

Refinement for Symbolic Trajectory Evaluation

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Abstract. Model refinement such that it preserves symbolic trajectory evaluations.

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1 Symbolic Trajectory Evaluation

Symbolic trajectory evaluation [5] (STE) is a high-performance model checking technique based on *symbolic simulation* extended with a temporal *next-time* operator to describe circuit behaviour over time. In its simplest form, STE tests the validity of an *assertion* of the form $A \Rightarrow C$, where both the *antecedent* A and *consequent* C are formulas in the following logic:

$$f ::= p \mid f \wedge f \mid P \rightarrow f \mid \mathbf{N} f$$

Here, p is a simple predicate over “values” in a circuit and P is a Boolean propositional formula, and the operators \wedge , \rightarrow and \mathbf{N} are conjunction, domain restriction and the next-time operator, respectively.

If the circuit contains Boolean signals, p is typically drawn from the following two predicates: $n \text{ is } 1$ and $n \text{ is } 0$, where n ranges over the signals (or nodes) in a circuit. For example, suppose we have a unit-delayed, two-input AND-gate, then it is reasonable to assume that the assertion $(in_1 \text{ is } 1 \wedge in_2 \text{ is } 1) \Rightarrow \mathbf{N}(out \text{ is } 1)$ is true. Indeed, STE efficiently validates such statements for us.

While the truth semantics of an assertion in STE is defined as the satisfaction of its “defining” trajectory (bounded sequence of states) relative to a model structure of the circuit, what the STE algorithm computes is exactly the solution of a data-flow equation [1] in the classic format [4]. . .

2 Set-theoretic STE

Consider an arbitrary, but fixed, digital circuit M operating in discrete time. A *configuration* of M , denoted by \mathbb{C} , is non-empty and finite set that represents a snapshot of M at a discrete point in time. If the circuit M has m boolean signals, then its set of configurations is typically represented as a sequence \mathbb{B}^m , where $\mathbb{B} = \{0, 1\}$ is the set of boolean values.

Circuit Model A simple conceptual model of M is a *transition relation*, $M_R \subseteq \mathbb{C} \times \mathbb{C}$, where $(c, c') \in M_R$ means that M can move from c to c' in one step¹. The power set of \mathbb{C} , denoted by $\wp(\mathbb{C})$, can be viewed as a the set of *predicates* on configurations, where \cap , \cup , and \subseteq correspond to conjunction, disjunction and implication, respectively. We denote by $\cap S$ and $\cup S$ the intersection and union of all members of any $S \subseteq \wp(\mathbb{C})$.

M_R induces a *predicate transformer* $M_F \in \wp(\mathbb{C}) \rightarrow \wp(\mathbb{C})$ using the relational image operation:

$$M_F(C) = \{c' \in \mathbb{C} \mid \exists c \in C : (c, c') \in M_R\}$$

It is intuitively obvious that if M is in one of the configurations in $C \in \wp(\mathbb{C})$, then in one time step it must be in one of the configurations in $M_F(p)$. We also see that M_F distributes over arbitrary unions:

$$M_F(\cup S) = \cup \{M_F(C) \mid C \in S\}$$

for all $S \subseteq \wp(\mathbb{C})$. In general, any M_F that satisfies this distributive property also defines a M_R through the equivalence $(c, c') \in M_R \Leftrightarrow c' \in M_F(\{c\})$, that is to say, there is no loss of information going from M_R to M_F or vice versa. We adopt this functional model of M and drop its subscript.

Exactly what \mathbb{C} and its signals are, is not important in this section. In practice, however, signals are typically divided into external, such as “inputs” and “outputs”, and internal parts. While an input signal is generally controlled by the external environment, and thus unconstrained by M itself, non-input signals are determined by the circuit topology and functionality. For example, supposed M is the earlier example of a unit-delayed two-input AND gate, we could then define its model $M \in \wp(\mathbb{B}^3) \rightarrow \wp(\mathbb{B}^3)$ as follows:

$$M(C) = \{\langle b_1, b_2, i_1 \wedge i_2 \rangle \in \mathbb{B}^3 \mid \langle i_1, i_2, o \rangle \in C\}$$

Here i_1 and i_2 refer to the two inputs of the AND gate, o the ignored output, and b_1 and b_2 are unconstrained inputs for the new configurations.

Assertions and satisfaction A *trajectory assertion* for M is quintuple $A = (S, s_0, R, \pi_a, \pi_c)$, where S is a finite set of *states*, $s_0 \in S$ is an *initial state*, $R \subseteq S \times S$ is a *transition relation*, $\pi_a \in S \rightarrow \wp(\mathbb{C})$ and $\pi_c \in S \rightarrow \wp(\mathbb{C})$ label each state s with an *antecedent* $\pi_a(s)$ and a *consequent* $\pi_c(s)$. We assume that $(s, s_0) \notin R$ for all $s \in S$ without any loss of generality.

