Gaussian Processes

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Recap: Model

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- ▶ Defines distribution on functions through $f(\mathbf{x}) = \phi(\mathbf{x})^\mathsf{T} \mathbf{w}$
- ► Observe data through likelihood $p(\mathbf{y}|f(X)) = \prod_{n=1}^{N} \mathcal{N}(y_n; f(\mathbf{x}_n), \sigma^2)$

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- ► Combine this with $p(\mathbf{y}^*|\mathbf{w})$ to find $p(\mathbf{y}^*|\mathbf{y})$:

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▶ Apply Woodbury to go from $O(NM^2 + M^3) \rightarrow O(N^3)$:

$$\begin{split} p(y_*|\mathbf{y}) &= \mathcal{N}\Big(y_*; \quad \boldsymbol{\phi}(\mathbf{x}_*)^\mathsf{T} \Phi(X)^\mathsf{T} \big[\Phi(X) \Phi(X)^\mathsf{T} + \sigma^2 \boldsymbol{I}_N \big]^{-1} \mathbf{y} \,, \\ \boldsymbol{\phi}(\mathbf{x}_*)^\mathsf{T} \boldsymbol{\phi}(\mathbf{x}_*) + \sigma^2 \\ &- \boldsymbol{\phi}(\mathbf{x}_*)^\mathsf{T} \Phi(X)^\mathsf{T} \big[\Phi(X) \Phi(X)^\mathsf{T} + \sigma^2 \boldsymbol{I}_N \big]^{-1} \Phi(X) \boldsymbol{\phi}(\mathbf{x}_*) \Big) \end{split}$$

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- ▶ Apply Woodbury to go from $O(NM^2 + M^3) \rightarrow O(N^3)$:
- ► Apply Kernel trick $\phi(\mathbf{x})^{\mathsf{T}}\phi(\mathbf{x}') = k(\mathbf{x}, \mathbf{x}')$

$$p(y_*|\mathbf{y}) = \mathcal{N}\left(y_*; \quad k(\mathbf{x}_*, \mathbf{X}) \left[k(\mathbf{X}, \mathbf{X}) + \sigma^2 \mathbf{I}_N\right]^{-1} \mathbf{y}, \\ k(\mathbf{x}_*, \mathbf{x}_*) + \sigma^2 - k(\mathbf{x}_*, \mathbf{X}) \left[k(\mathbf{X}, \mathbf{X}) + \sigma^2 \mathbf{I}_N\right]^{-1} k(\mathbf{X}, \mathbf{x}_*)\right)$$

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- Develop interpretation of the maths we got from Woodbury
- ► This is a way of specifying distributions on functions
- But without parameters!

Model:

$$p(\mathbf{w}) = \mathcal{N}(\mathbf{w}; 0, \mathbf{I}_M) \tag{1}$$

$$f(\mathbf{x}) = \boldsymbol{\phi}(\mathbf{x})^{\mathsf{T}} \mathbf{w} \tag{2}$$

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- Predicting function values $p(f(X^*))|\mathbf{y})$

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- Kernel trick applies! $[\Phi(X)\Phi(X)^{\mathsf{T}}]_{ij} = \phi(\mathbf{x}_i)^{\mathsf{T}}\phi(\mathbf{x}_j) = k(\mathbf{x}_i, \mathbf{x}_j)$

Let's focus on $p(f(X^*)|\mathbf{y})$.

$$\begin{split} p(f(X^*)|\mathbf{y}) &\overset{\text{AT}}{=} \frac{\int p(\mathbf{y}, f(X), f(X^*)) \ \mathrm{d}f(X)}{p(\mathbf{y})} \\ &\overset{\text{MA}}{=} \frac{\int p(\mathbf{y}|f(X)) \ p(f(X), f(X^*)) \ \mathrm{d}f(X)}{p(\mathbf{y})} \end{split}$$

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$$p(f(X), f(X^*)) = \mathcal{N}\left(\begin{bmatrix} f(X) \\ f(X^*) \end{bmatrix}; 0, \begin{bmatrix} \Phi(X)\Phi(X)^\mathsf{T} & \Phi(X)\Phi(X^*) \\ \Phi(X^*)\Phi(X)^\mathsf{T} & \Phi(X^*)\Phi(X^*)^\mathsf{T} \end{bmatrix}\right)$$

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Easiest way: Find joint, Gaussian conditioning (board)

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$$p(f(X^*)|\mathbf{y}) = \mathcal{N}\left(f(X^*); \qquad k(X^*, X) \left[k(X, X) + \sigma^2 \mathbf{I}_N\right]^{-1} \mathbf{y},$$
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Who needs parameters?

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⇒ Can answer any prediction question using only distribution on function *values*.

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$$p(f(x_1), f(x_2)) = \int p(f(x_1), f(x_2), f(x_3)) df(x_3)$$
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Specifying Gaussian Processes

Can specify the function value densities p(f(X)) using:

- ▶ Mean function $\mu : \mathcal{X} \to \mathbb{R}$
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Covariance function $k(\cdot, \cdot)$ must be a positive definite function. I.e. k(X, X) is PSD for any choice of X.

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- ► ⇒ BLR specifies a GP and a kernel
- Directly specifying a kernel, also specifies a GP
- We viewed BLR as specifying a distribution on functions

GPs as distributions on functions

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- To make predictions, we only need distributions on function values
- So who needs parameters?
- ▶ BLR specifies a GP

Recommended reading

► Rasmussen and Williams (2006) §2.1 + §2.2

References I

Rasmussen, C. E. and Williams, C. K. (2006). Gaussian processes for machine learning. MIT press, Cambridge, MA, USA.