

VARIATIONAL PREDICTION & TRANSDUCTIVE LEARNING

Mark van der Wilk

March 28, 2024



Department of
COMPUTER
SCIENCE

Variational Prediction

Bayesian Models

In ML, we only care about the **predictive distribution**:

$$p(\mathbf{y}^* \mid \mathbf{y}).$$

Impossible to specify directly (name one case where possible).

Usually easier to specify a *generative model* $p(\mathbf{y}, \mathbf{y}^*)$:

$$p(\mathbf{y}^* \mid \mathbf{y}) = \frac{p(\mathbf{y}^*, \mathbf{y})}{p(\mathbf{y})}$$

Usually easier to specify with parameters (exchangeable, de Finetti's theorem):

$$p(\mathbf{y}, \mathbf{y}^*) = \int \left[\prod_{y_i \in (\mathbf{y}, \mathbf{y}^*)} p(y_i \mid \theta) \right] p(\theta) \, d\theta$$

Bayesian Models: Take-homes

❓ If we reparameterise θ , will $p(\mathbf{y}^*, \mathbf{y})$ change?

I.e. $\theta' = t(\theta)$, $P_{\theta'}(B) = P_{\theta}(t^{-1}(B))$.

❓ If we reparameterise θ , will $p(\mathbf{y}^* | \mathbf{y})$ change?

❓ If we reparameterise θ , will $p(\mathbf{y})$ change?

- Specific parameterisation doesn't matter to *observables*.
- We don't really care about any properties of parameters, they are simply a **means to an end**.

Variational Inference

Find $q(\theta) \approx p(\theta|\mathbf{y})$ by

$$\arg \min_{q \in Q} \text{KL}[q(\theta) \parallel p(\theta|\mathbf{y})].$$

Find $p(\mathbf{y}^*|\mathbf{y})$ as

$$p(\mathbf{y}^*|\mathbf{y}) \approx q(\mathbf{y}^*) = \int p(\mathbf{y}^*|\theta)q(\theta) \, \mathrm{d}\theta.$$



This is a pain, needs Monte Carlo.



Can we not find $q(\mathbf{y}^*) \approx p(\mathbf{y}^*|\mathbf{y})$ directly?

We want to avoid:

- costly MC integration to find predictive $p(\mathbf{y}^*|\mathbf{y})$.
- computation wasted on parameters, and focus on prediction.

Variational Prediction

Want to minimise

$$\begin{aligned}\text{KL}[q_{\mathbf{y}^*} \| p_{\mathbf{y}^*|\mathbf{y}}] &= \int q(\mathbf{y}^*) \log \frac{q(\mathbf{y}^*)}{p(\theta|\mathbf{y})} d\mathbf{y}^* \\ &= \int q(\mathbf{y}^*) \log \frac{q(\mathbf{y}^*)p(\mathbf{y})}{\int p(\mathbf{y}^*|\theta)p(\mathbf{y}|\theta)p(\theta) d\theta} d\mathbf{y}^*\end{aligned}$$

So, sadly, the usual variational inference trick doesn't apply, since the integral prevents us from getting expectations over tractable densities (which allows low-variance MC estimation in VI).

Any ideas?

- Jensen's inequality over $\int \dots d\theta$?

Tractable Variational Prediction

We *can* instead minimise

$$\text{KL} [q_{\mathbf{y}^*, \theta} \| p_{\mathbf{y}^*, \theta | \mathbf{y}}] = \text{KL} [q_{\mathbf{y}^*} \| p_{\mathbf{y}^* | \mathbf{y}}] + \underbrace{\mathbb{E}_{q_{\mathbf{y}^*}} [\text{KL} [q_{\theta | \mathbf{y}^*} \| p_{\theta | \mathbf{y}, \mathbf{y}^*}]]}_{\geq 0}$$

$$\therefore \text{KL} [q_{\mathbf{y}^*, \theta} \| p_{\mathbf{y}^*, \theta | \mathbf{y}}] \geq \text{KL} [q_{\mathbf{y}^*} \| p_{\mathbf{y}^* | \mathbf{y}}]$$