The circuit model M intuitively *satisfies* an assertion A if, for every *trajectory* τ through M and every *run* ρ through A , τ satisfying the antecedents of ρ entails that τ also satisfies the consequents of ρ . To be specific, a *trajectory* of M is a non-empty sequences of configurations, $\tau \in \mathbb{C}^+$, such that $\tau_n \in M(\{\tau_{n-1}\})$ for all $n \in \mathbb{N} : 0 < n < |\tau|$. And a *run* of A is a non-empty sequence of states, $\rho \in S^+$, such that $\rho_0 = s_0$ and $(\rho_{n-1}, \rho_n) \in R$ for all $n \in \mathbb{N} : 0 < n < |\rho|$.

¹ Mention how this affects circuits with zero-delays?

A τ satisfies the antecedents of ρ , denoted by $\tau \models_a \rho$, iff $\tau_n \in \pi_a(\rho_n)$ for all $n \in \mathbb{N} : n < |\tau| = |\rho|$; satisfaction of consequents is defined similarly with π_c and denoted by $\tau \models_c \rho$.

That M satisfies A , denoted by $M \models A$, can then be formalized as follows:

$$\forall \tau \in \text{Traj}(M) : \forall \rho \in \text{Runs}(A) : |\tau| = |\rho| \Rightarrow (\tau \models_a \rho \Rightarrow \tau \models_c \rho)$$

where $\text{Traj}(M)$ and $\text{Runs}(A)$ denote the sets of all trajectories of M and runs of A , respectively. **This satisfaction can be formulated equivalently as a problem for deterministic finite automaton.**

2.1 Refinement

Consider another fixed, but arbitrary, circuit model $N \in \wp(\mathbb{D}) \rightarrow \wp(\mathbb{D})$, where \mathbb{D} is a non-empty and finite set of configurations. Exactly what configurations such as \mathbb{C} and \mathbb{D} are, were not important previously. But to reason about refinement, which relates the external behaviour of circuits, we make a distinction between their elements. Let $\sim \subseteq \mathbb{C} \times \mathbb{C}$ be an equivalence relation on \mathbb{C} . The equivalence class of a $c \in \mathbb{C}$ under \sim , denoted by $[c]$, is defined as $[c] = \{c' \in \mathbb{C} \mid c' \sim c\}$. With a slight abuse of notation, we overload both \sim and $[\cdot]$ to accept configurations in \mathbb{D} . We also extend $[\cdot]$ to sets $C \subseteq \mathbb{C}$ as $[C] = \cup\{[c] \in \wp(\mathbb{C}) \mid c \in C\}$.

Refinement by trajectories Let there be a Galois connection between **predicates $\wp(\mathbb{C})$ and $\wp(\mathbb{D})$ ordered by set inclusion**. The usual definition of a Galois connection is in terms of an *abstraction* $\alpha \in \wp(\mathbb{C}) \rightarrow \wp(\mathbb{D})$ and a *concretisation* $\gamma \in \wp(\mathbb{D}) \rightarrow \wp(\mathbb{C})$ function, such that $\alpha(C) \subseteq D \Leftrightarrow C \subseteq \gamma(D)$ for all $C \in \wp(\mathbb{C})$ and $D \in \wp(\mathbb{D})$. **For example, a Galois connection between ...**

Furthermore, let the binary relation $\ll \subseteq \wp(\mathbb{C}) \times \wp(\mathbb{D})$, where $C \ll D$ reads “ C can be approximated by D ”, be derived from the above α or γ , such that:

$$C \ll D \Leftrightarrow \alpha([C]) \subseteq [D] \qquad C \ll D \Leftrightarrow [C] \subseteq \gamma([D])$$

Here \subseteq on the α -derivation side is the inclusion order of $\wp(\mathbb{D})$, and on the γ -derivation side \subseteq is the inclusion order of $\wp(\mathbb{C})$. Intuitively, \ll acts as an extension of the orderings inside $\wp(\mathbb{C})$ and $\wp(\mathbb{D})$ to one **between equivalence classes of them. We require that $\alpha([c]) \neq \emptyset$ for all $c \in \mathbb{C}$** . We extend \ll to sequences component wise, such that $\tau \ll v$ iff $\{\tau_n\} \ll \{v_n\}$ for all $\tau \in \mathbb{C}^+$, $v \in \mathbb{D}^+$, and $n \in \mathbb{N} : n < |\tau| = |v|$.

We can now formalize that M *refines* N , denoted by $M \leq N$, as follows:

$$\forall \tau \in \text{Traj}(M) : \exists v \in \text{Traj}(N) : |\tau| = |v| \wedge \tau \ll v$$

In other words, for every sequence of configurations τ permitted by M , there must exist a sequence v for N which approximates the behaviour of τ according to **their equivalence relations. Example.**

Refinement & assertions Recall that a trajectory assertion for N is a quintuple $A = (S, s_0, R, \pi_a, \pi_c)$, where $\pi_a \in S \rightarrow \wp(\mathbb{D})$ and $\pi_c \in S \rightarrow \wp(\mathbb{D})$ label each $s \in S$ with its antecedents and consequents, respectively. If π_a and π_c are class invariant under \sim , i.e. $d \in \pi_a(s) \Leftrightarrow [d] \subseteq \pi_a(s)$ for all $s \in S$ and similarly for π_c , then we refer to A as an *name trajectory assertion* and suffix it as A_n . Furthermore, we define $\gamma(A) = (S, s_0, R, \gamma(\pi_a), \gamma(\pi_c))$, where $\gamma(\pi_a) = \lambda s \in S : \gamma(\pi_a(s))$ and $\gamma(\pi_c) = \lambda s \in S : \gamma(\pi_c(s))$. We require that γ preserves the invariance of π_a and π_c , i.e. $c \in \gamma(\pi_a(s)) \Leftrightarrow [c] \subseteq \gamma(\pi_a(s))$ and similarly for π_c .

