MT08 - Markose Jacob, Pooja Kabra Acme Ackermann Steering Controller Product Backlog

Use index colors to show revisions on task time

1 Todast Basinog							Use index colors to show revisions on task tim			
Unique ID	Task	Sprint	Estimated time (minutes)	Time after Iteration 1	Time after Iteration 2	Index	Information			
							Target Time			
1	Plan and Design		325	0	0		Revised Target Time			
1.01	Link github repo with travis CI	1	10				Actual Time Taken			
1.02	Link github repo with Coveralls	1	10				New Task Added			
1.03	Create skeleton code for Sensor class	1	10				New Idok/idded	-		
1.04	Write constructors and destructors for Sensor class	1	10							
1.05	Create unit tests for Sensor class	1	20							
1.05	Write getters for Sensor class	1	10							
1.00	Write setters for Sensor class	1	10							
1.07	Create skeleton code for RobotKinematics class	1	10							
1.09	Write constructors and destructors for RobotKinematics class	1	10							
1.09		1	20							
1.11	Create unit tests for RobotKinematics Class	1	10							
1.11	Write getters for RobotKinematics class	1	10							
1.12	Write setters for RobotKinematics class	1	20							
1.13	Inspect source code Create skeleton code for Controller class	2	20							
1.14	Write constructors and destructors for Controller class	2	10							
1.15	Create unit tests for Controller class	2	20							
1.17		2	10							
1.17	Write getters for Controller class Write setters for Controller class	2	10							
1.19		2	10							
1.19	Create skeleton code for ForwardKinematics class Write constructors and destructors for ForwardKinematics class	2	10							
1.21	Create skeleton code for InverseKinematics class	2	10							
		2	20							
1.22	Inspect source code	2	25							
1.23	Inspect unit test	2	20							
1.24	Update readme	4	20							
2	Implementation		410	0	0					
2.01	•		20		Ů					
	Implement calculateHeadingError method	3								
2.02	Create unit test for calculateHeadingError	3	20							
2.03	Implement calculateSpeedError method	3	20							
2.04	Create unit test for calculateSpeedError	3	20							
2.05	Inspect source code	3	20							
2.06	Implement solve method	4	40							
2.07	Create unit test for solve	4	30 20							
2.08	Inspect source code	4	20 15							
2.09	Implement calculateWheelSpeed method	4	15 15							
	Create unit test for calculateWheelSpeed									
2.11	Implement calculateWheelAngles method	4	15							
2.12	Create unit test for calculateWheelAngles	4	15							
2.13	Inspect source code	4	20							
2.14	Implement Main function	4	20							
2.15	Create visualization	5	60							
2.16	Tune parameters	5	40							
2.17	Update readme	5	20							

Remaining effort	735			
Total effort time				