GbtLinuxFunc API User Guide

Release Note

Release Date	Revision	Note
202001111	1.0.9	Enhance Watchdog Function
202001024	1.0.8.2	2. Add Ubuntu 5.4.0-52-generic Kernel support
20200924	1.0.8.1	3. Add Ubuntu 5.4.0-48-generic Kernel support
20200921	1.0.8	4. Add new HW support for GA-SBC4200 5. Add Ubuntu 5.4.0-47-generic Kernel support
20200703	1.0.7	Add new HW support for GA-SBC5005 Remove Ubuntu 16.04 Kernel support
20190827	1.0.6	Add new kernel support for a. Ubuntu 16.04.6-4.15.0-58-generic b. Ubuntu 18.04.5-5.0.0-25-generic 8. Add new HW support for GA-IMB4100TN
20190605	1.0.5	1. Add new kernel support for a. Ubuntu 16.04.6-4.15.0-51-generic b. Ubuntu 18.04.2-4.18.0-21-generic
20181025	1.0.4	Change Device Name as "GbtLinuxFunc"
20181024	1.0.3	Add new HW support for GA-IMBLAP3450
20180910	1.0.2	 Add new HW support for GA-IMB310TN Add new SW support for Watchdog Control API Add new SW support for SpeakerBeep (internal speaker) Control API Add new SW support for DebugPort write API
20180202	1.0.1	Redefine header26 pin number for GA-IMBLAP3350 and GA-N3160TN

1.0.0	1. First release	
	2. Add new HW support for	
	c. GA-IMBLAP3350	
	d. GA-N3160TN	
	e. GA-H110TN	
	Add new SW support for GPIO Control API	
	1.0.0	

Supported Kernel Build Version:

5.4.0-52-generic5.4.0-48-generic5.4.0-47-generic

Supported Hardware:

GA-SBC4200 GA-SBC5005SE GA-IMB4100TN GA-IMB310TN GA-IMBLAP3450 GA-IMBLAP3350 GA-N3160TN GA-H110TN

GPIO definition for GA-IMB310TN GPIO definition for GA-H110TN

10) GPIO (GPIO插座)

此插座可控制Low/High訊號。



接腳	定義	接腳	定義
1	IO_GP70	6	IO_GP75
2	IO_GP71	7	IO_GP76
3	IO_GP72	8	IO_GP77
4	IO_GP73	9	GP_IN_OUT
5 IO_GP74		10 接地腳	

Note: Supported GPIO Pin: 1~8

註:若輸入無效的Pin Number(例如: 9,10),將回應Error Code.

GPIO definition for GA-IMBLAP3350-CF

GPIO definition for GA-IMBLAP3450

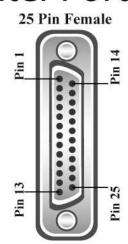
GPIO definition for GA-N3160TN

GPIO definition for GA-IMB4100TN

GPIO definition for GA-SBC4200

LPT Printer Port

Pin 1	Data Strobe
Pin 2	Data 0
Pin 3	Data 1
Pin 4	Data 2
Pin 5	Data 3
Pin 6	Data 4
Pin 7	Data 5
Pin 8	Data 6
Pin 9	Data 7
Pin 10	Acknowledge
Pin 11	Busy
Pin 12	Paper Out
Pin 13	Select
Pin 14	Auto Feed
Pin 15	Error
Pin 16	Init
Pin 17	Select Input
Pin 18-25	Ground



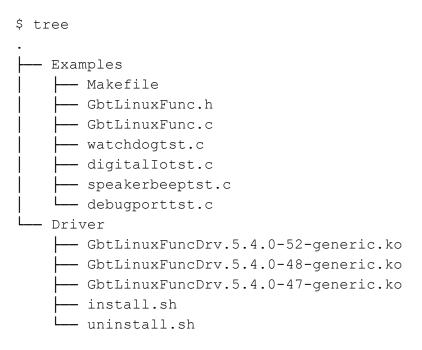
Note: Supported GPIO Pin: 1~14, 16~17

PIN	SIGNAL NAME	PIN	SIGNAL NAME
01	SIO_GP87	14	SIO_GP86
02	SIO_GP70	15	NA
03	SIO_GP71	16	SIO_GP85
04	SIO_GP72	17	SIO_GP84
05	SIO_GP73	18	GPIOPWR
06	SIO_GP74	19	GPIOPWR
07	SIO_GP75	20	GND
08	SIO_GP76	21	GND
09	SIO_GP77	22	GND
10	SIO_GP83	23	GND
11	SIO_GP82	24	GND
12	SIO_GP81	25	GND
13	SIO_GP80	26	NC

註1:若輸入無效的Pin Number(例如:0,15,18~26),將回應Error Code.