We are now ready to state that, if M refines N and A_n is satisfied in N , then a concretisation of A_n can also be satisfied in M :

Theorem 1. $M \leq N \Rightarrow (N \models A_n \Rightarrow M \models \gamma(A_n))$

Refinement can be equivalently formulated as \ll being a simulation relation. More specifically, we say that M refines N by *set-theoretic simulation*, denoted by $M \leq_{\text{set}} N$, iff (1) \ll is a *name*, i.e. $C \ll D \Rightarrow \forall c \in C : \exists d \in D : \{c\} \ll \{d\}$; and (2) \ll is a *simulation relation* from $\wp(\mathbb{C})$ to $\wp(\mathbb{D})$, i.e. $C \ll D \Rightarrow M(C) \ll N(D)$.

Theorem 2. $M \leq N \Leftrightarrow M \leq_{\text{set}} N$

Text.

3 Lattice-theoretic STE

Manipulating subsets of \mathbb{B}^m is impractical for even moderately large m , which leads us to one of the key insights of STE. Namely, instead of manipulating subsets of \mathbb{B}^m directly, one can use sequences of ternary values $\mathbb{T} = \mathbb{B} \cup \{X\}$ to approximate them, whose sizes are only linear in m . Here the 1 and 0 from \mathbb{B} denotes specific, defined values whereas X denotes an “unknown” value that could be either 1 or 0. This intuition induces a partial order \sqsubseteq on \mathbb{T} , where $0 \sqsubseteq X$ and $1 \sqsubseteq X$. For any $m \in \mathbb{N}$, this ordering on \mathbb{T} is lifted component-wise to \mathbb{T}^m .

Note that \mathbb{T}^m does not quite form a complete lattice because it lacks a bottom: both $0 \sqsubseteq X$ and $1 \sqsubseteq X$ but 0 and 1 are equally defined. A special bottom element \perp is therefore introduced, such that $\perp \sqsubseteq t$ and $\perp \neq t$ for all $t \in \mathbb{T}^m$. The extended $\mathbb{T}_\perp^m = \mathbb{T}^m \cup \{\perp\}$ then becomes a complete lattice. We denote the top element $\langle X, \dots, X \rangle$ of \mathbb{T}_\perp^m by \top .

Ternary lattices Generalising from any specific domain, let $(\hat{\mathbb{P}}, \sqsubseteq)$ be a finite, complete lattice of *abstract predicates* in which the meet \sqcap and join \sqcup of any subset $\hat{S} \subseteq \hat{\mathbb{P}}$ exists. Similar to the previous set operations for power sets, \sqcap , \sqcup and \sqsubseteq correspond to conjunction, disjunction and implication for abstract predicates, respectively. Furthermore, for any $\hat{S} \subseteq \hat{\mathbb{P}}$, we denote by $\sqcap \hat{S}$ and $\sqcup \hat{S}$ the meet and join of all members of \hat{S} .

² We use the reverse ordering of what is originally used in STE to make the abstraction-correspondence clear between \cap and \sqcap , \cup and \sqcup , and \subseteq and \sqsubseteq .

Let there be a Galois connection relating “concrete” predicates $\wp(\mathbb{C})$ and abstract predicates $\hat{\mathbb{P}}$. As before, the Galois connection is defined in terms of an *abstraction* $\hat{\alpha} \in \wp(\mathbb{C}) \rightarrow \hat{\mathbb{P}}$ and a *concretisation* $\hat{\gamma} \in \hat{\mathbb{P}} \rightarrow \wp(\mathbb{C})$ function, such that $\hat{\alpha}(C) \sqsubseteq \hat{p} \Leftrightarrow C \subseteq \hat{\gamma}(\hat{p})$ for all $C \in \wp(\mathbb{C})$ and $\hat{p} \in \hat{\mathbb{P}}$. For example, a Galois connection from $\wp(\mathbb{B}^m)$ to \mathbb{T}_\perp^m for any $m \in \mathbb{N}$ can be defined in a natural way through its concretisation function $\hat{\gamma} \in \mathbb{T}_\perp^m \rightarrow \wp(\mathbb{B}^m)$:

$$\begin{aligned}\hat{\gamma}(\langle t_0, \dots, t_{m-1} \rangle) &= \{ \langle b_0, \dots, b_{m-1} \rangle \in \mathbb{B}^m \mid \forall i < m : t_i \neq \text{X} \Rightarrow b_i = t_i \} \\ \hat{\gamma}(\perp) &= \emptyset\end{aligned}$$

which list each concrete predicate approximated by a given abstract predicate.

