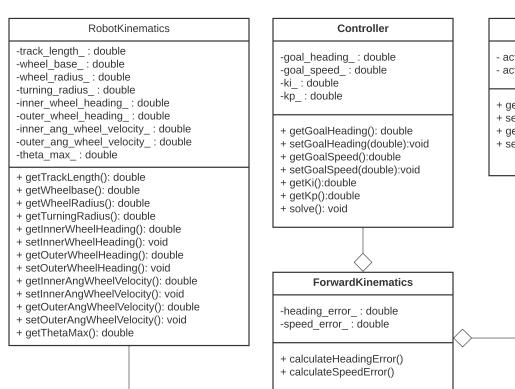
UML_class_diagram

Pooja Kabra | October 15, 2021



Sensor

- actual_heading_ : double
- actual_speed_: double
- + getActualHeading(): double
- + setActualHeading(double):void
- + getActualSpeed():double
- + setActualSpeed(double): void

InverseKinematics

- + calculateWheelSpeed()
- + calculateWheelAngles()