PHY 171 Formula Sheet

Fundamental SI Units

 $\begin{array}{lll} \textbf{Length} & meter \ (m) \\ \textbf{Mass} & kilogram \ (kg) \\ \textbf{Time} & second \ (s) \\ \textbf{Electric Current} & ampere \ (A) \\ \end{array}$

Some Derived SI Units

 $\begin{array}{lll} \text{Force} & N = kg \ m/s^2 \\ \text{Energy} & J = kg \ m^2/s^2 \\ \text{Power} & W = J/s \\ \text{Pressure} & Pa = N/m^2 \end{array}$

Some Important Constants

$$G = 6.674 \times 10^{-11} \text{ N} \cdot \text{m}^2/\text{kg}^2$$

$$c = 3.00 \times 10^8 \text{ m/s}$$

$$N_A = 6.02 \times 10^{23} \text{ particles/mole}$$

$$k = 1.38 \times 10^{-23} \text{ J/K}$$

$$g = 9.80 \text{ m/s}^2$$

$$R = 8.31 \text{ J/mol} \cdot K$$

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

Kinematics

 ${\tt Displacement} \hspace{0.5cm} \Delta x = x_f - x_0$

Velocity $v=rac{\Delta x}{\Delta t}=rac{x_f-x_0}{t_f-t_0}$

Acceleration $a=rac{\Delta v}{\Delta t}=rac{v_f-v_0}{t_f-t_0}$

constant a $x = x_0 + vt$ $v = v_0 + at$ $x = x_0 + v_0t + \frac{1}{2}at^2$ $v^2 = v_0^2 + 2a(x - x_0)$

 $\begin{aligned} &\text{freefall } a = -g \\ &v = v_0 - gt \\ &y = y_0 + v_0t - \frac{1}{2}gt^2 \\ &v^2 = v_0^2 - 2g(y - y_0) \end{aligned}$

Projectile motion

horizontal motion $a_x=0$ $x=x_0+v_xt$ $v_x=v_{0x}=v_x$ vertical motion $y=y_0+v_0t-\frac{1}{2}gt^2$ $v_y=v_{0y}-gt$ $v_y^2=v_{0y}^2-2g(y-y_0)$ $s=\sqrt{x^2+y^2}$ $\theta=\tan^{-1}(y/x)$ $v=\sqrt{v_x^2+v_y^2}$ $\theta_v=\tan^{-1}(v_y/v_x)$ Maximum height and range

 $h = \frac{v_{0y}^2}{v_{0y}^2}$

$$h = \frac{v_{0y}^2}{2g}$$
$$R = \frac{v_0^2 \sin 2\theta_0}{g}$$

Dynamics

$$a = \frac{F}{m}$$

$$F = ma$$

$$w = mg$$

friction

$$f_s \le \mu_s N$$

$$f_k = \mu_k N$$

Uniform Circular Motion

$$\Delta\theta = \frac{\Delta s}{r}$$

$$2\pi \text{ rad} = 360^{\circ} = 1 \text{ revolution}$$

$$\omega = \frac{\Delta\theta}{\Delta t}$$

$$v = r\omega \text{ or } \omega = \frac{v}{r}$$
Centripetal Acceleration
$$a_c = \frac{v^2}{r} \text{ ; } a_c = r\omega^2$$
Centripetal Force
$$F_c = ma_c$$

$$F_c = m\frac{v^2}{r}$$

$$F_c = mr\omega^2$$

$$\Delta L = \frac{F}{b}$$

Newton's Universal Law of Gravitation

$$F = G \frac{mM}{r^2}$$

Work and Energy

$$W = Fd \cos \theta$$

$$KE = \frac{1}{2}mv^{2}$$

$$\Delta PE_{g} = mgh$$

$$W = \Delta KE + \Delta PE$$

$$PE_{\text{spring}} = \frac{1}{2}kx^{2}$$

$$P = \frac{W}{t}$$

Linear Momentum

$$p = mv$$

$$F = \frac{\Delta p}{\Delta t}$$

$$p_{\text{tot}} = \text{constant}$$

$$PE_{\text{spring}} = \frac{1}{2}kx^2$$

Statics and Torque

$$\begin{split} \tau &= rF\sin\theta \\ \tau &= r_\perp F \\ F_{\text{net}} &= 0 \quad \text{net } \tau = 0 \end{split}$$

Rotational Motion and Angular Momentum

$$\begin{array}{ll} \omega = \frac{\Delta\theta}{\Delta t} & \alpha = \frac{\Delta\omega}{\Delta t} \\ a_t = r\frac{\Delta\omega}{\Delta t} & a_t = r\alpha \\ x = r\theta & v = r\omega \\ \theta = \omega_0 t + \frac{1}{2}\alpha t^2 \\ \omega = \omega_0 + \alpha t \\ \omega^2 = \omega_0^2 + 2\alpha\theta \\ \mathrm{net}\tau = I\alpha \\ \mathrm{KE_{TOt}} = \frac{1}{2}I\omega^2 \end{array}$$

Fluid Statics

$$\rho = \frac{m}{V}$$

$$P = \frac{F}{A}$$

$$P = h\rho g$$

$$\frac{F_1}{A_1} = \frac{F_2}{A_2}$$

Temperature, Kinetic Theory, & the Gas Laws

$$\begin{split} \Delta L &= \alpha L \Delta T \\ PV &= nRT \quad PV = NkT \\ \bar{KE} &= \frac{1}{2}m\bar{v^2} = \frac{3}{2}kT \end{split}$$

Heat and Heat Transfer

$$Q = mc\Delta T$$

$$\frac{Q}{t} = \frac{kA(T_2 - T_1)}{d}$$

$$\frac{Q}{t} = \sigma eAT^4$$