Abstract circuit model An *abstract predicate transformer* $\hat{M} \in \hat{\mathbb{P}} \rightarrow \hat{P}$ is an *abstract interpretation* [1, 2] of $M \in \wp(\mathbb{C}) \rightarrow \wp(\mathbb{C})$ iff (1) \hat{M} preserves \perp , i.e. $\hat{M}(\perp) = \perp$; (2) \hat{M} is monotonic, i.e. $\hat{p} \sqsubseteq \hat{q} \Rightarrow \hat{M}(\hat{p}) \sqsubseteq \hat{M}(\hat{q})$ for all $\hat{p}, \hat{q} \in \hat{\mathbb{P}}$; and (3) α , or γ , form a *simulation relation* between the predicates $\wp(\mathbb{C})$ and \hat{P} , i.e. $\alpha(M(C)) \sqsubseteq \hat{M}(\alpha(C))$ for all $C \in \wp(\mathbb{C})$, or $M(\gamma(\hat{p})) \subseteq \gamma(\hat{M}(\hat{p}))$ for all $\hat{p} \in \hat{\mathbb{P}}$.

Note that \hat{M} , unlike its concrete model M it interprets, does not distribute over arbitrary join; information is potentially discarded by the ternary logic that would have been kept in binary logic. As an example, let the following \hat{M} abstract the previous model of an unit-delayed two-input AND gate:

$$\begin{aligned}\hat{M}(\langle 1, 1, \hat{p}_2 \rangle) &= \langle \text{X}, \text{X}, 1 \rangle & \hat{M}(\langle 0, 0, \hat{p}_2 \rangle) &= \langle \text{X}, \text{X}, 0 \rangle \\ \hat{M}(\langle 0, \text{X}, \hat{p}_2 \rangle) &= \langle \text{X}, \text{X}, 0 \rangle & \hat{M}(\langle \text{X}, 0, \hat{p}_2 \rangle) &= \langle \text{X}, \text{X}, \text{X} \rangle \\ \hat{M}(\langle \hat{p}_0, \hat{p}_1, \hat{p}_2 \rangle) &= \langle \text{X}, \text{X}, \text{X} \rangle\end{aligned}$$

where the last and most general matching is overlapped by the more specific matchings above it. If we apply \hat{M} to the join of $\langle 0, 1, \text{X} \rangle$ and $\langle 1, 0, \text{X} \rangle$, or if we apply \hat{M} to them individually and then join, we get two different results:

$$\begin{aligned}\hat{M}(\langle 0, 1, \text{X} \rangle \sqcup \langle 1, 0, \text{X} \rangle) &= \hat{M}(\langle \text{X}, \text{X}, \text{X} \rangle) = \langle \text{X}, \text{X}, \text{X} \rangle \\ \hat{M}(\langle 0, 1, \text{X} \rangle) \sqcup \hat{M}(\langle 1, 0, \text{X} \rangle) &= \langle \text{X}, \text{X}, 0 \rangle \sqcup \langle \text{X}, \text{X}, 0 \rangle = \langle \text{X}, \text{X}, 0 \rangle\end{aligned}$$

The inequality $\sqcup \{ \hat{M}(\hat{p}) \mid \hat{p} \in \hat{S} \} \sqsubseteq \hat{M}(\sqcup \hat{S})$ for all $\hat{S} \sqsubseteq \hat{P}$ does however hold, since it is implied by the monotonicity of \hat{M} .

Assertions and satisfaction A trajectory assertion for an abstract model \hat{M} is a quintuple $\hat{A} = (S, s_0, R, \hat{\pi}_a, \hat{\pi}_c)$, where S , s_0 , and R are as in section 2 and $\hat{\pi}_a \in S \rightarrow \hat{\mathbb{P}}$ and $\hat{\pi}_c \in S \rightarrow \hat{\mathbb{P}}$ label each state $s \in S$ with an abstract predicate for its antecedent and consequent, respectively. *\hat{M} satisfies \hat{A} intuitively if, for every state $s \in S$, the information gathered from \hat{M} when restricted by the antecedents in states before s , implies the consequent for s . Before we can formalize this intuition, however, we must introduce a few functions.*

For all functions $\Phi \in S \rightarrow \hat{\mathbb{P}}$ and states $s \in S$, define $F \in S \rightarrow (\hat{\mathbb{P}} \rightarrow \hat{\mathbb{P}})$ and $\mathcal{F} \in (S \rightarrow \hat{\mathbb{P}}) \rightarrow (S \rightarrow \hat{\mathbb{P}})$ as follows:

$$F(s)(\hat{p}) = \hat{M}(\pi_a(s) \sqcap \hat{p}) \quad (1)$$

$$\mathcal{F}(\Phi)(s) = \text{if } (s = s_0) \text{ then } \top \text{ else } \sqcup \{F(s')(\Phi(s')) \mid (s', s) \in R\} \quad (2)$$