註2: 掛上Driver啟動後,Driver會強制切到GPIO mode,不會理會硬體LPT_SEL jumper 設定

Folder



install.sh

\$ cd Driver

\$ sudo modeporbe wmi

\$ sudo insmod GbtLinuxFuncDrv.ko

\$ sudo chmod 666 /dev/GbtLinuxFunc

\$ modinfo ./GbtLinuxFuncDrv5.4.0-47-generic.ko mark@mark-virtual-machine:~/GbtLinuxFunc/GbtLinuxFunc_release/Driver\$ modinfo ./GbtLinuxFuncDrv.5.4.0-47-generic.ko filename:

/home/mark/GbtLinuxFunc/GbtLinuxFunc_release/Driver/./GbtLinuxFuncDrv.5.4.0-47-generic.ko

version: 1.0.9 license: GPL

description: Gigabyte Embedded Board Linux Control Driver

author: Mark Tsai<mark@gigabyte.com><marktsai0316@gmail.com>

alias: wmi:DEADBEEF-2001-0000-00A0-C90629100000 alias: wmi:ABBC0F6F-8EA1-1459-00A0-C90629100000

srcversion: 5A50DD8C6A7CBD078732E94

dmi*:rn*SBC5005*: alias: alias: dmi*:rn*SBC4200*: alias: dmi*:rn*IMB4100TN*: alias: dmi*:rn*IMB310TN*: alias: dmi*:rn*IMBLAP3450*: alias: dmi*:rn*IMBLAP3350*: alias: dmi*:rn*N3160TN*: dmi*:rn*H110TN*: alias:

depends: wmi retpoline: Y

name: GbtLinuxFuncDrv

vermagic: 5.4.0-47-generic SMP mod_unload

\$ Ismod | grep GbtLinuxFuncDrv GbtLinuxFuncDrv 16384 0

\$ dmesg | tail -n 4

[74901.330051] GbtLinuxFuncDrv: GbtLinuxFunc module initial.

[74901.330053] Identified model 'GA-IMB310TN' ID=0xA0

[74901.330058] Force switch SIO mode from LPT to GPIO

[74901.330625] I got: 131072 bytes of memory

註2: 掛上Driver啟動後,Driver會強制切到GPIO mode,不會理會硬體LPT_SEL jumper 設定

\$ cat /proc/devices | grep GbtLinuxFunc 245 GbtLinuxFunc

\$ Is /dev/GbtLinuxFunc -la

crw------ 1 root root 245, 0 7月 21 13:00 /dev/GbtLinuxFunc

uninstall.sh

\$ sudo rmmod GbtLinuxFuncDrv

[74908.137850] GbtLinuxFuncdrv: Goodbye, GIGABYTE!

sudo apt install make g++

DigitalIO API Library

see GbtLinuxFunc.h and digitallo.c

```
//Defining Digital Pins modes: INPUT, INPUT_PULLUP, and OUTPUT
#define INPUT
#define INPUT_PULLUP 1
#define OUTPUT
//Defining Pin Levels: HIGH and LOW
#define HIGH
#define LOW
int DigitalIo_Init();
void DigitalIo_Uninit(int fd);
int DigitalIo_PinMode(int fd, int pin , int mode);
int DigitalIo_DigitalWrite(int fd, int pin,int value );
int DigitalIo_DigitalRead(int fd, int pin );
Example:
#include "GbtLinuxFunc.h"
int main(void)
       int fd=DigitalIo_Init();
       int ledPin = PIN1;
       DigitalIo_PinMode(fd, ledPin, OUTPUT);
       //sleep(1); // one second
       usleep(1000000); //one second
```

```
DigitalIo_DigitalWrite(fd, ledPin, HIGH ); //sets the LED on
    usleep(1000000); //one second
    DigitalIo_DigitalWrite(fd, ledPin, LOW ); //sets the LED off
    usleep(10000000); //one second
    DigitalIo_DigitalWrite(fd, ledPin, HIGH ); //sets the LED on
    usleep(10000000); //one second
    DigitalIo_DigitalWrite(fd, ledPin, LOW ); //sets the LED off
    usleep(10000000); //one second

DigitalIo_Uninit(fd);
    return 0;
}
```

