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# PLAYING YAHTZEE WITH DEEP REINFORCEMENT LEARNING - A SYSTEMATIC COMPARISON OF DIFFERENT APPROACHES

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A PREPRINT

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## ABSTRACT

In this paper we present an open source Q-learning algorithm for the dice game yahtzee. We implemented a variation of the Q-learning algorithm as used by Mnih [?], which he used for playing Atari games. The specific obstacles of yahtzee are thereby to handle two different types of possible actions: 1) choose what dice to re-roll; 2) choose a category on the score board, the significantly larger number possible actions of type 1 compared to an Atari game controller and the randomness in the response of the game to the players actions of type 1. By presenting different implementations of increasing complexity, we give the reader an overview of different concepts to improve the performance of Q-learning for certain situations and evaluate their performance in the specific use case. Among those concepts are different exploration strategies, concepts to handle randomness and a technique for the efficient handling of the two decision types. The most successful implementation achieves superhuman performance within a few thousand training cycles.

**Keywords** Q-learning · neural networks · exploration strategies · replay memory

## 1 Introduction

The complete source code of this project is publicly available at

<https://github.com/markusdutschke/yahtzee>

Since Mnih's famous publication 'Playing Atari with deep reinforcement learning' [?] strong research interest has evolved around the possibilities of Q-learning in combination with neural networks. Thereby computer and board games turned out to be an excellent playground for this research, due to their complex character, their easy reproducibility and the clear definition of the systems rules.

Especially the dice game Yahtzee has a set of interesting properties, which makes it especially suitable for a Q-learning test system.

- Yahtzee is a broadly known game.
- Even after several hundred games, Yahtzee is still challenging for human player.
- There is a mixture of randomness and strategy involved.
- Yahtzee is exactly solved, but this is far beyond the score of the abilities of a human brain.

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\*Use footnote for providing further information about author (webpage, alternative address)—*not* for acknowledging funding agencies.

## 2 The dice game Yahtzee

### 2.1 Rules

### 2.2 Code

Relate the rule with the different classes in the code. Especially: Dice, ScoreBoard, Game and AbstractPlayer

### 2.3 Existing literature

## 3 Q-learning

This chapter contains all the theoretical background of the code.

### 3.1 Background

### 3.2 Handling the two decision types

### 3.3 Information encoding

### 3.4 Exploration

### 3.5 Concepts to handle a stochastic system response

## 4 Implementations

This chapter is just a description of the different implementations and their performance.

### 4.1 Naive Implementations

- random implementation - greedy implementation with and without re-roll

### 4.2 AI player Version 0

### 4.3 AI player Version 1

### 4.4 AI player Version 2

## 5 Benchmark

In this chapter the benefit of different Q-learning concepts are quantitatively benchmarked. The implementation of these benchmarks can be found in the functions bench... in main.py with player implementations in botBench.py

### 5.1 Information encoding

Different encodings. Not yet sure, what to compare. Maybe: rgrSC with - 13 inputs (-1 for empty, otherwise score) - 26 inputs (first 13: 0 for empty, second 13: 0 or 1 for empty and used) - a good encoding (check maybe player v2)

### 5.2 Exploration

- epsilon greedy - softmax - minMaxRat

### 5.3 Concepts to handle a stochastic system response

- implicitly in MLP regressor (v0) - explicitly in mlprgr with pretraining and benchmarking (this is v1) - exactly by lookup table (v2)

## 6 Conclusion

Collection of key facts, whatever turned out to bring the most significant improvement.

## 7 NOW FOLLOWS THE TEMPLATE

### 8 Headings: first level

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See Section 8.

#### 8.1 Headings: second level

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$$\xi_{ij}(t) = P(x_t = i, x_{t+1} = j | y, v, w; \theta) = \frac{\alpha_i(t) a_{ij}^{w_t} \beta_j(t+1) b_j^{v_{t+1}}(y_{t+1})}{\sum_{i=1}^N \sum_{j=1}^N \alpha_i(t) a_{ij}^{w_t} \beta_j(t+1) b_j^{v_{t+1}}(y_{t+1})} \quad (1)$$

##### 8.1.1 Headings: third level

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## 9 Examples of citations, figures, tables, references

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[1, 2] and see [3].

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<http://mirrors.ctan.org/macros/latex/contrib/natbib/natnotes.pdf>

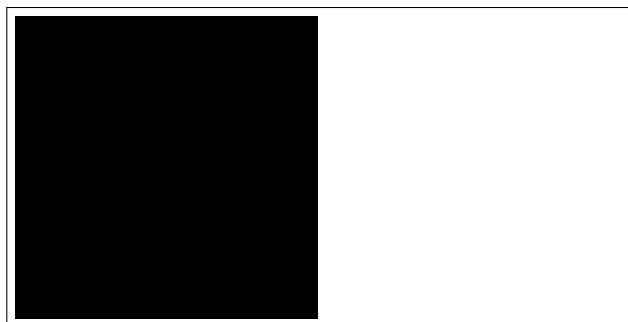


Figure 1: Sample figure caption.

Table 1: Sample table title

Part		
Name	Description	Size ( $\mu\text{m}$ )
Dendrite	Input terminal	$\sim 100$
Axon	Output terminal	$\sim 10$
Soma	Cell body	up to $10^6$

Of note is the command `\citet`, which produces citations appropriate for use in inline text. For example,

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produces

Hasselmo, et al. (1995) investigated...

<https://www.ctan.org/pkg/booktabs>

## 9.1 Figures

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See awesome Table 1.

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