We see that F preserves \perp , and both F and \mathcal{F} are monotonic; two $\Phi, \Phi' \in S \rightarrow \hat{\mathbb{P}}$ are ordered as $\Phi \sqsubseteq \Phi' \Leftrightarrow \forall s \in S : \Phi(s) \sqsubseteq \Phi'(s)$. Let $\Phi_* \in S \rightarrow \hat{\mathbb{P}}$ be the least fixpoint of the equation $\Phi = \mathcal{F}(\Phi)$ [3]. Since both S and $\hat{\mathbb{P}}$ are finite, Φ_* is given by $\lim \Phi_n(s)$, where Φ_n is defined as follows:

$$\Phi_n = \text{if } (n = 0) \text{ then } (\lambda s \in S : \perp) \text{ else } \mathcal{F}(\Phi_{n-1}) \quad (3)$$

We can now adopt the definition of satisfaction from [1], and say that \hat{M} satisfies a trajectory assertion \hat{A} , denoted by $\hat{M} \models_{\text{lat}} \hat{A}$, iff $\Phi_*(s) \sqcap \pi_a(s) \sqsubseteq \pi_c(s)$ for all $s \in S$. That \hat{M} satisfies \hat{A} implies that a concretisation of \hat{A} can also be satisfied by the original, set-based model M .

3.1 Refinement

Let the abstract predicate transformer $\hat{N} \in \hat{\mathbb{Q}} \rightarrow \hat{\mathbb{Q}}$ be an abstract interpretation of the earlier circuit model N , where $\hat{\mathbb{Q}}$ is an abstract predicate for which there exists a Galois connection to $\wp(\mathbb{D})$.

Let equivalent predicates in $\hat{\mathbb{P}}$ be identified by a function $\llbracket \cdot \rrbracket \in \hat{\mathbb{P}} \rightarrow \hat{\mathbb{P}}$, such that $\llbracket \cdot \rrbracket$ (?) preserves top and bottom, i.e. $\llbracket \top \rrbracket = \top$ and $\llbracket \perp \rrbracket = \perp$; (?) is idempotent, i.e. $\llbracket (\llbracket \hat{p} \rrbracket) \rrbracket = \llbracket \hat{p} \rrbracket$; (?) is monotonic, i.e. $\hat{p} \sqsubseteq \hat{q} \Rightarrow \llbracket \hat{p} \rrbracket \sqsubseteq \llbracket \hat{q} \rrbracket$; (?) **increasing**, i.e. $\hat{p} \sqsubseteq \llbracket \hat{p} \rrbracket$; (?) **name**, i.e. $\hat{q} = \llbracket \hat{q} \rrbracket \Rightarrow \llbracket \hat{p} \sqcap \hat{q} \rrbracket \Leftrightarrow \llbracket \hat{p} \rrbracket \sqcap \hat{q}$

Let there exist a Galois connection between $\hat{\mathbb{P}}$ and $\hat{\mathbb{Q}}$, given by the usual functions for abstraction $\hat{\alpha} \in \hat{\mathbb{P}} \rightarrow \hat{\mathbb{Q}}$ and concretisation $\hat{\gamma} \in \hat{\mathbb{Q}} \rightarrow \hat{\mathbb{P}}$, such that $\hat{\alpha}(\hat{p}) \sqsubseteq \hat{q} \Leftrightarrow \hat{p} \sqsubseteq \hat{\gamma}(\hat{q})$ for all $\hat{p} \in \hat{\mathbb{P}}$ and $\hat{q} \in \hat{\mathbb{Q}}$.

Let the binary relation $\lll \sqsubseteq \hat{\mathbb{P}} \times \hat{\mathbb{Q}}$ be derived from the above $\hat{\alpha}$ or $\hat{\gamma}$:

$$\hat{p} \lll \hat{q} \Leftrightarrow \hat{\alpha}(\llbracket \hat{p} \rrbracket) \sqsubseteq \llbracket \hat{q} \rrbracket \quad \hat{p} \lll \hat{q} \Leftrightarrow \llbracket \hat{p} \rrbracket \sqsubseteq \hat{\gamma}(\llbracket \hat{q} \rrbracket)$$

Here \sqsubseteq on $\hat{\alpha}$ -derivation side is the partial order of $\hat{\mathbb{Q}}$, and on the $\hat{\gamma}$ -derivation side \sqsubseteq is the partial order of $\hat{\mathbb{P}}$.

Finally, we say that \hat{M} refines \hat{N} by *lattice-theoretic simulation*, denoted by $\hat{M} \leq_{\text{lat}} \hat{N}$, iff (1) \lll is a simulation relation, i.e. $\hat{p} \lll \hat{q} \Rightarrow \hat{M}(\hat{p}) \lll \hat{N}(\hat{q})$. That \lll is a simulation relation can also be stated directly in terms of the usual functions for abstraction, $\hat{\alpha}(\llbracket \hat{M}(\hat{p}) \rrbracket) \sqsubseteq \llbracket \hat{N}(\hat{\alpha}(\hat{p})) \rrbracket$ for all $\hat{p} \in \hat{\mathbb{P}}$, or concretisation, $\llbracket \hat{M}(\hat{\gamma}(\hat{q})) \rrbracket \sqsubseteq \hat{\gamma}(\llbracket \hat{N}(\hat{q}) \rrbracket)$ for all $\hat{q} \in \hat{\mathbb{Q}}$.

