PHY 171 Formula Sheet

Fundamental SI Units

Length	meter (m)
Mass	kilogram (kg)
Time	second (s)
Electric Current	ampere (A)

Some Derived SI Units

Force	$N = kg m/s^2$
Energy	$J = kg m^2/s^2$
Power	W = J/s
Pressure	$Pa = N/m^2$

Some Important Constants

$$G = 6.674 \times 10^{-11} \text{ N} \cdot \text{m}^2/\text{kg}^2$$

$$c = 3.00 \times 10^8 \text{ m/s}$$

$$N_A = 6.02 \times 10^{23} \text{ particles/mole}$$

$$k = 1.38 \times 10^{-23} \text{ J/K}$$

$$g = 9.80 \text{ m/s}^2$$

$$R = 8.31 \text{ J/mol} \cdot K$$

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

Kinematics

Displacement
$$\Delta x = x_f - x_0$$

Velocity
$$v = \frac{\Delta x}{\Delta t} = \frac{x_f - x_0}{t_f - t_0}$$

Acceleration
$$a = \frac{\Delta v}{\Delta t} = \frac{v_f - v_0}{t_f - t_0}$$

$$\begin{aligned} & x = x_0 + vt \\ & v = v_0 + at \\ & x = x_0 + v_0t + \frac{1}{2}at^2 \\ & v^2 = v_0^2 + 2a(x - x_0) \end{aligned}$$

$$\begin{aligned} &\text{freefall } a = -g \\ &v = v_0 - gt \\ &y = y_0 + v_0t - \frac{1}{2}gt^2 \\ &v^2 = v_0^2 - 2g(y - y_0) \end{aligned}$$

Projectile motion

$$\begin{aligned} &\text{horizontal motion } a_x = 0 \\ &x = x_0 + v_x t \\ &v_x = v_{0x} = v_x \end{aligned}$$
 vertical motion
$$y = y_0 + v_0 t - \frac{1}{2} g t^2 \\ &v_y = v_{0y} - g t \\ &v_y^2 = v_{0y}^2 - 2g (y - y_0) \end{aligned}$$

$$s = \sqrt{x^2 + y^2} \\ \theta = \tan^{-1}(y/x) \\ v = \sqrt{v_x^2 + v_y^2} \\ \theta_v = \tan^{-1}(v_y/v_x) \end{aligned}$$
 Maximum height and range
$$h = \frac{v_{0y}^2}{2g} \\ R = \frac{v_0^2 \sin 2\theta_0}{g}$$

Dynamics

$$a = \frac{F}{m}$$

$$F = ma$$

$$w = mg$$

friction

$$f_s \le \mu_s N f_k = \mu_k N$$

Uniform Circular Motion

$$\Delta\theta = \frac{\Delta s}{s}$$

$$2\pi \text{ rad} = 360^{\circ} = 1 \text{ revolution}$$

$$\omega = \frac{\Delta\theta}{\Delta t}$$

$$v = r\omega \text{ or } \omega = \frac{v}{r}$$
Centripetal Acceleration
$$a_c = \frac{v^2}{r} ; \ a_c = r\omega^2$$
Centripetal Force
$$F_c = ma_c$$

$$F_c = m\frac{v^2}{r}$$

$$F_c = mr\omega^2$$

$$\Delta I = F$$

Newton's Universal Law of Gravitation

$$F = G \frac{mM}{r^2}$$

Work and Energy

$$W = Fd \cos \theta$$

$$KE = \frac{1}{2}mv^{2}$$

$$\Delta PE_{g} = mgh$$

$$W = \Delta KE + \Delta PE$$

$$PE_{\text{spring}} = \frac{1}{2}kx^{2}$$

$$P = \frac{W}{t}$$

Linear Momentum

$$\begin{aligned} p &= mv \\ F &= \frac{\Delta p}{\Delta t} \\ p_{\text{tot}} &= \text{constant} \\ \text{PE}_{\text{spring}} &= \frac{1}{2}kx^2 \end{aligned}$$

Statics and Torque

$$\begin{split} \tau &= rF\sin\theta \\ \tau &= r_\perp F \\ F_{\mathrm{net}} &= 0 \quad \mathrm{net} \ \tau = 0 \end{split}$$

Rotational Motion and Angular Momentum

$$\begin{array}{ll} \omega = \frac{\Delta\theta}{\Delta t} & \alpha = \frac{\Delta\omega}{\Delta t} \\ a_t = r\frac{\Delta\omega}{\Delta t} & a_t = r\alpha \\ x = r\theta & v = r\omega \\ \theta = \omega_0 t + \frac{1}{2}\alpha t^2 \\ \omega = \omega_0 + \alpha t \\ \omega^2 = \omega_0^2 + 2\alpha\theta \\ \mathrm{net}\tau = I\alpha \\ \mathrm{KE}_{\mathrm{rot}} = \frac{1}{2}I\omega^2 \end{array}$$

Fluid Statics

$$\rho = \frac{m}{V}$$

$$P = \frac{F}{A}$$

$$P = h\rho g$$

$$\frac{F_1}{A_1} = \frac{F_2}{A_2}$$

Temperature, Kinetic Theory, & the Gas Laws

$$\begin{split} \Delta L &= \alpha L \Delta T \\ PV &= nRT \quad PV = NkT \\ \bar{KE} &= \frac{1}{2}m\bar{v^2} = \frac{3}{2}kT \end{split}$$

Heat and Heat Transfer

$$\begin{aligned} Q &= mc\Delta T \\ \frac{Q}{t} &= \frac{kA(T_2 - T_1)}{d} \\ \frac{Q}{t} &= \sigma eAT^4 \end{aligned}$$

Oscillatory Motions and Waves

$$F = -kx$$

$$f = \frac{1}{T} \quad T = \frac{1}{f}$$

$$T = 2\pi \sqrt{\frac{L}{g}}$$

$$T = 2\pi \sqrt{\frac{m}{k}}$$

$$f = \frac{1}{2\pi} \sqrt{\frac{K}{m}}$$