Watchdog API Library

```
int WatchDog Control(int fd, unsigned int interval, unsigned int AutoBeatEn); //0 : Disable ,
1~255 unit in second
int WatchDog_Status(int fd, unsigned short *pTimeoutValue, unsigned short
*pAutoBeatStatus);
int WatchDog KeepAlive(int fd, unsigned short *pTimeoutValue, unsigned short
*pAutoBeatStatus);
Example:
int main(void)
      unsigned short TimeoutValue, AutoBeatStatus;
      int fd=GbtLinuxFuncDrv Init();
      //You can enable BeatBeep to hear system's heartbeat by internal speaker
      //Test1:When AutoBeat=Enable
      WatchDog Status(fd,&TimeoutValue,&AutoBeatStatus);
      printf("Old :Timeout value is %d secs, AutoBeat is %s\n",
             TimeoutValue ,(AutoBeatStatus == 0) ? "Enable" : "Disable" );
      WatchDog Control(fd, 10,1); //Set WDT Timeout Value as 10 secs,
AutoBeat=Enable
      WatchDog Status(fd,&TimeoutValue,&AutoBeatStatus);
      printf("New: Timeout value is %d secs, AutoBeat is %s\n",
             TimeoutValue,(AutoBeatStatus == 0)? "Enable": "Disable");
      usleep(1000000*5); //5 secs
      usleep(1000000*5); //5 secs
```

```
usleep(1000000*5); //5 secs
      //You never encounter system reset, unless system crash......
      //Test2:When AutoBeat=DIsable
      WatchDog_Status(fd,&TimeoutValue,&AutoBeatStatus);
      printf("Old: Timeout value is %d secs, AutoBeat is %s\n",
             TimeoutValue ,(AutoBeatStatus == 0) ? "Enable" : "Disable" );
      WatchDog_Control(fd, 10,0); //Set WDT Timeout Value as 10 secs,
AutoBeat=Disable
      WatchDog Status(fd,&TimeoutValue,&AutoBeatStatus);
      printf("New: Timeout value is %d secs, AutoBeat is %s\n",
             TimeoutValue ,(AutoBeatStatus == 0) ? "Enable" : "Disable" );
      usleep(1000000*5); //5 secs
      WatchDog KeepAlive(fd,&TimeoutValue,&AutoBeatStatus);
      printf(" Watchdog_KeepAlive : Timeout value is %d secs, AutoBeat is
%s\n",TimeoutValue,(AutoBeatStatus == 0)? "Enable": "Disable");
      usleep(1000000*5); //5 secs
      WatchDog KeepAlive(fd,&TimeoutValue,&AutoBeatStatus);
      printf(" Watchdog KeepAlive : Timeout value is %d secs, AutoBeat is
%s\n",TimeoutValue,(AutoBeatStatus == 0)? "Enable": "Disable");
      usleep(1000000*5); //5 secs
      WatchDog KeepAlive(fd,&TimeoutValue,&AutoBeatStatus);
      printf(" Watchdog KeepAlive : Timeout value is %d secs, AutoBeat is
%s\n",TimeoutValue,(AutoBeatStatus == 0)? "Enable": "Disable");
      WatchDog_Control(fd, 0,0); // Disable WDT function
      WatchDog Status(fd,&TimeoutValue,&AutoBeatStatus);
      printf(" WatchDog Status: Timeout value is %d secs, AutoBeat is %s\n",
             TimeoutValue ,(AutoBeatStatus == 0) ? "Enable" : "Disable" );
      //You must peroidly call keepAlive to avoid System reset
      GbtLinuxFuncDrv Uninit(fd);
      return 0;
}
```

usleep(1000000*5); //5 secs

SpeakerBeep (Internal Speaker) API Library

```
int SpeakerBeep_Control(int fd, unsigned short note,unsigned short duration);

Example :
int main(void)
{
    int fd=GbtLinuxFuncDrv_Init();
    int i;
    for(i=1;i<=21;i++)
    {
        SpeakerBeep_Control(fd,i,500); //set duration == 500 millisecond
    }

    GbtLinuxFuncDrv_Uninit(fd);
    return 0;
}</pre>
```

Debugport API Library

```
int DebugPort_Write(int fd, unsigned char value );
Example:
int main(void)
{
       int fd=GbtLinuxFuncDrv Init();
       DebugPort_Write(fd, 0xAA );
       usleep(1000000*1); //one second
       DebugPort Write(fd, 0x55);
       usleep(1000000*1); //one second
       DebugPort Write(fd, 0xAA);
       usleep(1000000*1); //one second
       DebugPort_Write(fd, 0x55 );
       usleep(1000000*1); //one second
       GbtLinuxFuncDrv_Uninit(fd);
       return 0;
}
```

dmidecode

mark@test:~/GbtLinuxFunc/Driver\$ sudo dmidecode -s baseboard-manufacturer Gigabyte Technology Co., Ltd.

mark@test:~/GbtLinuxFunc/Driver\$ sudo dmidecode -s baseboard-product-name IMBLAP3350-CF

mark@test:~/GbtLinuxFunc/Driver\$ sudo dmidecode -t 2

dmidecode 3.0

Getting SMBIOS data from sysfs.

SMBIOS 3.0.0 present.

Handle 0x0002, DMI type 2, 15 bytes

Base Board Information

Manufacturer: Gigabyte Technology Co., Ltd.

Product Name: IMBLAP3350-CF

Version: Default string

Serial Number: Default string Asset Tag: Default string

Features:

Board is a hosting board Board is replaceable

Location In Chassis: Default string

Chassis Handle: 0x0003 Type: Motherboard

Contained Object Handles: 0