

Electric Vehicles

Homework – DC Motor Drives

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Problem 1 - A permanent-magnet dc motor with the following parameters:

$K\phi := 0.5 \cdot \text{Wb}$ (in a permanent magnet motor, the flux cannot be changed)

The armature resistance is $R_A := 0.25 \text{ ohm}$; The rated torque $T_{rated} := 12 \text{ N}\cdot\text{m}$;

The rated speed: $\omega_m := 3700 \cdot \text{rpm}$

- a) Calculate the terminal voltage V_A , if the motor is required to deliver a torque of $T_{load_1} := 5 \cdot \text{N}\cdot\text{m}$ at a speed of $\omega_m := 1500 \cdot \text{rpm}$ (Answer: $V_A = 81.04 \text{ V}$)
- b) Compute the winding (copper) losses in the armature winding problem (a)
- c) Compute the input power and the efficiency of the motor for problem (a)

Problem 2 - A separately-excited dc motor with the following parameters:

The armature resistance is $R_A := 0.45 \text{ ohm}$; The rated torque $T_{rated} := 11 \text{ N}\cdot\text{m}$;

The rated speed: $\omega_{m_rated} := 2000 \cdot \text{rpm}$; Rated armature current $I_{A_rated} := 20 \text{ A}$

- At rated flux calculate the $K\phi$ of this motor to get rated torque at rated armature current (Answer $K\phi = 0.55 \text{ Wb}$)
- At rated power and rated speed, the efficiency is computed to be $Eff := 90\%$ calculate the field winding loss (Answer $P_{field_wdg} = 75.982 \text{ W}$)
- The motor is operated 120% rated speed, thus, the motor must be operated in flux weakening region (constant power region) because the voltage V_A has reached its maximum limit. Calculate the reduced flux for this operation (Answer $K\phi = 0.458 \text{ Wb}$)
- Calculate the maximum torque you can get for problem (c) without overloading the motor?

DC-Motor Drive Capabilities

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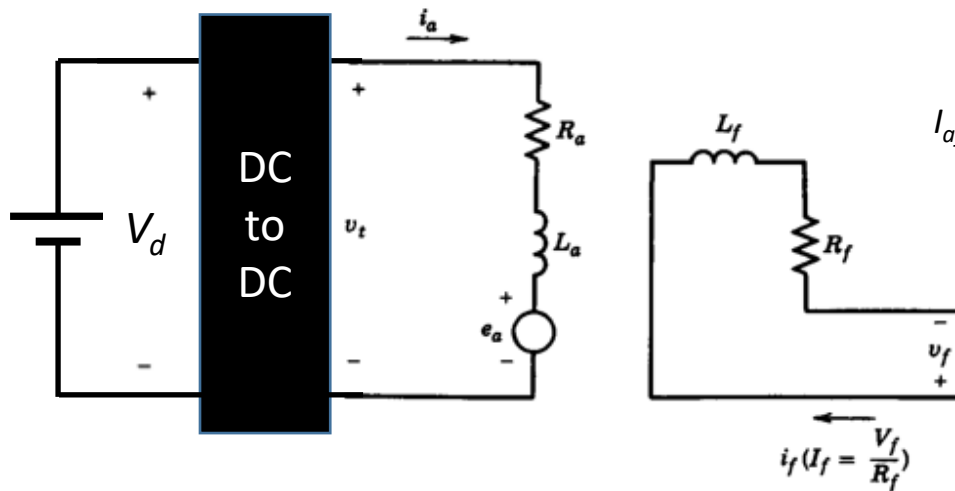
Problem 3

Describe the operation of the Separately excited DC Motor drives shown in this page.