Theorem 3. $\hat{M} \leq_{\text{lat}} \hat{N} \Rightarrow (\hat{N} \models_{\text{lat}} \hat{A}_{\text{r}} \Rightarrow \hat{M} \models_{\text{lat}} \hat{\gamma}(\hat{A}_{\text{r}}))$

Theorem 4. $\hat{M} \leq_{\text{lat}} \hat{N} \Rightarrow M \leq_{\text{set}} N$

A Appendices

A.1 Theorem 1

We use freely the fact that $[\{c\}] = [c]$ and first prove a few lemmas.

Lemma 1. $[d] \cap \pi_a(\rho) \neq \emptyset \Rightarrow [d] \subseteq \pi_a(\rho)$

Since they intersect, there must exist $d' \in [d]$ such that $d' \in \pi_a(\rho)$. By the invariance of $\pi_a(\rho)$, it must be that $[d'] = [d] \subseteq \pi_a(\rho)$. \square

Lemma 2. $d \in \pi_c(\rho) \wedge \{c\} \ll \{d\} \Rightarrow c \in \gamma(\pi_c(\rho))$

By the invariance of π_c , $d \in \pi_c(\rho)$ implies that $[d] \subseteq \pi_c(\rho)$, which in turn implies $\gamma([d]) \subseteq \gamma(\pi_c(\rho))$ by the monotonicity of γ . By definition of $\{c\} \ll \{d\}$, we know $[c] \subseteq \gamma([d])$, and thus $[c] \subseteq \gamma(\pi_c(\rho))$. That $c \in \gamma(\pi_c(\rho))$ then follows. \square

Lemma 3. $c \in \gamma(\pi_a(\rho)) \wedge \{c\} \ll \{d\} \Rightarrow d \in \pi_a(\rho)$

By the invariance of π_a , and the preservation of it by γ , $c \in \gamma(\pi_a(\rho))$ implies that $[c] \subseteq \gamma(\pi_a(\rho))$. And thus $\alpha([c]) \subseteq \alpha(\gamma(\pi_a(\rho))) \subseteq \pi_a(\rho)$ by the monotonicity of α . By definition of $\{c\} \ll \{d\}$, we also have that $\alpha([c]) \subseteq [d]$. Since $\alpha([c]) \neq \emptyset$, it must be that $[d] \cap \pi_a(\rho) \neq \emptyset$, and thus $[d] \subseteq \pi_a(\rho)$ by lemma 1. That $d \in \pi_a(\rho)$ then follows immediately. \square

For the theorem, we are given $\tau \in \text{Traj}(M)$ and $\rho \in \text{Runs}(\gamma(A))$, such that $|\tau| = |\rho|$ and $\tau_n \in \gamma(\pi_a(\rho_n))$ for all $n \in \mathbb{N} : n < |\tau|$. We must then show that $\tau_n \in \gamma(\pi_c(\rho_n))$. By the refinement assumption, there must exist a $v \in \text{Traj}(N)$ such that $|\tau| = |v| = |\rho|$ and $\{\tau_n\} \ll \{v_n\}$. Lemma 3 then shows that $v_n \in \pi_a(\rho_n)$ and, by the assumption, we have $v_n \in \pi_c(\rho_n)$. Lemma 2 then shows that $\tau_n \in \gamma(\pi_c(\rho_n))$. \square

A.2 Theorem 2

We first show a lemma.

Lemma 4. $C \ll D \wedge D \subseteq D' \Rightarrow C \ll D'$

That C is approximated by D' follows immediately: $\alpha(C) \subseteq D \subseteq D'$. The first property of \ll follows from the definition of subset, and the second by the monotonicity of N : $\alpha(M(C)) \subseteq N(D) \subseteq N(D')$. \square

We prove each direction of the theorem separately.

(\Rightarrow) : If $C \ll D$, then by definition $\alpha([C]) \subseteq [D]$. As α distributes over arbitrary union, it follows that $\alpha([c]) \subseteq [D]$ for all $c \in C$. We note that every such $c \in C$ is also the start of some trajectories in M , and it therefore follows from the refinement assumption that there exist a trajectory in N with a start $d \in \mathbb{D}$ such that $\{c\} \ll \{d\}$, or $\alpha([c]) \subseteq [d]$. By the requirement that $\alpha([c]) \neq \emptyset$,

it must be that $[d] \cap [D] \neq \emptyset$. By lemma 1 then, we know $[d] \subseteq [D]$ and thus $d \in D$, which is the first property required of \ll . For the second property, that \ll is a simulation relation, consider any “next-step” of these trajectories starting in c and d , i.e. $c' \in M(\{c\})$ and $d' \in N(\{d\})$. From the refinement assumption we know that $\{c'\} \ll \{d'\}$, or $\alpha(\{c'\}) \subseteq [d'] \subseteq [N(\{d\})] \subseteq [N(D)]$. Taking the union of every such ordering for $c' \in M(\{c\})$, we see that $M(\{c\}) \ll N(D)$ for all $c \in C$, or $M(C) \ll N(D)$, as required.

