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# Convex-Hull
import sys
import arqparse
import math
# point tuple indexes
p_x = 0
p_y = 1
def area2(a, b, c):
    """ The area of a triangle with three points. """
    return ((b[p_x] - a[p_x])*(c[p_y] - a[p_y]) -
           (b[p y] - a[p y])*(c[p x] - a[p x]))
def is_left_of(a, b, c):
    """ Checks if the point a is to the left of the line from b to c.
    return area2(a, b, c) > 0
def is_colinear(a, b, c):
    """ Checks if the point a is collinear with the line from a to b.
    return area2(a, b, c) == 0
def is_right_of(a, b, c):
       Checks if the point a is to the right of the line from b to c. """
    return area2(a, b, c) < 0
def brute(points):
    Find the convex hull of a number of points using a brute for method.
    hull_pairs = []
    # for every two points
    for i in xrange(len(points)):
        for j in xrange(len(points)):
            if i != j:
                # Go through all the points and check if they're all on one side
                on_right = False # if we have points on the right
                on_left = False # if we have points on the left
                colinear = False # if we have colinear points
                # for all points that are not part of the line we're considering
                for p in points:
                    if p != points[i] and p != points[j]:
                        a = area2(p, points[i], points[j])
                        if a > 0:
                            on left = True
                        elifa < 0:
                            on_right = True
                        el se:
                            colinear = True
                # check if we have situations where all points are on one side
                # or colinear (all points are in a line so the convex hull is
                # the line)
                if (on_right and not on_left and not colinear) \
                   or (on_left and not on_right and not colinear) \
                   or (colinear and not on_right and not on_left):
                    hull_pairs.append((points[i], points[j]))
    return hull_pairs
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def vector(p1, p2):

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""" Returns the vector of two points.
    return (p2[p_x] - p1[p_x], p2[p_y] - p1[p_y])
def flip(x, y):
    return y, x
def graham scan(points):
   n = len(points)
    # find the anchor point (O(n))
    anchor = None
    for i, p in enumerate(points):
        if anchor is None or p[p_q] < points[anchor][p_q] or \</pre>
           (p[p y] == points[anchor][p y] and p[p x] < points[anchor][p x]):
           # go ahead and set the anchor
           anchor = i
    # sort the remaining points by creating a new list of indecies that are
    # sorted (O(nlogn))
    p_srtd = [x for x in xrange(n) if x != anchor]
    p_srtd. sort(
        key=lambda x: math.atan2(*flip(*vector(points[anchor], points[x])))
    # insert the anchor point
    print "anchor", anchor, points
    points.insert(0, points[anchor])
    # insert a sentinal point
    points.insert(0, points[0])
    print len(points), points
   points = [points[i] for i in p_srtd if isinstance(i, int)]
    # push the first three points onto the stack
    m = 2
   i = 3
    while i Kin:
        while area2(points[m-1], points[m], points[i]) <= 0:</pre>
            print 'i', i
            print 'm', m
            if m == 2:
                points[m], points[i] = points[i], points[m]
            el se:
                m = 1
        points(m), points(i) = points(i), points(m)
        i += 1
    return points
def qift_wrap(points):
    Find the convex hull for a number of points using the gift
    wrapping method, also known as the Jarvis march method.
    # degenerate cases
    if len(points) == 1 or len(points) == 2:
        return points
   hull = []
    # find the leftmost point
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point_on_hull = (float('inf'), float('inf'))
    for p in points:
        if (p[p_x] < point_on_hull[p_x]) or \</pre>
           (p[p_x] == point_on_hull[p_x] and p[p_y] < point_on_hull[p_y]):</pre>
            point_on_hull = p
    i = 0 # TODO; maybe take out
    while True:
        hull.append(point_on_hull)
        # initial endpoint candidate
        endpoint = points[0]
        for j in xrange(1,len(points)):
            if endpoint == point on hull or \
               is_left_of(points[j], point_on_hull, endpoint):
                endpoint = points[j]
        i = i + 1
        point_on_hull = endpoint
        # end case
        if endpoint == hull[0]: # we got to the beginning of the hull
    return hull
def parse_points_file(file_name):
    f = open(file_name)
    if f:
        points = []
        for l in f:
            try:
                points.append(tuple(map(int, l.split(','))))
            except:
                pass
        return points
    el se:
        return []
def plot(points, hull):
    import matplotlib.puplot as plt
    # setup the figure
    fiq = plt.fiqure()
    ax = fiq. add subplot(111)
    # plot the points
    x, y = zip(*points)
    ax.plot(x, y, 'ro')
    # check if we're plotting hull pairs or an ordered point list
    print hull
    if isinstance(hull[0][0], tuple):
        # we have hull pairs
        # loop through the connections
        for h in hull:
            # plot the hull
            x, y = zip(*h)
            ax.plot(x, y, 'go-')
    el se:
        # we have a list of hull points
        # close the hull
        hull.append(hull[0])
        # plot the hull
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x, y = zip(*hull)
        ax.plot(x, y, 'qo-')
    # set additional settings and show plot
    x, y = zip(*points)
    # the fudge factor represents the spacing around the plot so it looks nicer
    fudge factor = math.ceil((max(x) + max(y))/2 * 0.1)
    ax. grid()
    ax. set_xlim(min(x)-fudge_factor, max(x)+fudge_factor)
    ax. set_ylim(min(y)-fudge_factor, max(y)+fudge_factor)
    ax.set_title('Convex Hull')
    plt.shoω()
def main():
    # A dict of the supported methods
    methods = {
        ˈqift_wrapˈ: qift_wrap,
         brute': brute,
         graham_scan': graham_scan,
    }
    # parse command line arguments
    parser = argparse. ArgumentParser(
        description="Find the convex hull of points using varius methods.")
    parser.add_arqument('--qraph', dest='qraph',# narqs=<sup>7</sup>?',
                         const=True, default=False, action='store_const',
                         help='Produce a graph.')
    parser.add_argument('method', metavar='METHOD', type=str,
                          help='The type of method to use. Supported methods are: '+\
    ', '.join(methods))
parser.add_argument('filename', metavar='FILE', type=str,
                         help='The file to parse the points out of. Expects a '+\
                               file of lines with comma seperated x/y values.')
    args = parser.parse args()
    # open the file and parse out the points
    points = parse_points_file(arqs.filename)
    # if we have points let's git-r-done
    if points:
        try:
            result = methods[arqs.method](points)
        except KeyError:
            sys.stderr.write("Invalid method selected\n")
            sys. exit(1)
        print "Convex hull: " + repr(result)
        if args.graph:
            plot(points, result)
        print "Can't parse points file."
if __name__ == "__main__":
    main()
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