## Linear Algebra

Notes by Markus Renoldner Based on the lecture Lineare Algebra für Technische Physik at the TU Wien March 25, 2023

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Let V be a vector space over K (usually  $K = \mathbb{R}$  or  $K = \mathbb{C}$ ) with a basis  $B = \{\boldsymbol{b}_1, ... \boldsymbol{b}_n\}$  then every  $\boldsymbol{v} \in V$  can be expressed as a linear combination of coefficients  $\lambda_i \in K$  and basis vectors  $\boldsymbol{b}_i$ :

$$v = \sum_{i=1}^{n} \lambda_i \cdot v_i \tag{1}$$

**Example 1** (Vector expressed in a basis). Let  $\boldsymbol{x} = \begin{pmatrix} 3 \\ 2 \end{pmatrix} \in \mathbb{R}^2$ 

$$B_1 = \{ \boldsymbol{e}_1, \boldsymbol{e}_2 \}$$
 (the canonical basis) and  $B_2 = \{ \boldsymbol{b}_1, \boldsymbol{b}_2 \}$  with  $\boldsymbol{b}_1 := \begin{pmatrix} 1 \\ -1 \end{pmatrix}$  and  $\boldsymbol{b}_2 := \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ 

1. Of course 
$$\mathbf{x} = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$$