(\Leftarrow) : We show this claim by induction on the length of τ . For the base case, $|\tau| = 1$, we are given $\tau = \langle \tau_1 \rangle$ where τ_1 is unconstrained, i.e. we only know that $\tau_1 \in \mathbb{C}$. But a Galois connection always relates the most general states of its two partially ordered sets, so $\alpha(\{\mathbb{C}\}) \subseteq \{\mathbb{D}\}$. As $[\{\mathbb{C}\}] = \{\mathbb{C}\}$ and $[\{\mathbb{D}\}] = \{\mathbb{D}\}$, we also have $\alpha([\{\mathbb{C}\}]) \subseteq [\{\mathbb{D}\}]$, or $\{\mathbb{C}\} \ll \{\mathbb{D}\}$. Using the first property of \ll then tells us that there exists $d \in \mathbb{D}$ such that $|\langle \tau_1 \rangle| = |\langle d \rangle|$ and $\{\tau_1\} \ll \{d\}$. For the inductive step, $|\tau| = n + 1$, we are given a sequence $\langle \dots, \tau_n, \tau_{n+1} \rangle$ and assume there exists another sequence $\langle \dots, v_n \rangle$ such that $|\langle \dots, \tau_n \rangle| = |\langle \dots, v_n \rangle|$ and $\langle \dots, \tau_n \rangle \ll \langle \dots, v_n \rangle$. From the simulation property of \ll , we know that $M(\tau_n) \ll N(v_n)$ and, by the definition of trajectories, that $\tau_{n+1} \in M(\tau_n)$. Applying the first property of \ll then states that there exists $d \in N(v_n)$ such that $\{\tau_{n+1}\} \ll \{d\}$. The concatenation of $\langle \dots, v_{n+1} \rangle$ and $\langle d \rangle$, i.e. $\langle \dots, v_n, d \rangle$, forms a valid trajectory in $\text{Traj}(N)$ and satisfies the properties $|\langle \dots, \tau_n, \tau_{n+1} \rangle| = |\langle \dots, v_n, d \rangle|$ and $\langle \dots, \tau_n, \tau_{n+1} \rangle \ll \langle \dots, v_n, d \rangle$. \square

A.3 Theorem 3

First a lemma that shows $[\hat{p} \sqcap \hat{\pi}_a(s)] \Leftrightarrow [\hat{p}] \sqcap \hat{\pi}_a(s)$ is a reasonable assumption.

Lemma 5. $([D] = D) \Rightarrow ([C \sqcap D] \Leftrightarrow [C] \sqcap D)$

$$\begin{aligned}
 x \in [C \sqcap D] &\Leftrightarrow \exists y : x \sim y \wedge y \in C \wedge y \in D && (\text{def. of } [\cdot] \text{ and } \sqcap) \\
 &\Leftrightarrow \exists y : x \sim y \wedge y \in C \wedge x \in D && (x \sim y \text{ and } D = [D]) \\
 &\Leftrightarrow x \in [C] \wedge x \in D && (\text{def. of } [\cdot]) \\
 &\Leftrightarrow x \in [C] \sqcap D && (\text{def. of } \sqcap)
 \end{aligned}$$

Secondly we show a few helpful lemmas that regard the fix-points and functions used to determine satisfaction with \hat{M} and \hat{N} . Before that, we duplicate the earlier definitions of F , \mathcal{F} and Φ to differentiate between those used with \hat{M} and those with \hat{N} . Specifically, let G , \mathcal{G} and Ψ be equivalent operations for \hat{N} , as F , \mathcal{F} and Φ are for \hat{M} :

$$\begin{aligned}
 G(s)(\hat{q}) &= \hat{N}(\pi_a(s) \sqcap \hat{q}) \\
 \mathcal{G}(\Psi)(s) &= \text{if } (s = s_0) \text{ then } \top \text{ else } \sqcup \{G(s')(\Psi(s')) \mid (s', s) \in R\} \\
 \Psi_n &= \text{if } (n = 0) \text{ then } (\lambda s \in S : \perp) \text{ else } \mathcal{G}(\Psi_{n-1})
 \end{aligned}$$

Furthermore, let Ψ_* be the least fixpoint of $\Psi = \mathcal{G}(\Psi)$ and given by $\lim \Psi_n(s)$.

Lemma 6. $\perp \lll \perp \mathcal{E} \top \lll \top$

A Galois connection always relates the two tops and bottoms, i.e. $\hat{\alpha}(\top) \sqsubseteq \top$ and $\hat{\alpha}(\perp) \sqsubseteq \perp$. Because $\llbracket \cdot \rrbracket$ preserves both tops and bottoms, it then follows that both $\hat{\alpha}(\llbracket \top \rrbracket) \sqsubseteq \llbracket \top \rrbracket$, or $\top \lll \top$, and $\hat{\alpha}(\llbracket \perp \rrbracket) \sqsubseteq \llbracket \perp \rrbracket$, or $\perp \lll \perp$, holds as well.

