

Linear maps and matrices

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1 Kernel and image

2 Matrices

2.1 Rank

2.2 Inverse

2.3 Linear systems of equations

3 Linear maps

3.1 Change of basis

Let V be a vector space over K (usually $K = \mathbb{R}$ or $K = \mathbb{C}$) with a basis $B = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$ then every $\mathbf{v} \in V$ can be expressed as a linear combination of coefficients $\lambda_i \in K$ and basis vectors \mathbf{b}_i :

$$\mathbf{v} = \sum_{i=1}^n \lambda_i \cdot \mathbf{v}_i \tag{1}$$

Example 1 (Vector expressed in a basis). Let $\mathbf{x} = \begin{pmatrix} 3 \\ 2 \end{pmatrix} \in \mathbb{R}^2$

$B_1 = \{\mathbf{e}_1, \mathbf{e}_2\}$ (the canonical basis) and $B_2 = \{\mathbf{b}_1, \mathbf{b}_2\}$ with $\mathbf{b}_1 := \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ and $\mathbf{b}_2 := \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

Then:

1. Of course $\mathbf{x} = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$