This *does* give a MC-tractable ELBO [1]:

$$\begin{aligned} \text{KL} [q_{\mathbf{y}^*, \theta} \| p_{\mathbf{y}^*, \theta | \mathbf{y}}] &= \int q(\mathbf{y}^*, \theta) \log \frac{q(\mathbf{y}^*, \theta) \textcolor{red}{p}(\textcolor{red}{y})}{p(\mathbf{y}^* | \theta) p(\mathbf{y} | \theta) p(\theta)} d\mathbf{y}^* d\theta \\ \therefore \textcolor{red}{\log p(\mathbf{y})} - \textcolor{red}{\text{KL}} [\textcolor{red}{q} \| \textcolor{red}{p}_{\mathbf{y}^*, \theta | \mathbf{y}}] &= \underbrace{\int q(\mathbf{y}^*, \theta) \log \frac{p(\mathbf{y}^* | \theta) p(\mathbf{y} | \theta) p(\theta)}{q(\mathbf{y}^*, \theta)} d\mathbf{y}^* d\theta}_{\mathcal{L}} \end{aligned}$$

Tractable Variational Prediction

Putting the bound in another form:

$$\begin{aligned}\mathcal{L} = & \mathbb{E}_{q_{\mathbf{y}^*}} \left[\mathbb{E}_{q_{\theta|\mathbf{y}^*}} [\log p(\mathbf{y}|\theta) + \log p(\mathbf{y}^*|\theta)] \right] + \\ & - \mathbb{E}_{q_{\mathbf{y}^*}} \left[\text{KL} \left[q_{\theta|\mathbf{y}^*} \parallel p_{\theta} \right] \right] + \\ & \mathcal{H}[q(\mathbf{y}^*)]\end{aligned}$$

This is very similar to the familiar variational bound.

A. A. Alemi and B. Poole [1] suggest to parameterise $q(\mathbf{y}^*, \theta)$ by taking

$$\begin{aligned}q_{\mathbf{y}^*} &\in Q_p \\ q_{\theta|\mathbf{y}^*} &\in Q_c\end{aligned}\quad \text{NB: Conditionals!}$$

When is this Useful?

Remember our goals!

- Definitely useful when we want to obtain $q(\mathbf{y}^*) \approx p(\mathbf{y}^*|\mathbf{y})$ *at training time*.

? What is an example of a model where this is useful?

Diffusion models? Good to amortise generation cost at training?

When does VP work?

What does “work” mean?

\Rightarrow We obtain low $\text{KL}[q_{\mathbf{y}^*} \parallel p_{\mathbf{y}^*|\mathbf{y}}]$.

Remember:

$$\text{KL}[q_{\mathbf{y}^*,\theta} \parallel p_{\mathbf{y}^*,\theta|\mathbf{y}}] = \text{KL}[q_{\mathbf{y}^*} \parallel p_{\mathbf{y}^*|\mathbf{y}}] + \mathbb{E}_{q_{\mathbf{y}^*}} [\text{KL}[q_{\theta|\mathbf{y}^*} \parallel p_{\theta|\mathbf{y},\mathbf{y}^*}]]$$

- Sufficient: $\text{KL}[q_{\mathbf{y}^*,\theta} \parallel p_{\mathbf{y}^*,\theta|\mathbf{y}}]$ is small.
- $\text{KL}[q_{\theta|\mathbf{y}^*} \parallel p_{\theta|\mathbf{y},\mathbf{y}^*}]$ is constant over \mathbf{y}^* , and our parameterisation of $q(\mathbf{y}^*)$ is flexible.

Transductive Learning

Defining (Bayesian) Transductive Learning

When can we say that transductive learning has taken place?

Transductive Learning

We want the predictions *that we care about* to be better, *without* our inductive learning capability getting better.

For transductive learning to have taken place, we need:

$$\begin{aligned}\text{KL}[q_{\theta}^{\text{VI}} \parallel p_{\theta|y}] &\leq \text{KL}[q_{\theta}^{\text{VP}} \parallel p_{\theta|y}] \\ \text{KL}[q_{y^*}^{\text{VI}} \parallel p_{y^*|y}] &\geq \text{KL}[q_{y^*}^{\text{VP}} \parallel p_{y^*|y}]\end{aligned}$$

 Can we prove that VP can/cannot do transductive learning?

I don't know, happy to chat.

Bayesian Transductive Learning

We only know

$$\begin{aligned}\text{KL} [q_{\mathbf{y}^*, \theta}^{\text{VP}} \| p_{\mathbf{y}^*, \theta | \mathbf{y}}] &= \text{KL} [q_{\mathbf{y}^*}^{\text{VP}} \| p_{\mathbf{y}^* | \mathbf{y}}] + \mathbb{E}_{q_{\mathbf{y}^*}} [\text{KL} [q_{\theta | \mathbf{y}^*}^{\text{VP}} \| p_{\theta | \mathbf{y}, \mathbf{y}^*}]] \\ &= \text{KL} [q_{\theta}^{\text{VP}} \| p_{\theta | \mathbf{y}}] + \mathbb{E}_{q_{\theta}} [\text{KL} [q_{\mathbf{y}^* | \theta}^{\text{VP}} \| p_{\mathbf{y}^* | \theta, \mathbf{y}}]]\end{aligned}$$

