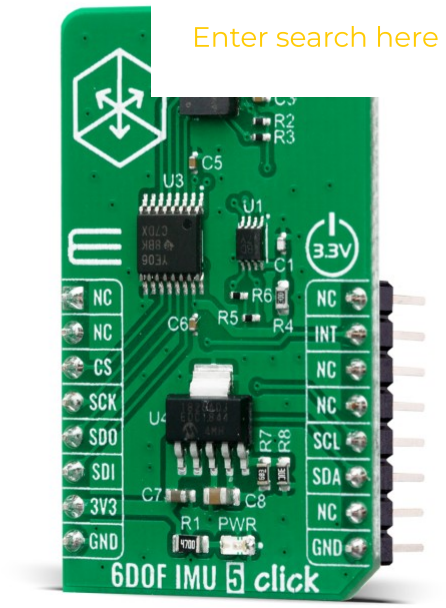

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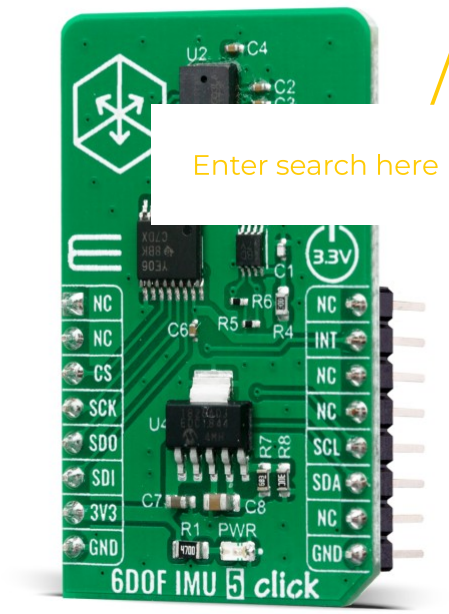







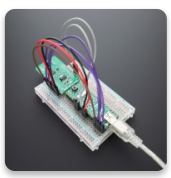

6DOF IMU 5 CLICK

accuracy enabling altitude measurement differentials as small as 8.5 cm. The pressure sensor's MEMS capacitive architecture provides the industry's lowest noise at the lowest power, high sensor throughput, and temperature coefficient offset of ±0.5 Pa/°C. The combination of high accuracy elevation measurements, low power, and temperature st makes it ideal for a wide range of motion tracking applications.

6DOF IMU 5 Click is supported by a mikroSI udes functions that simplify software development. This Click bo roduct, ready to be used on a system equipped with the mikroBUS™ socket.

1

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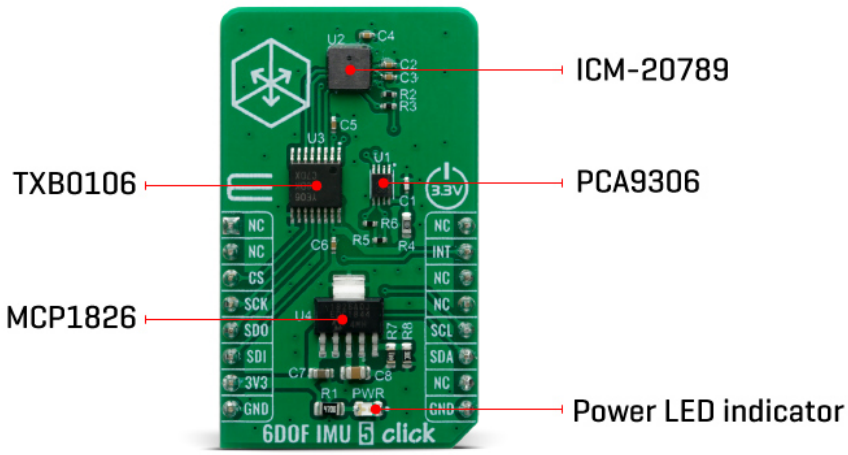
barometric pressure sensor in a 4 mm x 4 mm x 1.365 mm (24-pin LGA) package. ICM-20789 features a 4 KB FIFO that can lower the traffic on the serial bus interface. The digital output barometric pressure sensor is based on an ultra-low noise innovative MEMS capacitive technology that can ure pressure differences with an accuracy of ±1 Pa, an accuracy ena altitude measurement differentials as small lty of increased power consumption or reduced ser tive pressure sensor has a ±1 hPa absolute accuracy over its full range of 300 hPa -1100 hPa. The pressure sensor offers industry leading temperature stability of the pressure sensor with a temperature coefficient offset of ±0.5 Pa/°C, embedded temperature sensor and 400 kHz I2C bus for communication. The gyroscope has a programmable full-scale range of ±250 dps, ±500 dps, ±1000 dps, and ±2000 dps. The accelerometer has a user-programmable full-scale range of ±2g, ±4g, ±8g, and ±16g. Factory-calibrated initial sensitivity of both sensors reduces production-line calibration requirements. Other features include on-chip 16-bit ADCs, programmable digital filters, another embedded temperature sensor, and programmable interrupts. The device features I2C serial interface to access its registers at 400 kHz as well as at 8 MHz SPI.



