Linear Algebra

Notes by Markus Renoldner Based on the lecture Lineare Algebra für Technische Physik at the TU Wien March 25, 2023

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Let V be a vector space over K (usually $K = \mathbb{R}$ or $K = \mathbb{C}$) with a basis $B = \{\boldsymbol{b}_1, ... \boldsymbol{b}_n\}$ then every $\boldsymbol{v} \in V$ can be expressed as a linear combination of coefficients $\lambda_i \in K$ and basis vectors \boldsymbol{b}_i :

$$\boldsymbol{v} = \sum_{i=1}^{n} \lambda_i \cdot \boldsymbol{v}_i \tag{1}$$

Example 1 (Vector expressed in a basis). Let $\boldsymbol{x} = \begin{pmatrix} 3 \\ 2 \end{pmatrix} \in \mathbb{R}^2$

$$B_1 = \{ \boldsymbol{e}_1, \boldsymbol{e}_2 \}$$
 (the canonical basis) and $B_2 = \{ \boldsymbol{b}_1, \boldsymbol{b}_2 \}$ with $\boldsymbol{b}_1 := \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ and $\boldsymbol{b}_2 := \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ Then:

1. Of course x =