If we assume that $Q_M \subseteq Q$ the implied $q_{\theta}^{\text{VP}} \in Q_M$, then we have

$$\text{KL} [q_{\mathbf{y}^*, \theta}^{\text{VP}} \| p_{\mathbf{y}^*, \theta | \mathbf{y}}] \geq \text{KL} [q_{\theta}^{\text{VI}} \| p_{\theta | \mathbf{y}}]$$

We can also find (but of limited help):

$$\text{KL} [q_{\theta}^{\text{VI}} \| p_{\theta | \mathbf{y}}] > \text{KL} [q_{\mathbf{y}}^{\text{VI}} \| p_{\mathbf{y} | \mathbf{y}^*}] \quad \text{DPI}$$

Data Processing Inequality

Given a conditional $p(\mathbf{y}|\theta)$, and marginals

$$p(\theta) \quad \Rightarrow \quad p(\mathbf{y}) = \int p(\mathbf{y}|\theta)p(\theta) \, d\theta$$

$$q(\theta) \quad \Rightarrow \quad q(\mathbf{y}) = \int p(\mathbf{y}|\theta)q(\theta) \, d\theta$$

Then,

$$\text{KL}[q_\theta \parallel p_\theta] \geq \text{KL}[q_\mathbf{y} \parallel p_\mathbf{y}].$$



Data Processing Inequality

Any processing cannot make distributions easier to distinguish from one another.

**Variational Prediction
for
Sparse Gaussian Processes**

Sparse Gaussian Processes

They are a great testbed for inference methods, because:

- You can control for many variables (e.g. control for optimisation behaviour by finding variational dists in closed-form)
- You can mathematically characterise/understand the true posterior (closed-form, but *computationally* intractable) [2]
- It is actually possible to get to the very accurate regime [3], [4]
- Parameters *are* predictions (specifically relevant for this case)

Transductive learning in approx GPs should concentrate inducing points around prediction areas. Board.

Variational Prediction for Sparse GPs

VP tells us to minimise $\text{KL} \left[q_{\mathbf{y}^*, \theta}^{\text{VP}} \| p_{\mathbf{y}^*, \theta | \mathbf{y}} \right]$.

For Sparse GPs, $\theta = (\mathbf{f}, \mathbf{u})$, $\mathbf{y} = \mathbf{f}^*$, so

$$\text{KL} \left[q_{\mathbf{f}^*, \mathbf{f}, \mathbf{u}}^{\text{VP}} \| p_{\mathbf{f}^*, \mathbf{f}, \mathbf{u} | \mathbf{y}} \right].$$

We choose the usual special posterior, but we need an arbitrary joint between \mathbf{f}^* and \mathbf{u} :

$$q(\mathbf{f}^*, \mathbf{f}, \mathbf{u}) = q(\mathbf{f}^*, \mathbf{u})p(\mathbf{f} | \mathbf{u}, \mathbf{f}^*)$$



This is a normal inducing point approximation

The targeted distribution is just the normal *full* posterior over functions.

Conclusion

Conclusion

- You can train a predictive distribution with variational inference
A. A. Alemi and B. Poole [1].
 - They haven't managed to get it to work at large scale.
 - My guess is that the goal is to speed up generation in diffusion models.
- Can *also* be thought of as a way to do Bayesian transductive learning.
- Not clear whether it actually can.
 - Can *any* Bayesian method do transductive learning? Or are we forced to do inference over everything, and be hampered in performance by the poorest part?
- In GPs, it just becomes the usual method, approximating the whole posterior.

Bibliography

- [1] A. A. Alemi and B. Poole, “Variational Prediction,” *arXiv preprint arXiv:2307.07568*, 2023.
- [2] M. Bauer, M. Van der Wilk, and C. E. Rasmussen, “Understanding probabilistic sparse Gaussian process approximations,” *Advances in neural information processing systems*, vol. 29, 2016.
- [3] D. R. Burt, C. E. Rasmussen, and M. van der Wilk, “Rates of Convergence for Sparse Variational Gaussian Process Regression,” in *Proceedings of the 36th International Conference on Machine Learning*, in Proceedings of Machine Learning Research. 2019.

- [4] D. R. Burt, C. E. Rasmussen, and M. van der Wilk,
“Convergence of Sparse Variational Inference in Gaussian
Processes Regression,” *Journal of Machine Learning Research*,
2020.