Example $V_{t1}, I_{a1} > 1.0\text{pu}$, $T_{em1} > 1.0\text{pu}$, $P_{input1} < 1.0\text{pu}$, Overload

Questions:

V_{t2}
 V_{t3}
 V_{t4}
 V_{t5}
 V_{t6}
 V_{t7}



(a)

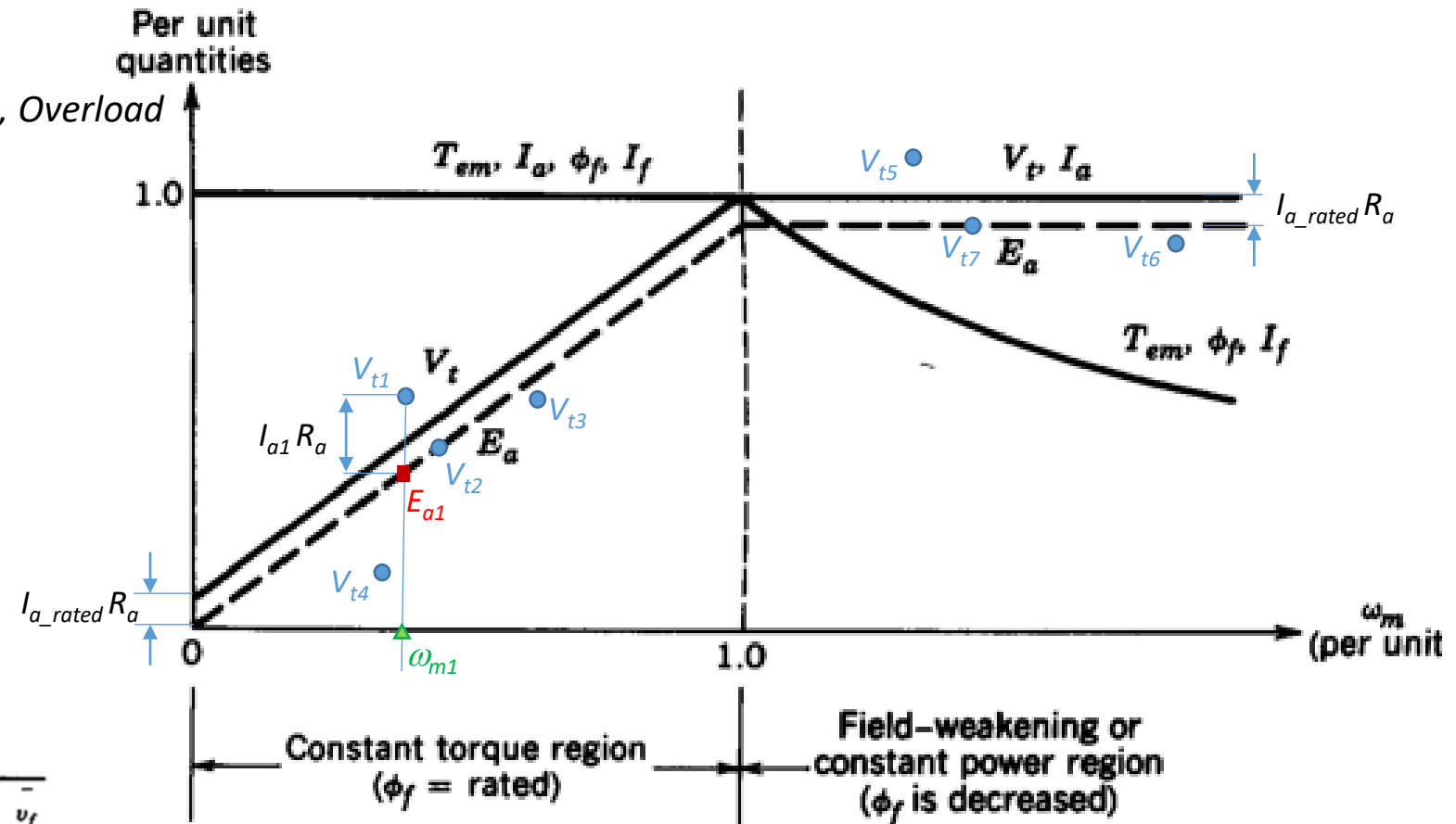


Figure 13-5 Separately excited dc motor: (a) equivalent circuit; (b) continuous torque–speed capability.