The onboard chip ICM-20789 requires stable voltage for power supply of input/output pins (VDDIO) at 1.8V which also supplies the pressure sensor. 6DOF IMU 5 click does all of the power supply regulations as well as the logic level translations needed for proper operation. The MCP1826, a 1000 mA Low Dropout (LDO) linear regulator provides high-current and low-output voltage of 1.8V to all

the I2C bus allows access to pressure sensors 16-bit address space registers.

This device is intended for implementation in Drones and Flying Toys, Motion-based gaming controllers, Virtual Reality Headsets & Co ers, Indoor/Outdoor Navigation (dead-reckoning, floor/elevation/step detec

This Click Board™ uses both I2C an aces. It is designed to be operated only with 3 gic voltage level conversion should be performed before the Click board™ is used with MCUs with logic levels of 5V.

SPECIFICATIONS

Type	Acceleration,Gyroscope,Motion,Pressure
Applications	Drones and Flying Toys, Motion-based gaming controllers, Virtual Reality Headsets & Controllers, Indoor/Outdoor Navigation (dead-reckoning, floor/elevation/step detection)
On-board modules	6DOF IMU 5 Click uses the ICM-20789 IC, a 6-axis inertial sensor, from TDK InvenSense
Key Features	Pressure operating range: 30 to 110 kPa, Pressure Sensor Relative Accuracy: ±1 Pa, Gyroscope programmable FSR, Accelerometer with Programmable FSR and many more
Interface	I2C,SPI
Compatibility	mikroBUS
Click board size	M (42.9 x 25.4 mm)
Input Voltage	3.3V

PINOUT DIAGRAM

	NC	1	AN	PWM	16	NC	
	NC	2	RST	INT	15	**INT**	Interrupt
SPI Chip Select	**CS**	3	CS	RX	14	N	
SPI Clock	**SCK**	4	SCK				
SPI Data OUT	**SDO**	5	MISC				Clock
SPI Data IN	**SDI**	6	MOSI	SDA	11	**SDA**	I2C Data
Power Supply	**3.3V**	7	3.3V	5V	10	NC	
Ground	**GND**	8	GND	GND	9	**GND**	Ground

ONBOARD SETTINGS AND INDICATORS

Label	Name	Default	Description
LD1	PWR	-	Power LED Indicator

6DOF IMU 5 CLICK ELECTRICAL SPECIFICATIONS

Description	Min	Typ	Max	Unit
Supply Voltage	-0.3	3.3	6	V
Acceleration (Any Axis, unpowered, for 0.2ms)	-	-	1000	g
Overpressure	-	-	600	kPa
Operating Temperature Range	-40	-	85	°C

SOFTWARE SUPPORT

We provide a library for the 6DOF IMU 5 Click on our LibStock page, as well as a demo application (example), developed using MikroElektronika compilers. The demo can run on all the main MikroElektronika development boards.

that offer a plethora of settings. The library also offers functions that allow reading of accelerometer,gyroscope pressure and temperature, as well as generic read and write function that offer reading(and writing) of different lenghts of data.

Key functions:

- `float *z_ang_rte );` - Function is u
- `float *z_accel_rte );` - Function is used to calculate acceleration rate.
- `float *temperature );` - Function processes raw data in order to get presure (in Pascals) and temperature(in degree Centigrade).

