Lecture 11 – 2-D Stability Analysis – Competition Part 2

Today: Formal stability analysis of two-species competition equilibria **Next class** move on to Consumer-Resource & nonlinear interactions.

Evaluate stability of equilibria

Just as for 1 species model:

Step #1: Solve for N^* steady state equilibria

Step #2: Find f' and evaluate at N^*

Let's use non-dimensionalized version of the LV-competition model! Let:

$$\begin{split} u_1 &= \frac{N_1}{K_1} \qquad u_2 = \frac{N_2}{K_2} \qquad \quad \tau = r_1 t \\ \rho &= \frac{r_2}{r_1} \qquad a_{12} = \alpha_{12} \frac{K_2}{K_1} \qquad a_{21} = \alpha_{21} \frac{K_1}{K_2} \end{split}$$

 u_i - % of carrying capacity

 τ - 'growth time'

 ρ - relative growth rates

 a_{ij} - relative resource requirements

New model becomes:

$$\frac{du_1}{d\tau} = u_1(1 - u_1 - a_{12}u_2) \qquad \frac{du_2}{d\tau} = \rho u_2(1 - u_2 - a_{21}u_1)$$

⇒ Mathematica 'Class10-LVcompetition-nonDim'

Isoclines:

$$u_1^* = \frac{1 - u_2}{a_{21}} \qquad u_2^* = \frac{1 - u_1}{a_{12}}$$

Step #1: Solve for u^* steady state equilibria

$$(u_1^*, u_2^*) = \begin{cases} 0, & 0\\ 0, & 1\\ 1, & 0\\ \frac{1 - a_{12}}{1 - a_{12} a_{21}}, & \frac{1 - a_{21}}{1 - a_{12} a_{21}} \end{cases}$$

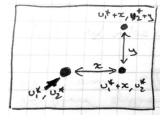
Step #2: Evaluate $f'(N^*)$

...but now in two dimensions: $f'_1(N_1^*, N_2^*)$ and $f'_2(N_1^*, N_2^*)$

\Rightarrow Stability analysis in two dimensions \Leftarrow

Perturbation to both u_1^* and u_2^* by amounts x and y.

$$u_1 = u_1^* + x$$
 $u_2 = u_2^* + y$
 $\Rightarrow x = u_1^* - u_1$ $y = u_2^* - u_2$



Thus:

$$\frac{du_1}{d\tau} = \frac{d(u_1^* + x)}{d\tau} = f_1(u_1^* + x, u_2^* + y)$$

and

$$\frac{du_2}{d\tau} = \frac{d(u_2^* + y)}{d\tau} = f_2(u_1^* + x, u_2^* + y)$$

Because u_1^* and u_2^* are constants w.r.t $\tau...$

$$\frac{dx}{d\tau} = \frac{du_1}{d\tau}$$
and
$$\frac{dy}{d\tau} = \frac{du_2}{d\tau}$$

Recall that we approximated response of single-sp. perturbation using a Taylor expansion:

$$f(N^* + n_t) \approx f(N^*) + f'(N^*) \cdot n_t + h.o.t.$$

Do same thing in two dimensions (note use of partial derivatives):

To simplify syntax, let's denote $f_i(u_1^*, u_2^*) = f_i$

(i.e. f_i is implicitly evaluated at steady state abundances)

$$f_{1}(u_{1}^{*} + x, u_{2}^{*} + y) = f_{1}(u_{1}^{*}, u_{2}^{*}) + \frac{\partial f_{1}}{1! \partial u_{1}} \cdot x + \frac{\partial^{2} f_{1}}{2! \partial u_{1}^{2}} \cdot x^{2} + \dots$$

$$\dots + \frac{\partial f_{1}}{1! \partial u_{2}} \cdot y + \frac{\partial^{2} f_{1}}{2! \partial u_{2}^{2}} \cdot y^{2} + h.o.t.$$

$$\approx f_{1}(u_{1}^{*}, u_{2}^{*}) + \frac{\partial f_{1}}{\partial u_{1}} \Big|_{u_{1}^{*}, u_{2}^{*}} \cdot x + \frac{\partial f_{1}}{\partial u_{2}} \Big|_{u_{1}^{*}, u_{2}^{*}} \cdot y$$

Since at steady-state (by definition)...

$$f_1(u_1^*, u_2^*) = 0$$

...we can simplify further to:

$$f_1(u_1^* + x, u_2^* + y) \approx \underbrace{\frac{\partial f_1}{\partial u_1}\Big|_{u_1^*, u_2^*}}_{A_{11}} \cdot x + \underbrace{\frac{\partial f_1}{\partial u_2}\Big|_{u_1^*, u_2^*}}_{A_{12}} \cdot y$$

Similarly

$$f_2(u_1^* + x, u_2^* + y) \approx \underbrace{\frac{\partial f_2}{\partial u_1}\Big|_{u_1^*, u_2^*}}_{A_{21}} \cdot x + \underbrace{\frac{\partial f_2}{\partial u_2}\Big|_{u_1^*, u_2^*}}_{A_{22}} \cdot y$$

Organize these elements into a Jacobian matrix:

$$\mathbf{A} = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix}.$$

Jacobian contains the partial derivatives of each i^{th} variable's function f_i w.r.t j.

A is referred to as the *Community matrix* when f_i 's reflect population growth rates (i.e. $f_i = \frac{dN_i}{dt}$).

Interpretation of elements:

How a small perturbation to j affects the population growth rate of i with other species held constant

The Jacobian's eigenvalues provide insight into the stability of the steady state(s). We will return to this in more detail next time.

For now note that eigenvalues can have both 'Real' and 'Imaginary' parts...

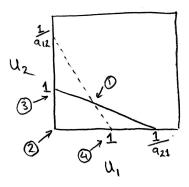
| $\overline{\text{Eigenvalues }(\lambda_i)}$ | Interpretation |
|---|---|
| All parts < 0 | Stable point attractor |
| Some real parts < 0 | Saddle equilibrium (repellor-attractor) |
| No real parts < 0 | Unstable point repellor |
| Real parts $= 0$ | Neutral stability |
| No imaginary parts | No oscillations |
| With imaginary parts | Oscillations |

Evaluate eigenvalues of LV-competition equilibria

 \Rightarrow Mathematica 'Class11-LVcompetition-nonDim'

When $\alpha_{ii} > \alpha_{ij}$

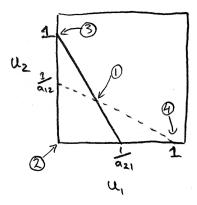
(intra- is stronger than inter-specific competition)...



- 1 Both $\lambda' s < 0 \Rightarrow$ Stable coexistence
- ② Both $\lambda' s > 0 \Rightarrow$ Unstable ③ $\lambda_1 > 0 \& \lambda_2 < 0 \Rightarrow$ unstable (attractor-repellor)
- $\overline{4}$ $\lambda_1 < 0 \ \& \ \lambda_2 > 0 \Rightarrow$ unstable (attractor-repellor)
- (3) and (4) are mutually invasible

When $\alpha_{ii} > \alpha_{ij} \& \alpha_{jj} < \alpha_{ji}$

(inter- is stronger than intra-specific competition for one species but not the other)...



- (1) $\lambda_1 < 0 \& \lambda_2 > 0 \Rightarrow \text{unstable (attractor-repellor)}$
- (2) Both $\lambda' s > 0 \Rightarrow$ Unstable
- (3) Both $\lambda' s < 0 \Rightarrow$ Stable
 - ...could do for third and fourth scenarios too.