
## 1st Qu.:-182.00 1st Qu.: -616.0 1st Qu.: 2.0 1st Qu.: 191.0
## Median : -39.00 Median : -378.0 Median : 591.0 Median : 511.0
## Mean : -55.29 Mean : -312.6 Mean : 380.1 Mean : 393.6
## 3rd Qu.: 26.00 3rd Qu.: -73.0 3rd Qu.: 737.0 3rd Qu.: 653.0
## Max. : 291.00 Max. : 672.0 Max. :1480.0 Max. :1090.0
##
## classe
## A:5580
## B:3797
## C:3422
## E:3607
##
```

FIRST LOOK CONCLUSIONS ON DATASET

There were reasonable number at each level in classe, so we don't have to worry about some levels of classe being poorly represented in samples. The data features many variables that have large numbers of missing values (NA) or values that are not numbers, such as apparent division by zero errors.

The modeling strategy will begin by deleting these columns and producing a model using the remaining columns. Also, the first loaded column (which just corresponds to a row number) and the time columns will be deleted to avoid dependence on time values.

In addition, columns concerning the window number will be deleted, as these may also be direct indices to the final classe variable.

INITIAL DATA EXPLORATION

Initial data exploration demonstrated that there was a large amount of cases and only 5 levels of "classe". So this implies that a smaller subset should be adequate. Use of a small subset in this case is particularly appropriate, given limitations in computer power.

Initial training will be done with 10% of the data. A further internal testing set was created with the remaining 90% of the full dataset. All were created using the createDatapartition function from the caret library to allow a reasonable sampling.

To determine if the 10% is adequate, the performance on the remaining dataset was examined. If the performance on these addition sets of data is poor, then this could be due to poor modeling or a sampling issue.

CREATING THE 10% dataset

```
#try 10% to begin
set.seed(505)
tenperdex <- createDataPartition(wltrain.full$classe,p=0.1,list=FALSE)
wl.small <- wltrain.full{tenperdex, }</pre>
```

Eliminating columns that have NAs or bad values or are linked directly to the final groups

All of these columns may cause problems. I chose to eliminate many columns that seemed like they would have correlations with the final classe variable solely due to things like the observations being in a certain order. Inspection of columns using the summary() function led to the deletion of several columns.

```
wl.small.nona <- wl.small[sapply(wl.small, function(x) !any(is.na(x)))]
#now, kill more that have bad values in them
badklist <- grep("kurtosis",colnames(wl.small.nona))
badslist <- grep("skewness",colnames(wl.small.nona))
badyawlist <- grep("_yaw_",colnames(wl.small.nona))
totbad <- c(badklist,badslist,badyawlist)

wl.small.v2 <- wl.small.nona[ , -totbad]
#kill the time columns
wl.small.v3 <- wl.small.v2[ , -c(3,4,5)] #eliminate some time columns
wl.small.v4 <- wl.small.v3[ , -c(1)] #eliminate row index column
wl.small.v5 <- wl.small.v4[ , -c(2,3)] #eliminate some final ones that seem to be falsely correlated</pre>
```

Make the testing group

```
wl.remainder <- wltrain.full[-tenperdex, ]</pre>
```

Make RandomForest model and performing predictions on the remaining 90% test set.

For random forest, we used cross-validation with 4 sets. We choose random forest because this modeling approach was repeatedly mentioned to give good results in lectures, based on performance in competitions. We also tried linear discriminant analysis (data not shown) but models performed relatively poorly with high misclassification rates.

```
Note that the last lines of code indicate the predictions for the test set and the misclassification level.
 wl.small.v5.rf3 <- train(classe ~ ., method="rf", data=wl.small.v5,trControl=trainControl(method="cv",number=4), p
 rox=TRUE, allowParallel=TRUE)
 ## Loading required package: randomForest
 ## randomForest 4.6-12
 ## Type rfNews() to see new features/changes/bug fixes.
 ## Attaching package: 'randomForest'
 ## The following object is masked from 'package:ggplot2':
 ##
 ##
        margin
 rfpred <- predict(wl.small.v5.rf3,wl.remainder)
 confusionMatrix(rfpred,wl.remainder$classe)
 ## Confusion Matrix and Statistics
 ##
             Reference
 ##
 ## Prediction A B C D E ## A 4954 248 0 31 5
             B 32 3013 234 14 36
           C 28 149 2799 144 46
D 5 4 45 2693 31
E 3 3 1 12 3128
 ##
 ##
 ##
 ## Overall Statistics
                   Accuracy: 0.9393
 ##
                      95% CI : (0.9357, 0.9428)
      No Information Rate : 0.2844
 ##
 ##
       P-Value [Acc > NIR] : < 2.2e-16
 ##
                       Kappa : 0.9232
 ## Mcnemar's Test P-Value : < 2.2e-16
 ##
 ## Statistics by Class:
 ##
                        Class: A Class: B Class: C Class: D Class: E
                          0.9865 0.8818 0.9091 0.9305 0.9636
 ## Sensitivity
 ## Specificity
                           0.9775 0.9778 0.9748 0.9942 0.9987
## Pos Pred Value 0.9458 0.9051 0.8841 0.9694 0.9940  
## Neg Pred Value 0.9945 0.9718 0.9807 0.9865 0.9919  
## Prevalence 0.2844 0.1935 0.1744 0.1639 0.1838  
## Detection Rate 0.2806 0.1706 0.1585 0.1525 0.1771
 ## Detection Prevalence 0.2966 0.1885 0.1793 0.1573 0.1782
 ## Balanced Accuracy 0.9820 0.9298 0.9419 0.9624 0.9812
 misClassified <- function(vals, preds) {
     sum(preds != vals)/length(vals)}
 misClassified(wl.remainder$classe,rfpred)
 ## [1] 0.0606524
```

FINAL CONCLUSIONS

The accuracy of 93.9% implies a reasonable out-of-sample error rate, as measured by misclassification (6.1%). This misclassification rate is somewhat troubling and additional studies seem warranted