Examples description

The application is composed of three sections :

- System Initialization - Initializes SPI and I2C modules, LOG and GPIO structures, sets INT pin as input.
- Application Initialization - Initalizes SPI and I2C drivers, performs safety check, applies default and barometer setups and writes an initial log.
- Application Task - (code snippet) Demonstrates use of 6DOF IMU 5 click board by reading angular rate, acceleration rate and pressure and temperature from on sensor barometer and displaying data via USART terminal.

```
void application_task ( )
{
    c6dofimu5_angular_rate( &x_gyro, &y_gyro, &z_gyro );

    mikrobus_logWrite( "Angular rate: ", _LOG_LINE );

    FloatToStr( x_gyro, log_txt );
    mikrobus_logWrite( "X-axis: ", _LOG_TEXT );
    Ltrim( log_txt );
    mikrobus_logWrite( log_txt, _LOG_LINE );

    FloatToStr( y_gyro, log_txt );
    mikrobus_logWrite( "Y-axis: ", _LOG_TEXT );
    Ltrim( log_txt );
    mikrobus_logWrite( log_txt, _LOG_LINE );

    FloatToStr( z_gyro, log_txt );
    mikrobus_logWrite( "Z-axis: ", _LOG_TEXT );
    Ltrim( log_txt );
    mikrobus_logWrite( log_txt, _LOG_LINE );
```

```
    mikrobus_logWrite( "X-axis: ", _LOG_TEXT );
    Ltrim( log_txt );
    mikrobus_logWrite( log_txt, _LOG_LINE );

    FloatToStr( y_accel, log_txt );
    mikrobus_logWrite( "Y-axis: ", _LOG_TEXT );
    Ltrim( log_txt );
    mikrobus_logWrite( log_txt, _LOG_L

    FloatToStr( z_accel, log_txt );
    mikrobus_logWrite( "Z-axis: ", _LOG_TEXT );
    Ltrim( log_txt );
    mikrobus_logWrite( log_txt, _LOG_LINE );
    mikrobus_logWrite( "---------------------", _LOG_LINE );

    c6dofimu5_read_raw_data( &raw_pres, &raw_temp );
    c6dofimu5_process_data ( raw_pres, raw_temp, &pressure, &temperature );

    FloatToStr( pressure, log_txt );
    mikrobus_logWrite( "Pressure: ", _LOG_TEXT );
    Ltrim( log_txt );
    mikrobus_logWrite( log_txt, _LOG_LINE );

    FloatToStr( temperature, log_txt );
    mikrobus_logWrite( "Temperature: ", _LOG_TEXT );
    Ltrim( log_txt );
    mikrobus_logWrite( log_txt, _LOG_LINE );

    mikrobus_logWrite( "---------------------", _LOG_LINE );
    mikrobus_logWrite( "", _LOG_LINE );
    mikrobus_logWrite( "---------------------", _LOG_LINE );
    Delay_ms( 1000 );
}
```

The full application code, and ready to use projects can be found on our LibStock page.

Other mikroE Libraries used in the example:

- I2C
- SPI
- UART
- Conversions

Additional notes and informations

Depending on the development board you are using, you may need USB UART

your choice, can be used to read the message.

MIKROSDK

This Click board™ is supported with mikroSDK - Mikro onika Software Development Kit. To ensure proper pliant Click board™ demo applications, mikroS rom the LibStock and installed for the compiler you are using.

For more information about mikroSDK, visit the official page.

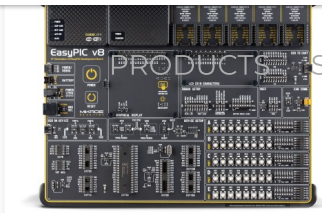
RESOURCES

- Click board™ Catalog
- Click Boards™
- mikroBUS™
- mikroSDK

DOWNLOADS

- 6DOF IMU 5 click example on Libstock
- 6DOF IMU 5 click 2D and 3D files
- 6DOF IMU 5 click schematic
- ICM-20789 datasheet

YOU MIGHT ALSO NEED



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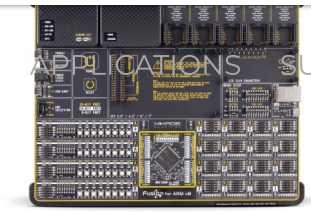

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