Lemma 7. $\hat{p} \lll \hat{q} \Rightarrow \forall s \in S : F(s)(\hat{p}) \lll G(s)(\hat{q})$

$$\begin{aligned}
\hat{\gamma}(\llbracket G(s)(\hat{q}) \rrbracket) &= \hat{\gamma}(\llbracket \hat{N}(\hat{\pi}_a(s) \sqcap \hat{q}) \rrbracket) && \text{(def. of } G) \\
&\sqsupseteq \llbracket \hat{M}(\hat{\gamma}(\hat{\pi}_a(s) \sqcap \hat{q})) \rrbracket && \text{(simulation rel.)} \\
&= \llbracket \hat{M}(\hat{\gamma}(\hat{\pi}_a(s)) \sqcap \hat{\gamma}(\hat{q})) \rrbracket && (\hat{\gamma} \text{ dist. over } \sqcap) \\
&\sqsupseteq \llbracket \hat{M}(\hat{\gamma}(\hat{\pi}_a(s)) \sqcap \hat{p}) \rrbracket && (?) \\
&= \llbracket F(s)(\hat{p}) \rrbracket && \text{(def. of } F)
\end{aligned}$$

Lemma 8. $\forall s \in S : \Phi_*(s) \lll \Psi_*(s)$

Since $\Phi_*(s) = \lim \Phi_n(s)$ and $\Psi_*(s) = \lim \Psi_n(s)$, it suffices to prove that $\Phi_n(s) \lll \Psi_n(s)$ for all $s \in S$ and $n \in \mathbb{N}$. We do so by induction on n . The base case, where $\Phi_0(s) = \perp$ and $\Psi_0(s) = \perp$, follows from lemma 6. For the inductive step, assume that $\Phi_n(s) \lll \Psi_n(s)$ for all $s \in S$. For $s = s_0$, we have that $\Phi_{n+1}(s_0) = \top$ and $\Psi_{n+1}(s_0) = \top$, which also follows from lemma 6. For any $s \neq s_0$, we have:

$$\begin{aligned}
\hat{\gamma}(\llbracket \Psi_{n+1}(s) \rrbracket) &= \hat{\gamma}(\llbracket \mathcal{G}(\Psi_n)(s) \rrbracket) && \text{(def. of } \Psi_{n+1}) \\
&= \hat{\gamma}(\llbracket \sqcup \{G(s')(\Psi_n(s')) \mid (s', s) \in R\} \rrbracket) && \text{(def. of } \mathcal{G}) \\
&= \hat{\gamma}(\sqcup \{\llbracket G(s')(\Psi_n(s')) \rrbracket \mid (s', s) \in R\}) && (\llbracket \cdot \rrbracket \text{ dist. over } \sqcup) \\
&\sqsupseteq \sqcup \{\hat{\gamma}(\llbracket G(s')(\Psi_n(s')) \rrbracket) \mid (s', s) \in R\} && (\hat{\gamma} \text{ is monotone}) \\
&\sqsupseteq \sqcup \{\llbracket F(s')(\Phi_n(s')) \rrbracket \mid (s', s) \in R\} && \text{(I.H and lemma 7)} \\
&= \llbracket \sqcup \{F(s')(\Phi_n(s')) \mid (s', s) \in R\} \rrbracket && (\llbracket \cdot \rrbracket \text{ dist. over } \sqcup) \\
&= \llbracket \mathcal{F}(\Phi_n)(s) \rrbracket && \text{(def. of } \mathcal{F}) \\
&= \llbracket \Phi_{n+1}(s) \rrbracket && \text{(def. of } \Phi_{n+1})
\end{aligned}$$

Consider an arbitrary $s \in S$ and let $\hat{p} = \Phi_*(s) \sqcap \hat{\gamma}(\hat{\pi}_a(s))$, where $\hat{p} \sqsubseteq \Phi_*(s)$ and $\hat{p} \sqsubseteq \hat{\gamma}(\hat{\pi}_a(s))$, or $\hat{\alpha}(\hat{p}) \sqsubseteq \hat{\pi}_a(s)$. From lemma 8 we know $\Phi_*(s) \lll \Psi_*(s)$, and thus $\hat{\alpha}(\hat{p}) \sqsubseteq \hat{\alpha}(\llbracket \hat{p} \rrbracket) \sqsubseteq \hat{\alpha}(\llbracket \Phi_*(s) \rrbracket) \sqsubseteq \llbracket \Psi_*(s) \rrbracket$ by the monotonicity of $\llbracket \cdot \rrbracket$ and $\hat{\alpha}$. Using the invariance of $\hat{\pi}_a(s)$ and property **name** of $\llbracket \cdot \rrbracket$, we note that the assumption can be restated as $\hat{\pi}_a(s) \sqsupseteq \Psi_*(s) \sqcap \hat{\pi}_a(s) = \llbracket \Psi_*(s) \rrbracket \sqcap \hat{\pi}_a(s)$. It then follows that $\hat{\alpha}(\hat{p}) \sqsubseteq \hat{\pi}_c(s)$, or $\hat{p} \sqsubseteq \hat{\gamma}(\hat{\pi}_c(s))$ as desired. \square

A.4 Theorem 4

Text.

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